



*Personal Computer
Hardware Reference
Library*

Technical Reference

Federal Communications Commission

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Revised Edition (April 1983)

Changes are periodically made to the information herein; these changes will be incorporated in new editions of this publication.

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PREFACE

The IBM Personal Computer Technical Reference manual describes the hardware design and provides interface information for the IBM Personal Computer. This publication also has information about the basic input/output system (BIOS) and programming support.

The information in this publication is both introductory and for reference, and is intended for hardware and software designers, programmers, engineers, and interested persons who need to understand the design and operation of the computer.

You should be familiar with the use of the Personal Computer, and you should understand the concepts of computer architecture and programming.

This manual has two sections:

“Section 1: Hardware” describes each functional part of the system. This section also has specifications for power, timing, and interface. Programming considerations are supported by coding tables, command codes, and registers.

“Section 2: ROM BIOS and System Usage” describes the basic input/output system and its use. This section also contains the software interrupt listing, a BIOS memory map, descriptions of vectors with special meanings, and a set of low memory maps. In addition, keyboard encoding and usage is discussed.

The publication has seven appendixes:

- Appendix A: ROM BIOS Listings
- Appendix B: 8088 Assembly Instruction Set Reference
- Appendix C: Of Characters, Keystrokes, and Color
- Appendix D: Logic Diagrams
- Appendix E: Specifications
- Appendix F: Communications
- Appendix G: Switch Settings

A glossary and bibliography are included.

Prerequisite Publication:

Guide to Operations for the IBM Personal Computer
Part Number 6025000

Suggested Reading:

BASIC for the IBM Personal Computer
Part Number 6025010

Disk Operating System (DOS) for the IBM Personal Computer
Part Number 6024061

Hardware Maintenance and Service for the IBM Personal
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Part Number 6025072

MACRO Assembler for the IBM Personal Computer
Part Number 6024002

Related publications are listed in the bibliography.

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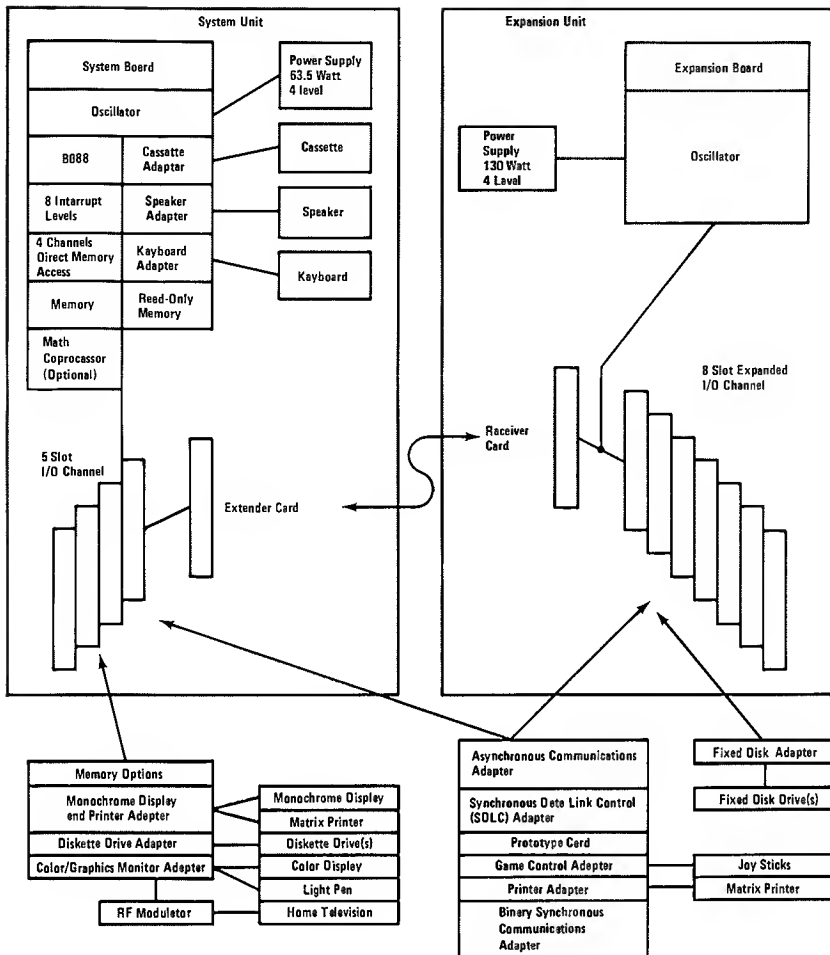
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System Block Diagram

IBM Personal Computer System Unit

The system unit is the standalone tabletop unit that contains the power supply, the speaker, and the system board.

The system unit contains one of two system boards. One system board supports 16K to 64K of read/write memory. The other system board supports 64K to 256K of read/write memory. Both system boards are functionally identical.

The power supply provides dc voltage to the system board and the internal drive(s).

System Board

The system board fits horizontally in the base of the system unit and is approximately 8-1/2 by 12 inches. It is a multilayer, single-land-per-channel design with ground and internal planes provided. DC power and a signal from the power supply enter the board through two six-pin connectors. Other connectors on the board are for attaching the keyboard, audio cassette, and speaker. Five 62-pin card edge-sockets are also mounted on the board. The I/O channel is bussed across these five I/O slots.

Two dual-in-line package (DIP) switches (two eight-switch packs) are mounted on the board and can be read under program control. The DIP switches provide the system software with information about the installed options, how much storage the system board has, what type of display adapter is installed, what operation modes are desired when power is switched on (color or black-and-white, 80- or 40-character lines), and the number of diskette drives attached.

The system board consists of five functional areas: the processor subsystem and its support elements, the read-only memory (ROM) subsystem, the read/write (R/W) memory subsystem, integrated I/O adapters, and the I/O channel. All are described in this section.

The heart of the system board is the Intel 8088 microprocessor. This processor is an 8-bit external bus version of Intel's 16-bit 8086 processor, and is software-compatible with the 8086. Thus, the 8088 supports 16-bit operations, including multiply and divide, and supports 20 bits of addressing (1 megabyte of storage). It also operates in maximum mode, so a co-processor can be added as a feature. The processor operates at a 4.77 MHz. This frequency, which is derived from a 14.31818-MHz crystal, is divided by 3 for the processor clock, and by 4 to obtain the 3.58-MHz color burst signal required for color televisions.

At the 4.77-MHz clock rate, the 8088 bus cycles are four clocks of 210 ns, or 840 ns. I/O cycles take five 210-ns clocks or 1.05 microseconds.

The processor is supported by a set of high-function support devices providing four channels of 20-bit direct-memory access (DMA), three 16-bit timer-counter channels, and eight prioritized interrupt levels.

Three of the four DMA channels are available on the I/O bus and support high-speed data transfers between I/O devices and memory without processor intervention. The fourth DMA channel is programmed to refresh the system dynamic memory. This is done by programming a channel of the timer-counter device to periodically request a dummy DMA transfer. This action creates a memory-read cycle, which is available to refresh dynamic storage both on the system board and in the system expansion slots. All DMA data transfers, except the refresh channel, take five processor clocks of 210 ns, or 1.05 μ s if the processor-ready line is not deactivated. Refresh DMA cycles take four clocks or 840 ns.

The three programmable timer/counters are used by the system as follows: Channel 0 is used as a general-purpose timer providing a constant time base for implementing a time-of-day clock; Channel 1 is used to time and request refresh cycles from the DMA channel; and Channel 2 is used to support the tone generation for the audio speaker. Each channel has a minimum timing resolution of 1.05 μ s.

Of the eight prioritized levels of interrupt, six are bussed to the system expansion slots for use by feature cards. Two levels are used on the system board. Level 0, the highest priority, is attached to Channel 0 of the timer/counter and provides a periodic interrupt for the time-of-day clock. Level 1 is attached to the keyboard adapter circuits and receives an interrupt for each scan code sent by the keyboard. The non-maskable interrupt (NMI) of the 8088 is used to report memory parity errors.

The system board supports both ROM and R/W memory. It has space for 48K x 8 of ROM or EPROM. Six module sockets are provided, each of which can accept an 8K by 8 byte device. Five of the sockets are populated with 40K bytes of ROM. This ROM contains the cassette BASIC interpreter, cassette operating system, power-on self-test, I/O drivers, dot patterns for 128 characters in graphics mode, and a diskette bootstrap loader. The ROM is packaged in 24-pin modules and has an access time of 250 ns and a cycle time of 375 ns.

The difference between the R/W memory on the two system boards is shown in the following chart.

System Board	Minimum Storage	Maximum Storage	Memory Modules	Soldered (Bank 0)	Pluggable (Bank 1-3)
16/64K	16K	64K	16K by 1 Bit	1 Bank of 9	3 Banks of 9
64/256K	64K	256K	64K by 1 Bit	1 Bank of 9	3 Banks of 9

Memory greater than either system board's maximum is obtained by adding memory cards in the expansion slots. All memory is parity-checked and consists of dynamic 16K by 1 bit or (64K by 1 bit) chips with an access time of 250 ns and a cycle time of 410 ns.

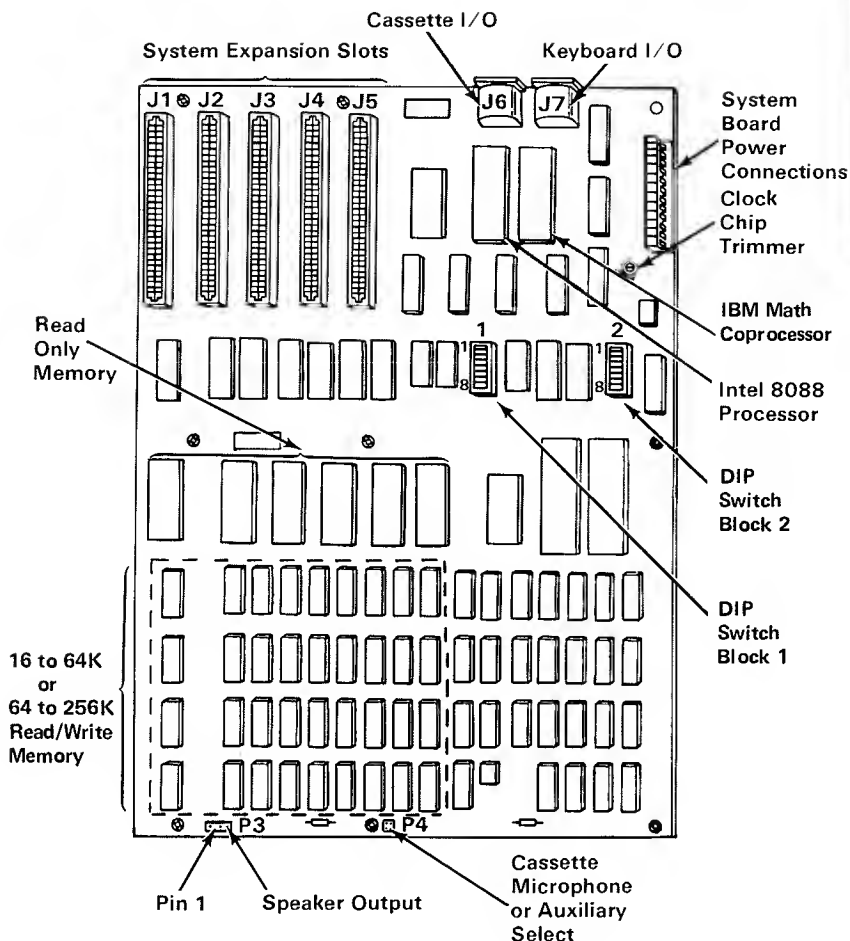
The system board contains circuits for attaching an audio cassette, the keyboard, and the speaker. The cassette adapter allows the attachment of any good quality audio cassette through the earphone output and either the microphone or auxiliary inputs. The system board has a jumper for either input. This interface also provides a cassette motor control line for transport starting and stopping under program control. This interface reads and writes the audio cassette at a data rate of between 1,000 and 2,000 baud. The baud rate is variable and dependent on data content, because a different bit-cell time is used for 0's and 1's. For diagnostic purposes, the tape interface can loop read to write for testing the system board's circuits. The ROM cassette software blocks cassette data and generates a cyclic redundancy check (CRC) to check this data.

The system board contains the adapter circuits for attaching the serial interface from the keyboard. These circuits generate an interrupt to the processor when a complete scan code is received. The interface can request execution of a diagnostic test in the keyboard.

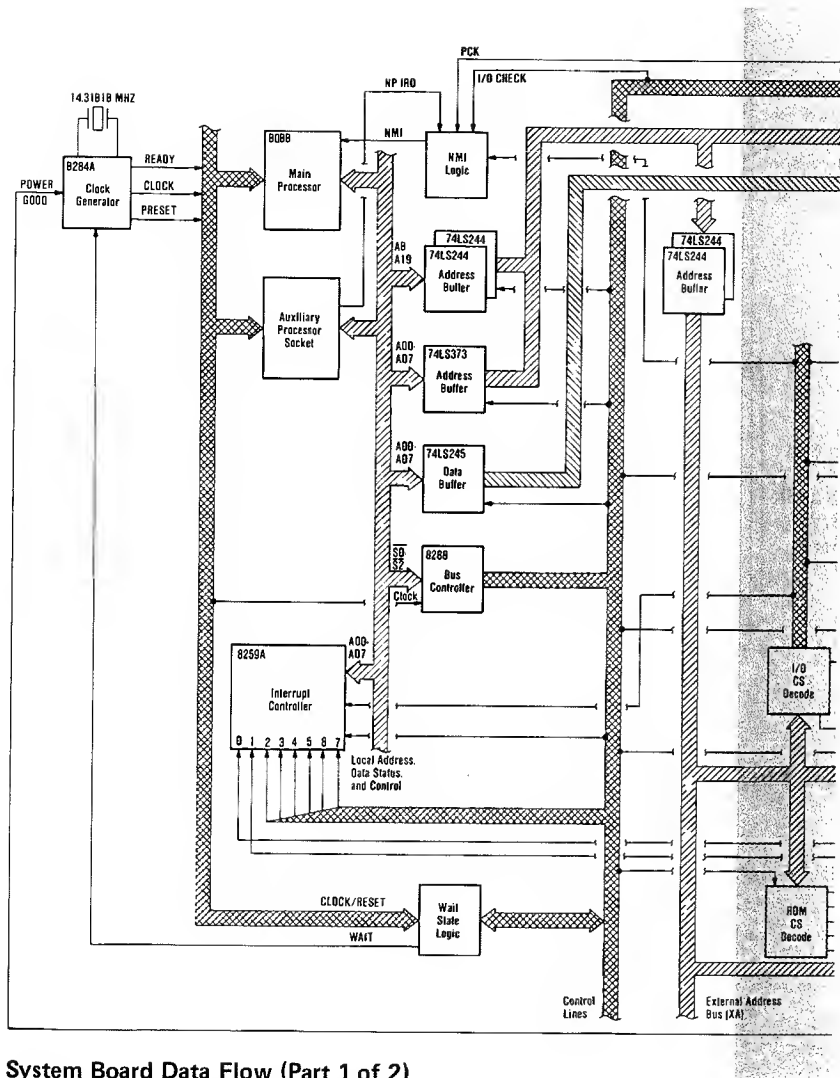
Both the keyboard and cassette interfaces are 5-pin DIN connectors on the system board that extend through the rear panel of the system unit.

The system unit has a 2-1/4 inch audio speaker. The speaker's control circuits and driver are on the system board. The speaker connects through a 2-wire interface that attaches to a 3-pin connector on the system board.

The speaker drive circuit is capable of approximately 1/2 watt of power. The control circuits allow the speaker to be driven three different ways: 1.) a direct program control register bit may be toggled to generate a pulse train; 2.) the output from Channel 2 of the timer counter may be programmed to generate a waveform to the speaker; 3.) the clock input to the timer counter can be modulated with a program-controlled I/O register bit. All three methods may be performed simultaneously.



System Board Component Diagram



System Board Data Flow (Part 1 of 2)

Hex Range	Usage
000-00F	DMA Chip 8237A-5
020-021	Interrupt 8259A
040-043	Timer 8253-5
060-063	PPI 8255A-5
080-083	DMA Page Registers
0A _x *	NMI Mask Register
0C _x	Reserved
0E _x	Reserved
100-1FF	Not Usable
200-20F	Game Control
210-217	Expansion Unit
220-24F	Reserved
278-27F	Reserved
2F0-2F7	Reserved
2F8-2FF	Asynchronous Communications (Secondary)
300-31F	Prototype Card
320-32F	Fixed Disk
378-37F	Printer
380-38C**	SDLC Communications
380-389**	Binary Synchronous Communications (Secondary)
3A0-3A9	Binary Synchronous Communications (Primary)
380-38F	18M Monochrome Display/Printer
3C0-3CF	Reserved
3D0-3DF	Color/Graphics
3E0-3F7	Reserved
3F0-3F7	Diskette
3F8-3FF	Asynchronous Communications (Primary)
<p>* At power-on time, the Non Mask Interrupt into the 8088 is masked off. This mask bit can be set and reset through system software as follows:</p> <p>Set mask: Write hex 80 to I/O Address hex A0 (enable NMI)</p> <p>Clear mask: Write hex 00 to I/O Address hex A0 (disable NMI)</p> <p>** SDLC Communications and Secondary Binary Synchronous Communications cannot be used together because their hex addresses overlap.</p>	

I/O Address Map

Number	Usage
NMI	Parity
0	Timer
1	Keyboard
2	Reserved
3	Asynchronous Communications (Secondary) SDLC Communications BSC (Secondary)
4	Asynchronous Communications (Primary) SDLC Communications BSC (Primary)
5	Fixed Disk
6	Diskette
7	Printer

8088 Hardware Interrupt Listing

Hex Port Number 0060	I N P U T	PA0	+Keyboard Scan Code	0	Or	IPL 5-1/4 Diskette Drive	(SW1—1)																
		1		1		Reserved	(SW1—2)																
		2		2		System Board Read/Write	*(SW1—3)																
		3		3		Memory Size																	
		4		4		System Board Read/Write	*(SW1—4)																
		5		5		Memory Size																	
		6		6		+Display Type 1	**(SW1—5)																
0061	O U T P U T	PB0	+Timer 2 Gate Speaker		Or	+Display Type 2	**(SW1—6)																
		1	+Speaker Data			No. of 5-1/4 Drives	*** (SW1—7)																
		2	+(Read Read/Write Memory Size) or (Read Spare Key)			No. of 5-1/4 Drives	*** (SW1—8)																
		3	+Cassette Motor Off																				
		4	-Enable Read/Write Memory																				
		5	-Enable I/O Channel Check																				
		6	-Hold Keyboard Clock Low																				
0062	I N P U T	7	-(Enable Keyboard) or + (Clear Keyboard and Enable Sense Switches)																				
		PC0	I/O Read/Write Memory (Sw2—1)	Binary Value X 32K	Or	I/O Read/																	
		1	I/O Read/Write Memory (Sw2—2)			Write																	
		2	I/O Read/Write Memory (Sw2—3)			Memory																	
		3	I/O Read/Write Memory (Sw2—4)			(Sw2—5)																	
		4	+Cassette Data In																				
		5	+Timer Channel 2 Out																				
6	+I/O Channel Check																						
0063		7	+Read/Write Memory Parity Check																				
		Command/Mode Register		Hex 99																			
Mode Register Value				<table><tr><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td></tr></table>				7	6	5	4	3	2	1	0	1	0	0	1	1	0	0	1
7	6	5	4	3	2	1	0																
1	0	0	1	1	0	0	1																

*	PA3	PA2	Amount of Memory Located on System Board	
	Sw1—4	Sw1—3		
	0	0		16K
	0	1		32K
	1	0		48K
1	1	64 to 256K		
**	PA5	PA4	Display at Power-Up Mode	
	Sw1—6	Sw1—5		
	0	0		Reserved
	0	1		Color 40 X 25 (BW Mode)
	1	0		Color 80 X 25 (BW Mode)
1	1	IBM Monochrome (80 X 25)		
***	PA7	PA6	Number of 5-1/4" Drives in System	
	Sw1—8	Sw1—7		
	0	0		1
	0	1		2
	1	0		3
1	1	4		

Note: A plus (+) indicates a bit value of 1 performs the specified function.
A minus (-) indicates a bit value of 0 performs the specified function.
PA Bit = 0 implies switch "ON." PA bit = 1 implies switch "OFF."

8255A I/O Bit Map

1-12 System Unit

Start Address		Function
Decimal	Hex	
0	00000	16 to 64K Read/Write Memory on System Board
16K	04000	
32K	08000	
48K	0C000	
64K	10000	Up to 576K Read/Write Memory in I/O Channel
80K	14000	
96K	18000	
112K	1C000	
128K	20000	
144K	24000	
160K	28000	
176K	2C000	
192K	30000	
208K	34000	
224K	38000	
240K	3C000	
256K	40000	
272K	44000	
288K	48000	
304K	4C000	
320K	50000	
336K	54000	
352K	58000	
368K	5C000	
384K	60000	
400K	64000	
416K	68000	
432K	6C000	
448K	70000	
464K	74000	
480K	78000	
496K	7C000	
512K	80000	
528K	84000	
544K	88000	
560K	8C000	
576K	90000	
592K	94000	
608K	98000	
624K	9C000	

System Memory Map for 16/64K System Board (Part 1 of 2)

Start Address		Function
Decimal	Hex	
640K	A0000	128K Reserved
656K	A4000	
672K	A8000	
688K	AC000	
704K	B0000	Monochrome
720K	B4000	
736K	B8000	Color/Graphics
752K	BC000	
768K	C0000	Fixed Disk Control
784K	C4000	
800K	C8000	
816K	CC000	
832K	D0000	192K Read Only Memory Expansion and Control
848K	D4000	
864K	D8000	
880K	DC000	
896K	E0000	
912K	E4000	
928K	E8000	
944K	EC000	
960K	F0000	Reserved
976K	F4000	48K Base System ROM
992K	F8000	
1008K	FC000	

System Memory Map for 16/64K System Board (Part 2 of 2)

Start Address		Function
Decimal	Hex	
0	00000	64 to 256K Read/Write Memory on System Board
16K	04000	
32K	08000	
48K	0C000	
64K	10000	
80K	14000	
96K	18000	
112K	1C000	
128K	20000	
144K	24000	
160K	28000	
176K	2C000	
192K	30000	
208K	34000	
224K	38000	
240K	3C000	
256K	40000	Up to 384K Read/Write Memory in I/O Channel Up to 384K in I/O Channel
272K	44000	
288K	48000	
304K	4C000	
320K	50000	
336K	54000	
352K	58000	
368K	5C000	
384K	60000	
400K	64000	
416K	68000	
432K	6C000	
448K	70000	
464K	74000	
480K	78000	
496K	7C000	
512K	80000	
528K	84000	
544K	88000	
560K	8C000	
576K	90000	
592K	94000	
608K	98000	
624K	9C000	

System Memory Map for 64/256K System Board (Part 1 of 2)

Start Address		Function
Decimal	Hex	
640K	A0000	128K Reserved
656K	A4000	
672K	A8000	
688K	AC000	
704K	B0000	Monochrome
720K	B4000	
736K	B8000	Color/Graphics
752K	BC000	
768K	C0000	192K Read Only Memory Expansion and Control
784K	C4000	
800K	C8000	
816K	CC000	
832K	D0000	
848K	D4000	
864K	D8000	
880K	DC000	
896K	E0000	
912K	E4000	
928K	E8000	
944K	EC000	
960K	F0000	Reserved
976K	F4000	48K Base System ROM
992K	F8000	
1008K	FC000	

System Memory Map for 64/256K System Board (Part 2 of 2)

System Board Switch Settings

All system board switch settings for total system memory, number of diskette drives, and type of display adapter are located in "Appendix G: Switch Settings."

I/O Channel

The I/O channel is an extension of the 8088 microprocessor bus. It is, however, demultiplexed, repowered, and enhanced by the addition of interrupts and direct memory access (DMA) functions.

The I/O channel contains an 8-bit, bidirectional data bus, 20 address lines, 6 levels of interrupt, control lines for memory and I/O read or write, clock and timing lines, 3 channels of DMA control lines, memory refresh timing control lines, a channel-check line, and power and ground for the adapters. Four voltage levels are provided for I/O cards: +5 Vdc, -5 Vdc, +12 Vdc, and -12 Vdc. These functions are provided in a 62-pin connector with 100-mil card tab spacing.

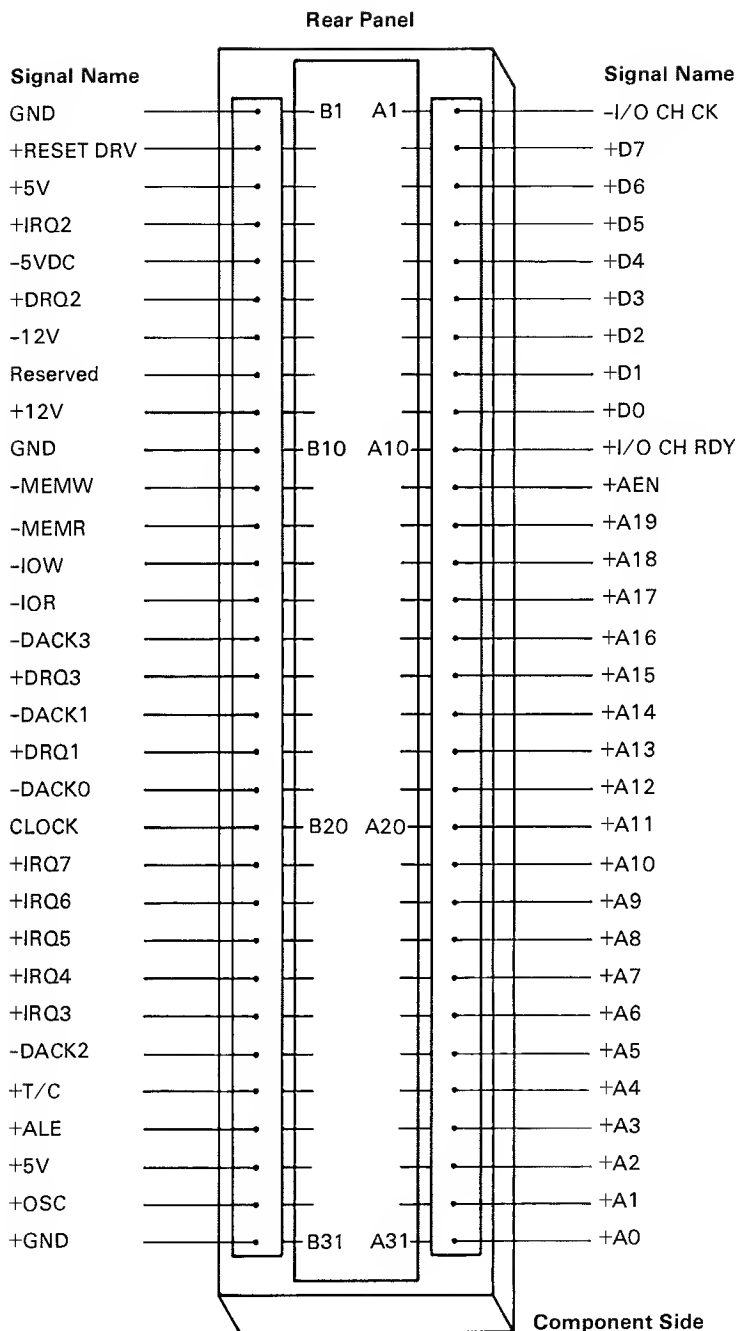
A 'ready' line is available on the I/O channel to allow operation with slow I/O or memory devices. If the channel's ready line is not activated by an addressed device, all processor-generated memory read and write cycles take four 210-ns clock or 840-ns/byte. All processor-generated I/O read and write cycles require five clocks for a cycle time of 1.05 μ s/byte. All DMA transfers require five clocks for a cycle time of 1.05 μ s/byte. Refresh cycles occur once every 72 clocks (approximately 15 μ s) and require four clocks or approximately 7% of the bus bandwidth.

I/O devices are addressed using I/O mapped address space. The channel is designed so that 512 I/O device addresses are available to the I/O channel cards.

A 'channel check' line exists for reporting error conditions to the processor. Activating this line results in a Non-Maskable Interrupt (NMI) to the 8088 processor. Memory expansion options use this line to report parity errors.

The I/O channel is repowered to provide sufficient drive to power all five system unit expansion slots, assuming two low-power Schottky loads per slot. The IBM I/O adapters typically use only one load.

The following pages describe the system board's I/O channel.



I/O Channel Diagram

I/O Channel Description

The following is a description of the IBM Personal Computer I/O Channel. All lines are TTL-compatible.

Signal	I/O	Description
OSC	O	Oscillator: High-speed clock with a 70-ns period (14.31818 MHz). It has a 50% duty cycle.
CLK	O	System clock: It is a divide-by-three of the oscillator and has a period of 210 ns (4.77 MHz). The clock has a 33% duty cycle.
RESET DRV	O	This line is used to reset or initialize system logic upon power-up or during a low line voltage outage. This signal is synchronized to the falling edge of clock and is active high.
A0-A19	O	Address bits 0 to 19: These lines are used to address memory and I/O devices within the system. The 20 address lines allow access of up to 1 megabyte of memory. A0 is the least significant bit (LSB) and A19 is the most significant bit (MSB). These lines are generated by either the processor or DMA controller. They are active high.
D0-D7	I/O	Data Bits 0 to 7: These lines provide data bus bits 0 to 7 for the processor, memory, and I/O devices. D0 is the least significant bit (LSB) and D7 is the most significant bit (MSB). These lines are active high.

Signal	I/O	Description
ALE	O	Address Latch Enable: This line is provided by the 8288 Bus Controller and is used on the system board to latch valid addresses from the processor. It is available to the I/O channel as an indicator of a valid processor address (when used with AEN). Processor addresses are latched with the falling edge of ALE.
$\overline{\text{I/O CH CK}}$	I	-I/O Channel Check: This line provides the processor with parity (error) information on memory or devices in the I/O channel. When this signal is active low, a parity error is indicated.
I/O CH RDY	I	I/O Channel Ready: This line, normally high (ready), is pulled low (not ready) by a memory or I/O device to lengthen I/O or memory cycles. It allows slower devices to attach to the I/O channel with a minimum of difficulty. Any slow device using this line should drive it low immediately upon detecting a valid address and a read or write command. This line should never be held low longer than 10 clock cycles. Machine cycles (I/O or memory) are extended by an integral number of CLK cycles (210 ns).
IRQ2-IRQ7	I	Interrupt Request 2 to 7: These lines are used to signal the processor that an I/O device requires attention. They are prioritized with IRQ2 as the highest priority and IRQ7 as the lowest. An Interrupt Request is generated by raising an IRQ line (low to high) and holding it high until it is acknowledged by the processor (interrupt service routine).

Signal	I/O	Description
$\overline{\text{IOR}}$	O	-I/O Read Command: This command line instructs an I/O device to drive its data onto the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{IOW}}$	O	-I/O Write Command: This command line instructs an I/O device to read the data on the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{MEMR}}$	O	Memory Read Command: This command line instructs the memory to drive its data onto the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
$\overline{\text{MEMW}}$	O	Memory Write Command: This command line instructs the memory to store the data present on the data bus. It may be driven by the processor or the DMA controller. This signal is active low.
DRQ1-DRQ3	I	DMA Request 1 to 3: These lines are asynchronous channel requests used by peripheral devices to gain DMA service. They are prioritized with DRQ3 being the lowest and DRQ1 being the highest. A request is generated by bringing a DRQ line to an active level (high). A DRQ line must be held high until the corresponding DACK line goes active.
$\overline{\text{DACK0-}}\overline{\text{DACK3}}$	O	-DMA Acknowledge 0 to 3: These lines are used to acknowledge DMA requests (DRQ1-DRQ3) and to refresh system dynamic memory (DACK0). They are active low.

Signal	I/O Description
AEN	O Address Enable: This line is used to de-gate the processor and other devices from the I/O channel to allow DMA transfers to take place. When this line is active (high), the DMA controller has control of the address bus, data bus, read command lines (memory and I/O), and the write command lines (memory and I/O).
T/C	O Terminal Count: This line provides a pulse when the terminal count for any DMA channel is reached. This signal is active high.

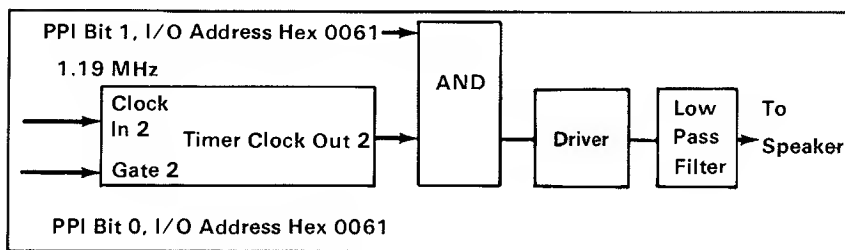
The following voltages are available on the system board I/O channel:

- +5 Vdc $\pm 5\%$, located on 2 connector pins
- 5 Vdc $\pm 10\%$, located on 1 connector pin
- +12 Vdc $\pm 5\%$, located on 1 connector pin
- 12 Vdc $\pm 10\%$, located on 1 connector pin
- GND (Ground), located on 3 connector pins

Speaker Interface

The sound system has a small, permanent-magnet, 2-1/4 inch speaker. The speaker can be driven from one or both of two sources:

- An 8255A-5 PPI output bit. The address and bit are defined in the “I/O Address Map.”
- A timer clock channel, the output of which is programmable within the functions of the 8253-5 timer when using a 1.19-MHz clock input. The timer gate also is controlled by an 8255A-5 PPI output-port bit. Address and bit assignment are in the “I/O Address Map.”



Speaker Drive System Block Diagram

Channel 2 (Tone generation for speaker)
 Gate 2 — Controller by 8255A-5 PPI Bit
 (See I/O Map)
 Clock In 2 — 1.19318 - MHz OSC
 Clock Out 2 — Used to drive speaker

Speaker Tone Generation

The speaker connection is a 4-pin Berg connector. See “System Board Component Diagram,” earlier in this section, for speaker connection or placement.

Pin	Function
1	Data
2	Key
3	Ground
4	+5 Volts

Speaker Connector

Power Supply

The system power supply is located at the right rear of the system unit. It is designed to be an integral part of the system-unit chassis. Its housing provides support for the rear panel, and its fan furnishes cooling for the whole system.

It supplies the power and reset signal necessary for the operation of the system board, installable options, and the keyboard. It also provides a switched ac socket for the IBM Monochrome Display and two separate connectors for power to the 5-1/4 inch diskette drives.

It is a dc-switching power supply designed for continuous operation at 63.5 watts. It has a fused 120-Vac input and provides four regulated dc output voltages: 7 A of +5 Vdc, 2 A of +12 Vdc, 0.3 A of -5 Vdc, and 0.25 A of -12 Vdc. These outputs are over-voltage, over-current, open-circuit, and short-circuit protected. If a dc overload or over-voltage condition occurs, all dc outputs are shut down as long as the condition exists.

The +5 Vdc powers the logic on the system board and the diskette drives and allows approximately 4 A of +5 Vdc for the adapters in the system-unit expansion slots. The +12 Vdc power level is designed to power the system's dynamic memory and the two internal 5-1/4 inch diskette drive motors. It is assumed that only one drive is active at a time. The -5 Vdc level is designed for dynamic memory bias voltage; it tracks the +5 Vdc and +12 Vdc very quickly at power-on and has a longer decay on power-off than the +5 Vdc and +12 Vdc outputs. The +12 Vdc and -12 Vdc are used for powering the EIA drivers on the communications adapters. All four power levels are bussed across the five system-unit expansion slots.

Operating Characteristics

Input Requirements

The following are the input requirements for the system unit power supply.

Voltage (Vac)			Frequency (Hz)	Current (Amps)
Nominal	Minimum	Maximum	+/- 3Hz	Maximum
120	104	127	60	2.5 at 104 Vac

Vdc Output

The following are the dc outputs for the system unit power supply.

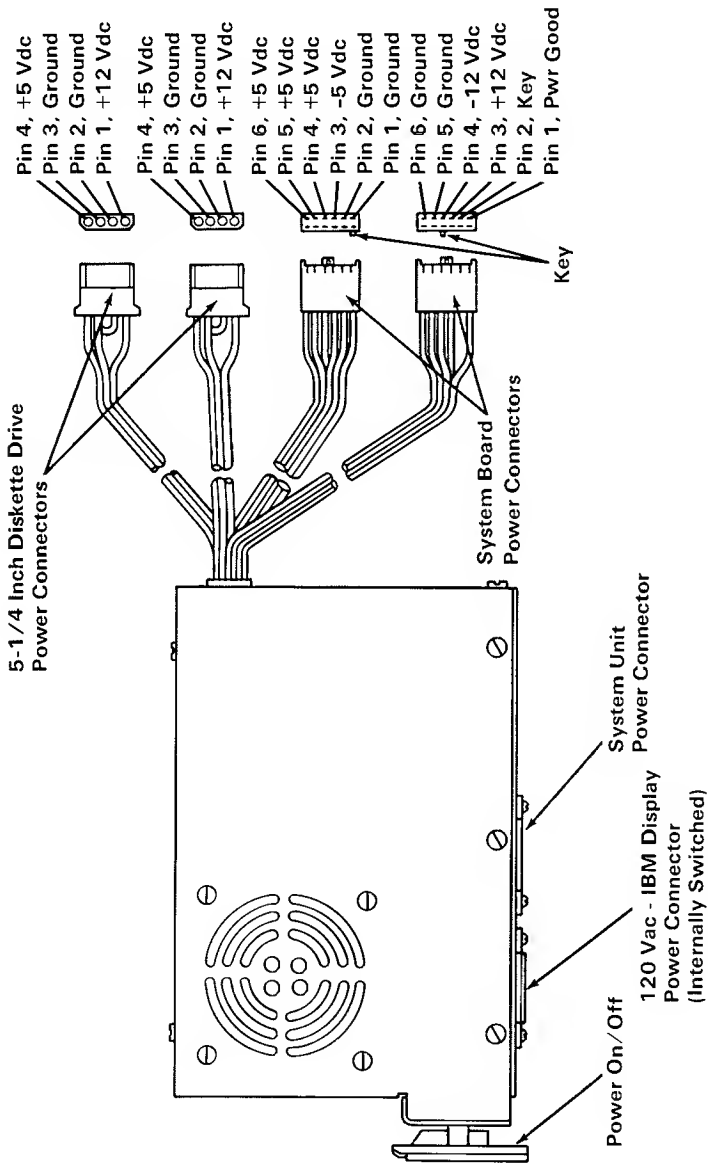
Voltage (Vdc)	Current (Amps)		Regulation (Tolerance)	
Nominal	Minimum	Maximum	+	-
+5.0	2.3	7.0	5	4
-5.0	0.0	0.3	10	8
+12.0	0.4	2.0	5	4
-12.0	0.0	0.25	10	9

Vac Output

The power supply provides a filtered, ac output that is switched on and off with the main power switch. The maximum current available at this output is 0.75 A. The receptacle provided at the rear of the power supply for this ac output is a nonstandard connector designed to be used only for the IBM Monochrome Display.

Power Supply Connectors and Pin Assignments

The power connector on the system board is a 12-pin male connector that plugs into the power-supply connectors. The pin configurations and locations are shown below:



Over-Voltage/Over-Current Protection

The system power supply employs protection features which are described below.

Primary (Input)

The following table describes the primary (input voltage) protection for the system-unit power supply.

Voltage (Nominal Vac)	Type Protection	Rating (Amps)
120	Fuse	2

Secondary (Output)

On over-voltage, the power supply is designed to shut down all outputs when either the +5 Vdc or the +12 Vdc output exceeds 200% of its maximum rated voltage. On over-current, the supply will turn off if any output exceeds 130% of its nominal value.

Power-Good Signal

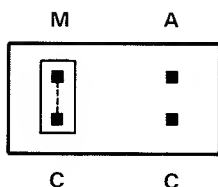
When the power supply is turned on after it has been off for a minimum of 5 seconds, it generates a power-good signal which indicates that there is adequate power for processing. When the four output voltages are above the minimum sense levels, as described below, the signal sequences to a TTL-compatible up level (2.4 Vdc to 5.5 Vdc), which is capable of sourcing 60 μ A. When any of the four output voltages is below its minimum sense level or above its maximum sense level, the power good signal will be a TTL-compatible down level (0.0 Vdc to 0.4 Vdc) capable of sourcing 500 μ A. The power good signal has a turn-on delay of 100 ms after the output voltages have reached their respective minimum sense levels.

Output Voltage	Under-Voltage Nominal Sense Level	Over-Voltage Nominal Sense Level
+5 Vdc	+4.0 Vdc	+5.9 Vdc
-5 Vdc	-4.0 Vdc	-5.9 Vdc
+12 Vdc	+9.6 Vdc	+14.2 Vdc
-12 Vdc	-9.6 Vdc	-14.2 Vdc

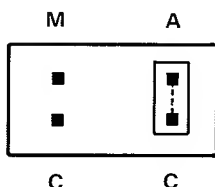
Cassette Interface

The cassette interface is controlled through software. An output from the 8253 timer controls the data to the cassette recorder through pin 5 of the cassette DIN connector at the rear of the system board. The cassette input data is read by an input port bit of the 8255A-5 programmable peripheral interface (8255A-5 PPI). This data is received through pin 4 of the cassette connector. Software algorithms are used to generate and read cassette data. The cassette drive motor is controlled through pins 1 and 3 of the cassette connector. The drive motor on/off switching is controlled by an 8255A-5 PPI output-port bit (hex 61, bit 3). The 8255A-5 address and bit assignments are defined in "I/O Address Map" earlier in this section.

A 2 by 2 Berg pin and a jumper are used on the cassette 'data out' line. The jumper allows use of the 'data out' line as a 0.075-Vdc microphone input when placed across the M and C pins of the Berg connector. A 0.68-Vdc auxiliary input to the cassette recorder is available when the jumper is placed across the A and C pins of the Berg connector. The "System Board Component Diagram" shows the location of the cassette Berg pins.



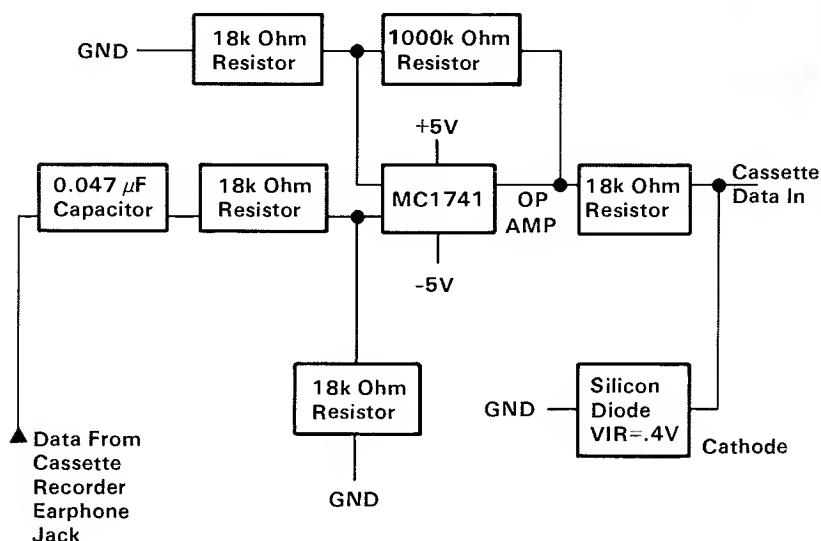
Microphone Input
(0.075 Vdc)



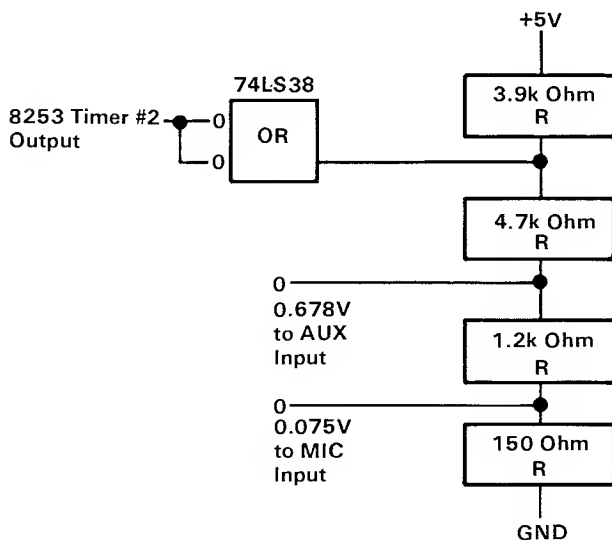
Auxiliary Input
(0.68 Vdc)

Cassette Circuit Block Diagrams

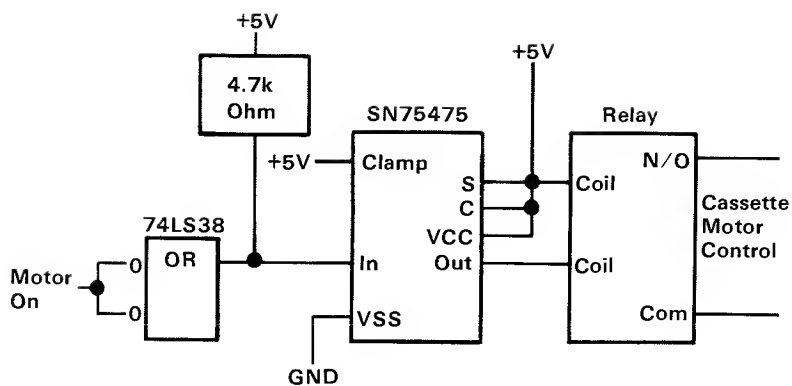
Circuit block diagrams for the cassette-interface read hardware, write hardware, and motor control are illustrated below.



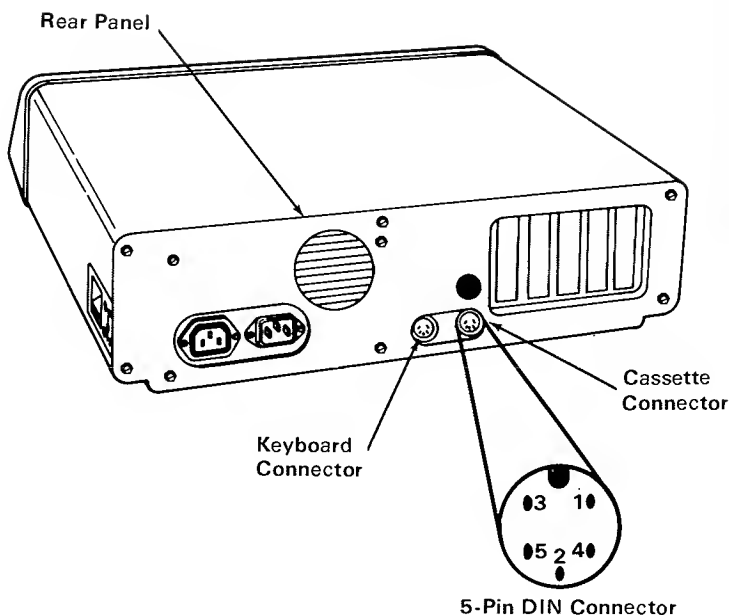
Cassette Interface Read Hardware Block Diagram



Cassette Interface Write Hardware Block Diagram



Cassette Motor Control Block Diagram



Pin	Signal	Electrical Characteristics
1	Motor Control	Common from Relay
2	Ground	
3	Motor Control	Relay N.O. (6 Vdc at 1A)
4	Data In	500nA at $\pm 13V$ - at 1,000 - 2,000 Baud
5	Data Out (Microphone or Auxiliary)	250 μA at 0.68 Vdc or ** 0.075 Vdc

*All voltages and currents are maximum ratings and should not be exceeded.

**Data out can be chosen using a jumper located on the system board.
(Auxiliary \rightarrow 0.68 Vdc or Microphone \rightarrow 0.075 Vdc).

Interchange of these voltages on the cassette recorder could lead to damage of recorder inputs.

Cassette Interface Connector Specifications

Notes:

IBM Personal Computer Math Coprocessor

The IBM Personal Computer Math Coprocessor enables the IBM Personal Computer to perform high speed arithmetic, logarithmic functions, and trigonometric operations with extreme accuracy.

The coprocessor works in parallel with the processor. The parallel operation decreases operation time by allowing the coprocessor to do mathematical calculations while the processor continues to do other functions.

The first five bits of every instruction opcode for the coprocessor are identical (11011 binary). When the processor and the coprocessor see this instruction opcode, the processor calculates the address, of any variables in memory, while the coprocessor checks the instruction. The coprocessor will then take the memory address from the processor if necessary. To access locations in memory, the coprocessor takes the local bus from the processor when the processor finishes its current instruction. When the coprocessor is finished with the memory transfer, it returns the local bus to the processor.

The IBM Math Coprocessor works with seven numeric data types divided into the three classes listed below.

- Binary integers (3 types)
- Decimal integers (1 type)
- Real numbers (3 types)

Programming Interface

The coprocessor extends the data types, registers, and instructions to the processor.

The coprocessor has eight 80-bit registers which provide the equivalent capacity of 40 16-bit registers found in the processor. This register space allows constants and temporary results to be held in registers during calculations, thus reducing memory access and improving speed as well as bus availability. The register space can be used as a stack or as a fixed register set. When used as a stack, only the top two stack elements are operated on: when used as a fixed register set, all registers are operated on. The Figure below shows representations of large and small numbers in each data type.

Data Type	Bits	Significant Digits (Decimal)	Approximate Range (decimal)
Word Integer	16	4	$-32,768 \leq X \leq +32,767$
Short Integer	32	9	$-2 \times 10^9 \leq X \leq +2 \times 10^9$
Long Integer	64	18	$-9 \times 10^{18} \leq X \leq +9 \times 10^{18}$
Packed Decimal	80	18	$-99...99 \leq X \leq +99...99$ (18 digits)
Short Real*	32	6-7	$8.43 \times 10^{-37} \leq X \leq 3.37 \times 10^{38}$
Long Real*	64	15-16	$4.19 \times 10^{-307} \leq X \leq 1.67 \times 10^{308}$
Temporary Real	80	19	$3.4 \times 10^{-4932} \leq X \leq 1.2 \times 10^{4932}$

*The short and long real data types correspond to the single and double precision data types

Data Types

Hardware Interface

The coprocessor utilizes the same clock generator and system bus interface components as the processor. The coprocessor is wired directly into the processor, as shown in the coprocessor interconnection diagram. The processor's queue status lines (QS0 and QS1) enable the coprocessor to obtain and decode instructions simultaneously with the processor. The coprocessor's busy signal informs the processor that it is executing; the processor's WAIT instruction forces the processor to wait until the coprocessor is finished executing (wait for NOT BUSY).

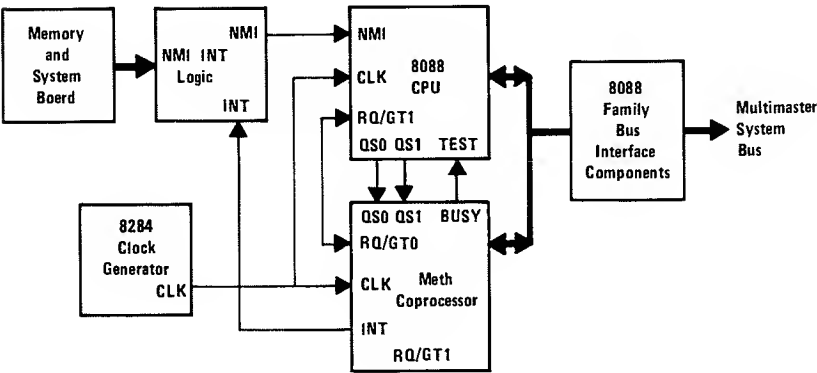
When an incorrect instruction is sent to the coprocessor (for example; divide by zero or load a full register), the coprocessor can signal the processor with an interrupt. There are three conditions that will disable the coprocessor interrupt to the processor:

1. Exception and Interrupt Enable bits of the control word are set to 1's.
2. System board switch block 1 switch 2 set in the On position.
3. NMI Mask REG is set to zero.

At power-on time the NMI Mask REG is cleared to disable the NMI. Any software using the coprocessor's interrupt capability must ensure that conditions 2 and 3 are never met during the operation of the software or an "Endless Wait" will occur. An "Endless Wait" will have the processor waiting for the "Not Busy" signal from the coprocessor while the coprocessor is waiting for the processor to interrupt.

Because a memory parity error may also cause an interrupt to the 8088 NMI line, the program should check that a parity error did not occur (by reading the 8255 port), then clear exceptions by executing the FNSAVE or the FNCLEX instruction. In most cases, the status word would be looked at, and the exception would be identified and acted upon.

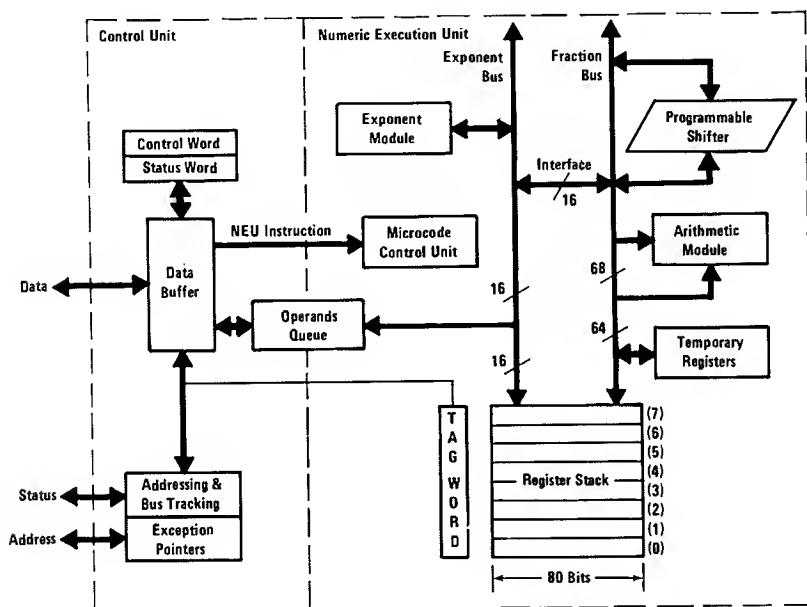
The NMI Mask REG and the coprocessors interrupt are tied to the NMI line through the NMI interrupt logic. Minor conversions of software designed for use with an 8087 must be made before existing software will be compatible with the IBM Personal Computer Math Coprocessor.



Coprocessor Interconnection

Control Unit

The control unit (CU) of the coprocessor and the processor fetch all instructions at the same time, as well as every byte of the instruction stream at the same time. The simultaneous fetching allows the coprocessor to know what the processor is doing at all times. This is necessary to keep a coprocessor instruction from going unnoticed. Coprocessor instructions are mixed with processor instructions in a single data stream. To aid the coprocessor in tracking the processor, nine status lines are interconnected (QS0, QS1, and S0 through S6).



Coprocessor Block Diagram

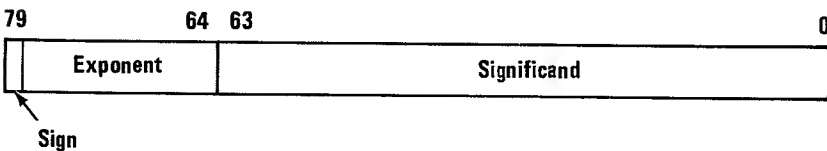
Register Stack

Each of the eight registers in the coprocessor's register stack is 80 bits wide, and each is divided into the "fields" shown in the figure below. The format in the figure below corresponds to the coprocessor's temporary real data type that is used for all calculations.

The ST field in the status word identifies the current top-of-stack register. A load ("push") operation decreases ST by 1 and loads a new value into the top register. A store operation stores the value from the current top register and then increases ST by 1. Thus, the coprocessor's register stack grows "down" toward lower-addressed registers.

Instructions may address registers either implicitly or explicitly. Instructions that operate at the top of the stack, implicitly address the register pointed to by ST. The instruction, FSQRT, replaces the number at the top with its square root; this instruction takes no operands, because the top-of-stack register is implied as the operand. Other instructions specify the register that is to be used. Explicit register addressing is "top-relative." The expression, ST, denotes the current stack top, and ST(i) refers to the ith register from the ST in the stack. If ST contains "binary 011" (register 3 is at the top of the stack), the instruction, FADD ST,ST(2), would add registers 3 and 5.

Passing subroutine parameters to the register stack eliminates the need for the subroutine to know which registers actually contain the parameters. This allows different routines to call the same subroutine without having to observe a convention for passing parameters in dedicated registers. As long as the stack is not full, each routine simply loads the parameters to the stack and calls the subroutine.



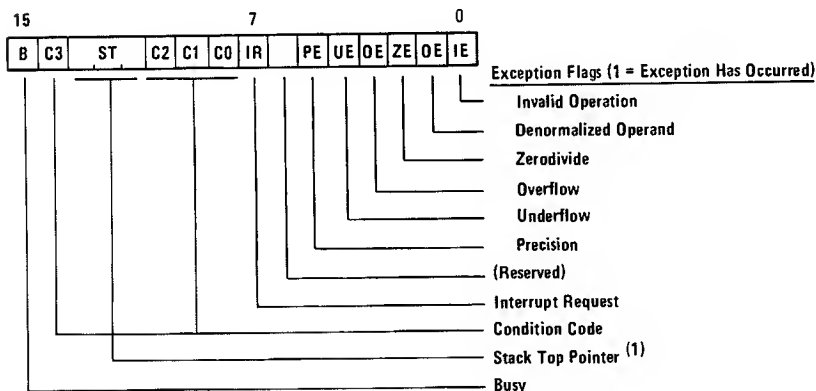
Register Structure

Status Word

The status word reflects the overall condition of the coprocessor. It may be stored in memory with a coprocessor instruction then inspected with a processor code. The status word is divided into the fields shown in the figure below. Bit 15 (BUSY) indicates when the coprocessor is executing an instruction (B=1) or when it is idle (B=0).

Several instructions (for example, the comparison instructions) post their results to the condition code (bits 14 and 10 through 8 of the status word). The main use of the condition code is for conditional branching. This may be accomplished by first executing an instruction that sets the condition code, then storing the status word in memory, and then examining the condition code with processor instructions.

Bits 13 through 11 of the status word point to the coprocessor register that is the current stack top (ST). Bit 7 is the interrupt request field, and bits 5 through 0 are set to indicate that the numeric execution unit has detected an exception while executing the instruction.

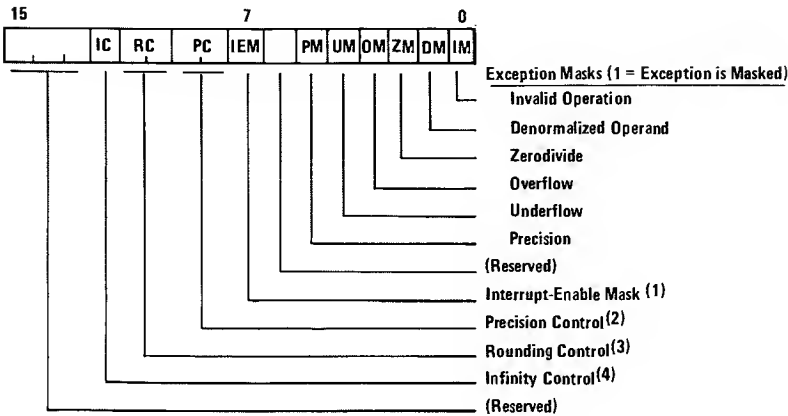


- (1) ST values:
- 000 = register 0 is stack top
 - 001 = register 1 is stack top
 - .
 - .
 - .
 - 111 = register 7 is stack top

Status Word Format

Control Word

The coprocessor provides several options that, are selected by loading a control word register.

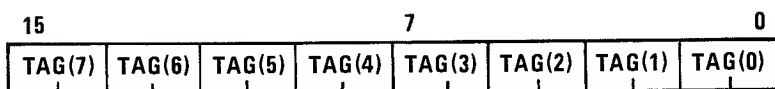


- (1) Interrupt-Enable Mask:
 - 0 = Interrupts Enabled
 - 1 = Interrupts Disabled (Masked)
- (2) Precision Control:
 - 00 = 24 bits
 - 01 = (reserved)
 - 10 = 53 bits
 - 11 = 64 bits
- (3) Rounding Control:
 - 00 = Round to Nearest or Even
 - 01 = Round Down (toward ∞)
 - 10 = Round Up (toward ∞)
 - 11 = Chop (Truncate Toward Zero)
- (4) Infinity Control:
 - 0 = Projective
 - 1 = Affine

Control Word Format

Tag Word

The tag word marks the content of each register, as shown in the Figure below. The main function of the tag word is to optimize the coprocessor's performance under certain circumstances, and programmers ordinarily need not be concerned with it.



Tag values:

00 = Valid (Normal or Unnormal)

01 = Zero (True)

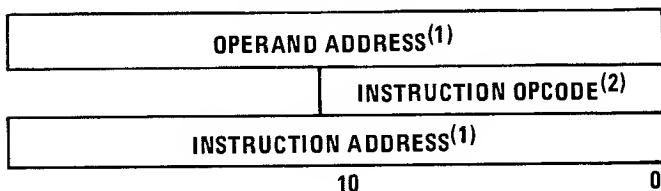
10 = Special (Not-A-Number, ∞ , or Denormal)

11 = Empty

Tag Word Format

Exception Pointers

The exception pointers in the figure below are provided for user-written exception handlers. When the coprocessor executes an instruction, the control unit saves the instruction address and the instruction opcode in the exception pointer registers. An exception handler subroutine can store these pointers in memory and determine which instruction caused the exception.



⁽¹⁾20-bit physical address

⁽²⁾11 least significant bits of opcode: 5 most significant bits are always
COPROCESSOR HOOK (11011B)

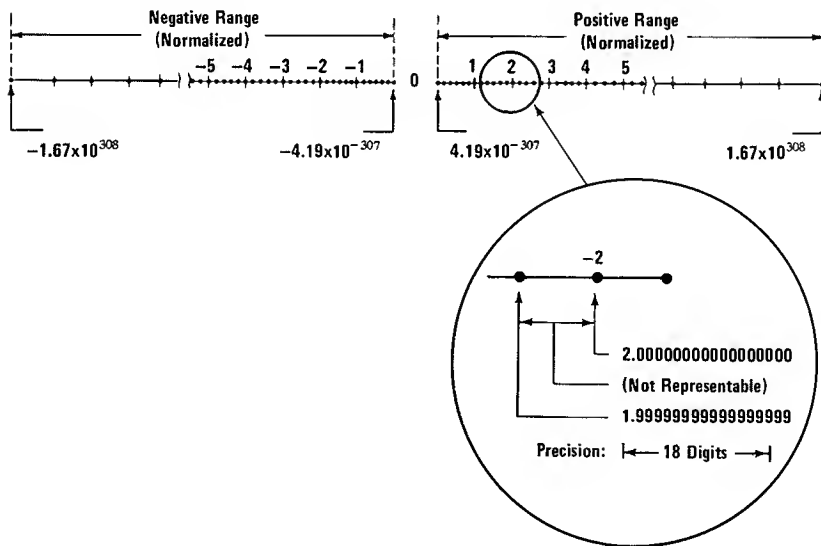
Exception Pointers Format

Number System

The figure below shows the basic coprocessor real number system on a real number line (decimal numbers are shown for clarity, although the coprocessor actually represents numbers in binary). The dots indicate the subset of real numbers the coprocessor can represent as data and final results of calculations. The coprocessor's range is approximately $\pm 4.19 \times 10^{-307}$ to $\pm 1.67 \times 10^{308}$.

The coprocessor can represent a great many of, but not all, the real numbers in its range. There is always a "gap" between two adjacent coprocessor numbers, and the result of a calculation may fall within this space. When this occurs, the coprocessor rounds the true result to a number it can represent.

The coprocessor actually uses a number system that is a superset of that shown in the figure below. The internal format (called temporary real) extends the coprocessor's range to about $\pm 3.4 \times 10^{-4932}$ to $\pm 1.2 \times 10^{4932}$, and its precision to about 19 (equivalent decimal) digits. This format is designed to provide extra range and precision for constants and intermediate results, and is not normally intended for data or final results.



Coprocessor Number System

Instruction Set

On the following pages are descriptions of the operation for the coprocessor's 69 instructions.

An instruction has two basic types of operands – sources and destinations. A source operand simply supplies one of the “inputs” to an instruction; it is not altered by the instruction. A destination operand may also provide an input to an instruction. It is distinguished from a source operand, however, because its content can be altered when it receives the result produced by that operation; that is the destination is replaced by the result.

The operands of any instructions can be coded in more than one way. For example, **FADD** (add real) may be written without operands, with only a source, or with a destination and a source operand. The instruction descriptions use the simple convention of separating alternative operand forms with slashes; the slashes, however, are not coded. Consecutive slashes indicate there are no explicit operands. The operands for **FADD** are thus described as:

source/destination, source

This means that **FADD** may be written in any of three ways:

FADD

FADD source

FADD destination,source

It is important to bear in mind that memory operands may be coded with any of the processor's memory addressing modes.

FABS

FABS (absolute value) changes the top stack element to its absolute value by making its sign positive.

FABS (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	14	10-17	0	2	FABS

FADD

Addition

FADD // source/destination,source

FADDP destination,source

FIADD source

The addition instructions (add real, add real and pop, integer add) add the source and destination operands and return the sum to the destination. The operand at the stack top may be doubled by coding FADD ST,ST(0).

FADD			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	85	70-100	0	2	FADD ST,ST(4)
short-real	105+EA	90-120+EA	4	2-4	FADD AIR_TEMP [SI]
long-real	110+EA	95-125+EA	8	2-4	FADD [BX],MEAN

FADDP Exceptions: I, D, O, U, P					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(I),ST	90	75-105	0	2	FADD ST(2), ST

FIADD Exceptions: I, D, O, P					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	102-137+EA	2	2-4	FIADD DISTANCE_TRAVELLED
short-integer	125+EA	108-143+EA	4	2-4	FIADD PULSE_COUNT(SI)

FBLD

FBLD Source

FBLD (packed decimal BCD) load)) converts the content of the source operand from packed decimal to temporary real and loads (pushes) the result onto the stack. The packed decimal digits of the source are assumed to be in the range X '0-9H'.

FBLD Exceptions: I					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
packed-decimal	300+EA	290-310+EA	10	2-4	FBLD YTD_SALES

FBSTP

FBSTP destination

FBSTP (packed decimal (BCD) store and pop) performs the inverse of FBLD, where the stack top is stored to the destination in the packed-decimal data type.

FBSTP			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
packed-decimal	530+EA	520-542+EA	12	2-4	FBSTP [BX].FORCAST

FCHS

FCHS (change sign) complements (reverses) the sign of the top stack element.

FCHS (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	15	10-17	0	2	FCHS

FCLEX/FNCLEX

FCLEX/FNCLEX (clear exceptions) clears all exception flags, the interrupt request flag, and the busy flag in the status word.

FCLEX/FNCLEX (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FNCLEX

FCOM

FCOM/ /source

FCOM (compare real) compares the stack top to the source operand. This results in the setting of the condition code bits.

FCOM		Exceptions: I, D			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	45	40-50	0	2	FCOM ST(1)
short-real	65+EA	63-70+EA	4	2-4	FCOM [BP.]UPPER_LIMIT
long-real	70+EA	65-75+EA	8	2-4	FCOM WAVELENGTH

C3	C0	Order
0	0	ST > source
0	1	ST < source
1	0	ST = source
1	1	ST ? source

NANS and ∞ (projective) cannot be compared and return C3=C0=1 as shown above.

FCOMP

FCOMP/ /source

FCOMP (compare real and pop) operates like FCOM, and in addition pops the stack

FCOMP		Exceptions: I, D			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	47	42-52	0	2	FCOMP ST(2)
short-real	68+EA	63-73+EA	4	2-4	FCOMP [8P].N_READINGS
long-real	72+EA	67-77+EA	8	2-4	FCOMP DENSITY

FCOMPP

FCOMPP/ /source

FCOMPP (compare real and pop twice) operates like FCOM and, additionally, pops the stack twice, discarding both operands. The comparison is of the stack top to ST(1); no operands may be explicitly coded.

FCOMPP (no operands)			Exceptions: I, D		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	50	45-55	0	2	FCOMPP

FDECSTP

FDECSTP (decrement stack pointer) subtracts 1 from ST, the stack top pointer in the status word.

FDECSTP (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	9	6-12	0	2	FDECSTP

FDISI/FNDISI

FDISI/FNDISI (disable interrupts) sets the interrupt enable mask in the control word.

FDISI/FNDISI (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FDISI

FDIV

Normal division

FDIV / /source/ destination,source

FDIVP destination,source

FIDIV source

The normal division instructions (divide real, divide real and pop, integer divide) divide the destination by the source and return the quotient to the destination.

FDIV		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i),ST	198	193-203	0	2	FDIV
short-real	220+EA	215-225+EA	4	2-4	FDIV DISTANCE
long-real	225+EA	220-230+EA	8	2-4	FDIV ARC[DI]

FDIVP		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	202	197-207	0	2	FDIVP ST(4), ST

FIDIV		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	230+EA	224-238+EA	2	2-4	FIDIV SURVEY.OBSERVATIONS
short-integer	236+EA	230-243+EA	4	2-4	FIDIV RELATIVE_ANGLE[DI]

FDIVR

Reversed Division

FDIVR / /source/ destination,source

FDIVRP destination,source

FIDIVR source

The reversed division instructions (divide real reversed, divide real reversed and pop, integer divide reversed) divide the source operand by the destination and return the quotient to the destination.

FDIVR		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	199	194-204	0	2	FDIVR ST(2), ST
short-real	221+EA	216-226+EA	6	2-4	FDIVR [BX].PULSE_RATE
long-real	226+EA	221-231+EA	8	2-4	FDIVR RECORDER.FREQUENCY

FDIVRP		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	203	198-208	0	2	FDIVRP ST(1), ST

FIDIVR		Exceptions: I, D, Z, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	230+EA	225-239+EA	2	2-4	FIDIVR [BP].X_CDORD
short-integer	237+EA	231-245+EA	4	2-4	FIDIVR FREQUENCY

FENI/FNENI

FENI/FNENI (enable interrupts) clear the interrupt enable mask in the control word.

FENI/FNENI (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FNENI

FFREE

FFREE destination

FFREE (free register) changes the destination register's tag to empty; the content of the register is not affected.

FFREE			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	186	9-16	0	2	FFREE ST(1)

FICOM

FICOM source

FICOM (integer compare) compares the source to the stack top.

FICOM			Exceptions: I, D		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	80+EA	72-86+EA	2	2-4	FICOM TOOL.N_PASSES
short-integer	85+EA	78-91+EA	2	2-4	FICOM [BP+41].PARAM_COUNT

FICOMP

FICOMP source

FICOMP (integer compare and pop) operates the same as FICOM and additionally pops the stack.

FICOMP		Exceptions: I, D			
Operands	Execution Clocks		Transfers 8088	Bytas	Coding Example
	Typical	Range			
word-integer	82+EA	74-88+EA	2	2-4	FICOMP [BP].LIMIT [SI]
short-inter	87+EA	80-93+EA	4	2-4	FICOMP N_SAMPLES

FILD

FILD source

FILD (integer load) loads (pushes) the source onto the stack.

FILD		Exceptions: I			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	50+EA	46-54+EA	2	2-4	FILD [BX].SEQUENCE
short-integer	56+EA	52-60+EA	4	2-4	FILD STANDOFF[DI]
long-integer	64+EA	60-68+EA	8	2-4	FILD RESPONSE.COUNT

FINCSTP

FINCSTP (increment stack pointer) adds 1 to the stack top pointer (ST) in the status word.

FINCSTP (no operands)		Exceptions: None			
Operands	Execution Clocks		Transfers 8088	Bytas	Coding Exempla
	Typical	Range			
(no operands)	9	6-12	0	2	FINCSTP

FINIT/FNINIT

FINIT/FNINIT (initialize processor) performs the functional equivalent of a hardware RESET.

FINIT/FNINIT (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	5	2-8	0	2	FINIT

Field	Value	Interpretation
Control Word		
Infinity Control	0	Projective
Rounding Control	00	Round to nearest
Precision Control	11	64 bits
Interrupt-enable Mask	1	Interrupts disabled
Exception Masks	111111	All exceptions masked
Status Word		
Busy	0	Not Busy
Condition Code	????	(Indeterminate)
Stack Top	000	Empty stack
Interrupt Request	0	No interrupt
Exception Flags	000000	No exceptions
Tag Word		
Tags	11	Empty
Registers	N.C.	Not changed
Exception Pointers		
Instruction Code	N.C.	Not changed
Instruction Address	N.C.	Not changed
Operand Address	N.C.	Not changed

FIST

FIST destination

FIST (integer store) stores the stack top to the destination in the integer format.

FIST		Exceptions: I, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	86+EA	80-90+EA	4	2-4	FIST DBS.COUNT[SI]
short-integer	88+EA	82-92+EA	6	2-4	FIST (BP).FACTORED_PULSES

FISTP

FISTP destination

FISTP (integer store and pop) operates like FIST and also pops the stack following the transfer. The destination may be any of the binary integer data types.

FISTP		Exceptions: I, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	88+EA	82-92+EA	4	2-4	FISTP (8X).ALPHA_COUNT[SI]
short-integer	90+EA	84-94+EA	6	2-4	FISTP CORRECTED_TIME
long-integer	100+EA	94-105+EA	10	2-4	FISTP PANEL.N_READINGS

FLD

FLD source

FLD (load real) loads (pushes) the source operand onto the top of the register stack.

FLD		Exceptions: I, D			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	20	17-22	0	2	FLD ST(0)
short-real	43+EA	38-56+EA	4	2-4	FLD READING(SI).PRESSURE
long-real	46+EA	40-60+EA	8	2-4	FLD [BP].TEMPERATURE
temp-real	57+EA	53-65+EA	10	2-4	FLD SAVEREADING

FLDCW

FLDCW source

FLDCW (load control word) replaces the current processor control word with the word defined by the source operand.

FLDCW		Exceptions: None			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	10+EA	7-14+EA	2	2-4	FLDCW CONTRDL_WORD

FLDENV

FLDENV source

FLDENV (load environment) reloads the coprocessor environment from the memory area defined by the source operand.

FLDENV			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
14-bytes	40+EA	35-45+EA	14	2-4	FLDENV [BP+6]

FLDLG2

FLDLG2 (load log base 10 of 2) loads (pushes) the value of LOG₁₀2 onto the stack.

FLDLG2 (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	21	18-24	0	2	FLDLG2

FLDLN2

FLDLN2 (load log base e of 2) loads (pushes) the value of LOG_e2 onto the stack.

FLDLN2 (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	20	17-23	0	2	FLDLN2

FLDL2E

FLDL2E (load log base 2 of e) loads (pushes) the value $\text{LOG}_2 e$ onto the stack.

FLDL2E (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	18	15-21	0	2	FLDL2E

FLDL2T

FLDL2T (load log base 2 of 10) loads (pushes) the value of $\text{LOG}_2 10$ onto the stack.

FLDL2T (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	19	16-22	0	2	FLDL2T

FLDPI

FLDPI (load π) loads (pushes) π onto the stack.

FLDPI (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	8bytes	Coding Example
	Typical	Range			
(no operands)	19	16-22	0	2	FLDPI

FLDZ

FLDZ (load zero) loads (pushes) +0.0 onto the stack.

FLDZ (no operands)			Exceptions: I		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	14	11-17	0	2	FLD1

FLD1

FLD1 (load one) loads (pushes) +1.0 onto the stack.

FLD1 (no operands)			Exceptions: I		
Oparends	Exacution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	18	15-21	0	2	FLDZ

FMUL

Multiplication

FMUL //source/destination,source

FMULP destination,source

FIMUL source

The multiplication instructions (multiply real, multiply real and pop, integer multiply) multiply the source and destination operands and return the product to the destination. Coding FMUL ST,ST(0) square the content of the stack top.

FMUL Exceptions: I, D, O, U, P					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i),ST/ST,ST(i) ¹	97	90-105	0	2	FMUL ST,ST(3)
//ST(i),ST/ST,ST(i)	138	130-145	0	2	FMUL ST,ST(3)
short-real	118+EA	110-125+EA	4	2-4	FMUL SPEED_FACTOR
long-real ¹	120+EA	112-126+EA	8	2-4	FMUL [BP].HEIGHT
long-real	161+EA	154-168+EA	8	2-4	FMUL [BP].HEIGHT

¹ occurs when one or both operands is "short" - it has 40 trailing zeros in its fraction.

FMULP Exceptions: I, D, O, U, P					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST ¹	100	94-108	0	2	FMULP ST(1),ST
ST(i),ST	142	134-148	0	2	FMULP ST(1),ST

¹ occurs when one or both operands is "short" - it has 40 trailing zeros in its fraction.

FIMUL Exceptions: I, D, O, P					
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	130+EA	124-138+EA	2	2-4	FIMUL BEARING
short-integer	136+EA	130-144+EA	4	2-4	FIMUL POSITION.Z_AXIS

FNOP

FNOP (no operation) stores the stack top to the stack top (FST ST,ST(0)) and thus effectively performs no operation.

FNOP (no operands)			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	13	10-16	0	2	FNOP

FPATAN

FPATAN (partial arctangent) computes the function $\theta = \text{ARCTAN}(Y/X)$. X is taken from the top stack element and Y from ST(1). Y and X must observe the inequality $0 < Y < X < \infty$. The instruction pops the stack and returns θ to the (new) stack top, overwriting the Y operand.

FPATAN (no operands)			Exceptions: U, P (operands not checked)		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	650	250-800	0	2	FPATAN

FPREM

FPREM (partial remainder) performs modulo division on the top stack element by the next stack element, that is, ST(1) is the modulus.

FPREM (no operands)			Exceptions: I, D, U		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	125	15-190	0	2	FPREM

FPTAN

FPTAN (partial tangent) computes the function $Y/X = \text{TAN}(\theta)$. θ is taken from the top stack element; it must lie in the range $0 < \theta < \pi/4$. The result of the operation is a ratio; Y replaces θ in the stack and X is pushed, becoming the new stack top.

FPTAN		Exceptions: I, P (operands not checked)			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	450	30-540	0	2	FPTAN

FRNDINT

FRNDINT (round to integer) rounds the top stack element to an integer.

FRNDINT (no operands)		Exceptions: I, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	45	16-50	0	2	FRNDINT

FRSTOR

FRSTOR source

FRSTOR (restore state) reloads the coprocessor from the 94-byte memory area defined by the source operand.

FRSTOR		Exceptions: None			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
94-bytes	210+EA	205-215+EA	96	2-4	FRSTOR [BP]

FSAVE/FNSAVE

FSAVE/FNSAVE destination

FSAVE/FNSAVE (save state) writes the full coprocessor state – environment plus register stack – to the memory location defined by the destination operand.

FSAVE/FNSAVE			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
94-bytes	210+EA	205-215+EA	94	2-4	FSAVE [BP]

FSCALE

FSCALE (scale) interprets the value contained in ST(1) as an integer, and adds this value to the exponent of the number in ST. This is equivalent to:

$$ST \leftarrow ST \cdot 2^{ST(1)}$$

Thus, FSCALE provides rapid multiplication or division by integral powers of 2.

FSCALE (no operands)			Exceptions: I, O, U		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	35	32-38	0	2	FSCALE

FSQRT

FSQRT (square root) replaces the content of the top stack element with its square root.

Note: the square root of -0 is defined to be -0.

FSQRT (no operands)			Exceptions: I, D, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	183	180-186	0	2	FSQRT

FST

FST destination

FST (store real) transfers the stack top to the destination, which may be another register on the stack or long real memory operand.

FST		Exceptions: I, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	18	15-22	0	2	FST ST(3)
short-real	87+EA	84-90+EA	6	2-4	FST CDRRELATION [DI]
long-real	100+EA	96-104+EA	10	2-4	FST MEAN_READING

FSTCW/FNSTCW

FSTCW/FNSTCW destination

FSTCW/FNSTCW (store control word) writes the current processor control word to the memory location defined by the destination.

FSTCW/FNSTCW		Exceptions: None			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	15+EA	12-18+EA	4	2-4	FSTCW SAVE_CNTRDL

FSTENV/FNSTENV

FSTENV/FNSTENV destination

FSTENV/FNSTENV (store environment) writes the coprocessor's basic status – control, status and tag words, and exception pointers – to the memory location defined by the destination operand.

FSTENV/FNSTENV			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
14-bytes	45+EA	40-50+EA	16	2-4	FSTENV [BP]

FSTP

FSTP destination

FSTP (store real and pop) operates the same as FST, except that the stack is popped following the transfer.

FSTP			Exceptions: I, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i)	20	17-24	0	2	FSTP ST(2)
short-real	89+EA	86-92+EA	6	2-4	FSTP [BX].ADJUSTED_RPM
long-real	102+EA	98-106+EA	10	2-4	FSTP TOTAL_DOSAGE
temp-real	55+EA	52-58+EA	12	2-4	FSTP REG_SAVE[SI]

FSTSW/FNSTSW

FSTSW/FNSTSW destination

FSTSW/FNSTSW (store status word) writes the current value of the coprocessor status word to the destination operand in memory.

FSTSW/FNSTSW			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
2-bytes	14+EA	12-18+EA	4	2-4	FSTSW SAVE_STATUS

FSUB

Subtraction

FSUB / /source/destination,source

FSUBP destination,source

FISUB source

The normal subtraction instructions (subtract real, subtract real and pop, integer subtract) subtract the source operand from the destination and return the difference to the destination.

FSUB			Exceptions: I, D, O, U, P		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	85	70-100	0	2	FSUB ST,ST(2)
short-real	105+EA	90-120+EA	4	2-4	FSUB BASE_VALUE
long-real	110+EA	95-125+EA	8	2-4	FSUB COORDINATE.X

FSUBP		Exceptions: I, D, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	90	75-105	0	2	FSUBP ST(2),ST

FISUB		Exceptions: I, D, O, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	102-137+EA	2	2-4	FISUB BASE_FREQUENCY
short-integer	125+EA	108-143+EA	4	2-4	FISUB TRAIN_SIZE[DI]

FSUBR

Reversed Subtraction

FSUBR / /source/destination,source

FSUBRP destination,source

FISUBR source

The reversed subtraction instructions (subtract real reversed, subtract real reversed and pop, integer subtract reversed) subtract the destination from the source and return the difference to the destination.

FSUBR		Exceptions: I, D, O, U, P			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST,ST(i)/ST(i),ST	87	70-100	0	2	FSUBR ST,ST(1)
short-real	105+EA	90-120+EA	4	2-4	FSUBR VECTOR[SI]
long-real	110+EA	95-125+EA	8	2-4	FSUBR [BX].INDEX

FSUBRP	Exceptions: I, D, O, U, P				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
ST(i),ST	90	75-105	0	2	FSUBRP ST(1),ST

FISUBR	Exceptions: I, D, O, P				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
word-integer	120+EA	103-139+EA	2	2-4	FISUBR FLOOR[BX] [SI]
short-integer	125+EA	109-144+EA	4	2-4	FISUBR BALANCE

FTST

FTST (test) tests the top stack element by comparing it to zero. The result is posted to the condition codes.

FTST (no operands)	Exceptions: I, D				
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	42	38-48	0	2	FTST

C3	C0	Result
0	0	ST is positive and nonzero
0	1	ST is negative and nonzero
1	0	ST is zero (+ or -)
1	1	ST is not comparable (that is, it is a NAN or projective ∞)

FWAIT

FWAIT (processor instruction)

FWAIT is not actually a coprocessor instruction, but an alternate mnemonic for the processor WAIT instruction. The FWAIT mnemonic should be coded whenever the programmer wants to synchronize the processor to the coprocessor, that is, to suspend further instruction decoding until the coprocessor has completed the current instruction.

FWAIT (no operands)			Exceptions: Non (CPU instruction)		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	3+5n	3+5n	0	1	FWAIT

FXAM

FXAM (examine) reports the content of the top stack element as positive/negative and NAN/unnormal/denormal/normal/zero, or empty.

FXAM			Exceptions: None		
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	17	12-23	0	2	FXAM

Condition Code				Interpretation
C3	C2	C1	C0	
0	0	0	0	+ Unnormal
0	0	0	1	+ NAN
0	0	1	0	– Unnormal
0	0	1	1	– NAN
0	1	0	0	+ Normal
0	1	0	1	+ ∞
0	1	1	0	– Normal
0	1	1	1	– ∞
1	0	0	0	+ 0
1	0	0	1	Empty
1	0	1	0	– 0
1	0	1	1	Empty
1	1	0	0	+ Denormal
1	1	0	1	Empty
1	1	1	0	– Denormal
1	1	1	1	Empty

FXCH

FXCH/ /destination

FXCH (exchange registers) swaps the contents of the destination and the stack top registers. If the destination is not coded explicitly, ST(1) is used.

FXCH		Exceptions: 1			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
//ST(i)	12	10-15	0	2	FXCH ST(2)

FXTRACT

FXTRACT (extract exponent and significant) “decomposes” the number in the stack top into two numbers that represent the actual value of the operand’s exponent and significand fields contained in the stack top and ST(1).

FXTRACT		Exceptions: I			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	50	27-55	0	2	FXTRACT

FYL2X

FYL2X (Y log base 2 of X) calculates the function $Z=Y \cdot \text{LOG}_2$. X is taken from the stack top and Y from ST(1). The operands must be in the ranges $0 < X < \infty$ and $-\infty < Y < +\infty$. The instruction pops the stack and returns Z at the (new) stack top, replacing the Y operand.

$$\text{LOG}_n 2 \cdot \text{LOG}_2 X$$

FYL2X		Exceptions: P (operands not checked)			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	950	900-1100	0	2	FYL2X

FYL2XP1

FYL2XP1 ($Y \log_2(X + 1)$) calculates the function $Z = Y \cdot \log_2(X + 1)$. X is taken from the stack top and must be in the range $0 < |X| < (1 - (\sqrt{2}/2))$. Y is taken from ST(1) and must be in the range $-\infty < Y < \infty$. FYL2XP1 pops the stack and returns Z at the (new) stack top, replacing Y.

FYL2XP1		Exceptions: P (operands not checked)			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	850	700-1000	0	2	FYL2XP1

F2XM1

F2XM1 ($2 \text{ to the } X \text{ minus } 1$) calculates the function $Y = 2^X - 1$. X is taken from the stack top and must be in the range $0 < X < 0.5$. The result Y replaces the stack top.

This instruction is designed to produce a very accurate result even when X is close to zero. To obtain $Y = 2^X$, add 1 to the result delivered by F2XM1.

F2XM1		Exceptions: U, P (operands not checked)			
Operands	Execution Clocks		Transfers 8088	Bytes	Coding Example
	Typical	Range			
(no operands)	500	310-630	0	2	F2XM1

Notes:

IBM Keyboard

The keyboard has a permanently attached cable that connects to a DIN connector at the rear of the system unit. This shielded four-wire cable has power (+5 Vdc), ground, and two bidirectional signal lines. The cable is approximately 6-feet long and is coiled, like that of a telephone handset.

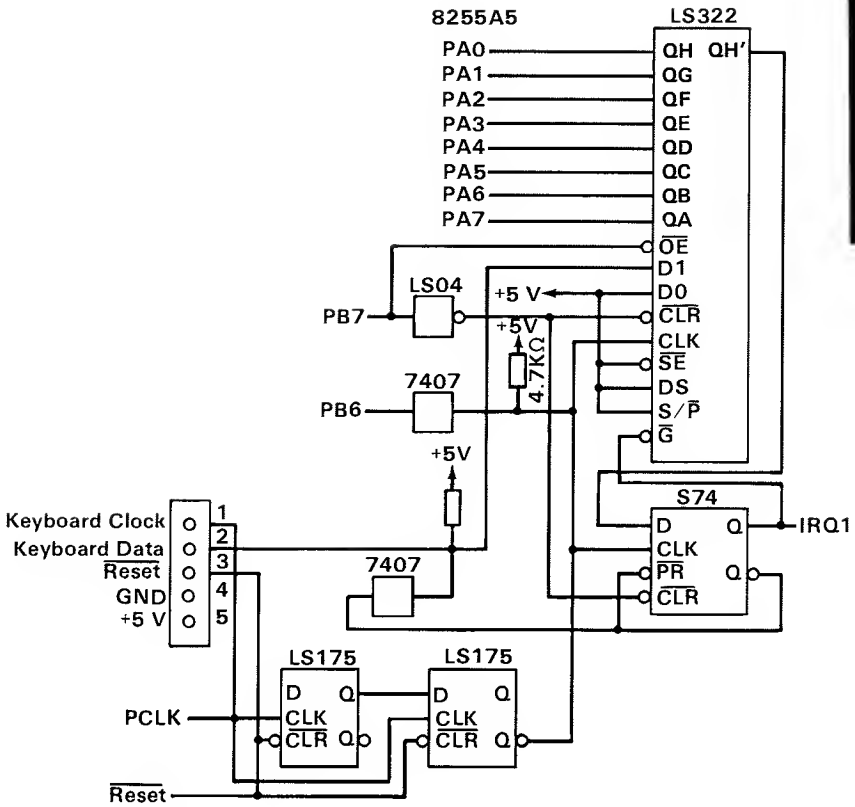
The keyboard uses a capacitive technology with a microcomputer (Intel 8048) performing the keyboard scan function. The keyboard has three tilt positions for operator comfort (5-, 7-, or 15-degree tilt orientations).

The keyboard has 83 keys arranged in three major groupings. The central portion of the keyboard is a standard typewriter keyboard layout. On the left side are 10 function keys. These keys are user-defined by the software. On the right is a 15-key keypad. These keys are also defined by the software, but have legends for the functions of numeric entry, cursor control, calculator pad, and screen edit.

The keyboard interface is defined so that system software has maximum flexibility in defining certain keyboard operations. This is accomplished by having the keyboard return scan codes rather than American Standard Code for Information Interchange (ASCII) codes. In addition, all keys are typematic and generate both a make and a break scan code. For example, key 1 produces scan code hex 01 on make and code hex 81 on break. Break codes are formed by adding hex 80 to make codes. The keyboard I/O driver can define keyboard keys as shift keys or typematic, as required by the application.

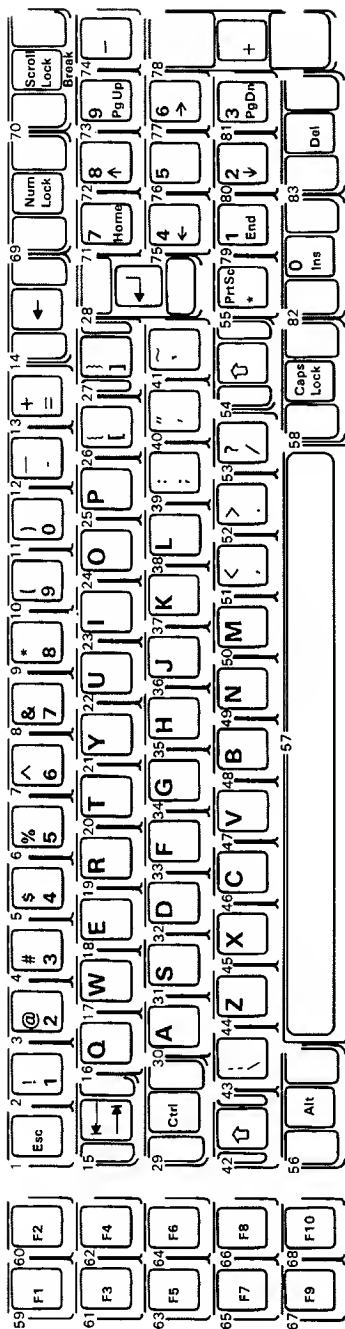
The microcomputer (Intel 8048) in the keyboard performs several functions, including a power-on self-test when requested by the system unit. This test checks the microcomputer ROM, tests memory, and checks for stuck keys. Additional functions are: keyboard scanning, buffering of up to 16 key scan codes, maintaining bidirectional serial communications with the system unit, and executing the hand-shake protocol required by each scan-code transfer.

The following pages have figures that show the keyboard, the scan codes, and the keyboard interface connector specifications.



Keyboard Interface Block Diagram

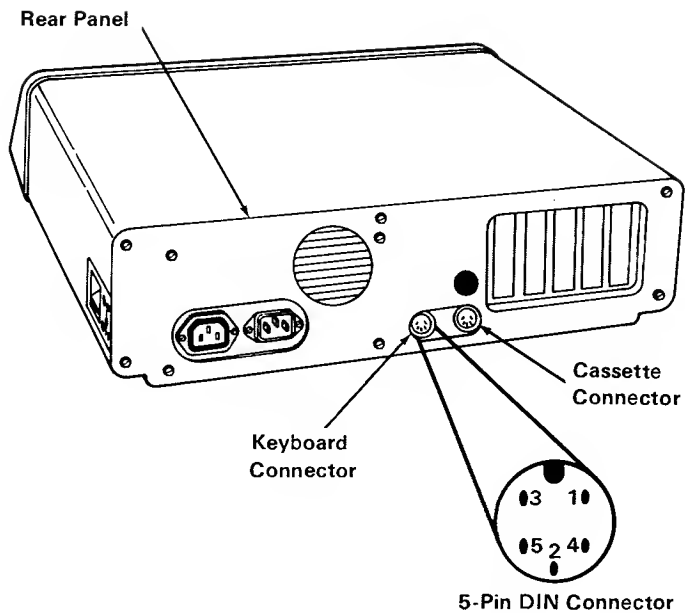
Keyboard Diagram



Note: Nomenclature is on both the top and front face of the keybutton as shown. The number to the upper left designates the button position.

Key Position	Scan Code in Hex	Key Position	Scan Code in Hex
1	01	43	2B
2	02	44	2C
3	03	45	2D
4	04	46	2E
5	05	47	2F
6	06	48	30
7	07	49	31
8	08	50	32
9	09	51	33
10	0A	52	34
11	0B	53	35
12	0C	54	36
13	0D	55	37
14	0E	56	38
15	0F	57	39
16	10	58	3A
17	11	59	3B
18	12	60	3C
19	13	61	3D
20	14	62	3E
21	15	63	3F
22	16	64	40
23	17	65	41
24	18	66	42
25	19	67	43
26	1A	68	44
27	1B	69	45
28	1C	70	46
29	1D	71	47
30	1E	72	48
31	1F	73	49
32	20	74	4A
33	21	75	4B
34	22	76	4C
35	23	77	4D
36	24	78	4E
37	25	79	4F
38	26	80	50
39	27	81	51
40	28	82	52
41	29	83	53
42	2A		

Keyboard Scan Codes



Pin	TTL Signal	Signal Level
1	+Keyboard Clock	+5 Vdc
2	+Keyboard Data	+5 Vdc
3	-Keyboard Reset (Not used by keyboard)	
Power Supply Voltages		Voltage
4	Ground	0
5	+5 Volts	+5 Vdc

Keyboard Interface Connector Specifications

Expansion Unit

The expansion unit option upgrades the IBM Personal Computer by adding expansion slots in a separate unit. This option consists of an extender card, an expansion cable, and the expansion unit. The expansion unit contains a power supply, an expansion board, and a receiver card. This option utilizes one expansion slot in the system unit to provide seven additional expansion slots in the expansion unit.

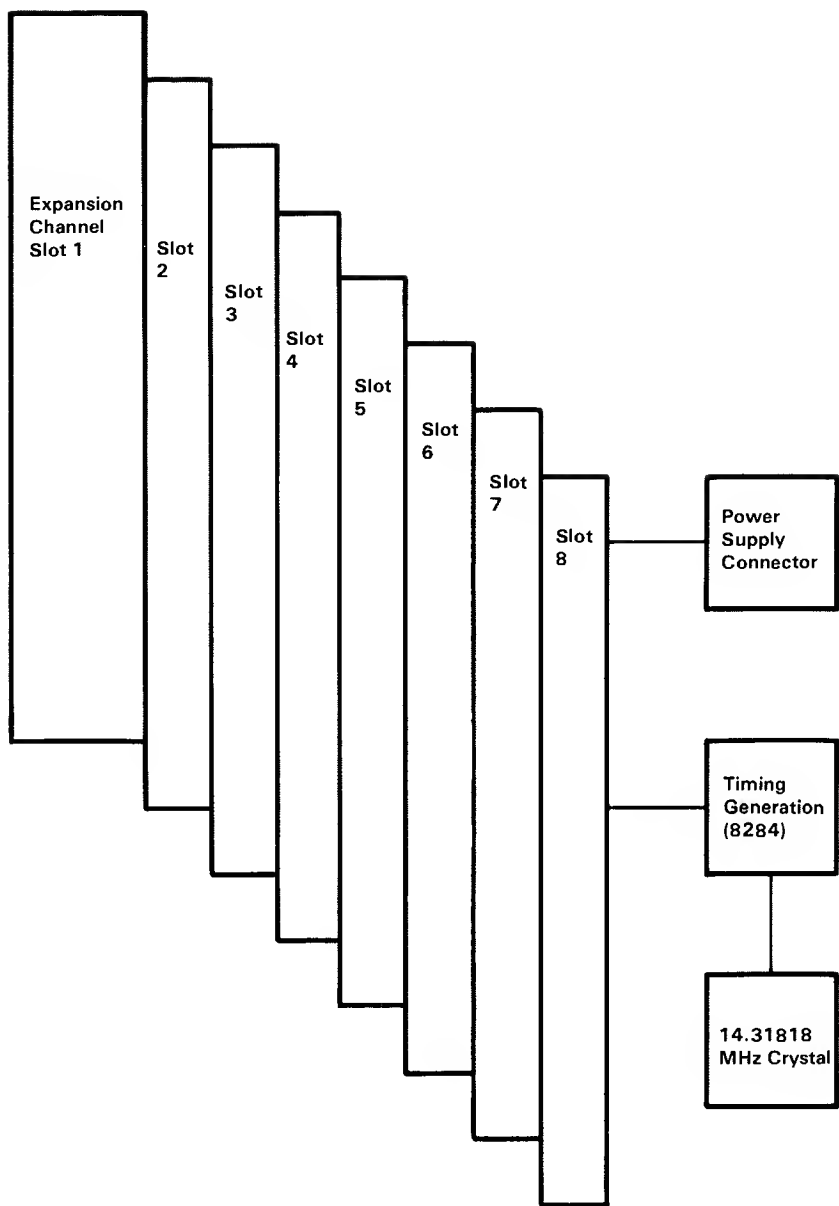
Expansion Unit Cable

The expansion unit cable consists of a 56-wire, foil-shielded cable terminated on each end with a 62-pin D-shell male connector. Either end of the expansion unit cable can be plugged into the extender card or the receiver card.

Expansion Board

The expansion board is a support board that carries the I/O channel signals from the option adapters and receiver card. These signals, except 'osc,' are carried over the expansion cable. Because 'osc' is not sent over the expansion cable, a 14.31818-MHz signal is generated on the expansion board. This signal may not be in phase with the 'osc' signal in the system unit.

Decoupling capacitors provided on the expansion board aid in noise filtering.



Expansion Board Block Diagram

Expansion Channel

All signals found on the system unit's I/O channel will be provided to expansion slots in the expansion unit, with the exception of the 'osc' signal and the voltages mentioned previously.

A 'ready' line on the expansion channel makes it possible to operate with slow I/O or memory devices. If the channel's 'I/O ch rdy' line is not activated by an addressed device, all processor-generated memory cycles take five processor clock cycles per byte for memory in the expansion unit.

The following table contains a list of all the signals that are redriven by the extender and receiver cards, and their associated time delays. The delay times include the delay due to signal propagation in the expansion cable. Assume a nominal cable delay of 3 ns. As such, device access will be less than 260 ns.

Signal	Nominal Delay (ns)	Maximum Delay (ns)	Direction (*)
A0 - A19	27	39	Output
AEN	27	39	Output
DACK0 - DACK3	27	39	Output
MEMR	27	39	Output
MEMW	51	75	Output
IOR	51	75	Output
IOW	27	39	Output
ALE	27	39	Output
CLK	27	39	Output
T/C	27	39	Output
RESET	27	39	Output
IRQ2 - IRQ7	36	(**)	Input
DRQ1 - DRQ3	36	(**)	Input
I/O CH RDY	36	51	Input
I/O CH CK	36	51	Input
D0 - D7 (Read)	84	133	Input
D0 - D7 (Write)	19	27	Output

(*) With respect to the system unit.

(**) Asynchronous nature of interrupts and other requests are more dependent on processor recognition than electrical signal propagation through expansion logic.

Power Supply

The expansion unit dc power supply is a 130-watt, 4 voltage level switching regulator. It is integrated into the expansion unit and supplies power for the expansion unit, and its options. The supply provides 15 A of +5 Vdc, plus or minus 5%, 4.2A of +12 Vdc, plus or minus 5%, 300 mA of -5 Vdc, plus or minus 10%, and 250 mA of -12 Vdc, plus or minus 10%. All power levels are regulated with over-voltage and over-current protection. The input is 120 Vac and fused. If dc over-load or over-voltage conditions exist, the supply automatically shuts down until the condition is corrected. The supply is designed for continuous operation at 130 watts.

The power supply is located at the right rear of the expansion unit. It supplies operating voltages to the expansion board, and provides two separate connections for power to the fixed disk drives. The nominal power requirements and output voltages are listed in the following tables:

Voltage (Vac at 50/60 Hz)			Frequency (Hz)	Current (Amps)
Nominal	Minimum	Maximum	+/- 3 Hz	Maximum
110	90	137	50/60	4.1 at 90 Vac

Input Requirements

Voltage (Vdc)	Current (Amps)		Regulation (Tolerance)	
	Minimum	Maximum	+	-
+5.0	2.3	15.0	5	4
-5.0	0.0	0.3	10	8
+12.0	0.4	4.2	5	4
-12.0	0.0	0.25	10	9

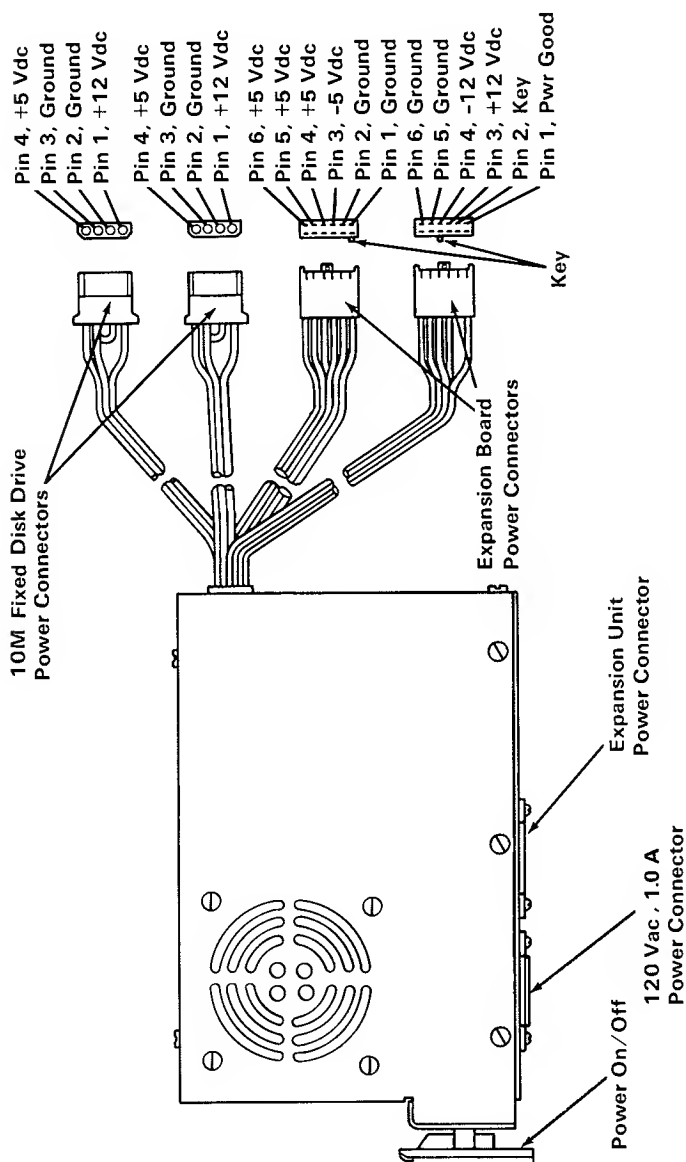
Vdc Output

Voltage (Vac)	Current (Amps)		Voltage Limits (Vac)	
	Minimum	Maximum	Minimum	Maximum
120	0.0	1.0	88	137

Vac Output

Power Supply Connectors and Pin Assignments

The power connector on the expansion board is a 12-pin male connector that plugs into the power-supply connectors. The pin configurations and locations are shown below:



Power Supply and Connectors

Over-Voltage/Over-Current Protection

Voltage Nominal Vac	Type Protection	Rating Amps
110	Fuse	5

Power On/Off Cycle: When the supply is turned off for a minimum of 1.0 second, and then turned on, the power-good signal will be regenerated.

The power-good signal indicates that there is adequate power to continue processing. If the power goes below the specified levels, the power-good signal triggers a system shutdown.

This signal is the logical AND of the dc output-voltage sense signal and the ac input voltage fail signal. This signal is TTL-compatible up-level for normal operation or down-level for fault conditions. The ac fail signal causes power-good to go to a down-level when any output voltage falls below the regulation limits.

The dc output-voltage sense signal holds the power-good signal at a down level (during power-on) until all output voltages have reached their respective minimum sense levels. The power-good signal has a turn-on delay of at least 100 ms but no greater than 500 ms.

The sense levels of the dc outputs are:

Output (Vdc)	Minimum (Vdc)	Sense Voltage Nominal (Vdc)	Maximum (Vdc)
+5	+4.5	+5.0	+5.5
-5	-4.3	-5.0	-5.5
+12	+10.8	+12.0	+13.2
-12	-10.2	-12.0	-13.2

Extender Card

The extender card is a four-plane card. The extender card redrives the I/O channel to provide sufficient power to avoid capacitive effects of the cable. The extender card presents only one load per line of the I/O channel.

The extender card has a wait-state generator that inserts a wait-state on 'memory read' and 'memory write' operations (except refreshing) for all memory contained in the expansion unit. The address range for wait-state generation is controlled by switch settings on the extender card.

The DIP switch on the extender card should be set to indicate the maximum contiguous read/write memory housed in the system unit. The extender card switch settings are located in "Appendix G: Switch Settings." Switch positions 1 through 4 correspond to address bits hex A19 to hex A16, respectively.

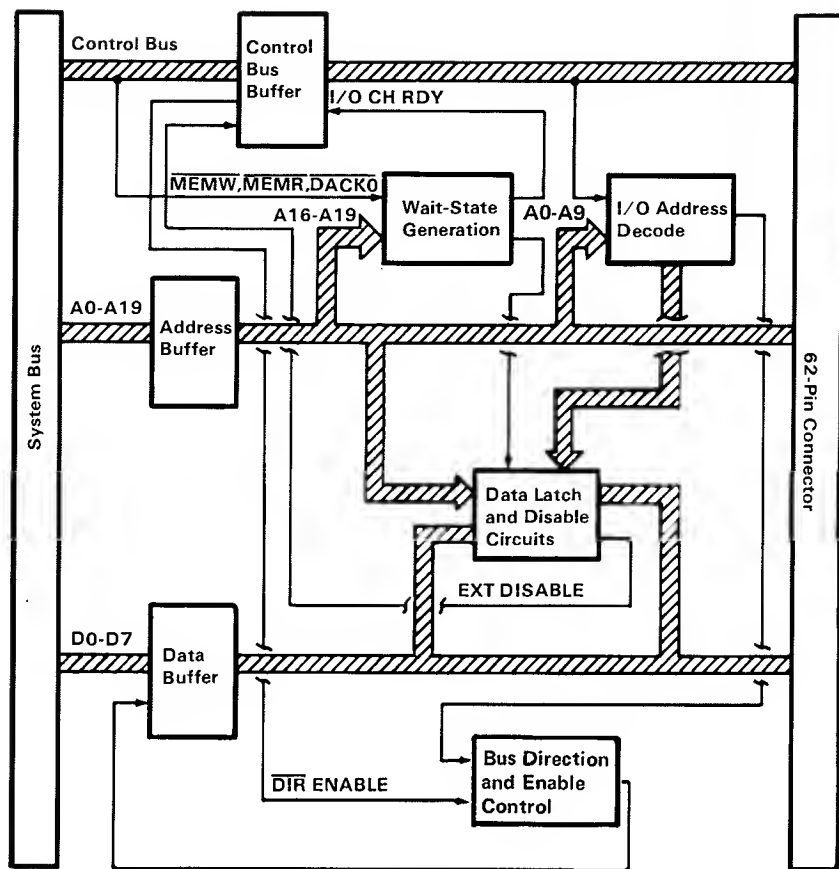
The switch settings determine which address segments have a wait state inserted during 'memory read' and 'memory write' operations. Wait states are required for any memory, including ROM on option adapters, in the expansion unit. Wait states are not inserted in the highest segment, hex addresses F0000 to FFFFF (segment F).

Extender Card Programming Considerations

Several registers associated with the expansion option are programmable and readable for diagnostic purposes. The following figure indicates the locations and functions of the registers on the extender card.

Location	Function
Memory FXXXX(*)	Write to memory to latch address bits
Port 210	Write to latch expansion bus data (ED0 - ED7)
Port 210	Read to verify expansion bus data (ED0 - ED7)
Port 211	Read high-order address bits (A8 - A15)
Port 211	Write to clear wait test latch
Port 212	Read low-order address bits (A0 - A7)
Port 213	Write 00 to disable expansion unit
Port 213	Write 01 to enable expansion unit
Port 213	Read status of expansion unit
	D0 = enable/disable
	D1 = wait-state request flag
	D2-D3 = not used
	D4-D7 = switch position
	1 = Off
	0 = On
(*) Example: Write to memory location F123:4=00	
Read Port 211 = 12	
Read Port 212 = 34	
(All values in hex)	

The expansion unit is automatically enabled upon power-up. The extender card and receiver card will both be written to, if the expansion unit is not disabled when writing to FXXXX. However, the system unit and the expansion unit are read back separately.



Extender Card Block Diagram

Receiver Card

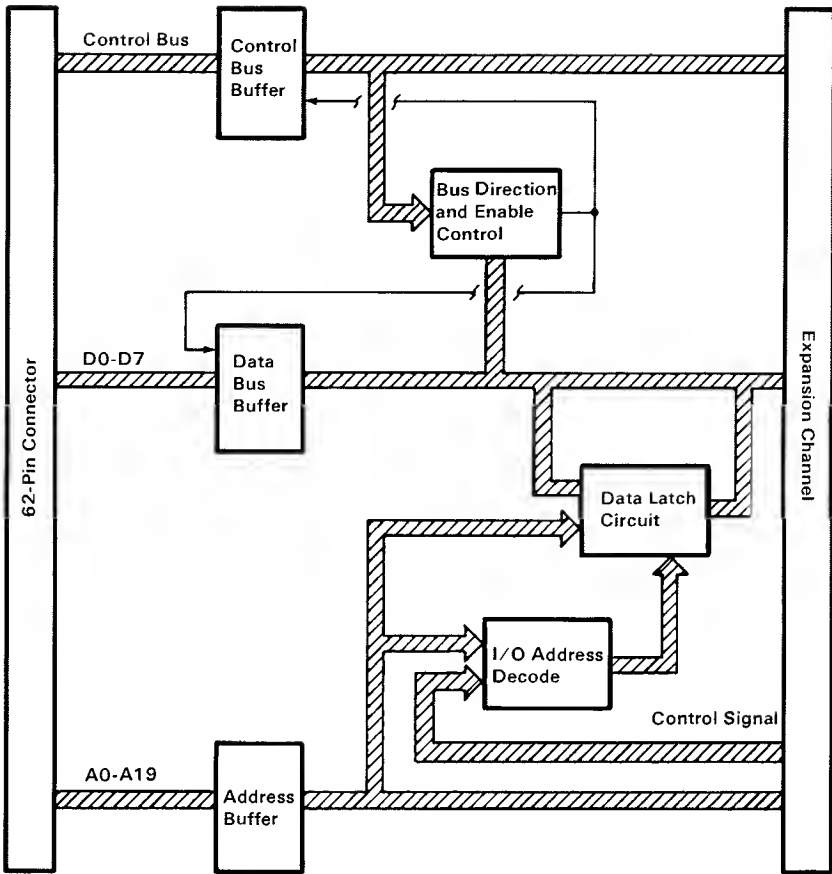
The receiver card is a four-plane card that fits in expansion slot 8 of the expansion unit. The receiver card redrives the I/O channel to provide sufficient power for additional options and to avoid capacitive effects. Directional control logic is contained on the receiver card to resolve contention and direct data flow on the I/O channel. Steering signals are transmitted back over the expansion cable for use on the extender card.

Receiver Card Programming Considerations

Several registers associated with the expansion option are programmable and readable for diagnostic purposes. The following figure indicates the locations and functions of the registers on the receiver card.

Location	Function
Memory FXXXX(*)	Write to memory to latch address bits
Port 214	Write to latch data bus bits (D0 - D7)
Port 214	Read data bus bits (D0 - D7)
Port 215	Read high-order address bits (A8 - A15)
Port 216	Read low-order address bits (A0 - A7)
(*) Example: Write to memory location F123:4=00 Read Port 215 =12 Read Port 216 =34 (All values in hex)	

The expansion unit is automatically enabled upon power-up. The expansion unit and the system unit will be written to, if the expansion unit is not disabled when writing to FXXXX. However, the system unit and the expansion unit are read back separately.

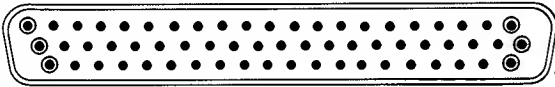


Receiver Card Block Diagram

Expansion Unit Interface Information

The extender card and receiver card rear-panel connectors are the same. Pin and signal assignments for the extender and receiver cards are shown below.

21
42
62



1
22
43
62

Pin	Signal	Pin	Signal	Pin	Signal
1	+E IRQ6	22	+E D5	43	+E IRQ7
2	+E DRQ2	23	+E DRQ1	44	+E D6
3	+E DIR	24	+E DRQ3	45	+E I/O CH RDY
4	+E ENABLE	25	RESERVED	46	+E IRQ3
5	+E CLK	26	+E ALE	47	+E D7
6	-E MEM IN EXP	27	+E T/C	48	+E D1
7	+E A17	28	+E RESET	49	-E I/O CH CK
8	+E A16	29	+E AEN	50	+E IRQ2
9	+E A5	30	+E A19	51	+E D0
10	-E DACK0	31	+E A14	52	+E D2
11	+E A15	32	+E A12	53	+E D4
12	+E A11	33	+E A18	54	+E IRQ5
13	+E A10	34	-E MEMR	55	+E IRQ4
14	+E A9	35	-E MEMW	56	+E D3
15	+E A1	36	+E A0	57	GND
16	+E A3	37	-E DACK3	58	GND
17	-E DACK1	38	+E A6	59	GND
18	+E A4	39	-E IOR	60	GND
19	-E DACK2	40	+E A8	61	GND
20	-E IOW	41	+E A2	62	GND
21	+E A13	42	+E A7		

E = Extended

Connector Specifications

IBM 80 CPS Printers

The IBM 80 CPS (characters-per-second) Printers are self-powered, stand-alone, tabletop units. They attach to the system unit through a parallel signal cable, 6 feet in length. The units obtain ac power from a standard wall outlet (120 Vac). The printers are 80 cps, bidirectional, wire-matrix devices. They print characters in a 9 by 9 dot matrix with a 9-wire head. They can print in a compressed mode of 132 characters per line, in a standard mode of 80 characters per line, in a double width, compressed mode of 66 characters per line, and in a double width mode of 40 characters per line. The printers can print double-size characters and double-strike characters. The printers print the standard ASCII, 96-character, uppercase and lowercase character sets. A printer without an extended character set also has a set of 64 special block graphic characters.

The IBM 80 CPS Graphics Printer has additional capabilities including: an extended character set for international languages, subscript, superscript, an underline mode, and programmable graphics.

The printers can also accept commands setting the line-feed control desired for the application. They attach to the system unit through the printer adapter or the combination monochrome display and printer adapter. The cable is a 25-lead shielded cable with a 25-pin D-shell connector at the system unit end, and a 36-pin connector at the printer end.

- | | | | | | | | | | | | | | | | | |
|--------------------------------------|---|-----------------------------------|------------------------|-----------------------------------|---------|----|----|---------------|---|----|-------------|------|-----|--------------------------|------|----|
| (1) Print Method: | Serial-impact dot matrix | | | | | | | | | | | | | | | |
| (2) Print Speed: | 80 cps | | | | | | | | | | | | | | | |
| (3) Print Direction: | Bidirectional with logical seeking | | | | | | | | | | | | | | | |
| (4) Number of Pins in Head: | 9 | | | | | | | | | | | | | | | |
| (5) Line Spacing: | 1/16 inch (4.23 mm) or programmable | | | | | | | | | | | | | | | |
| (6) Printing Characteristics | | | | | | | | | | | | | | | | |
| Matrix: | 9 x 9 | | | | | | | | | | | | | | | |
| Character Set: | Full 96-character ASCII with descenders plus 9 international characters/symbols. | | | | | | | | | | | | | | | |
| Graphic Character: | See "Additional Printer Specifications" | | | | | | | | | | | | | | | |
| (7) Printing Sizes | | | | | | | | | | | | | | | | |
| | <table border="0"> <tr> <td></td> <td>Characters
per inch</td> <td>Maximum
characters
per inch</td> </tr> <tr> <td>Normal:</td> <td>10</td> <td>80</td> </tr> <tr> <td>Double Width:</td> <td>5</td> <td>40</td> </tr> <tr> <td>Compressed:</td> <td>16.5</td> <td>132</td> </tr> <tr> <td>Double Width-Compressed:</td> <td>8.25</td> <td>66</td> </tr> </table> | | Characters
per inch | Maximum
characters
per inch | Normal: | 10 | 80 | Double Width: | 5 | 40 | Compressed: | 16.5 | 132 | Double Width-Compressed: | 8.25 | 66 |
| | Characters
per inch | Maximum
characters
per inch | | | | | | | | | | | | | | |
| Normal: | 10 | 80 | | | | | | | | | | | | | | |
| Double Width: | 5 | 40 | | | | | | | | | | | | | | |
| Compressed: | 16.5 | 132 | | | | | | | | | | | | | | |
| Double Width-Compressed: | 8.25 | 66 | | | | | | | | | | | | | | |
| (8) Media Handling | | | | | | | | | | | | | | | | |
| Paper Feed: | Adjustable sprocket pin feed | | | | | | | | | | | | | | | |
| Paper Width Range: | 4 inch (101.6 mm) to 10 inch (254 mm) | | | | | | | | | | | | | | | |
| Copies: | One original plus two carbon copies (total thickness not to exceed 0.012 inch (0.3 mm)). Minimum paper thickness is 0.0025 inch (0.064 mm). | | | | | | | | | | | | | | | |
| Paper Path: | Rear | | | | | | | | | | | | | | | |
| (9) Interfaces | | | | | | | | | | | | | | | | |
| Standard: | Parallel 8-bit
Data and Control Lines | | | | | | | | | | | | | | | |
| (10) Inked Ribbon | | | | | | | | | | | | | | | | |
| Color: | Black | | | | | | | | | | | | | | | |
| Type: | Cartridge | | | | | | | | | | | | | | | |
| Life Expectancy: | 3 million characters | | | | | | | | | | | | | | | |
| (11) Environmental Conditions | | | | | | | | | | | | | | | | |
| Operating Temperature Range: | 41 to 95°F (5 to 35°C) | | | | | | | | | | | | | | | |
| Operating Humidity: | 10 to 80% non-condensing | | | | | | | | | | | | | | | |
| (12) Power Requirement | | | | | | | | | | | | | | | | |
| Voltage: | 120 Vac, 60 Hz | | | | | | | | | | | | | | | |
| Current: | 1 A maximum | | | | | | | | | | | | | | | |
| Power Consumption: | 100 VA maximum | | | | | | | | | | | | | | | |
| (13) Physical Characteristics | | | | | | | | | | | | | | | | |
| Height: | 4.2 inches (107 mm) | | | | | | | | | | | | | | | |
| Width: | 14.7 inches (374 mm) | | | | | | | | | | | | | | | |
| Depth: | 12.0 inches (305 mm) | | | | | | | | | | | | | | | |
| Weight: | 12 pounds (5.5 kg) | | | | | | | | | | | | | | | |

Printer Specifications

(6) Printing Characteristics

IBM 80 CPS Matrix Printer

Graphics:

64 block characters.

(6) Printing Characteristics

IBM 80 CPS Graphics Printer

Extra Character Set:

Set 1

Additional ASCII numbers 160 to 175 contain European characters. Numbers 176 to 223 contain graphic characters. Numbers 224 to 239 contain selected Greek characters. Numbers 240 to 255 contain math and extra symbols.

Set 2

The difference in set 2 are ASCII numbers 3, 4, 5, 6, and 21. ASCII numbers 128 to 175 contain European characters.

Graphics:

There are 20 block characters and programmable graphics.

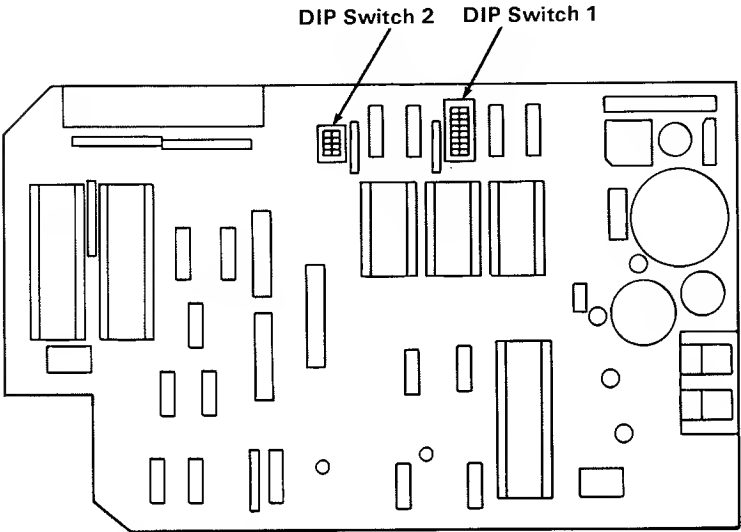
(7) Printing Sizes

	Characters per inch	Maximum characters per line
Subscript:	10	80
Superscript:	10	80

Additional Printer Specifications

Setting the DIP Switches

There are two DIP switches on the control circuit board. In order to satisfy the user's specific requirements, desired control modes are selectable by the DIP switches. The functions of the switches and their preset conditions at the time of shipment are as shown in the following figures.



Location of Printer DIP Switches

Switch Number	Function	On	Off	Factory-Set Condition
1-1	Not Applicable	—	—	On
1-2	CR	Print Only	Print & Line Feed	On
1-3	Buffer Full	Print Only	Print & Line Feed	Off
1-4	Cancel Code	Invalid	Valid	Off
1-5	Delete Code	Invalid	Valid	On
1-6	Error Buzzer	Sounds	Does Not Sound	On
1-7	Character Generator	N.A.	Graphic Patterns Select	Off
1-8	SLCT IN Signal	Fixed	Not Fixed	On

Functions and Conditions of DIP Switch 1 (Matrix)

Switch Number	Function	On	Off	Factory-Set Condition
2-1	Not Applicable	—	—	On
2-2	Not Applicable	—	—	On
2-3	Auto Feed XT Signal	Fixed Internally	Not Fixed Internally	Off
2-4	Coding Table Select	N.A.	Standard	Off

Functions and Conditions of DIP Switch 2 (Matrix)

Switch Number	Function	On	Off	Factory-Set Condition
1-1	Not Applicable	—	—	On
1-2	CR	Print Only	Print & Line Feed	On
1-3	Buffer Full	Print Only	Print & Line Feed	Off
1-4	Cancel Code	Invalid	Valid	Off
1-5	Not Applicable	—	—	On
1-6	Error Buzzer	Sound	Does Not Sound	On
1-7	Character Generator	Set 2	Set 1	Off
1-8	SLCT IN Signal	Fixed Internally	Not Fixed Internally	On

Functions and Conditions of DIP Switch 1 (Graphics)

Switch Number	Function	On	Off	Factory-Set Condition
2-1	Form Length	12 Inches	11 Inches	Off
2-2	Line Spacing	1/8 Inch	1/6 Inch	Off
2-3	Auto Feed XT Signal	Fixed Internally	Not Fixed Internally	Off
2-4	1 Inch Skip Over Perforation	Valid	Not Valid	Off

Functions and Conditions of DIP Switch 2 (Graphics)

Parallel Interface Description

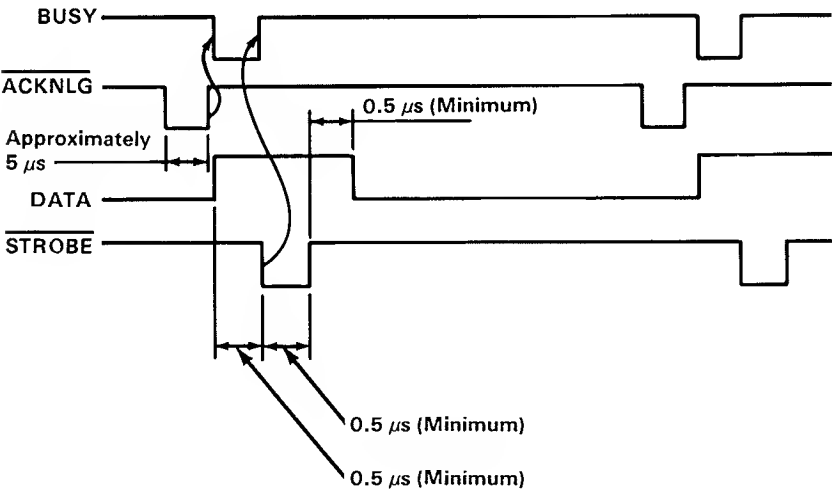
Specifications:

- Data transfer rate: 1000 cps (maximum)
- Synchronization: By externally-supplied STROBE pulses.
- Handshaking ACKNLG or BUSY signals.
- Logic level: Input data and all interface control signals are compatible with the TTL level.

Connector: Plug: 57-30360 (Amphenol)

Connector pin assignment and descriptions of respective interface signals are provided on the following pages.

Data transfer sequence:



Parallel Interface Timing Diagram

Signal Pin No.	Return Pin No.	Signal	Direction	Description
1	19	<u>STROBE</u>	In	STROBE pulse to read data in. Pulse width must be more than 0.5 μ s at receiving terminal. The signal level is normally "high"; read-in of data is performed at the "low" level of this signal.
2	20	DATA 1	In	These signals represent information of the 1st to 8th bits of parallel data respectively. Each signal is at "high" level when data is logical "1" and "low" when logical "0."
3	21	DATA 2	In	
4	22	DATA 3	In	
5	23	DATA 4	In	
6	24	DATA 5	In	
7	25	DATA 6	In	
8	26	DATA 7	In	
9	27	DATA 8	In	
10	28	<u>ACKNLG</u>	Out	Approximately 5 μ s pulse; "low" indicates that data has been received and the printer is ready to accept other data.
11	29	BUSY	Out	A "high" signal indicates that the printer cannot receive data. The signal becomes "high" in the following cases: 1. During data entry. 2. During printing operation. 3. In "offline" state. 4. During printer error status.

Connector Pin Assignment and Descriptions of Interface Signals
(Part 1 of 3)

Signal Pin No.	Return Pin No.	Signal	Direction	Description
12	30	PE	Out	A "high" signal indicates that the printer is out of paper.
13	—	SLCT	Out	This signal indicates that the printer is in the selected state.
14	—	$\overline{\text{AUTO FEED XT}}$	In	With this signal being at "low" level, the paper is automatically fed one line after printing. (The signal level can be fixed to "low" with DIP SW pin 2-3 provided on the control circuit board.)
15	—	NC		Not used.
16	—	OV		Logic GND level.
17	—	CHASSIS-GND	—	Printer chassis GND. In the printer, the chassis GND and the logic GND are isolated from each other.
18	—	NC	—	Not used.
19-30	—	GND	—	"Twisted-Pair Return" signal; GND level.
31	—	$\overline{\text{INIT}}$	In	When the level of this signal becomes "low" the printer controller is reset to its initial state and the print buffer is cleared. This signal is normally at "high" level, and its pulse width must be more than 50 μs at the receiving terminal.

Connector Pin Assignment and Descriptions of Interface Signals
(Part 2 of 3)

Signal Pin No.	Return Pin No.	Signal	Direction	Description
32		<u>ERROR</u>	Out	The level of this signal becomes "low" when the printer is in "Paper End" state, "Offline" state and "Error" state.
33	—	GND	—	Same as with pin numbers 19 to 30.
34	—	NC	—	Not used.
35				Pulled up to +5 Vdc through 4.7 k-ohms resistance.
36	—	<u>SLCT IN</u>	In	Data entry to the printer is possible only when the level of this signal is "low." (Internal fixing can be carried out with DIP SW 1-8. The condition at the time of shipment is set "low" for this signal.)

- Notes:**
1. "Direction" refers to the direction of signal flow as viewed from the printer.
 2. "Return" denotes "Twisted-Pair Return" and is to be connected at signal-ground level.
When wiring the interface, be sure to use a twisted-pair cable for each signal and never fail to complete connection on the return side. To prevent noise effectively, these cables should be shielded and connected to the chassis of the system unit and printer, respectively.
 3. All interface conditions are based on TTL level. Both the rise and fall times of each signal must be less than $0.2 \mu\text{s}$.
 4. Data transfer must not be carried out by ignoring the ACKNLG or BUSY signal. (Data transfer to this printer can be carried out only after confirming the ACKNLG signal or when the level of the BUSY signal is "low.")

Connector Pin Assignment and Descriptions of Interface Signals (Part 3 of 3)

Printer Modes for the IBM 80 CPS Printers

The IBM 80 CPS Graphics Printer can use any of the combinations listed below, and the print mode can be changed at any place within a line.

The IBM 80 CPS Matrix Printer cannot use the Subscript, Superscript, or Underline print modes. The Double Width print mode will affect the entire line with the matrix printer.

The allowed combinations of print modes that can be selected are listed in the following table. Modes can be selected and combined if they are in the same vertical column.

Printer Modes											
Normal	X	X	X								
Compressed					X	X	X				
Emphasized									X	X	X
Double Strike	X				X				X		
Subscript		X				X				X	
Superscript			X				X				X
Double Width	X	X	X		X	X	X		X	X	X
Underline	X	X	X		X	X	X		X	X	X

Printer Control Codes

On the following pages you will find complete codes for printer characters, controls, and graphics. You may want to keep them handy for future reference. The printer codes are listed in ASCII decimal numeric order (from NUL which is 0 to DEL which is 127). The examples given in the Printer Function descriptions are written in the BASIC language. The “input” description is given when more information is needed for programming considerations.

ASCII decimal values for the printer control codes can be found under “Printer Character Sets.”

The descriptions that follow assume that the printer DIP switches have not been changed from their factory settings.

Printer Code	Printer Function
NUL	<p>Null</p> <p>Used with ESC B and ESC D as a list terminator. NUL is also used with other printer control codes to select options (for example, ESC S).</p> <p>Example: LPRINT CHR\$(0);</p>
BEL	<p>Bell</p> <p>Sounds the printer buzzer for 1 second.</p> <p>Example: LPRINT CHR\$(7);</p>
HT	<p>Horizontal Tab</p> <p>Tabs to the next horizontal tab stop. Tab stops are set with ESC D. No tab stops are set when the printer is powered on. (Graphics Printer sets a tab stop every 8 columns when powered on.)</p> <p>Example: LPRINT CHR\$(9);</p>
LF	<p>Line Feed</p> <p>Spaces the paper up one line. Line spacing is 1/6-inch unless reset by ESC A, ESC 0, ESC 1, ESC 2 or ESC 3.</p> <p>Example: LPRINT CHR\$(10);</p>
VT	<p>Vertical Tab</p> <p>Spaces the paper to the next vertical tab position. (Graphics Printer does not allow vertical tabs to be set; therefore, the VT code is treated as LF.)</p> <p>Example: LPRINT CHR\$(11);</p>
FF	<p>Form Feed</p> <p>Advances the paper to the top of the next page.</p> <p>Note: The location of the paper, when the printer is powered on, determines the top of the page. The next top of page is 11 inches from that position. ESC C can be used to change the page length.</p> <p>Example: LPRINT CHR\$(12);</p>
CR	<p>Carriage Return</p> <p>Ends the line that the printer is on and prints the data remaining in the printer buffer. (No Line Feed operation takes place.)</p> <p>Note: IBM Personal Computer BASIC adds a Line Feed unless 128 is added [for example, CHR\$(141)].</p> <p>Example: LPRINT CHR\$(13);</p>

Printer Code	Printer Function
SO	<p>Shift Out (Double Width) Changes the printer to the Double Width print mode. Note: A Carriage Return, Line Feed or DC4 cancels Double Width print mode. Example: LPRINT CHR\$(14);</p>
SI	<p>Shift In (Compressed) Changes the printer to the Compressed Character print mode. Example: LPRINT CHR\$(15);</p>
DC1	<p>Device Control 1 (Printer Selected) (Graphics Printer ignores DC1) Printer accepts data from the system unit. Printer DIP switch 1-8 must be set to the Off position. Example: LPRINT CHR\$(17);</p>
DC2	<p>Device Control 2 (Compressed Off) Stops printing in the Compressed print mode. Example: LPRINT CHR\$(18);</p>
DC3	<p>Device Control 3 (Printer Deselected) (Graphics Printer ignores DC3) Printer does not accept data from the system unit. The system unit must have the printer select line low, and DIP switch 1-8 must be in the Off position. Example: LPRINT CHR\$(19);</p>
DC4	<p>Device Control 4 (Double Width Off) Stops printing in the Double Width print mode. Example: LPRINT CHR\$(20);</p>
CAN	<p>Cancel Clears the printer buffer. Control codes, except SO, remain in effect. Example: LPRINT CHR\$(24);</p>
ESC	<p>Escape Lets the printer know that the next data sent is a printer command. (See the following list of commands.) Example: LPRINT CHR\$(27);</p>

Printer Code	Printer Function
ESC -	<p>Escape Minus (Underline) Format: ESC -;n; (Graphics Printer only) ESC - followed by a 1, prints all of the following data with an underline. ESC - followed by a 0 (zero), cancels the Underline print mode. Example: LPRINT CHR\$(27);CHR\$(45);CHR\$(1);</p>
ESC 0	<p>Escape Zero (1/8-Inch Line Feeding) Changes paper feeding to 1/8 inch. Example: LPRINT CHR\$(27);CHR\$(48);</p>
ESC 1	<p>Escape 1 (7/72-Inch Line Feeding) Changes paper feed to 7/72 inch. Example: LPRINT CHR\$(27);CHR\$(49);</p>
ESC 2	<p>Escape Two (Starts Variable Line Feeding) ESC 2 is an execution command for ESC A. If no ESC A command has been given, line feeding returns to 1/6-inch. Example: LPRINT CHR\$(27);CHR\$(50);</p>
ESC 3	<p>Escape Three (Variable Line Feeding) Format: ESC 3;n; (Graphics Printer only) Changes the-paper feeding to n/216-inch. The example below sets the paper feeding to 54/216 (1/4) inch. The value of n must be between 1 and 255. Example: LPRINT CHR\$(27);CHR\$(51);CHR\$(54);</p>
ESC 6	<p>Escape Six (Select Character Set 2) (Graphics Printer only) Selects character set 2. (See "Printer Character Set 2.") Example: LPRINT CHR\$(27);CHR\$(54);</p>
ESC 7	<p>Escape Seven (Select Character Set 1.) (Graphics Printer only) Selects character set 1. (See "Printer Character Set 1.") Character set 1 is selected when the printer is powered on or reset. Example: LPRINT CHR\$(27);CHR\$(55);</p>
ESC 8	<p>Escape Eight (Ignore Paper End) Allows the printer to print to the end of the paper. The printer ignores the Paper End switch. Example: LPRINT CHR\$(27);CHR\$(56);</p>

Printer Code	Printer Function
ESC 9	<p>Escape Nine (Cancel Ignore Paper End) Cancels the Ignore Paper End command. ESC 9 is selected when the printer is powered on or reset. Example: LPRINT CHR\$(27);CHR\$(57);</p>
ESC <	<p>Escape Less Than (Home Head) (Graphics Printer only) The print head will return to the left margin to print the line following ESC <. This will occur for one line only. Example: LPRINT CHR\$(27);CHR\$(60);</p>
ESC A	<p>Escape A (Sets Variable Line Feeding) Format: ESC A;n; Escape A sets the line-feed to n/72-inch. The example below tells the printer to set line feeding to 24/72-inch. ESC 2 must be sent to the printer before the line feeding will change. For example, ESC A;24 (text) ESC 2 (text). The text following ESC A;24 will space at the previously set line-feed increments. The text following ESC 2 will be printed with new line-feed increments of 24/72-inch. Any increment between 1/72 and 85/72 may be used. Example: LPRINT CHR\$(27);CHR\$(65);CHR\$(24);CHR\$(27);CHR\$(50);</p>
ESC B	<p>Escape B (Set Vertical Tabs) Format: ESC B;n₁;n₂;...n_k;NUL; (Graphics Printer ignores ESC B) Sets vertical tab stop positions. Up to 64 vertical tab stop positions are recognized by the printer. The n's, in the format above, are used to indicate tab stop positions. Tab stop numbers must be received in ascending numeric order. The tab stop numbers will not become valid until the NUL code is entered. Once vertical tab stops are established, they will be valid until new tab stops are specified. (If the printer is reset or powered Off, set tab stops are cleared.) If no tab stop is set, the Vertical Tab command behaves as a Line Feed command. ESC B followed only by NUL will cancel tab stops. The form length must be set by the ESC C command prior to setting tabs. Example: LPRINT CHR\$(27);CHR\$(66);CHR\$(10);CHR\$(20);CHR\$(40);CHR\$(0);</p>

Printer Code	Printer Function
ESC C	<p>Escape C (Set Lines per Page) Format: ESC C;n; Sets the page length. The ESC C command must have a value following it to specify the length of page desired. (Maximum form length for the printer is 127 lines.) The example below sets the page length to 55 lines. The printer defaults to 66 lines per page when powered on or reset. Example: LPRINT CHR\$(27);CHR\$(67);CHR\$(55);</p> <p>Escape C (Set Inches per Page) Format: ESC C;n;m; (Graphics Printer only) Escape C sets the length of the page in inches. This command requires a value of 0 (zero) for n, and a value between 1 and 22 for m. Example: LPRINT CHR\$(27);CHR\$(67);CHR\$(0);CHR\$(12);</p>
ESC D	<p>Escape D (Set Horizontal Tab Stops) Format: ESC D;n₁;n₂;...n_k;NUL; Sets the horizontal tab stop positions. The example below shows the horizontal tab stop positions set at printer column positions of 10, 20, and 40. They are followed by CHR\$(0), the NUL code. They must also be in ascending numeric order as shown. Tab stops can be set between 1 and 80. When in the Compressed print mode, tab stops can be set up to 132. The maximum number of tabs that can be set is 112. The Graphics Printer can have a maximum of 28 tab stops. The HT (CHR\$(9)) is used to execute a tab operation. Example: LPRINT CHR\$(27);CHR\$(68);CHR\$(10)CHR\$(20)CHR\$(40);CHR\$(0);</p>
ESC E	<p>Escape E (Emphasized) Changes the printer to the Emphasized print mode. The speed of the printer is reduced to half speed during the Emphasized print mode. Example: LPRINT CHR\$(27);CHR\$(69);</p>
ESC F	<p>Escape F (Emphasized Off) Stops printing in the Emphasized print mode. Example: LPRINT CHR\$(27);CHR\$(70);</p>
ESC G	<p>Escape G (Double Strike) Changes the printer to the Double Strike print mode. The paper is spaced 1/216 of an inch before the second pass of the print head. Example: LPRINT CHR\$(27);CHR\$(71);</p>

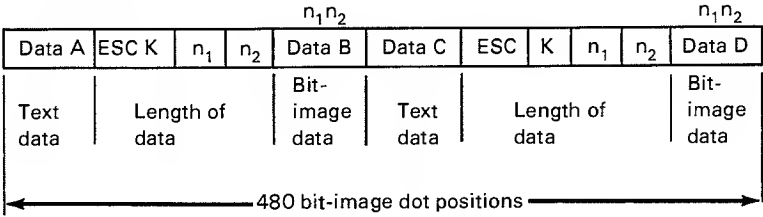
Printer Code	Printer Function
ESC H	Escape H (Double Strike Off) Stops printing in the Double Strike mode. Example: LPRINT CHR\$(27);CHR\$(72);
ESC J	Escape J (Set Variable Line Feeding) Format: ESC J;n; (Graphics Printer only) When ESC J is sent to the printer, the paper will feed in increments of n/216 of an inch. The value of n must be between 1 and 255. The example below gives a line feed of 50/216-inch. ESC J is canceled after the line feed takes place. Example: LPRINT CHR\$(27);CHR\$(74);CHR\$(50);
ESC K	Escape K (480 Bit-Image Graphics Mode) Format ESC K;n ₁ ;n ₂ ;v ₁ ;v ₂ ;...v _k ; (Graphics Printer only) Changes from the Text mode to the Bit-Image Graphics mode. n ₁ and n ₂ are one byte, which specify the number of bit-image data bytes to be transferred. v ₁ through v _k are the bytes of the bit-image data. The number of bit-image data bytes (k) is equal to n ₁ + 256n ₂ and cannot exceed 480 bytes. At every horizontal position, each byte can print up to 8 vertical dots. Bit-image data may be mixed with text data on the same line. Note: Assign values to n ₁ and n ₂ as follows: n ₁ represents values from 0 - 255. n ₂ represents values from 0 - 1 x 256. MSB is most significant bit and LSB is least significant bit. <div style="text-align: center;"><div style="margin-bottom: 20px;"><div style="display: flex; justify-content: space-between; align-items: center;"><div style="text-align: center;">n₂</div><div style="width: 100%; border: 1px solid black; padding: 5px; position: relative;"><div style="position: absolute; left: 0; top: -10px; font-weight: bold;">MSB</div><div style="position: absolute; right: 0; top: -10px; font-weight: bold;">LSB</div><div style="display: flex; justify-content: space-around; padding: 5px 0;"><div style="text-align: center;">15 2</div><div style="text-align: center;">14 2</div><div style="text-align: center;">13 2</div><div style="text-align: center;">12 2</div><div style="text-align: center;">11 2</div><div style="text-align: center;">10 2</div><div style="text-align: center;">9 2</div><div style="text-align: center;">8 2</div></div></div></div><div style="display: flex; justify-content: space-between; align-items: center;"><div style="text-align: center;">n₁</div><div style="width: 100%; border: 1px solid black; padding: 5px; position: relative;"><div style="position: absolute; left: 0; top: -10px; font-weight: bold;">MSB</div><div style="position: absolute; right: 0; top: -10px; font-weight: bold;">LSB</div><div style="display: flex; justify-content: space-around; padding: 5px 0;"><div style="text-align: center;">7 2</div><div style="text-align: center;">6 2</div><div style="text-align: center;">5 2</div><div style="text-align: center;">4 2</div><div style="text-align: center;">3 2</div><div style="text-align: center;">2 2</div><div style="text-align: center;">1 2</div><div style="text-align: center;">0 2</div></div></div></div></div></div>

Data sent to the printer.

Text (20 characters)	ESC	K	n=360	Bit-image data	Next data
----------------------	-----	---	-------	----------------	-----------

In text mode, 20 characters in text mode correspond to 120 bit-image positions ($20 \times 6 = 120$). The printable portion left in Bit-Image mode is 360 dot positions ($480 - 120 = 360$).

Data sent to the printer.



Example:

```
TYPE B:GRAPH.TXT
1 'OPEN PRINTER IN RANDOM MODE WITH LENGTH OF 255
2 OPEN "LPT1:" AS #1
3 WIDTH "LPT1:",255
4 PRINT #1,CHR$(13);CHR$(10);
5 SLASH$=CHR$(1)+CHR$(02)+CHR$(04)+CHR$(08)
6 SLASH$=SLASH$+CHR$(16)+CHR$(32)+CHR$(64)+CHR$(128)+CHR$(0)
7 GAP$=CHR$(0)+CHR$(0)+CHR$(0)
8 NDOTS=480
9 'ESC K N1 N2
10 PRINT #1,CHR$(27);"K";CHR$(NDOTS MOD 256);CHR$(FIX (NDOTS/256));
11 ' SEND NDOTS NUMBER OF BIT IMAGE BYTES
12 FOR I=1 TO NDOTS/12 'NUMBER OF SLASHES TO PRINT USING
  GRAPHICS
13 PRINT #1,SLASH$;GAP$;
14 NEXT I
15 CLOSE
16 END
```

This example will give you a row of slashes printed in the 480 Bit-Image mode.

Printer Code	Printer Function
ESC L	<p>Escape L (960 Bit-Image Graphics Mode) Format: ESC L;n_1;n_2;v_1;v_2;...;v_k; (Graphics Printer only) Changes from the Text mode to the Bit-Image Graphics mode. The input is similar to ESC K. The 960 Bit-Image mode prints at half the speed of the 480 Bit-Image Graphics mode, but can produce a denser graphic image. The number of bytes of bit-image Data (k) is $n_1 + 256n_2$ but cannot exceed 960. n_1 is in the range of 0 to 255.</p>
ESC N	<p>Escape N (Set Skip Perforation) Format ESC N;n; (Graphics Printer only) Sets the Skip Perforation function. The number following ESC N sets the value for the number of lines of Skip Perforation. The example shows a 12-line skip perforation. This will print 54 lines and feed the paper 12 lines. The value of n must be between 1 and 127. ESC N must be reset anytime the page length (ESC C) is changed. Example: CHR\$(27);CHR\$(78);CHR\$(12);</p>
ESC O	<p>Escape O (Cancel Skip Perforation) (Graphics Printer only) Cancels the Skip Perforation function. Example: LPRINT CHR\$(27);CHR\$(79);</p>
ESC S	<p>Escape S (Subscript/Superscript) Format: ESC S;n; (Graphics Printer only) Changes the printer to the Subscript print mode when ESC S is followed by a 1, as in the example below. When ESC S is followed by a 0 (zero), the printer will print in the Superscript print mode. Example: LPRINT CHR\$(27);CHR\$(83);CHR\$(1);</p>
ESC T	<p>Escape T (Subscript/Superscript Off) (Graphics Printer only) The printer stops printing in the Subscript or Superscript print mode. Example: LPRINT CHR\$(27);CHR\$(84);</p>
ESC U	<p>Escape U (Unidirectional Printing) Format: ESC U;n; (Graphics Printer only) The printer will print from left to right following the input of ESC U;1. When ESC U is followed by a 0 (zero), the left to right printing operation is canceled. The Unidirectional print mode (ESC U) ensures a more accurate print-start position for better print quality. Example: LPRINT CHR\$(27);CHR\$(85);CHR\$(1);</p>

Printer Code	Printer Function
ESC W	<p>Escape W (Double Width) Format: ESC W;n; (Graphics Printer only) Changes the printer to the Double Width print mode when ESC W is followed by a 1. This mode is not canceled by a line-feed operation and must be canceled with ESC W followed by a 0 (zero). Example: LPRINT CHR\$(27);CHR\$(B7);CHR\$(1);</p>
ESC Y	<p>Escape Y (960 Bit-Image Graphics Mode Normal Speed) Format: ESC Y n₁;n₂;v₁;v₂;...v_k; (Graphics Printer only) Changes from the Text mode to the 960 Bit-Image Graphics mode. The printer prints at normal speed during this operation and cannot print dots on consecutive dot positions. The input of data is similar to ESC L.</p>
ESC Z	<p>Escape Z (1920 Bit-Image Graphics Mode) Format: ESC Z;n₁;n₂;v₁;v₂;...v_k; (Graphics Printer only) Changes from the Text mode to the 1920 Bit-Image Graphics mode. The input is similar to the other Bit-Image Graphics modes. ESC Z can print only every third dot position.</p>
DEL	<p>Delete (Clear Printer Buffer) (Graphics Printer ignores DEL) Clears the printer buffer. Control codes, except SO, still remain in effect. DIP switch 1-5 must be in the Off position. Example: LPRINT CHR\$(127);</p>

0	1	2	3	4	5	6	7	8	9
NUL							BEL		HT
10	11	12	13	14	15	16	17	18	19
LF	VT	FF	CR	SO	SI		DC1	DC2	DC3
20	21	22	23	24	25	26	27	28	29
DC4				CAN			ESC		
30	31	32	33	34	35	36	37	38	39
		SP	!	''	#	\$	%	&	'
40	41	42	43	44	45	46	47	48	49
()	*	+	,	—	.	/	0	1
50	51	52	53	54	55	56	57	58	59
2	3	4	5	6	7	8	9	:	;
60	61	62	63	64	65	66	67	68	69
<	=	>	?	⌚	A	B	C	D	E
70	71	72	73	74	75	76	77	78	79
F	G	H	I	J	K	L	M	N	O
80	81	82	83	84	85	86	87	88	89
P	Q	R	S	T	U	V	W	X	Y
90	91	92	93	94	95	96	97	98	99
Z	[\]	^	_	`	a	b	c
100	101	102	103	104	105	106	107	108	109
d	e	f	g	h	i	j	k	l	m
110	111	112	113	114	115	116	117	118	119
n	o	p	q	r	s	t	u	v	w
120	121	122	123	124	125	126	127	128	129
x	y	z	{		}	~	DEL	NUL	





























































Matrix Printer Character Set (Part 1 of 2)

130	131	132	133	134	135	136	137	138	139
					BEL		HT	LF	
140	141	142	143	144	145	146	147	148	149
FF	CR	SD	SI		DC1	DC2	DC3	DC4	
150	151	152	153	154	155	156	157	158	159
		CAN			ESC				
160	161	162	163	164	165	166	167	168	169
170	171	172	173	174	175	176	177	178	179
180	181	182	183	184	185	186	187	188	189
190	191	192	193	194	195	196	197	198	199
200	201	202	203	204	205	206	207	208	209
210	211	212	213	214	215	216	217	218	219
220	221	222	223						

Matrix Printer Character Set (Part 2 of 2)

0	1	2	3	4	5	6	7	8	9
NUL							BEL		HT
10	11	12	13	14	15	16	17	18	19
LF	VT	FF	CR	SD	SI			DC2	
20	21	22	23	24	25	26	27	28	29
DC4				CAN			ESC		
30	31	32	33	34	35	36	37	38	39
		SP	!	''	#	\$	%	&	'
40	41	42	43	44	45	46	47	48	49
()	*	+	,	—	.	/	0	1
50	51	52	53	54	55	56	57	58	59
2	3	4	5	6	7	8	9	:	;
60	61	62	63	64	65	66	67	68	69
<	=	>	?	⊙	A	B	C	D	E
70	71	72	73	74	75	76	77	78	79
F	G	H	I	J	K	L	M	N	O
80	81	82	83	84	85	86	87	88	89
P	Q	R	S	T	U	V	W	X	Y
90	91	92	93	94	95	96	97	98	99
Z	[\]	^	_	`	a	b	c
100	101	102	103	104	105	106	107	108	109
d	e	f	g	h	i	j	k	l	m
110	111	112	113	114	115	116	117	118	119
n	o	p	q	r	s	t	u	v	w
120	121	122	123	124	125	126	127	128	129
x	y	z	{		}	~		NUL	

















































Graphics Printer Character Set 1 (Part 1 of 2)

130	131	132	133	134	135	136	137	138	139
					BEL		HT	LF	VT
140	141	142	143	144	145	146	147	148	149
FF	CR	SO	SI			OC2		DC4	
150	151	152	153	154	155	156	157	158	159
		CAN			ESC				
160	161	162	163	164	165	166	167	168	169
á	í	ó	ú	ñ	Ñ	<u>a</u>	<u>o</u>	¿	¬
170	171	172	173	174	175	176	177	178	179
¬	½	¼	¡	<<	>>				
180	181	182	183	184	185	186	187	188	189
									
190	191	192	193	194	195	196	197	198	199
									
200	201	202	203	204	205	206	207	208	209
									
210	211	212	213	214	215	216	217	218	219
									
220	221	222	223	224	225	226	227	228	229
									
230	231	232	233	234	235	236	237	238	239
				α	β	Γ	Π	Σ	σ
240	241	242	243	244	245	246	247	248	249
μ	τ	ϕ	θ	Ω	δ	∞	∅	€	∩
250	251	252	253	254	255				
≡	±	≥	≤			÷	≈	○	■
-	√	ⁿ	²	■	SP				

Graphics Printer Character Set 1 (Part 2 of 2)

0	1	2	3	4	5	6	7	8	9
NUL			♥	♦	♣	♠	BEL		HT
10	11	12	13	14	15	16	17	18	19
LF	VT	FF	CR	SO	SI			DC2	
20	21	22	23	24	25	26	27	28	29
DC4	§			CAN			ESC		
30	31	32	33	34	35	36	37	38	39
		SP	!	"	#	\$	%	&	'
40	41	42	43	44	45	46	47	48	49
()	*	+	,	—	.	/	0	1
50	51	52	53	54	55	56	57	58	59
2	3	4	5	6	7	8	9	:	;
60	61	62	63	64	65	66	67	68	69
<	=	>	?	⌚	A	B	C	D	E
70	71	72	73	74	75	76	77	78	79
F	G	H	I	J	K	L	M	N	O
80	81	82	83	84	85	86	87	88	89
P	Q	R	S	T	U	V	W	X	Y
90	91	92	93	94	95	96	97	98	99
Z	[\]	^	_	`	a	b	c
100	101	102	103	104	105	106	107	108	109
d	e	f	g	h	i	j	k	l	m
110	111	112	113	114	115	116	117	118	119
n	o	p	q	r	s	t	u	v	w
120	121	122	123	124	125	126	127	128	129
x	y	z	{		}	~		ç	ü

Graphics Printer Character Set 2 (Part 1 of 2)

130	131	132	133	134	135	136	137	138	139
é	â	ä	à	å	ç	ê	ë	è	ï
140	141	142	143	144	145	146	147	148	149
î	ì	Ä	Â	É	æ	Æ	ô	ö	ò
150	151	152	153	154	155	156	157	158	159
û	ù	ÿ	ö	ü	ç	£	¥	₤	ƒ
160	161	162	163	164	165	166	167	168	169
á	í	ó	ú	ñ	Ñ	à	ó	¿	¬
170	171	172	173	174	175	176	177	178	179
¬	½	¼	ï	<<	>>				
180	181	182	183	184	185	186	187	188	189
									
190	191	192	193	194	195	196	197	198	199
									
200	201	202	203	204	205	206	207	208	209
									
210	211	212	213	214	215	216	217	218	219
									
220	221	222	223	224	225	226	227	228	229
				α	β	Γ	Π	Σ	σ
230	231	232	233	234	235	236	237	238	239
μ	τ	ϕ	θ	Ω	δ	∞	\emptyset	ϵ	\cap
240	241	242	243	244	245	246	247	248	249
\equiv	\pm	\geq	\leq	\int	\int	\div	\approx	\circ	\blacksquare
250	251	252	253	254	255				
$-$	$\sqrt{}$	n	2	\blacksquare	SP				

Graphics Printer Character Set 2 (Part 2 of 2)

IBM Printer Adapter

The printer adapter is specifically designed to attach printers with a parallel port interface, but it can be used as a general input/output port for any device or application that matches its input/output capabilities. It has 12 TTL-buffer output points, which are latched and can be written and read under program control using the processor In or Out instruction. The adapter also has five steady-state input points that may be read using the processor's In instructions.

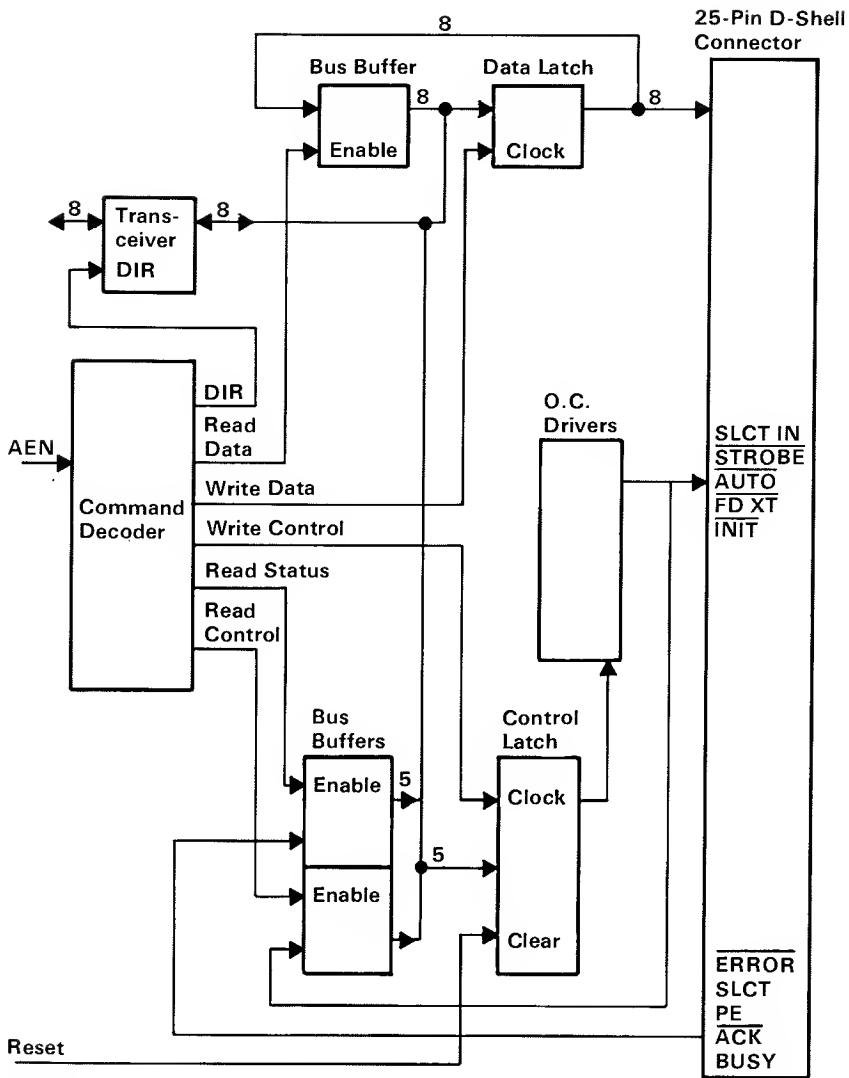
In addition, one input can also be used to create a processor interrupt. This interrupt can be enabled and disabled under program control. Reset from the power-on circuit is also ORed with a program output point, allowing a device to receive a power-on reset when the processor is reset.

The input/output signals are made available at the back of the adapter through a right-angled, PCB-mounted, 25-pin, D-shell connector. This connector protrudes through the rear panel of the system or expansion unit, where a cable may be attached.

When this adapter is used to attach a printer, data or printer commands are loaded into an 8-bit, latched, output port, and the strobe line is activated, writing data to the printer. The program then may read the input ports for printer status indicating when the next character can be written, or it may use the interrupt line to indicate "not busy" to the software.

The output ports may also be read at the card's interface for diagnostic loop functions. This allows faults to be isolated between the adapter and the attaching device.

This same function is also part of the combination IBM Monochrome Display and Printer Adapter. A block diagram of the printer adapter is on the next page.



Printer Adapter Block Diagram

Programming Considerations

The printer adapter responds to five I/O instructions: two output and three input. The output instructions transfer data into 2 latches whose outputs are presented on pins of a 25-pin D-shell connector.

Two of the three input instructions allow the processor to read back the contents of the two latches. The third allows the processor to read the real time status of a group of pins on the connector.

A description of each instruction follows.

IBM Monochrome Display & Printer Adapter				Printer Adapter			
Output to address hex 3BC				Output to address hex 378			
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Pin 9	Pin 8	Pin 7	Pin 6	Pin 5	Pin 4	Pin 3	Pin 2

The instruction captures data from the data bus and is present on the respective pins. These pins are each capable of sourcing 2.6 mA and sinking 24 mA.

It is essential that the external device not try to pull these lines to ground.

IBM Monochrome Display & Printer Adapter		Printer Adapter			
Output to address hex 3BE		Output to address hex 37A			
		Bit 3	Bit 2	Bit 1	Bit 0
IRQ Enable		Pin 17	Pin 16	Pin 14	Pin 1

This instruction causes the latch to capture the five least significant bits of the data bus. The four least significant bits present their outputs, or inverted versions of their outputs, to the respective pins shown above. If bit 4 is written as 1, the card will interrupt the processor on the condition that pin 10 transitions high to low.

These pins are driven by open collector drivers pulled to +5 Vdc through 4.7 k-ohm resistors. They can each sink approximately 7 mA and maintain 0.8 volts down-level.

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BC	Input from address hex 378

This command presents the processor with data present on the pins associated with the out to hex 3BC. This should normally reflect the exact value that was last written to hex 3BC. If an external device should be driving data on these pins (in violation of usage ground rules) at the time of an input, this data will be ORed with the latch contents.

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BD	Input from address hex 379

This command presents realtime status to the processor from the pins as follows.

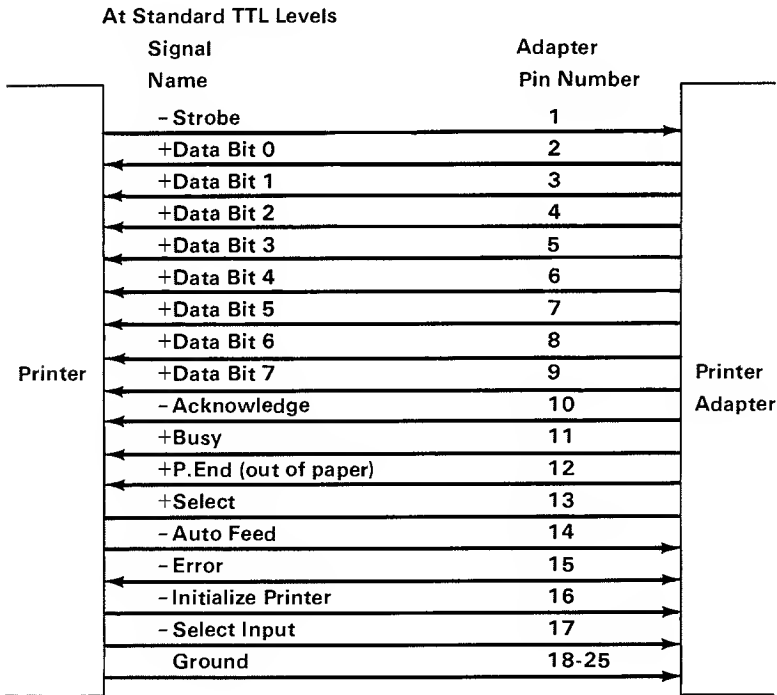
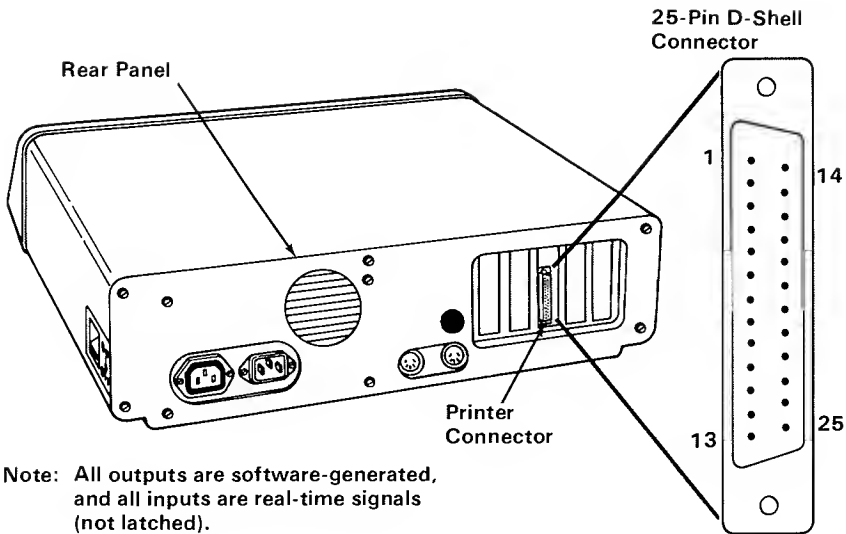
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
Pin 11	Pin 10	Pin 12	Pin 13	Pin 15	—	—	—

IBM Monochrome Display & Printer Adapter	Printer Adapter
Input from address hex 3BE	Input from address hex 37A

This instruction causes the data present on pins 1, 14, 16, 17, and the IRQ bit to read by the processor. In the absence of external drive applied to these pins, data read by the processor will exactly match data last written to hex 3BE in the same bit positions. Note that data bits 0-2 are not included. If external drivers are dotted to these pins, that data will be ORed with data applied to the pins by the hex 3BE latch.

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
			IRQ Enable	<u>Pin 17</u>	Pin 16	<u>Pin 14</u>	<u>Pin 1</u>
			Por=0	Por=1	Por=0	Por=1	Por=1

These pins assume the states shown after a reset from the processor.



Connector Specifications

IBM Monochrome Display and Printer Adapter

This chapter has two functions. The first is to provide the interface to the IBM Monochrome Display. The second provides a parallel interface for the IBM 80 CPS Printer. This second function is fully discussed in the “IBM Printer Adapter” section.

The monitor adapter is designed around the Motorola 6845 CRT controller module. There are 4K bytes of static memory on the adapter which is used for the display buffer. This buffer has two ports and may be accessed directly by the processor. No parity is provided on the display buffer.

Two bytes are fetched from the display buffer in 553 ns, providing a data rate of 1.8M bytes/second.

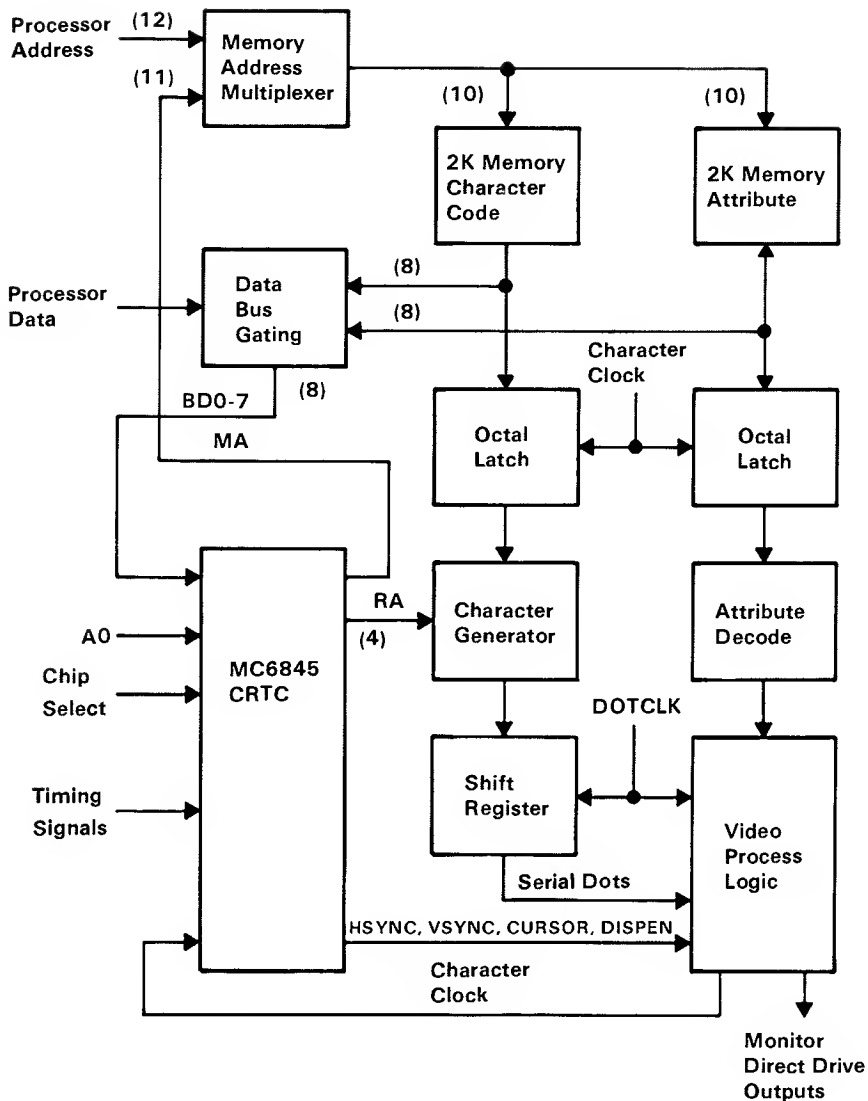
The monitor adapter supports 256 different character codes. An 8K-byte character generator contains the fonts for the character codes. The characters, values, and screen characteristics are given in “Appendix C: Of Characters, Keystrokes, and Color.”

This monitor adapter, when used with a display containing P39 phosphor, will not support a light pen.

Where possible, only one low-power Schottky (LS) load is present on any I/O slot. Some of the address bus lines have two LS loads. No signal has more than two LS loads.

Characteristics of the monitor adapter are listed below:

- 80 by 25 screen
- Direct-drive output
- 9 by 14 character box
- 7 by 9 character
- 18 kHz monitor
- Character attributes



IBM Monochrome Display Adapter Block Diagram

Programming Considerations

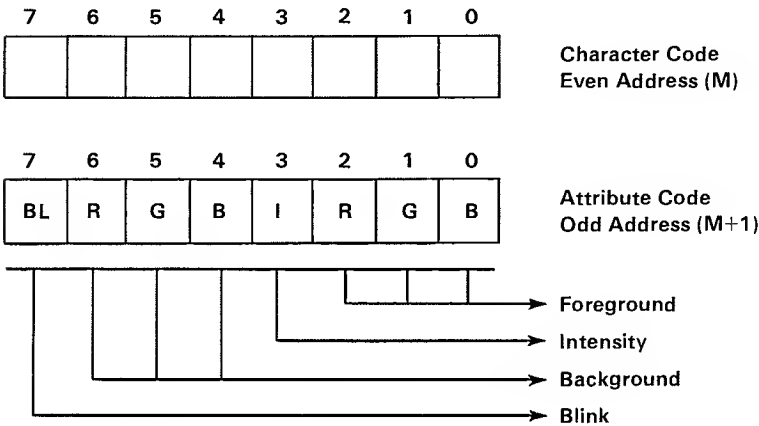
The following table summarizes the 6845 internal data registers, their functions, and their parameters. For the IBM Monochrome Display, the values must be programmed into the 6845 to ensure proper initialization of the device.

Register Number	Register File	Program Unit	IBM Monochrome Display (Address in hex)
R0	Horizontal Total	Characters	61
R1	Horizontal Displayed	Characters	50
R2	Horizontal Sync Position	Characters	52
R3	Horizontal Sync Width	Characters	F
R4	Vertical Total	Character Rows	19
R5	Vertical Total Adjust	Scan Line	6
R6	Vertical Displayed	Character Row	19
R7	Vertical Sync Position	Character Row	19
R8	Interlace Mode	-----	02
R9	Maximum Scan Line Address	Scan Line	D
R10	Cursor Start	Scan Line	B
R11	Cursor End	Scan Line	C
R12	Start Address (H)	-----	00
R13	Start Address (L)	-----	00
R14	Cursor (H)	-----	00
R15	Cursor (L)	-----	00
R16	Reserved	-----	--
R17	Reserved	-----	--

To ensure proper initialization, the first command issued to the attachment must be to send to CRT control port 1 (hex 3B8), a hex 01, to set the high-resolution mode. If this bit is not set, then the processor access to the monochrome adapter must never occur. If the high-resolution bit is not set, the processor will stop running.

System configurations that have both an IBM Monochrome Display Adapter and Printer Adapter, and an IBM Color/Graphics Monitor Adapter, must ensure that both adapters are properly initialized after a power-on reset. Damage to either display may occur if not properly initialized.

The IBM Monochrome Display and Printer Adapter supports 256 different character codes. In the character set are alphanumerics and block graphics. Each character in the display buffer has a corresponding character attribute. The character code must be an even address, and the attribute code must be an odd address in the display buffer.



The adapter decodes the character attribute byte as defined above. The blink and intensity bits may be combined with the foreground and background bits to further enhance the character attribute functions listed below.

Background R G B	Foreground R G B	Function
0 0 0	0 0 0	Non-Display
0 0 0	0 0 1	Underline
0 0 0	1 1 1	White Character/Black Background
1 1 1	0 0 0	Reverse Video

The 4K display buffer supports one screen of 25 rows of 80 characters, plus a character attribute for each display character. The starting address of the buffer is hex B0000. The display buffer can be read from using DMA; however, at least one wait-state will be inserted by the processor. The duration of the wait-state will vary, because the processor/monitor access is synchronized with the character clock on this adapter.

Interrupt level 7 is used on the parallel interface. Interrupts can be enabled or disabled through the printer control port. The interrupt is a high-level active signal.

The figure below breaks down the functions of the I/O address decode for the adapter. The I/O address decode is from hex 3B0 through hex 3BF. The bit assignment for each I/O address follows:

I/O Register Address	Function
3B0	Not Used
3B1	Not Used
3B2	Not Used
3B3	Not Used
3B4*	6845 Index Register
3B5*	6845 Data Register
3B6	Not Used
3B7	Not Used
3B8	CRT Control Port 1
3B9	Reserved
3BA	CRT Status Port
3BB	Reserved
3BC	Parallel Data Port
3BD	Printer Status Port
3BE	Printer Control Port
3BF	Not Used
*The 6845 Index and Data Registers are used to program the CRT controller to interface the high-resolution IBM Monochrome Display.	

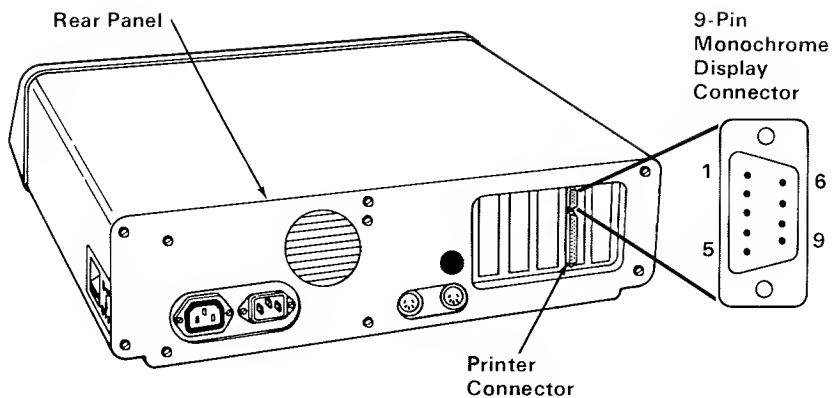
I/O Address and Bit Map

Bit Number	Function
0	+High Resolution Mode
1	Not Used
2	Not Used
3	+Video Enable
4	Not Used
5	+Enable Blink
6,7	Not Used

6845 CRT Control Port 1 (Hex 3B8)

Bit Number	Function
0	+Horizontal Drive
1	Reserved
2	Reserved
3	+Black/White Video

6845 CRT Status Port (Hex 3BA)



At Standard TTL Levels

IBM Monochrome Display	Ground	1	IBM Monochrome Display and Printer Adapter
	Ground	2	
	Not Used	3	
	Not Used	4	
	Not Used	5	
	+Intensity	6	
	+Video	7	
	+Horizontal	8	
	- Vertical	9	

Note: Signal voltages are 0.0 to 0.6 Vdc at down level and +2.4 to 3.5 Vdc at high level.

Connector Specifications

Notes:

IBM Monochrome Display

The high-resolution IBM Monochrome Display attaches to the system unit through two cables approximately 3 feet (914 millimeters) in length. One cable is a signal cable that contains the direct drive interface from the IBM Monochrome Display and Printer Adapter.

The second cable provides ac power to the display from the system unit. This allows the system-unit power switch to also control the display unit. An additional benefit is a reduction in the requirements for wall outlets to power the system. The display contains an 11-½ inch (283 millimeters), diagonal 90° deflection CRT. The CRT and analog circuits are packaged in an enclosure so the display may either sit on top of the system unit or on a nearby tabletop or desk. The unit has both brightness and contrast adjustment controls on the front surface that are easily accessible to the operator.

Operating Characteristics

Screen

- High-persistence green phosphor (P 39).
- Etched surface to reduce glare.
- Size is 80 characters by 25 lines.
- Character box is 9 dots wide by 14 dots high.

Video Signal

- Maximum bandwidth of 16.257 MHz.

Vertical Drive

- Screen refreshed at 50 Hz with 350 lines of vertical resolution and 720 lines of horizontal resolution.

Horizontal Drive

- Positive-level, TTL-compatibility at a frequency of 18.432 kHz.

IBM Color/Graphics Monitor Adapter

The IBM Color/Graphics Monitor Adapter is designed to attach to the IBM Color Display, to a variety of television-frequency monitors, or to home television sets (user-supplied RF modulator is required for home television sets). The adapter is capable of operating in black-and-white or color. It provides three video interfaces: a composite-video port, a direct-drive port, and a connection interface for driving a user-supplied RF modulator. In addition, a light pen interface is provided.

The adapter has two basic modes of operation: alphanumeric (A/N) and all-points-addressable graphics (APA). Additional modes are available within the A/N and APA modes. In the A/N mode, the display can be operated in either a 40-column by 25-row mode for a low-resolution monitor or home television, or in an 80-column by 25-row mode for high-resolution monitors. In both modes, characters are defined in an 8-wide by 8-high character box and are 7-wide by 7-high, with one line of descender for lowercase characters. Both uppercase and lowercase characters are supported in all modes.

The character attributes of reverse video, blinking, and highlighting are available in the black-and-white mode. In the color mode, sixteen foreground and eight background colors are available for each character. In addition, blinking on a per-character basis is available.

The monitor adapter contains 16K bytes of storage. As an example, a 40-column by 25-row display screen uses 1000 bytes to store character information, and 1000 bytes to store attribute/color information. This would mean that up to eight display screens can be stored in the adapter memory. Similarly, in an 80-column by 25-row mode, four display screens may be stored in the adapter. The entire 16K bytes of storage on the display adapter are directly addressable by the processor, which allows maximum software flexibility in managing the screen.

In A/N color modes, it is also possible to select the color of the screen's border. One of sixteen colors can be selected.

In the APA mode, there are two resolutions available: a medium-resolution color graphics mode (320 PELs by 200 rows) and a high-resolution black-and-white graphics mode (640 PELs by 200 rows). In the medium-resolution mode, each picture element (PEL) may have one of four colors. The background color (color 0) may be any of the 16 possible colors. The remaining three colors come from one of the two software-selectable palettes. One palette contains green/red/brown; the other contains cyan/magenta/white.

The high-resolution mode is available only in black-and-white because the entire 16K bytes of storage in the adapter is used to define the on or off of the PELs.

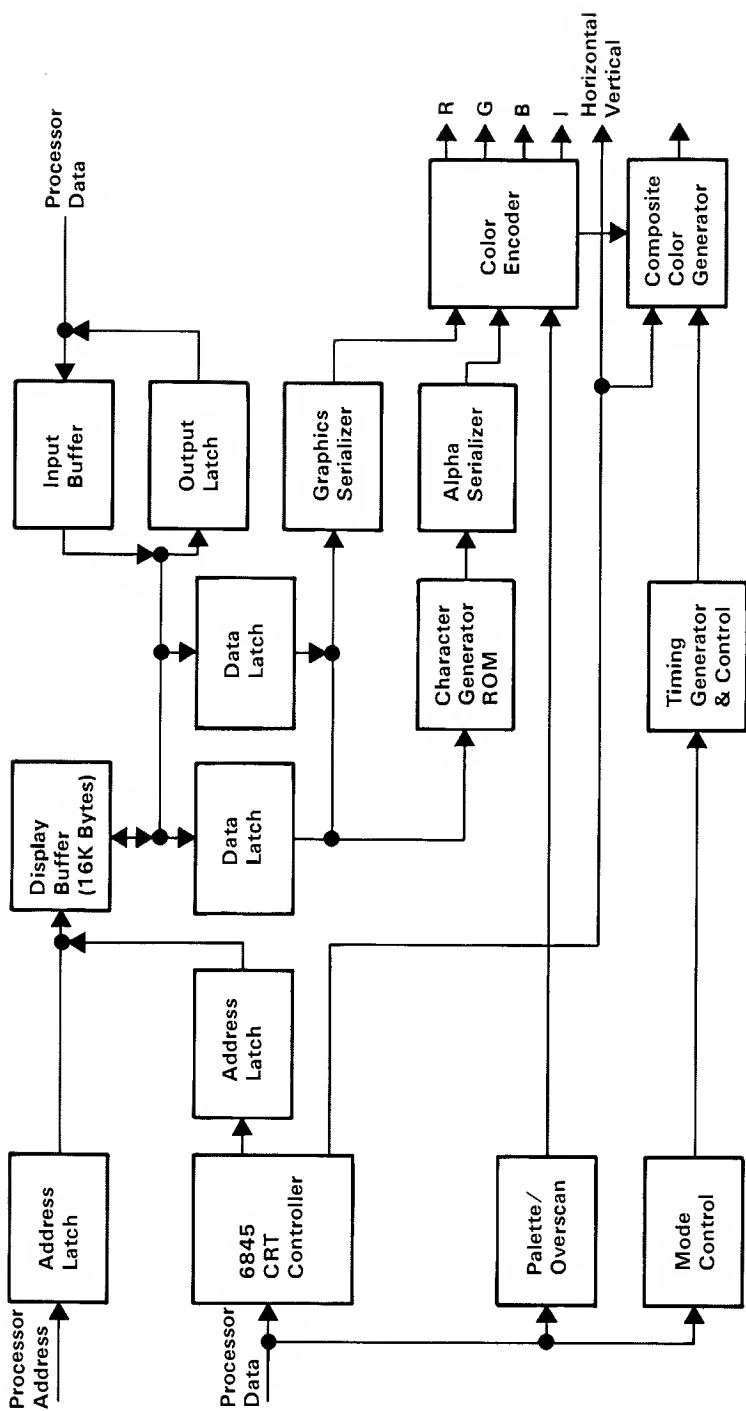
The adapter operates in noninterlace mode at either 7 or 14 MHz, depending on the mode of operation selected.

In the A/N mode, characters are formed from a ROM character generator. The character generator contains dot patterns for 256 different characters. The character set contains the following major groupings of characters:

- 16 special characters for game support
- 15 characters for word-processing editing support
- 96 characters for the standard ASCII graphics set
- 48 characters for foreign-language support
- 48 characters for business block-graphics support (allowing drawing of charts, boxes, and tables using single and double lines)
- 16 selected Greek characters
- 15 selected scientific-notation characters

The color/graphics monitor adapter function is packaged on a single card. The direct-drive and composite-video ports are right-angle mounted connectors on the adapter, and extend through the rear panel of the unit. The direct-drive video port is a 9-pin D-shell female connector. The composite-video port is a standard female phono-jack.

The display adapter is implemented using a Motorola 6845 CRT controller device. This adapter is highly programmable with respect to raster and character parameters. Therefore, many additional modes are possible with clever programming of the adapter.



Descriptions of Major Components

Motorola 6845 CRT Controller

This device provides the necessary interface to drive a raster-scan CRT.

Mode Set Register

This is a general-purpose, programmable, I/O register. It has I/O ports that may be individually programmed. Its function in this attachment is to provide mode selection and color selection in the medium-resolution color-graphics mode.

Display Buffer

The display buffer resides in the processor-address space, starting at address hex B8000. It provides 16K bytes of dynamic read/write memory. A dual-ported implementation allows the processor and the graphics control unit to access the buffer. The processor and the CRT control unit have equal access to this buffer during all modes of operation, except in the high-resolution alphanumeric mode. In this mode, only the processor should access to this buffer during the horizontal-retrace intervals. While the processor may write to the required buffer at any time, a small amount of display interference will result if this does not occur during the horizontal-retrace intervals.

Character Generator

This attachment utilizes a ROM character generator. It consists of 8K bytes of storage that cannot be read from or written to under software control. This is a general-purpose ROM character generator with three different character fonts. Two character fonts are used on the color/graphics adapter: a 7-high by 7-wide double-dot font and a 5-wide by 7-high single-dot font. The font is selected by a jumper (P3). The single-dot font is selected by inserting the jumper; the double-dot font is selected by removing the jumper.

Timing Generator

This generator produces the timing signals used by the 6845 CRT controller and by the dynamic memory. It also resolves the processor/graphic controller contentions for accessing the display buffer.

Composite Color Generator

This generator produces base band video color information.

Alphanumeric Mode

Every display-character position in the alphanumeric mode is defined by two bytes in the regen buffer (a part of the monitor adapter), not the system memory. Both the color/graphics and the monochrome display adapter use the following 2-byte character/attribute format.

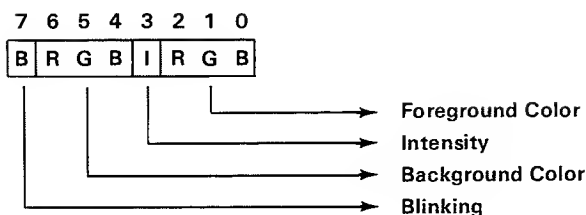
Display-Character Code Byte								Attribute Byte							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0

The functions of the attribute byte are defined by the following table:

Attribute Function	Attribute Byte						
	7	6 5 4			3	2 1 0	
	B	R G B			I	R G B	
	FG	Background			Foreground		
	B	0	0	0	I	1	1 1
	B	1	1	1	I	0	0 0
Normal	B	0	0	0	I	0	0 0
Reverse Video	B	1	1	1	I	1	1 1
Nondisplay (Black)	B	1	1	1	I	0	0 0
Nondisplay (White)	B	0	0	0	I	1	1 1

I = Highlighted Foreground (Character)
B = Blinking Foreground (Character)

The attribute byte definitions are:



In the alphanumeric mode, the display mode can be operated in either a low-resolution mode or a high-resolution mode.

The low-resolution alphanumeric mode has the following features:

- Supports home color televisions or low-resolution monitors
- Displays up to 25 rows of 40 characters each
- ROM character generator that contains dot patterns for a maximum of 256 different characters
- Requires 2,000 bytes of read/write memory (on the adapter)
- Character box is 8-high by 8-wide
- Two jumper-controlled character fonts are available:
 5-wide by 7-high single-dot character font with one descender
 7-wide by 7-high double-dot character font with one descender
- One character attribute for each character

The high-resolution alphanumeric mode has the following features:

- Supports the IBM Color Display or other color monitor with direct-drive input capability
- Supports a black-and-white composite-video monitor
- Displays up to 25 rows of 80 characters each

- ROM displays generator that contains dot patterns for a maximum of 256 different characters
- Requires 4,000 bytes of read/write memory (on the adapter)
- Character box is 8-high by 8-wide
- Two jumper-controlled character fonts are available:
5-wide by 7-high single-dot character font with one descender
7-wide by 7-high double-dot character font with one descender
- One character attribute for each character

Monochrome vs Color/Graphics Character Attributes

Foreground and background colors are defined by the attribute byte of each character, whether using the IBM Monochrome Display and Printer Adapter or the IBM Color/Graphics Monitor Adapter. The following table describes the colors for each adapter:

Attribute Byte								Monochrome Display Adapter		Color/Graphics Monitor Adapter	
7	6	5	4	3	2	1	0				
B	R	G	B	I	R	G	B	Background Color	Character Color	Background Color	Character Color
FG	Background			Foreground							
B	0	0	0	I	1	1	1	Black	White	Black	White
B	1	1	1	I	0	0	0	White	Black	White	Black
B	0	0	0	I	0	0	0	Black	Black	Black	Black
B	1	1	1	I	1	1	1	White	White	White	White

The monochrome display adapter will produce white characters on a white background with any other code. The color/graphics adapter will change foreground and background colors according to the color value selected. The color values for the various red, green, blue, and intensity bit settings are given in the following table.

R	G	B	I	Color
0	0	0	0	Black
0	0	1	0	Blue
0	1	0	0	Green
0	1	1	0	Cyan
1	0	0	0	Red
1	0	1	0	Magenta
1	1	0	0	Brown
1	1	1	0	White
0	0	0	1	Gray
0	0	1	1	Light Blue
0	1	0	1	Light Green
0	1	1	1	Light Cyan
1	0	0	1	Light Red
1	0	1	1	Light Magenta
1	1	0	1	Yellow
1	1	1	1	White (High Intensity)

Code written with an underline attribute for the IBM Monochrome Display, when executed on a color/graphics monitor adapter, will result in a blue character where the underline attribute is encountered. Also, code written on a color/graphics monitor adapter with blue characters will be displayed as white characters on a black background, with a white underline on the IBM Monochrome Display.

Remember that not all monitors recognize the intensity (I) bit.

Graphics Mode

The IBM Color/Graphics Monitor Adapter has three modes available within the graphics mode. They are low-resolution color graphics, medium-resolution color graphics, and high-resolution color graphics. However, only medium- and high-resolution graphics are supported in ROM. The following table summarizes the three modes.

Mode	Horizontal (PELs)	Vertical (Rows)	Number of Colors Available (Includes Background Color)
Low Resolution	160	100	16 (Includes black-and-white)
Medium Resolution	320	200	4 Colors Total 1 of 16 for Background and 1 of Green, Red, or Brown or 1 of Cyan, Magenta, or White
High Resolution	640	200	Black-and-white only

Low-Resolution Color-Graphics Mode

The low-resolution mode supports home television or color monitors. This mode is not supported in ROM. It has the following features:

- Contains a maximum of 100 rows of 160 PELs, with each PEL being 2-high by 2-wide
- Specifies 1 of 16 colors for each PEL by the I, R, G, and B bits
- Requires 16,000 bytes of read/write memory (on the adapter)
- Uses memory-mapped graphics

Medium-Resolution Color-Graphics Mode

The medium-resolution mode supports home televisions or color monitors. It has the following features:

- Contains a maximum of 200 rows of 320 PELs, with each PEL being 1-high by 1-wide
- Preselects one of four colors for each PEL
- Requires 16,000 bytes of read/write memory (on the adapter)
- Uses memory-mapped graphics

- Formats 4 PELs per byte in the following table:

7	6	5	4	3	2	1	0
C1	C0	C1	C0	C1	C0	C1	C0
First Display PEL		Second Display PEL		Third Display PEL		Fourth Display PEL	

- Organizes graphics storage in two banks of 8,000 bytes, using the following format:

Memory
Address
(in hex)

Function

B8000

Even Scans
(0,2,4,...198)
8,000 bytes

B9F3F

Not Used

BA000

Odd Scans
(1,3,5...199)
8,000 Bytes

BBF3F

Not Used

BBFFF

Address hex B8000 contains PEL instruction for the upper-left corner of the display area.

- Color selection is determined by the following logic:

C1	C0	Function
0	0	Dot takes on the color of 1 of 16 preselected background colors
0	1	Selects first color of preselected Color Set 1 or Color Set 2
1	0	Selects second color of preselected Color Set 1 or Color Set 2
1	1	Selects third color of preselected Color Set 1 or Color Set 2

C1 and C0 will select 4 of 16 preselected colors. This color selection (palette) is preloaded in an I/O port.

Tow two colors sets are:

Color Set 1	Color Set 2
Color 1 is Green	Color 1 is Cyan
Color 2 is Red	Color 2 is Magenta
Color 3 is Brown	Color 3 is White

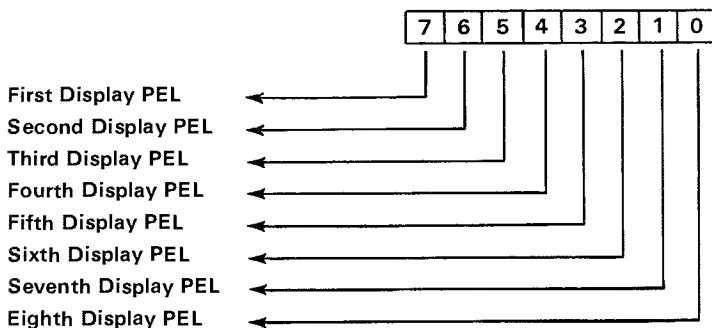
The background colors are the same basic 8 colors as defined for low-resolution graphics, plus 8 alternate intensities defined by the intensity bit, for a total of 16 colors, including black and white.

High-Resolution Black-and-White Graphics Mode

The high-resolution mode supports color monitors. This mode has the following features:

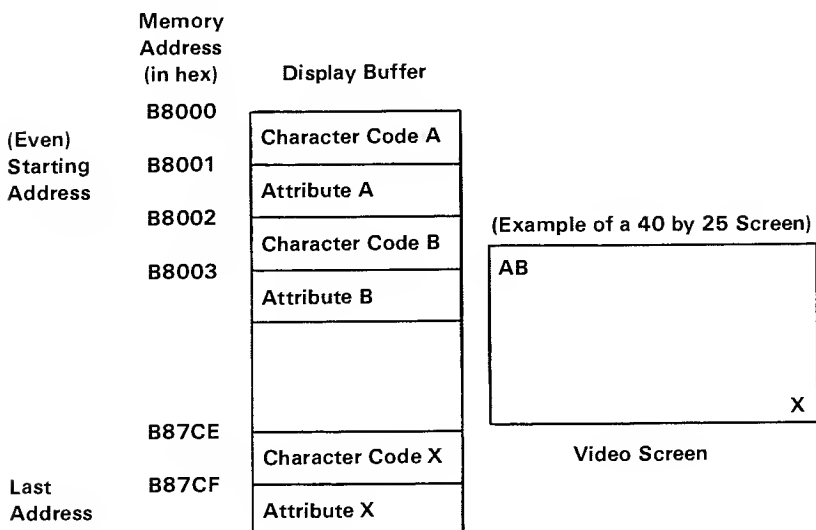
- Contains a maximum of 200 rows of 640 PELs, with each PEL being 1-high by 1-wide.
- Supports black-and-white mode only.
- Requires 16,000 bytes of read/write memory (on the adapter).

- Addressing and mapping procedures are the same as medium-resolution color graphics, but the data format is different. In this mode, each bit in memory is mapped to a PEL on the screen.
- Formats 8 PELs per byte in the following manner:



Description of Basic Operations

In the alphanumeric mode, the adapter fetches character and attribute information from its display buffer. The starting address of the display buffer is programmable through the 6845, but it must be an even address. The character codes and attributes are then displayed according to their relative positions in the buffer.



The processor and the display control unit have equal access to the display buffer during all the operating modes, except the high-resolution alphanumeric mode. During this mode, the processor should access the display buffer during the vertical retrace time. If it does not, the display will be affected with random patterns as the processor is using the display buffer. In the alphanumeric mode, the characters are displayed from a prestored ROM character generator that contains the dot patterns of all the displayable characters.

In the graphics mode, the displayed dots and colors (up to 16K bytes) are also fetched from the display buffer. The bit configuration for each graphics mode is explained in “Graphics Mode.”

I	R	G	B	Color
0	0	0	0	Black
0	0	0	1	Blue
0	0	1	0	Green
0	0	1	1	Cyan
0	1	0	0	Red
0	1	0	1	Magenta
0	1	1	0	Brown
0	1	1	1	White
1	0	0	0	Gray
1	0	0	1	Light Blue
1	0	1	0	Light Green
1	0	1	1	Light Cyan
1	1	0	0	Light Red
1	1	0	1	Light Magenta
1	1	1	0	Yellow
1	1	1	1	High Intensity White

Note: “I” provides extra luminance (brightness) to each available shade. This results in the light colors listed above, except for monitors that do not recognize the “I” bit.

Summary of Available Colors

Programming Considerations

Programming the 6845 CRT Controller

The 6845 has 19 accessible internal registers, which are used to define and control a raster-scan CRT display. One of these registers, the Index register, is actually used as a pointer to the other 18 registers. It is a write-only register, which is loaded from the processor by executing an 'out' instruction to I/O address hex 3D4. The five least significant bits of the I/O bus are loaded into the Index register.

In order to load any of the other 18 registers, the Index register is first loaded with the necessary pointer; then the Data Register is loaded with the information to be placed in the selected register. The Data Register is loaded from the processor by executing an Out instruction to I/O address hex 3D5.

The following table defines the values that must be loaded into the 6845 CRT Controller registers to control the different modes of operation supported by the attachment:

Address Register	Register Number	Register Type	Units	I/O	40 by 25 Alpha-numeric	80 by 25 Alpha-numeric	Graphic Modes
0	R0	Horizontal Total	Character	Write Only	38	71	38
1	R1	Horizontal Displayed	Character	Write Only	28	50	28
2	R2	Horizontal Sync Position	Character	Write Only	2D	5A	2D
3	R3	Horizontal Sync Width	Character	Write Only	0A	0A	0A
4	R4	Vertical Total	Character Row	Write Only	1F	1F	7F
5	R5	Vertical Total Adjust	Scan Line	Write Only	06	06	06
6	R6	Vertical Displayed	Character Row	Write Only	19	19	64
7	R7	Vertical Sync Position	Character Row	Write Only	1C	1C	70
8	R8	Interlace Mode	-	Write Only	02	02	02
9	R9	Maximum Scan Line Address	Scan Line	Write Only	07	07	01
A	R10	Cursor Start	Scan Line	Write Only	06	06	06
B	R11	Cursor End	Scan Line	Write Only	07	07	07
C	R12	Start Address (H)	-	Write Only	00	00	00
D	R13	Start Address (L)	-	Write Only	00	00	00
E	R14	Cursor Address (H)	-	Read/Write	XX	XX	XX
F	R15	Cursor Address (L)	-	Read/Write	XX	XX	XX
10	R16	Light Pen (H)	-	Read Only	XX	XX	XX
11	R17	Light Pen (L)	-	Read Only	XX	XX	XX
Note: All register values are given in hexadecimal							

6845 Register Description

Programming the Mode Control and Status Register

The following I/O devices are defined on the color/graphics adapter.

Hex Address	A9	A8	A7	A6	A5	A4	A3	A2	A1	A0	Function of Register
3D8	1	1	1	1	0	1	1	0	0	0	Mode Control Register (D0)
3D9	1	1	1	1	0	1	1	0	0	1	Color Select Register (D0)
3DA	1	1	1	1	0	1	1	0	1	0	Status Register (D1)
3DB	1	1	1	1	0	1	1	0	1	1	Clear Light Pen Latch
3DC	1	1	1	1	0	1	1	1	0	0	Preset Light Pen Latch
3D4	1	1	1	1	0	1	0	Z	Z	0	6845 Index Register
3D5	1	1	1	1	0	1	0	Z	Z	1	6845 Data Register
3D0	1	1	1	1	0	1	0	Z	Z	0	6845 Registers
3D1	1	1	1	1	0	1	0	Z	Z	1	6845 Registers
Z = don't care condition											

Color-Select Register

This is a 6-bit output-only register (cannot be read). Its I/O address is hex 3D9, and it can be written to by using the 8088 I/O Out command.

Bit 0	Selects B (Blue) Border Color in 40 x 25 Alphanumeric Mode Selects B (Blue) Background Color in 320 x 200 Graphics Mode Selects B (Blue) Foreground Color in 640 x 200 Graphics Mode
Bit 1	Selects G (Green) Border Color in 40 x 25 Alphanumeric Mode Selects G (Green) Background Color in 320 x 200 Graphics Mode Selects G (Green) Foreground Color in 640 x 200 Graphics Mode
Bit 2	Selects R (Red) Border Color in 40 x 25 Alphanumeric Mode Selects R (Red) Background Color in 320 x 200 Graphics Mode Selects R (Red) Foreground Color in 640 x 200 Graphics Mode
Bit 3	Selects I (Intensified) Border Color in 40 x 25 Alphanumeric Mode Selects I (Intensified) Background Color in 320 x 200 Graphics Mode Selects I (Intensified) Foreground Color in 640 x 200 Graphics Mode
Bit 4	Selects Alternate, Intensified Set of Colors in Graphics Mode Selects Background Colors in the Alphanumeric Mode
Bit 5	Selects Active Color Set in 320 x 200 Graphics Mode
Bit 6	Not Used
Bit 7	Not Used

Bits 0, 1, 2, 3 These bits select the screen's border color in the 40 by 25 alphanumeric mode. They select the screen's background color (C0-C1) in the medium-resolution (320 by 200) color-graphics mode.

Bits 4 This bit, when set, will select an alternate, intensified set of colors. Selects background colors in the alphanumeric mode.

Bit 5 This bit is only used in the medium-resolution (320 by 200) color-graphics mode. It is used to select the active set of screen colors for the display.

When bit 5 is set to 1, colors are determined as follows:

C1	C0	Set Selected
0	0	Background (Defined by bits 0-3 of port hex 3D9)
0	1	Cyan
1	0	Magenta
1	1	White

When bit 5 is set to 0, colors are determined as follows:

C1	C0	Set Selected
0	0	Background (Defined by bits 0-3 of port hex 3D9)
0	1	Green
1	0	Red
1	1	Brown

Mode-Select Register

This is a 6-bit output-only register (cannot be read). Its I/O address is hex 3D8, and it can be written to using the 8088 I/O Out command.

The following is a description of the register's functions:

Bit 0	80 x 25 Alphanumeric Mode
Bit 1	Graphics Select
Bit 2	Black/White Select
Bit 3	Enable Video Signal
Bit 4	High-Resolution (640 x 200) Black/White Mode
Bit 5	Change Background Intensity to Blink Bit
Bit 6	Not Used
Bit 7	Not Used

Bit 0 A 1 selects 80 by 25 alphanumeric mode
 A 0 selects 40 by 25 alphanumeric mode

Bit 1 A 1 selects 320 by 200 graphics mode
 A 0 selects alphanumeric mode

Bit 2 A 1 selects black-and-white mode
 A 0 selects color mode

Bit 3 A 1 enables the video signal at certain times when modes are being changed. The video signal should be disabled when changing modes.

Bit 4 A 1 selects the high-resolution (640 by 200) black-and-white graphics mode. One color of 8 can be selected on direct-drive sets in this mode by using register hex 3D9.

Bit 5 When on, this bit will change the character background intensity to the blinking attribute function for alphanumeric modes. When the high-order attribute bit is not selected, 16 background colors (or intensified colors) are available. For normal operation, this bit should be set to 1 to allow the blinking function.

Mode Register Summary

Bits					
0	1	2	3	4	5
0	0	1	1	0	1
0	0	0	1	0	1
1	0	1	1	0	1
1	0	0	1	0	1
0	1	1	1	0	z
0	1	0	1	0	z
0	1	1	1	1	z

40 x 25 Alphanumeric Black-and-White

40 x 25 Alphanumeric Color

80 x 25 Alphanumeric Black-and-White

80 x 25 Alphanumeric Color

320 x 200 Black-and-White Graphics

320 x 200 Color Graphics

640 x 200 Black-and-White Graphics

Enable Blink Attribute

640 x 200 Black-and-White

Enable Video Signal

Select Black-and-White Mode

Select 320 x 200 Graphics

80 x 25 Alphanumeric Select

z = don't care condition

Note: The low-resolution (160 by 100) mode requires special programming and is set up as the 40 by 25 alphanumeric mode.

Status Register

The status register is a 4-bit read-only register. Its I/O address is hex 3DA, and it can be read using the 8088 I/O In instruction. The following is a description of the register functions:

Bit 0	Display Enable
Bit 1	Light-Pen Trigger Set
Bit 2	Light-Pen Switch Made
Bit 3	Vertical Sync
Bit 4	Not Used
Bit 5	Not Used
Bit 6	Not Used
Bit 7	Not Used

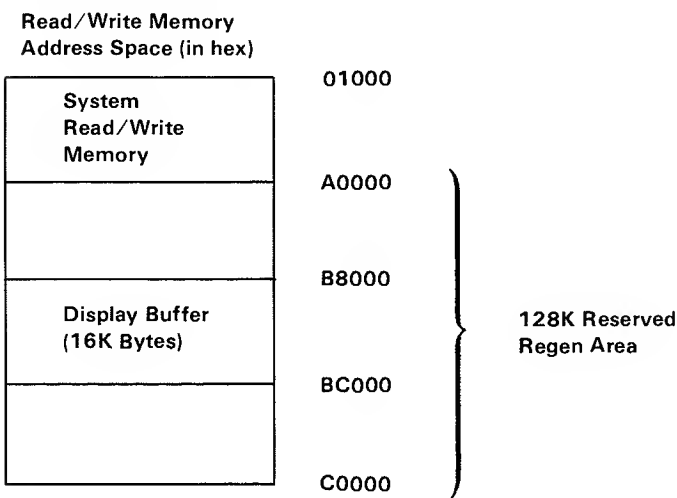
- Bit 0 This bit, when active, indicates that a regen buffer memory access can be made without interfering with the display.
- Bit 1 This bit, when active, indicates that a positive-going edge from the light-pen has set the light pen's trigger. This trigger is reset upon power-on and may also be cleared by performing an I/O Out command to hex address 3DB. No specific data setting is required; the action is address-activated.
- Bit 2 The light-pen switch status is reflected in this status bit. The switch is not latched or debounced. A 0 indicates that the switch is on.
- Bit 3 This bit, when active, indicates that the raster is in a vertical retrace mode. This is a good time to perform screen-buffer updating.

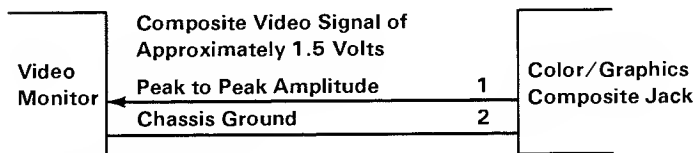
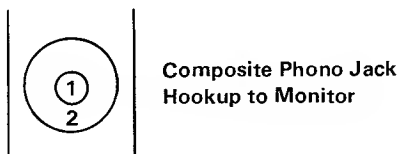
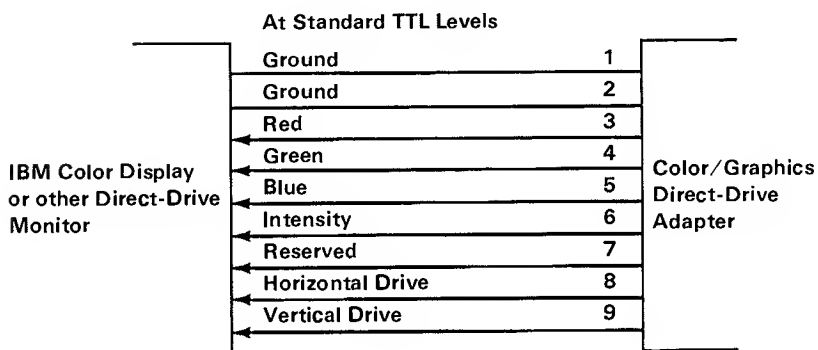
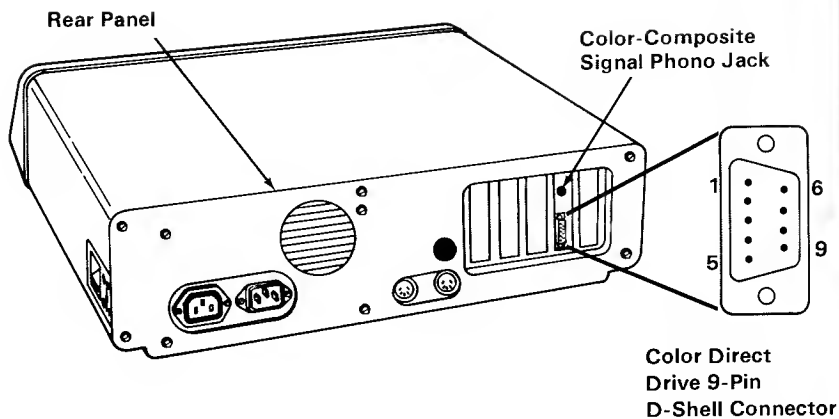
Sequence of Events for Changing Modes

1. Determine the mode of operation.
2. Reset 'video enable' bit in mode-select register.
3. Program 6845 to select mode.
4. Program mode/color select registers including re-enabling video.

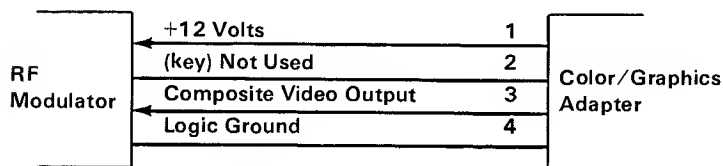
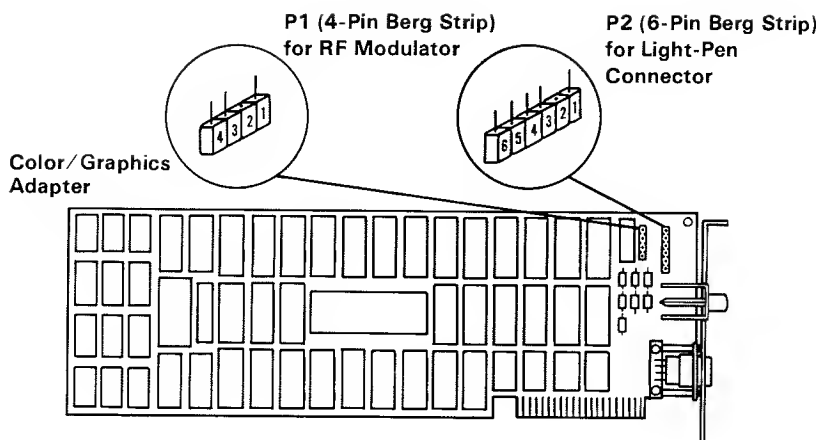
Memory Requirements

The memory used by this adapter is self-contained. It consists of 16K bytes of memory without parity. This memory is used as both a display buffer for alphanumeric data and as a bit map for graphics data. The regen buffer's address starts at hex B8000.

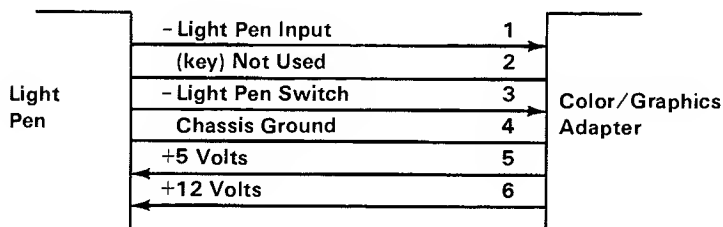




Connector Specifications (Part 1 of 2)



RF Modulator Interface



Light Pen Interface

Connector Specifications (Part 2 of 2)

IBM Color Display

The IBM Color Display attaches to the system unit by a signal cable that is approximately 5 feet (1.5 meters) in length. This signal cable provides a direct-drive interface from the IBM Color/Graphics Monitor Adapter.

A second cable provides ac power to the display from a standard wall outlet. The display has its own power control and indicator. The display will accept either 120-volt 60-Hz, or 220-volt 50-Hz power. The power supply in the display automatically switches to match the applied power.

The display has a 13-inch (340 millimeters) CRT. The CRT and analog circuits are packaged in an enclosure so the display may sit either on top of the system unit or on a nearby tabletop or desk. Front panel controls and indicators include: Power-On control, Power-On indicator, Brightness and Contrast controls. Two additional rear-panel controls are the Vertical Hold and Vertical Size controls.

Operating Characteristics

Screen

- High contrast (black) screen.
- Displays up to 16 colors, when used with the IBM Color/Graphics Monitor Adapter.
- Characters defined in an 8-high by 8-wide matrix.

Video Signal

- Maximum video bandwidth of 14 MHz.
- Red, green, and blue video signals and intensity are all independent.

Vertical Drive

- Screen refreshed at 60 Hz with 200 vertical lines of resolution.

Horizontal Drive

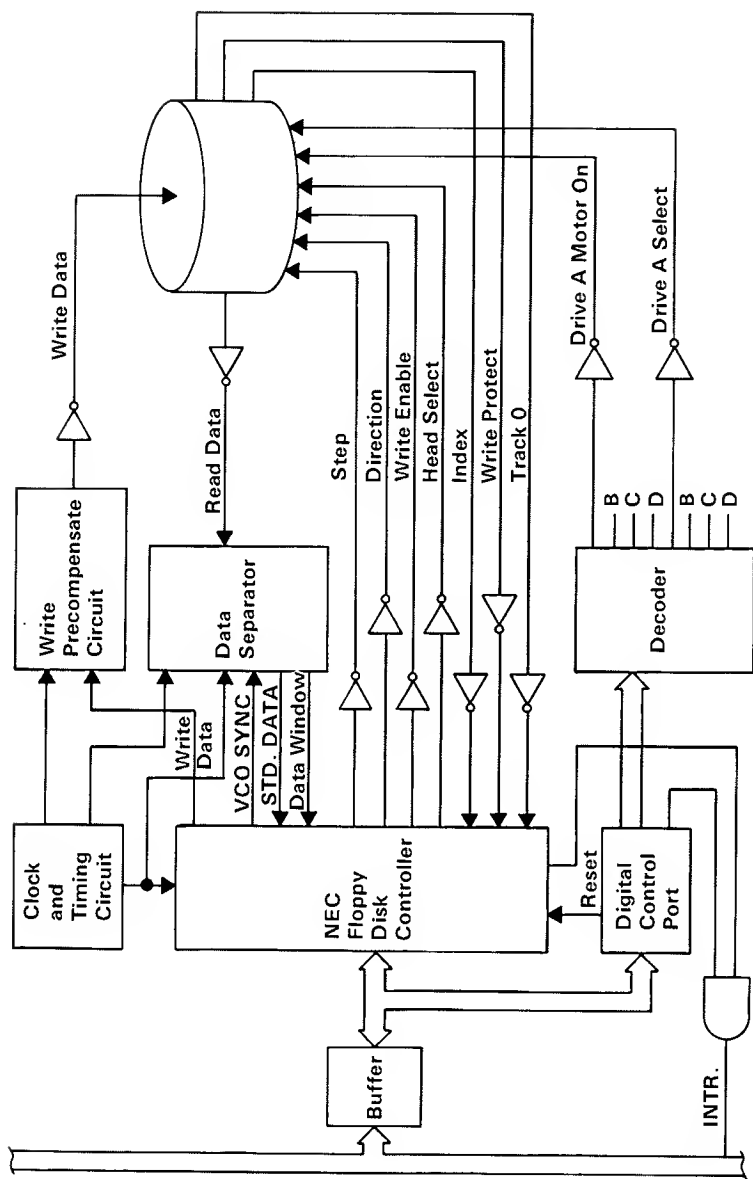
- Positive-level, TTL-compatibility, at a frequency of 15.75 kHz.

IBM 5-1/4" Diskette Drive Adapter

The 5-1/4 inch diskette drive adapter fits into one of the expansion slots in the system unit. It attaches to one or two diskette drives through an internal, daisy-chained flat cable that connects to one end of the drive adapter. The adapter has a connector at the other end that extends through the rear panel of the system unit. This connector has signals for two additional external diskette drives; thus the 5-1/4 inch diskette drive adapter can attach four 5-1/4 inch drives – two internal and two external.

The adapter is designed for double-density, MFM-coded, diskette drives and uses write precompensation with an analog phase-lock loop for clock and data recovery. The adapter is a general-purpose device using the NEC μ PD765 compatible controller. Therefore, the diskette drive parameters are programmable. In addition, the attachment supports the diskette drive's write-protect feature. The adapter is buffered on the I/O bus and uses the system board's direct memory access (DMA) for record data transfers. An interrupt level is also used to indicate when an operation is complete and that a status condition requires processor attention.

In general, the 5-1/4 inch diskette drive adapter presents a high-level command interface to software I/O drivers. A block diagram of the 5-1/4 inch diskette drive adapter is on the following page.



5-1/4 Inch Diskette Drive Adapter Block Diagram

Functional Description

From a programming point of view, this attachment consists of an 8-bit digital-output register in parallel with an NEC μ PD765 or equivalent floppy disk controller (FDC).

In the following description, drive numbers 0, 1, 2, and 3 are equivalent to drives A, B, C, and D.

Digital-Output Register

The digital-output register (DOR) is an output-only register used to control drive motors, drive selection, and feature enable. All bits are cleared by the I/O interface reset line. The bits have the following functions:

Bits 0 and 1 These bits are decoded by the hardware to select one drive if its motor is on:

Bit	1	0	Drive
	0	0	0 (A)
	0	1	1 (B)
	1	0	2 (C)
	1	1	3 (D)

Bit 2 The FDC is held reset when this bit is clear. It must be set by the program to enable the FDC.

Bit 3 This bit allows the FDC interrupt and DMA requests to be gated onto the I/O interface. If this bit is cleared, the interrupt and DMA request I/O interface drivers are disabled.

Bits 4, 5, 6, and 7 These bits control, respectively, the motors of drives 0, 1, 2 (A, B, C), and 3 (D). If a bit is clear, the associated motor is off, and the drive cannot be selected.

Floppy Disk Controller

The floppy disk controller (FDC) contains two registers that may be accessed by the main system processor: a status register and a data register. The 8-bit main status register contains the status information of the FDC and may be accessed at any time. The 8-bit data register (actually consisting of several registers in a stack with only one register presented to the data bus at a time) stores data, commands, parameters, and provides floppy disk drive (FDD) status information. Data bytes are read from or written to the data register in order to program or obtain results after a particular command. The main status register may only be read and is used to facilitate the transfer of data between the processor and FDC.

The bits in the main status register (hex 34F) are defined as follows:

Bit Number	Name	Symbol	Description
DB0	FDD A Busy	DAB	FDD number 0 is in the Seek mode.
DB1	FDD B Busy	DBB	FDD number 1 is in the Seek mode.
DB2	FDD C Busy	DCB	FDD number 2 is in the Seek mode.
DB3	FDD D Busy	DDb	FDD number 3 is in the Seek mode.
DB4	FDC Busy	CB	A read or write command is in process.
DB5	Non-DMA Mode	NDM	The FDC is in the non-DMA mode.
DB6	Data Input/ Output	DIO	Indicates direction of data transfer between FDC and processor. If DIO = "1," then transfer is from FDC data register to the processor. If DIO = "0," then transfer is from the processor to FDC data register.
DB7	Request for Master	RQM	Indicates data register is ready to send or receive data to or from the processor. Both bits DIO and RQM should be used to perform the handshaking functions of "ready" and "direction" to the processor.

The FDC is capable of performing 15 different commands. Each command is initiated by a multi-byte transfer from the processor, and the result after execution of the command may also be a multi-byte transfer back to the processor. Because of this multi-byte interchange of information between the FDC and the processor, it is convenient to consider each command as consisting of three phases:

Command Phase

The FDC receives all information required to perform a particular operation from the processor.

Execution Phase

The FDC performs the operation it was instructed to do.

Result Phase

After completion of the operation, status and other housekeeping information is made available to the processor.

Programming Considerations

The following tables define the symbols used in the command summary, which follows.

Symbol	Name	Description
A0	Address Line 0	A0 controls selection of main status register (A0 = 0) or data register (A0 = 1).
C	Cylinder Number	C stands for the current/selected cylinder (track) number of the medium.
D	Data	D stands for the data pattern that is going to be written into a sector.
D7-D0	Data Bus	8-bit data bus, where D7 stands for a most significant bit, and D0 stands for a least significant bit.
DTL	Data Length	When N is defined as 00, DTL stands for the data length that users are going to read from or write to the sector.
EOT	End of Track	EOT stands for the final sector number on a cylinder.
GPL	Gap Length	GPL stands for the length of gap 3 (spacing between sectors excluding VCO sync field).
H	Head Address	H stands for head number 0 or 1, as specified in ID field.
HD	Head	HD stands for a selected head number 0 or 1. (H = HD in all command words.)
HLT	Head Load Time	HLT stands for the head load time in the FDD (4 to 512 ms in 4-ms increments).
HUT	Head Unload Time	HUT stands for the head unload time after a read or write operation has occurred (0 to 480 ms in 32-ms increments).
MF	FM or MFM Mode	If MF is low, FM mode is selected; if it is high, MFM mode is selected only if MFM is implemented.
MT	Multi-Track	If MT is high, a multi-track operation is to be performed. (A cylinder under both HDO and HD1 will be read or written.)
N	Number	N stands for the number of data bytes written in a sector.

Symbol Descriptions (Part 1 of 2)

Symbol	Name	Description
NCN	New Cylinder Number	NCN stands for a new cylinder number, which is going to be reached as a result of the seek operation. (Desired position of the head.)
ND	Non-DMA Mode	ND stands for operation in the non-DMA mode.
PCN	Present Cylinder Number	PCN stands for cylinder number at the completion of sense-interrupt-status command indicating the position of the head at present time.
R	Record	R stands for the sector number, which will be read or written.
R/W	Read/Write	R/W stands for either read (R) or write (W) signal.
SC	Sector	SC indicates the number of sectors per cylinder.
SK	Skip	SK stands for skip deleted-data address mark.
SRT	Step Rate Time	SRT stands for the stepping rate for the FDD (2 to 32 ms in 2-ms increments).
ST 0 ST 1 ST 2 ST 3	Status 0 Status 1 Status 2 Status 3	ST 0-3 stand for one of four registers that store the status information after a command has been executed. This information is available during the result phase after command execution. These registers should not be confused with the main status register (selected by A0 = 0). ST 0-3 may be read only after a command has been executed and contain information relevant to that particular command.
STP	Scan Test	During a scan operation, if STP = 1, the data in contiguous sectors is compared byte-by-byte with data sent from the processor (or DMA), and if STP = 2, then alternate sectors are read and compared.
US0, US1	Unit Select	US stands for a selected drive number encoded the same as bits 0 and 1 of the digital output register (DOR).

Symbol Descriptions (Part 2 of 2)

Command Summary

In the following table, 0 indicates “logical 0” for that bit, 1 means “logical 1,” and X means “don’t care.”

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	MT	MF	SK	0	0	1	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
Execution	W				DTL					Data transfer between the FDD and main system.
Result	R				ST 0					Status information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	MT	MF	SK	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
Execution	W				DTL					Data transfer between the FDD and main system.
Result	R				ST 0					Status information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	MT	MF	SK	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
Command	W				C					Command Codes
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
	W				DTL					
Execution										Data transfer between the FDD and main system.
Result	R				ST 0					Status information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	MT	MF	SK	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
Command	W				C					Command Codes
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
	W				DTL					
Execution										Data transfer between the FDD and main system.
Result	R				ST 0					Status information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	MT	MF	0	0	0	1	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
Execution	W				DTL					Data transfer between the main system and FDD.
Result	R				ST 0					Status information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
	R				N					
Command	W	MT	MF	0	0	1	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
Execution	W				DTL					Data transfer between FDD and main system.
Result	R				ST 0					Status ID information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
	R				N					

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	0	MF	SK	0	0	0	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
	W				GPL					
Execution	W				DTL					Data transfer between the FDD and main system. FDC reads all of cylinder's contents from index hole to EOT.
Result	R				ST 0					Status information after command execution. Sector ID information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
	R				N					
Command	W	0	MF	0	0	1	0	1	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
Execution										The first correct ID information on the cylinder is stored in data register.
Result	R				ST 0					Status information after command execution. Sector ID information during execution phase.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
	R				N					

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	0	MF	0	0	1	1	0	0	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				N					
	W				SC					
	W				GPL					
	W				D					
Execution										FDC formats an entire cylinder.
Result	R				ST 0					Status information after command execution. In this case, the ID information has no meaning.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	MT	MF	SK	1	0	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
Execution	W				EOT					Data compared between the FDD and the main system.
	W				GPL					
	W				STP					
Result	R				ST 0					Status information after command execution. Sector ID information after Command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	MT	MF	SK	1	0	0	0	1	Command Codes
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
Execution	W				EOT					Data compared between the FDD and the main system.
	W				GPL					
	W				STP					
Result	R				ST 0					Status information after command execution. Sector ID information after Command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	Scan Low or Equal								Command Codes Sector ID information prior to command execution.
	W	MT	MF	SK	1	1	0	0	1	
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
Execution	W				GPL					Data compared between the FDD and main system. Status information after command execution.
	W				STP					
Result	R				ST 0					Status information after command execution. Sector ID information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W	Scan High or Equal								Command Codes Sector ID information prior to command execution.
	W	MT	MF	SK	1	1	1	0	1	
	W	X	X	X	X	X	HD	US1	US0	
	W				C					
	W				H					
	W				R					
	W				N					
	W				EOT					
Execution	W				GPL					Data compared between the FDD and main system. Status information after command execution.
	W				STP					
Result	R				ST 0					Status information after command execution. Sector ID information after command execution.
	R				ST 1					
	R				ST 2					
	R				C					
	R				H					
	R				R					
Command	W				N					
	W									

Phase	R/W	Data Bus								Remarks
		D7	D6	D5	D4	D3	D2	D1	D0	
Command	W	Recalibrate								Command Codes
	W	0	0	0	0	0	1	1	1	
Execution		X	X	X	X	X	0	US1	US0	Head retracted to track 0
No Result Phase										
Command Result	W	Sense Interrupt Status								Command Codes
	R	0	0	0	0	1	0	0	0	
	R	ST 0 PCN								Status information at the end of seek operation about the FDC
Command	W	Specify								Command Codes
	W	0	0	0	0	0	0	1	1	
	W	—SRT—				HUT—				
No Result Phase	W	—HLT—				ND				
Command Result	W	Sense Drive Status								Command Codes
	W	0	0	0	0	0	1	0	0	
	R	X	X	X	X	X	HD	US1	US0	Status information about FDD.
						ST 3				
Command	W	Seek								Command Codes
	W	0	0	0	0	1	1	1	1	
Execution	W	X	X	X	X	X	HD	US1	US0	Head is positioned over proper cylinder on diskette.
No Result Phase						NCN				
Command Result	W	Invalid								Invalid command codes (NoOp - FDC goes into standby state). ST 0 = 80.
	R	Invalid Codes								
						ST 0				

Bit			Description
No.	Name	Symbol	
D7 D6	Interrupt Code	IC	<p>D7 = 0 and D6 = 0 Normal termination of command (NT). Command was completed and properly executed.</p> <p>D7 = 0 and D6 = 1 Abnormal termination of command (AT). Execution of command was started, but was not successfully completed.</p> <p>D7 = 1 and D6 = 0 Invalid command issue (IC). Command that was issued was never started.</p> <p>D7 = 1 and D6 = 1 Abnormal termination because, during command execution, the ready signal from FDD changed state.</p>
D5	Seek End	SE	When the FDC completes the seek command, this flag is set to 1 (high).
D4	Equipment Check	EC	If a fault signal is received from the FDD, or if the track 0 signal fails to occur after 77 step pulses (recalibrate command), then this flag is set.
D3	Not Ready	NR	When the FDD is in the not-ready state and a read or write command is issued, this flag is set. If a read or write command is issued to side 1 of a single-sided drive, then this flag is set.
D2	Head Address	HD	This flag is used to indicate the state of the head at interrupt.
D1 D0	Unit Select 1 Unit Select 0	US 1 US 0	These flags are used to indicate a drive unit number at interrupt.

Command Status Register 0

No.	Bit		Description
	Name	Symbol	
D7	End of Cylinder	EN	When the FDC tries to access a sector beyond the final sector of a cylinder, this flag is set.
D6	—	—	Not used. This bit is always 0 (low).
D5	Data Error	DE	When the FDC detects a CRC error in either the ID field or the data field, this flag is set.
D4	Over Run	OR	If the FDC is not serviced by the main system during data transfers within a certain time interval, this flag is set.
D3	—	—	Not used. This bit is always 0 (low).
D2	No Data	ND	During execution of a read data, write deleted data, or scan command, if the FDC cannot find the sector specified in the ID register, this flag is set. During execution of the read ID command, if the FDC cannot read the ID field without an error, then this flag is set. During the execution of the read a cylinder command, if the starting sector cannot be found, then this flag is set.
D1	Not Writable	NW	During execution of a write data, write deleted data, or format-a-cylinder command, if the FDC detects a write-protect signal from the FDD, then this flag is set.
D0	Missing Address Mark	MA	If the FDC cannot detect the ID address mark, this flag is set. Also, at the same time, the MD (missing address mark in the data field) of status register 2 is set.

Command Status Register 1

Bit			Description
No.	Name	Symbol	
D7	—	—	Not used. This bit is always 0 (low).
D6	Control Mark	CM	During execution of the read data or scan command, if the FDC encounters a sector that contains a deleted data address mark, this flag is set.
D5	Data Error in Data Field	DD	If the FDC detects a CRC error in the data, then this flag is set.
D4	Wrong Cylinder	WC	This bit is related to the ND bit, and when the contents of C on the medium are different from that stored in the ID register, this flag is set.
D3	Scan Equal Hit	SH	During execution of the scan command, if the condition of "equal" is satisfied, this flag is set.
D2	Scan Not Satisfied	SN	During execution of the scan command, if the FDC cannot find a sector on the cylinder that meets the condition, then this flag is set.
D1	Bad Cylinder	BC	This bit is related to the ND bit, and when the contents of C on the medium are different from that stored in the ID register, and the contents of C is FF, then this flag is set.
D0	Missing Address Mark in Data Field	MD	When data is read from the medium, if the FDC cannot find a data address mark or deleted data address mark, then this flag is set.

Command Status Register 2

Bit			Description
No.	Name	Symbol	
D7	Fault	FT	This bit is the status of the fault signal from the FDD.
D6	Write Protected	WP	This bit is the status of the write-protected signal from the FDD.
D5	Ready	RY	This bit is the status of the ready signal from the FDD.
D4	Track 0	T0	This bit is the status of the track 0 signal from the FDD.
D3	Two Side	TS	This bit is the status of the two-side signal from the FDD.
D2	Head Address	HD	This bit is the status of the side-select signal from the FDD.
D1	Unit Select 1	US 1	This bit is the status of the unit-select-1 signal from the FDD.
D0	Unit Select 0	US 0	This bit is the status of the unit-select-0 signal from the FDD.

Command Status Register 3

Programming Summary

FDC Data Register	I/O Address Hex 3F5
FDC Main Status Register	I/O Address Hex 3F4
Digital Output Register	I/O Address Hex 3F2
Bit 0	Drive 00: DR #A 10: DR #C
1	Select 01: DR #B 11: DR #D
2	Not FDC Reset
3	Enable INT & DMA Requests
4	Drive A Motor Enable
5	Drive B Motor Enable
6	Drive C Motor Enable
7	Drive D Motor Enable
All bits cleared with channel reset.	

DPC Registers

FDC Constants (in hex)

N:	02	GPL Format:	05
SC:	08	GPL R/W:	2A
HUT:	F	HLT:	01
SRT:	C		(6 ms track-to-track)

Drive Constants

Head Load	35 ms
Head Settle	15 ms
Motor Start	250 ms

Comments

- Head loads with drive select, wait HD load before R/W.
- Following access, wait HD settle time before R/W.
- Drive motors should be off when not in use. Only A or B and C or D may run simultaneously. Wait motor start time before R/W.
- Motor must be on for drive to be selected.
- Data errors can occur while using a home television as the system display. Locating the TV too close to the diskette area can cause this to occur. To correct the problem, move the TV away from, or to the opposite side of the system unit.

System I/O Channel Interface

All signals are TTL-compatible:

Most Positive Up Level	5.5 Vdc
Least Positive Up Level	2.7 Vdc
Most Positive Down Level	0.5 Vdc
Least Positive Down Level	−0.5 Vdc

The following lines are used by this adapter.

- +D0-7** (Bidirectional, load: 1 74LS, driver: 74LS 3-state).
These eight lines form a bus by which all commands, status, and data are transferred. Bit 0 is the low-order bit.
- +A0-9** (Adapter input, load: 1 74LS)
These ten lines form an address bus by which a register is selected to receive or supply the byte transferred through lines D0-7. Bit 0 is the low-order bit.
- +AEN** (Adapter input, load: 1 74LS)
The content of lines A0-9 is ignored if this line is active.
- IOW** (Adapter input, load: 1 74LS)
The content of lines D0-7 is stored in the register addressed by lines A0-9 or DACK2 at the trailing edge of this signal.
- IOR** (Adapter input, load: 1 74LS)
The content of the register addressed by lines A0-9 or DACK2 is gated onto lines D0-7 when this line is active.
- DACK2** (Adapter input, load: 2 74LS)
This line being active de-gates output DRQ2, selects the FDC data register as the source/destination of bus D0-7, and indirectly gates T/C to IRQ6.
- +T/C** (Adapter input, load: 4 74LS)
This line and DACK2 being active indicates that the byte of data for which the DMA count was initialized is now being transferred.
- +RESET** (Adapter input, load: 1 74LS)
An up level aborts any operation in process and clears the digital output register (DOR).

- +DRQ2** (Adapter output, driver: 74LS 3-state)
 This line is made active when the attachment is ready to transfer a byte of data to or from main storage. The line is made inactive by DACK2 becoming active or an I/O read of the FDC data register.
- +IRQ6** (Adapter output, driver: 74LS 3-state)
 This line is made active when the FDC has completed an operation. It results in an interrupt to a routine which should examine the FDC result bytes to reset the line and determine the ending condition.

Drive A and B Interface

All signals are TTL-compatible:

Most Positive Up Level	5.5 Vdc
Least Positive Up Level	2.4 Vdc
Most Positive Down Level	0.4 Vdc
Least Positive Down Level	-0.5 Vdc

All adapter outputs are driven by open-collector gates. The drive(s) must provide termination networks to Vcc (except motor enable, which has a 2000-ohm resistor to Vcc).

Each adapter input is terminated with a 150-ohm resistor to Vcc.

Adapter Outputs

- Drive Select A and B** (Driver: 7438)
 These two lines are used by drives A and B to degate all drivers to the adapter and receivers from the attachment (except motor enable) when the line associated with a drive is inactive.

- Motor Enable A and B (Driver: 7438)
The drive associated with each of these lines must control its spindle motor such that it starts when the line becomes active and stops when the line becomes inactive.
- Step (Driver: 7438)
The selected drive moves the read/write head one cylinder in or out per the direction line for each pulse present on this line.
- Direction (Driver: 7438)
For each recognized pulse of the step line, the read/write head moves one cylinder toward the spindle if this line is active, and away from the spindle if inactive.
- Head Select (Driver: 7438)
Head 1 (upper head) will be selected when this line is active (low).
- Write Data (Driver: 7438)
For each inactive to active transition of this line while write enable is active, the selected drive causes a flux change to be stored on the diskette.
- Write Enable (Driver: 7438)
The drive disables write current in the head unless this line is active.

Adapter Inputs

- Index
The selected drive supplies one pulse per diskette revolution on this line.
- Write Protect
The selected drive makes this line active if a write-protected diskette is mounted in the drive.

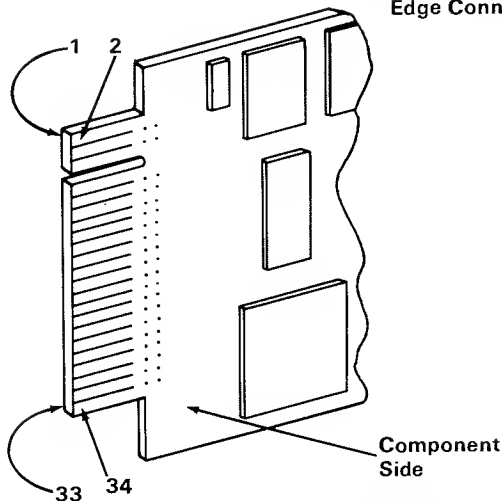
—Track 0

The selected drive makes this line active if the read/write head is over track 0.

—Read Data

The selected drive supplies a pulse on this line for each flux change encountered on the diskette.

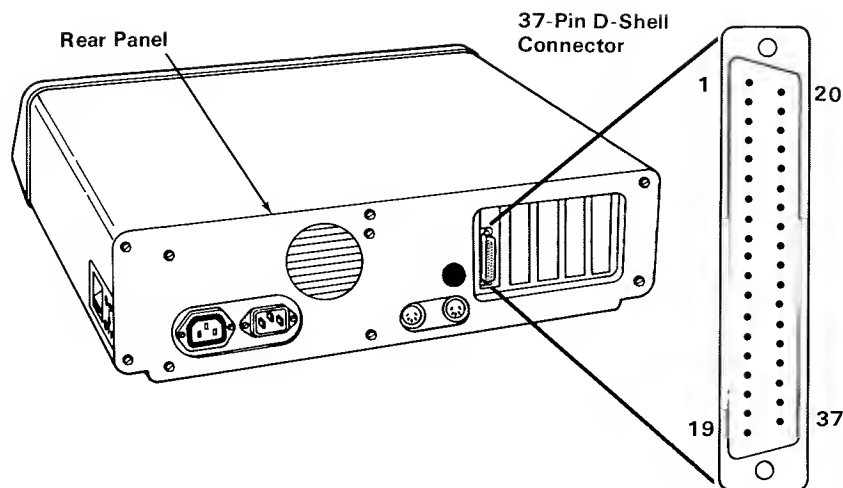
34-Pin Keyed Edge Connector



Note: Lands 1-33 (odd numbers) are on the back of the board. Lands 2-34 (even numbers) are on the front, or component side.

At Standard TTL Levels		Land Number
Ground-Odd Numbers		1-33
Unused		2,4,6
Index		8
Diskette Drives	Motor Enable A	10
	Drive Select B	12
	Drive Select A	14
	Motor Enable B	16
	Direction (Stepper Motor)	18
	Step Pulse	20
	Write Data	22
	Write Enable	24
	Track 0	26
	Write Protect	28
	Read Data	30
	Select Head 1	32
	Unused	34
		Drive Adapter

Connector Specifications (Part 1 of 2)



At Standard TTL Levels		Pin Number
External Drives	Unused	1-5
	Index	6
	Motor Enable C	7
	Drive Select D	8
	Drive Select C	9
	Motor Enable D	10
	Direction (Stepper Motor)	11
	Step Pulse	12
	Write Data	13
	Write Enable	14
	Track 0	15
	Write Protect	16
	Read Data	17
	Select Head 1	18
	Ground	20-37
		Drive Adapter

Connector Specifications (Part 2 of 2)

IBM 5-1/4" Diskette Drive

The system unit has space and power for one or two 5-1/4 inch diskette drives. A drive can be single-sided or double-sided with 40 tracks for each side, is fully self-contained, and consists of a spindle drive system, a read positioning system, and a read/write/erase system.

The diskette drive uses modified frequency modulation (MFM) to read and write digital data, with a track-to-track access time of 6 milliseconds.

To load a diskette, the operator raises the latch at the front of the diskette drive and inserts the diskette into the slot. Plastic guides in the slot ensure the diskette is in the correct position. Closing the latch centers the diskette and clamps it to the drive hub. After 250 milliseconds, the servo-controlled dc drive motor starts and drives the hub at a constant speed of 300 rpm. The head positioning system, which consists of a 4-phase stepper-motor and band assembly with its associated electronics, moves the magnetic head so it comes in contact with the desired track of the diskette. The stepper-motor and band assembly uses one-step rotation to cause a one-track linear movement of the magnetic head. No operator intervention is required during normal operation. During a write operation, a 0.013-inch (0.33 millimeter) data track is recorded, then tunnel-erased to 0.012 inch (0.030 millimeter). If the diskette is write-protected, a write-protect sensor disables the drive's circuitry, and an appropriate signal is sent to the interface.

Data is read from the diskette by the data-recovery circuitry, which consists of a low-level read amplifier, differentiator, zero-crossing detector, and digitizing circuits. All data decoding is done by an adapter card.

The diskette drive also has the following sensor systems:

1. The track 00 switch, which senses when the head/carriage assembly is at track 00.

2. The index sensor, which consists of an LED light source and phototransistor. This sensor is positioned so that when an index hole is detected, a digital signal is generated.
3. The write-protect sensor disables the diskette drive's electronics whenever a write-protect tab is applied to the diskette.

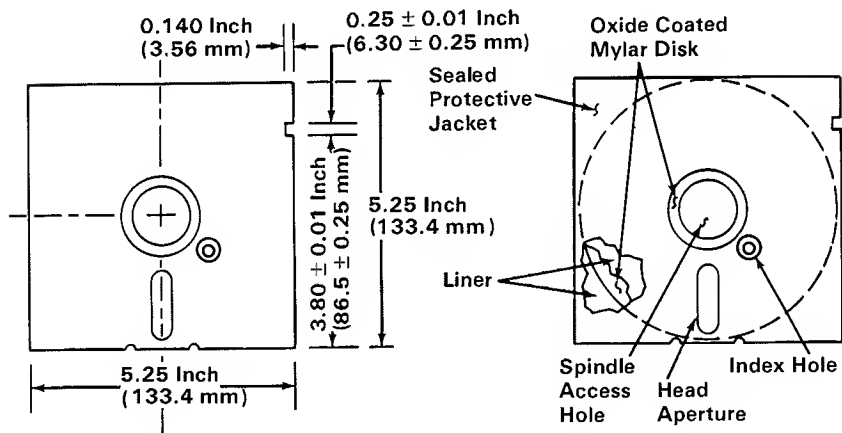
For interface information, refer to "IBM 5-1/4" Diskette Drive Adapter" earlier in this section.

Media	Industry-compatible 5-1/4 inch diskette
Tracks per inch	48
Number of tracks	40
Dimensions	
Height	3.38 inches (85.85 mm)
Width	5.87 inches (149.10 mm)
Depth	8.00 inches (203.2 mm)
Weight	4.50 pounds (2.04 kg)
Temperature	
(Exclusive of media)	
Operating	50°F to 112°F (10°C to 44°C)
Non operating	-40°F to 140°F (-40°C to 60°C)
Relative humidity	
(Exclusive of media)	
Operating	20% to 80% (non condensing)
Non operating	5% to 95% (non condensing)
Seek Time	6 ms track-to-track
Head Settling Time	15 ms (last track addressed)
Error Rate	1 per 10 ⁹ (recoverable) 1 per 10 ¹² (non recoverable) 1 per 10 ⁶ (seeks)
Head Life	20,000 hours (normal use)
Media Life	3.0 x 10 ⁶ passes per track
Disk Speed	300 rpm +/- 1.5% (long term)
Instantaneous Speed Variation	+/- 3.0%
Start/Stop Time	250 ms (maximum)
Transfer Rate	250K bits/sec
Recording Mode	MFM
Power	+12 Vdc +/- 0.6 V, 900 mA average +5 Vdc +/- 0.25 V, 600 mA average

Mechanical and Electrical Specifications

Diskettes

The IBM 5-1/4" Diskette Drive uses a standard 5.25-inch (133.4-millimeter) diskette. For programming considerations, single-sided, double-density, soft-sectored diskettes are used for single-sided drives. Double-sided drives use double-sided, double-density, soft-sectored diskettes. The figure below is a simplified drawing of the diskette used with the diskette drive. This recording medium is a flexible magnetic disk enclosed in a protective jacket. The protected disk, free to rotate within the jacket, is continuously cleaned by the soft fabric lining of the jacket during normal operation. Read/write/erase head access is made through an opening in the jacket. Openings for the drive hub and diskette index hole are also provided.



Recording Medium

Notes:

IBM Fixed Disk Drive Adapter

The fixed disk drive adapter attaches to one or two fixed disk drive units, through an internal daisy-chained flat cable (data/control cable). Each system supports a maximum of one fixed disk drive adapter and two fixed disk drives.

The adapter is buffered on the I/O bus and uses the system board direct memory access (DMA) for record data transfers. An interrupt level also is used to indicate operation completion and status conditions that require processor attention.

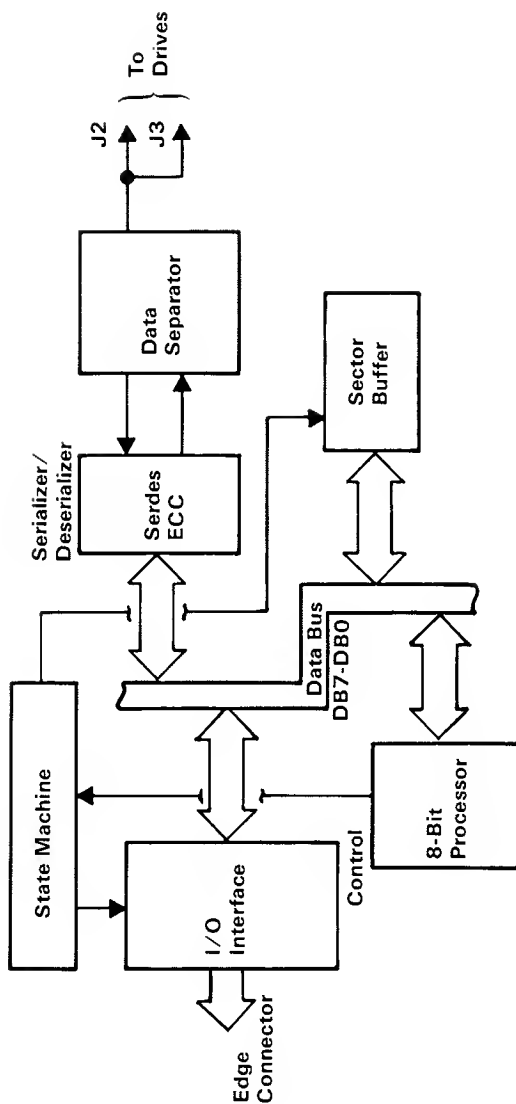
The fixed disk drive adapter provides automatic 11-bit burst error detection and correction in the form of 32-bit error checking and correction (ECC).

The device level control for the fixed disk drive adapter is contained on a ROM module on the adapter. A listing of this device level control can be found in "Appendix A: ROM BIOS Listings."

WARNING: The last cylinder on the fixed disk drive is reserved for diagnostic use. Diagnostic write tests will destroy any data on this cylinder.

Fixed Disk Controller

The disk controller has two registers that may be accessed by the main system processor: a status register and a data register. The 8-bit status register contains the status information of the disk controller, and can be accessed at any time. The 8-bit data register (actually consisting of several registers in a stack with only one register presented to the data bus) stores data, commands, parameters, and provides the disk controller's status information. Data bytes are read from, or written to the data register in order to program or obtain the results after a particular command. The status register is a read-only register, and is used to help the transfer of data between the processor and the disk controller. The controller-select pulse is generated by writing to port address hex 322.



Fixed Disk Drive Adapter Block Diagram

Programming Considerations

Status Register

At the end of all commands from the system board, the disk controller returns a completion status byte back to the system board. This byte informs the system unit if an error occurred during the execution of the command. The following shows the format of this byte.

Bit	7	6	5	4	3	2	1	0
	0	0	d	0	0	0	e	0

Bits 0, 1, 2, 3, 4, 6, 7 These bits are set to zero.

Bit 1 When set, this bit shows an error has occurred during command execution.

Bit 5 This bit shows the logical unit number of the drive.

If the interrupts are enabled, the controller sends an interrupt when it is ready to transfer the status byte. Busy from the disk controller is unasserted when the byte is transferred to complete the command.

Sense Bytes

If the status register receives an error (bit 1 is set), then the disk controller requests four bytes of sense data. The format for the four bytes is as follows:

Bits	7	6	5	4	3	2	1	0
Byte 0	Address Valid		0	Error Type		Error Code		
Byte 1	0	0	d	Head Number				
Byte 2	Cylinder High			Sector Number				
Byte 3	Cylinder Low							

Remarks

d = drive

Byte 0	Bits 0, 1, 2, 3	Error code.
Byte 0	Bits 4, 5	Error type.
Byte 0	Bit 6	Set to 0 (spare).
Byte 0	Bit 7	The address valid bit. Set only when the previous command required a disk address, in which case it is returned as a 1; otherwise, it is a 0.

The following disk controller tables list the error types and error codes found in byte 0:

	Error Type	Error Code	
Bits	5 4	3 2 1 0	Description
	0 0	0 0 0 0	The controller did not detect any error during the execution of the previous operation.
	0 0	0 0 0 1	The controller did not detect an index signal from the drive.
	0 0	0 0 1 0	The controller did not get a seek-complete signal from the drive after a seek operation (for all non-buffered step seeks).
	0 0	0 0 1 1	The controller detected a write fault from the drive during the last operation.
	0 0	0 1 0 0	After the controller selected the drive, the drive did not respond with a ready signal.
	0 0	0 1 0 1	Not used.
	0 0	0 1 1 0	After stepping the maximum number of cylinders, the controller did not receive the track 00 signal from the drive.
	0 0	0 1 1 1	Not used.
	0 0	1 0 0 0	The drive is still seeking. This status is reported by the Test Drive Ready command for an overlap seek condition when the drive has not completed the seek. No time-out is measured by the controller for the seek to complete.

	Error Type	Error Code	Description
Bits	5 4	3 2 1 0	
	0 1	0 0 0 0	ID Read Error: The controller detected an ECC error in the target ID field on the disk.
	0 1	0 0 0 1	Data Error: The controller detected an uncorrectable ECC error in the target sector during a read operation.
	0 1	0 0 1 0	Address Mark: The controller did not detect the target address mark (AM) on the disk.
	0 1	0 0 1 1	Not used.
	0 1	0 1 0 0	Sector Not Found: The controller found the correct cylinder and head, but not the target sector.
	0 1	0 1 0 1	Seek Error: The cylinder or head address (either or both) did not compare with the expected target address as a result of a seek.
	0 1	0 1 1 0	Not used.
	0 1	0 1 1 1	Not used.
	0 1	1 0 0 0	Correctable Data Error: The controller detected a correctable ECC error in the target field.
	0 1	1 0 0 1	Bad Track: The controller detected a bad track flag during the last operation. No retries are attempted on this error.

	Error Type	Error Code	Description
Bits	5 4	3 2 1 0	
	1 0	0 0 0 0	Invalid Command: The controller has received an invalid command from the system unit.
	1 0	0 0 0 1	Illegal Disk Address: The controller detected an address that is beyond the maximum range.

	Error Type	Error Code	Description
Bits	5 4	3 2 1 0	
	1 1	0 0 0 0	RAM Error: The controller detected a data error during the RAM sector-buffer diagnostic test.
	1 1	0 0 0 1	Program Memory Checksum Error: During this internal diagnostic test, the controller detected a program-memory checksum error.
	1 1	0 0 1 0	ECC Polynomial Error: During the controller's internal diagnostic tests, the hardware ECC generator failed its test.

Data Register

The processor specifies the operation by sending the 6-byte device control block (DCB) to the controller. The figure below shows the composition of the DCB, and defines the bytes that make up the DCB.

Bit	7	6	5	4	3	2	1	0
Byte 0	Command Class			Opcode				
Byte 1	0	0	d	Head Number				
Byte 2	Cylinder High		Sector Number					
Byte 3	Cylinder Low							
Byte 4	Interleave or Block Count							
Byte 5	Control Field							

Byte 0 – Bits 7, 6, and 5 identify the class of the command.
Bits 4 through 0 contain the Opcode command.

Byte 1 – Bit 5 identifies the drive number.
Bits 4 through 0 contain the disk head number to be selected.
Bits 6 and 7 are not used.

Byte 2 – Bits 6 and 7 contain the two most significant bits of the cylinder number.
Bits 0 through 5 contain the sector number.

Byte 3 – Bits 0 through 7 are the eight least significant bits of the cylinder number.

Byte 4 – Bits 0 through 7 specify the interleave or block count.

Byte 5 – Bits 0 through 7 contain the control field.

Control Byte

Byte 5 is the control field of the DCB and allows the user to select options for several types of disk drives. The format of this byte is as follows:

Bits	7	6	5	4	3	2	1	0
	r	a	0	0	0	s	s	s

Remarks
r = retries
s = step option
a = retry option on data ECC error

- Bit 7 Disables the four retries by the controller on all disk-access commands. Set this bit only during the evaluation of the performance of a disk drive.
- Bit 6 If set to 0 during read commands, a reread is attempted when an ECC error occurs. If no error occurs during reread, the command will complete with no error status. If this bit is set to 1, no reread is attempted.
- Bits 5, 4, 3 Set to 0.
- Bits 2, 1, 0 These bits define the type of drive and select the step option. See the following figure.

Bits	2, 1, 0		
0	0	0	This drive is not specified and defaults to 3 milliseconds per step.
0	0	1	N/A
0	1	0	N/A
0	1	1	N/A
1	0	0	200 microseconds per step.
1	0	1	70 microseconds per step (specified by BIOS).
1	1	0	3 milliseconds per step.
1	1	1	3 milliseconds per step.

Command Summary

Command	Data Control Block	Remarks																																																															
Test Drive Ready (Class 0, Opcode 00)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	0	0	0	Byte 1	0	0	d	x	x	x	x	x	d = drive (0 or 1) x = don't care Bytes 2, 3, 4, 5 = don't care																																				
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	0	0	0																																																									
Byte 1	0	0	d	x	x	x	x	x																																																									
Recalibrate (Class 0, Opcode 01)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	0	0	1	Byte 1	0	0	d	x	x	x	x	x	Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) x = don't care r = retries s = Step Option Bytes 2, 3, 4 = don't care ch = cylinder high																											
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	0	0	1																																																									
Byte 1	0	0	d	x	x	x	x	x																																																									
Byte 5	r	0	0	0	0	s	s	s																																																									
Reserved (Class 0, Opcode 02)		This Opcode is not used.																																																															
Request Sense Status (Class 0, Opcode 03)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	0	1	1	Byte 1	0	0	d	x	x	x	x	x	d = drive (0 or 1) x = don't care Bytes 2, 3, 4, 5 = don't care																																				
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	0	1	1																																																									
Byte 1	0	0	d	x	x	x	x	x																																																									
Format Drive (Class 0, Opcode 04)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">0 0 0 0 0 0 0</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td>0</td><td>0</td><td>0</td><td colspan="5">Interleave</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	1	0	0	Byte 1	0	0	d	Head Number					Byte 2	ch	0 0 0 0 0 0 0							Byte 3	Cylinder Low								Byte 4	0	0	0	Interleave					Byte 5	r	0	0	0	0	0	s	s	d = drive (0 or 1) r = retries s = step option ch = cylinder high Interleave: 1 to 16 for 512-byte sectors.
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	1	0	0																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	0 0 0 0 0 0 0																																																															
Byte 3	Cylinder Low																																																																
Byte 4	0	0	0	Interleave																																																													
Byte 5	r	0	0	0	0	0	s	s																																																									
Ready Verify (Class 0, Opcode 05)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">Sector Number</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td colspan="8">Block Count</td></tr><tr><td>Byte 5</td><td>r</td><td>a</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 1	0	0	0	0	0	1	0	1	Byte 1	0	0	d	Head Number					Byte 2	ch	Sector Number							Byte 3	Cylinder Low								Byte 4	Block Count								Byte 5	r	a	0	0	0	0	s	s	d = drive (0 or 1) r = retries s = step option a = retry option on data ECC ch = cylinder high
Bit	7	6	5	4	3	2	1	0																																																									
Byte 1	0	0	0	0	0	1	0	1																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	Sector Number																																																															
Byte 3	Cylinder Low																																																																
Byte 4	Block Count																																																																
Byte 5	r	a	0	0	0	0	s	s																																																									

Command	Data Control Block	Remarks																																																															
Format Track (Class 0, Opcode 06)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">0 0 0 0 0 0 0</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td>0</td><td>0</td><td>0</td><td colspan="5">Interleave</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	1	1	0	Byte 1	0	0	d	Head Number					Byte 2	ch	0 0 0 0 0 0 0							Byte 3	Cylinder Low								Byte 4	0	0	0	Interleave					Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) r = retries s = step option ch =cylinder high Interleave: 1 to 16 for 512-byte sectors
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	1	1	0																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	0 0 0 0 0 0 0																																																															
Byte 3	Cylinder Low																																																																
Byte 4	0	0	0	Interleave																																																													
Byte 5	r	0	0	0	0	s	s	s																																																									
Format Bad Track (Class 0, Opcode 07)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">0 0 0 0 0 0 0</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td>0</td><td>0</td><td>0</td><td colspan="5">Interleave</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	0	1	1	1	Byte 1	0	0	d	Head Number					Byte 2	ch	0 0 0 0 0 0 0							Byte 3	Cylinder Low								Byte 4	0	0	0	Interleave					Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) r = retries s = step option ch = cylinder high Interleave: 1 to 16 for 512-byte sectors
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	0	1	1	1																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	0 0 0 0 0 0 0																																																															
Byte 3	Cylinder Low																																																																
Byte 4	0	0	0	Interleave																																																													
Byte 5	r	0	0	0	0	s	s	s																																																									
Read (Class 0, Opcode 08)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">Sector Number</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 5</td><td>r</td><td>a</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	0	0	0	Byte 1	0	0	d	Head Number					Byte 2	ch	Sector Number							Byte 3	Cylinder Low								Byte 5	r	a	0	0	0	s	s	s	d = drive (0 or 1) r = retries a = retry option on data ECC error s = step option ch =cylinder high									
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	1	0	0	0																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	Sector Number																																																															
Byte 3	Cylinder Low																																																																
Byte 5	r	a	0	0	0	s	s	s																																																									
Reserved (Class 0, Opcode 09)		This Opcode is not used																																																															
Write (Class 0, Opcode 0A)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">Sector Number</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td colspan="8">Block Count</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	0	1	0	Byte 1	0	0	d	Head Number					Byte 2	ch	Sector Number							Byte 3	Cylinder Low								Byte 4	Block Count								Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) r = retries s = step option ch = cylinder high
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	1	0	1	0																																																									
Byte 1	0	0	d	Head Number																																																													
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Byte 3	Cylinder Low																																																																
Byte 4	Block Count																																																																
Byte 5	r	0	0	0	0	s	s	s																																																									
Seek (Class 0, Opcode 0B)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">0 0 0 0 0 0 0</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	0	1	1	Byte 1	0	0	d	Head Number					Byte 2	ch	0 0 0 0 0 0 0							Byte 3	Cylinder Low								Byte 4	x	x	x	x	x	x	x	x	Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) r = retries s = step option x = don't care ch = cylinder high
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	0	0	0	0	1	0	1	1																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	0 0 0 0 0 0 0																																																															
Byte 3	Cylinder Low																																																																
Byte 4	x	x	x	x	x	x	x	x																																																									
Byte 5	r	0	0	0	0	s	s	s																																																									

Command	Data Control Block	Remarks																		
Initialize Drive Characteristics* (Class 0, Opcode 0C)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>0</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	1	0	0	Bytes 1, 2, 3, 4, 5 = don't care
Bit	7	6	5	4	3	2	1	0												
Byte 0	0	0	0	0	1	1	0	0												
Read ECC Burst Error Length (Class 0, Opcode 0D)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td><td>1</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	1	0	1	Bytes 1, 2, 3, 4, 5 = don't care
Bit	7	6	5	4	3	2	1	0												
Byte 0	0	0	0	0	1	1	0	1												
Read Data from Sector Buffer (Class 0, Opcode 0E)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>0</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	1	1	0	Bytes 1, 2, 3, 4, 5 = don't care
Bit	7	6	5	4	3	2	1	0												
Byte 0	0	0	0	0	1	1	1	0												
Write Data to Sector Buffer (Class 0, Opcode 0F)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>0</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td><td>1</td><td>1</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	0	0	0	0	1	1	1	1	Bytes 1, 2, 3, 4, 5 = don't care
Bit	7	6	5	4	3	2	1	0												
Byte 0	0	0	0	0	1	1	1	1												
RAM Diagnostic (Class 7, Opcode 00)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>0</td><td>0</td><td>0</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	1	1	1	0	0	0	0	0	Bytes 1, 2, 3, 4, 5 = don't care
Bit	7	6	5	4	3	2	1	0												
Byte 0	1	1	1	0	0	0	0	0												
Reserved (Class 7, Opcode 01)		This Opcode is not used																		
Reserved (Class 7, Opcode 02)		This Opcode is not used																		

*Initialize Drive Characteristics: The DCB must be followed by eight additional bytes.

Maximum number of cylinders	(2 bytes)
Maximum number of heads	(1 byte)
Start reduced write current cylinder	(2 bytes)
Start write precompensation cylinder	(2 bytes)
Maximum ECC data burst length	(1 byte)

Command	Data Control Block	Remarks																																																															
Drive Diagnostic (Class 7, Opcode 03)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>0</td><td>1</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 2</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 3</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 4</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td><td>x</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	1	1	1	0	0	0	1	1	Byte 1	0	0	d	x	x	x	x	x	Byte 2	x	x	x	x	x	x	x	x	Byte 3	x	x	x	x	x	x	x	x	Byte 4	x	x	x	x	x	x	x	x	Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) s = step option r = retries x = don't care
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	1	1	1	0	0	0	1	1																																																									
Byte 1	0	0	d	x	x	x	x	x																																																									
Byte 2	x	x	x	x	x	x	x	x																																																									
Byte 3	x	x	x	x	x	x	x	x																																																									
Byte 4	x	x	x	x	x	x	x	x																																																									
Byte 5	r	0	0	0	0	s	s	s																																																									
Controller Internal Diagnostics (Class 7, Opcode 04)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>0</td><td>0</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	1	1	1	0	0	1	0	0	Bytes 1, 2, 3, 4, 5 = don't care																																													
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	1	1	1	0	0	1	0	0																																																									
Read Long* (Class 7, Opcode 05)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>0</td><td>1</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">Sector Number</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td colspan="8">Block Count</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	1	1	1	0	0	1	0	1	Byte 1	0	0	d	Head Number					Byte 2	ch	Sector Number							Byte 3	Cylinder Low								Byte 4	Block Count								Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) s = step option r = retries ch = cylinder high
Bit	7	6	5	4	3	2	1	0																																																									
Byte 0	1	1	1	0	0	1	0	1																																																									
Byte 1	0	0	d	Head Number																																																													
Byte 2	ch	Sector Number																																																															
Byte 3	Cylinder Low																																																																
Byte 4	Block Count																																																																
Byte 5	r	0	0	0	0	s	s	s																																																									
Write Long** (Class 7, Opcode 06)	<table><tr><td>Bit</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td></tr><tr><td>Byte 0</td><td>1</td><td>1</td><td>1</td><td>0</td><td>0</td><td>1</td><td>1</td><td>0</td></tr><tr><td>Byte 1</td><td>0</td><td>0</td><td>d</td><td colspan="5">Head Number</td></tr><tr><td>Byte 2</td><td>ch</td><td colspan="7">Sector Number</td></tr><tr><td>Byte 3</td><td colspan="8">Cylinder Low</td></tr><tr><td>Byte 4</td><td colspan="8">Block Count</td></tr><tr><td>Byte 5</td><td>r</td><td>0</td><td>0</td><td>0</td><td>0</td><td>s</td><td>s</td><td>s</td></tr></table>	Bit	7	6	5	4	3	2	1	0	Byte 0	1	1	1	0	0	1	1	0	Byte 1	0	0	d	Head Number					Byte 2	ch	Sector Number							Byte 3	Cylinder Low								Byte 4	Block Count								Byte 5	r	0	0	0	0	s	s	s	d = drive (0 or 1) s = step option r = retries ch = cylinder high
Bit	7	6	5	4	3	2	1	0																																																									
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Byte 4	Block Count																																																																
Byte 5	r	0	0	0	0	s	s	s																																																									

*Returns 512 bytes plus 4 bytes of ECC data per sector.

**Requires 512 bytes plus 4 bytes of ECC data per sector.

Programming Summary

The two least-significant bits of the address bus are sent to the system board's I/O port decoder, which has two sections. One section is enabled by the I/O read signal ($-\text{IOR}$) and the other by the I/O write signal ($-\text{IOW}$). The result is a total of four read/write ports assigned to the disk controller board.

The address enable signal (AEN) is asserted by the system board when DMA is controlling data transfer. When AEN is asserted, the I/O port decoder is disabled.

The following figure is a table of the four read/write ports:

R/W	Port Address	Function
Read Write	320 320	Read data (from controller to system unit). Write data (from system unit to controller).
Read Write	321 321	Read controller hardware status. Controller reset.
Read Write	322 322	Reserved. Generate controller-select pulse.
Read Write	323 323	Not used. Write pattern to DMA and interrupt mask register.

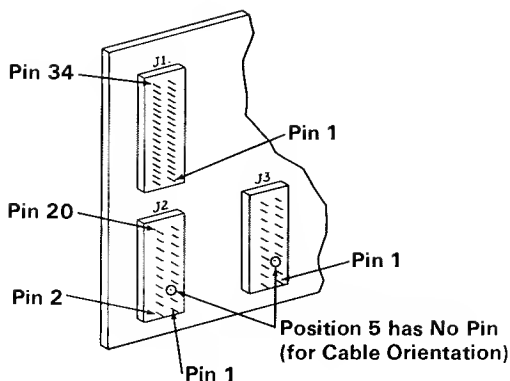
System I/O Channel Interface

The following lines are used by the disk controller:

A0-A19	Positive true 20-bit address. The least-significant 10 bits contain the I/O address within the range of hex 320 to hex 323 when an I/O read or write is executed by the system unit. The full 20 bits are decoded to address the read-only memory (ROM) between the addresses of hex C8000 and C9FFF.
D0-D7	Positive 8-bit data bus over which data and status information is passed between the system board and the controller.
$\overline{\text{IOR}}$	Negative true signal that is asserted when the system board reads status or data from the controller under either programmed I/O or DMA control.
$\overline{\text{IOW}}$	Negative true signal that is asserted when the system board sends a command or data to the controller under either programmed I/O or DMA control.
AEN	Positive true signal that is asserted when the DMA in the system board is generating the I/O Read ($-\text{IOR}$) or I/O Write ($-\text{IOW}$) signals and has control of the address and data buses.
RESET	Positive true signal that forces the disk controller to its initial power-up condition.
IRQ 5	Positive true interrupt request signal that is asserted by the controller, when enabled to interrupt the system board on the return ending status byte from the controller.

DRQ 3 Positive-true DMA-request signal that is asserted by the controller when data is available for transfer to or from the controller under DMA control. This signal remains active until the system board's DMA channel activates the DMA-acknowledge signal ($\overline{\text{DACK 3}}$) in response.

$\overline{\text{DACK 3}}$ This signal is true when negative, and is generated by the system board DMA channel in response to a DMA request (DRQ 3).



Signal	Pin Number
Ground - Odd Numbers	1-33
Reserved	4, 16, 30, 32
-Reduced Write Current	2
-Write Gate	6
-Seek Complete	8
-Track 00	10
-Write Fault	12
-Head Select 2 ⁰	14
-Head Select 2 ¹	18
-Index	20
-Ready	22
-Step	24
-Drive Select 1	26
-Drive Select 2	28
-Direction In	34

Signal	Pin Number
Ground	2, 4, 6, 8, 12, 16, 20
Drive Select	1
Reserved	3, 7
Spare	9, 10, 5 (No Pin)
Ground	11
MFM Write Data	13
-MFM Write Data	14
Ground	15
MFM Read Data	17
-MFM Read Data	18
Ground	19

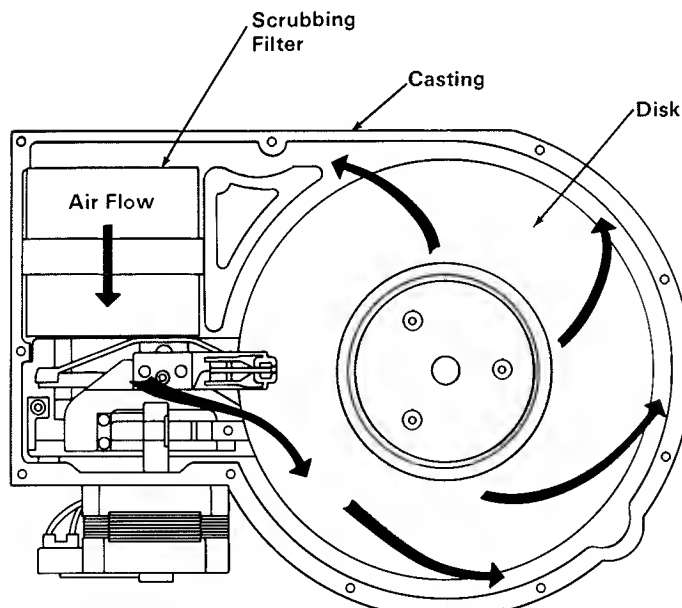
Fixed Disk Adapter Interface Specifications

1-202 Fixed Disk Adapter

IBM 10MB Fixed Disk Drive

The disk drive is a random-access storage device that uses two non-removable 5-1/4 inch disks for storage. Each disk surface employs one movable head to service 306 cylinders. The total formatted capacity of the four heads and surfaces is 10 megabytes (17 sectors per track with 512 bytes per sector and a total of 1224 tracks).

An impact-resistant enclosure provides mechanical and contamination protection for the heads, actuator, and disks. A self-contained recirculating system supplies clean air through a 0.3-micron filter. Thermal isolation of the stepper and spindle motor assemblies from the disk enclosure results in a very low temperature rise within the enclosure. This isolation provides a greater off-track margin and the ability to perform read and write operations immediately after power-up with no thermal stabilization delay.



Media	Rigid media disk
Number of Tracks	1224
Track Density	345 tracks per inch
Dimensions	
Height	3.25 inches (82.55 mm)
Width	5.75 inches (146.05 mm)
Depth	8.0 inches (203.2 mm)
Weight	4.6 lb (2.08 kg)
Temperature	
Operating	40°F to 122°F (4°C to 50°C)
Non operating	-40°F to 140°F (-40°C to 60°C)
Relative Humidity	
Operating	8% to 80% (non condensing)
Maximum Wet Bulb	78°F (26°C)
Shock	
Operating	10 Gs
Non operating	20 Gs
Access Time	3 ms track-to-track
Average Latency	8.33 ms
Error Rates	
Soft Read Errors	1 per 10 ¹⁰ bits read
Hard Read Errors	1 per 10 ¹² bits read
Seek Errors	1 per 10 ⁶ seeks
Design Life	5-years (8,000 hours MTF)
Disk Speed	3600 rpm ±1%
Transfer Rate	5.0 M bits/sec
Recording Mode	MFM
Power	+12 Vdc ± 5% 1.8 A (4.5 A maximum) +5 Vdc ± 5% 0.7 A (1.0 A maximum)
Maximum Ripple	1% with equivalent resistive load

Mechanical and Electrical Specifications

IBM Memory Expansion Options

Three memory expansion options (32KB, 64KB, and 64/256KB) and two memory module kits (16KB and 64KB) are available for the IBM Personal Computer. Memory expansion is described in the following chart:

	Minimum Memory	Maximum Memory	Number of 16K Memory Module Kits	Number of 64K Memory Module Kits	Memory Module Type
16/64K System Board	16K	64K	1, 2, or 3		16K by 1 Bit, 16 pin
64/256K System Board	64K	256K		1, 2, or 3	64K by 1 Bit, 16 pin
64/256K Memory Option	64K	256K		1, 2, or 3	64K by 1 Bit, 16 pin
32K Memory Option	32K				16K by 1 Bit, 16 pin
64K Memory Option	64K				Stacked 32K by 1 Bit, 18 pin

The system board must be fully populated before any memory expansion options can be installed. An expansion option must be configured to reside at a sequential 32K or 64K memory address boundary within the system address space. This is done by setting the DIP switches on the option.

All memory expansion options are parity checked. If a parity error is detected, a latch is set and an I/O channel check line is activated, indicating an error to the processor.

In addition to the memory modules, the memory expansion options contain the following circuits: bus buffering, dynamic memory timing generation, address multiplexing, and card-select decode logic.

Dynamic-memory refresh timing and address generation are functions performed on the system board and made available in the I/O channel for all devices.

To allow the system to address 32K, 64K, or 64/256K memory expansion options, refer to “Appendix G: Switch Settings” for the proper memory expansion option switch settings.

Operating Characteristics

The system board operates at a frequency of 4.77 MHz, which results in a clock cycle of 210 ns.

Normally four clock cycles are required for a bus cycle so that an 840-ns memory cycle time is achieved. Memory-write and memory-read cycles both take four clock cycles, or 840 ns.

General specifications for memory used on all cards are:

	16K by 1 Bit	32K by 1 Bit	64K by 1 Bit
Access	250 ns	250 ns	200 ns
Cycle	410 ns	410 ns	345 ns

Memory Module Description

Both the 32K and the 64K options contain 18 dynamic memory modules. The 32K memory expansion option utilizes 16K by 1 bit modules, and the 64K memory expansion option utilizes 32K by 1 bit modules.

The 64/256K option has four banks of 9 pluggable sockets. Each bank will accept a 64K memory module kit, consisting of 9 (64K by 1) modules. The kits must be installed sequentially into banks 1, 2, and 3. The base 64/256K option comes with modules installed in bank 0, providing 64K of memory. One, two, or three 64K bits may be added, upgrading the option to 128K, 192K, or 256K of memory.

The 16K by 1 and the 32K by 1 modules require three voltage levels: +5 Vdc, -5 Vdc, and +12 Vdc. The 64K by 1 modules require only one voltage level of +5 Vdc. All three memory modules require 128 refresh cycles every 2 ns. Absolute maximum access times are:

	16K by 1 Bit	32K by 1 Bit	64K by 1 Bit
From $\overline{\text{RAS}}$	250 ns	250 ns	200 ns
From $\overline{\text{CAS}}$	165 ns	165 ns	115 ns

Pin	16K by 1 Bit Module (used on 32K option and 16/64K system board)	32K by 1 Bit Module (used on 64K option)	64K by 1 Bit Module (used on 64/256K option and 64/256K system board)
1	-5 Vdc	-5 Vdc	N/C
2	Data In**	Data In**	Data In***
3	-Write	-Write	-Write
4	-RAS	-RAS 0	-RAS
5	A0	-RAS 1	A0
6	A2	A0	A2
7	A1	A2	A1
8	+12 Vdc	A1	+5 Vdc
9	+5 Vdc	+12 Vdc	A7
10	A5	+5 Vdc	A5
11	A4	A5	A4
12	A3	A4	A3
13	A6	A3	A6
14	Data Out**	A6	Data Out***
15	-CAS	Data Out**	-CAS
16	GND	-CAS 1	GND
17	*	-CAS 0	*
18	*	GND	*

*16K by 1 and 64K by 1 bit modules have 16 pins.

**Data In and Data Out are tied together (three-state bus).

***Data In and Data Out are tied together on Data Bits 0-7 (three-state bus).

Memory Module Pin Configuration

Switch-Configurable Start Address

Each card has a small DIP module, that contains eight switches. The switches are used to set the card start address as follows:

Number	32K and 64K Options	64/256K Options
1	ON: A19=0; OFF: A19=1	ON: A19=0; OFF: A19=1
2	ON: A18=0; OFF: A18=1	ON: A18=0; OFF: A18=1
3	ON: A17=0; OFF: A17=1	ON: A17=0; OFF: A17=1
4	ON: A16=0; OFF: A16=1	ON: A16=0; OFF: A16=1
5	ON: A15=0; OFF: A15=1*	ON: Select 64K
6	Not used	ON: Select 128K
7	Not used	ON: Select 192K
8	Used only in 64K RAM Card*	ON: Select 256K

*Switch 8 may be set on the 64K memory expansion option to use only half the memory on the card (that is, 32K). If switch 8 is on, all 64K is accessible. If switch 8 is off, address bit A15 (as set by switch 5) is used to determine which 32K are accessible, and the 64K option behaves as a 32K option.

DIP Module Start Address

Memory Option Switch Settings

Switch settings for all memory expansion options are located in “Appendix G: Switch Settings.”

The following method can be used to determine the switch settings for the 32K memory expansion option.

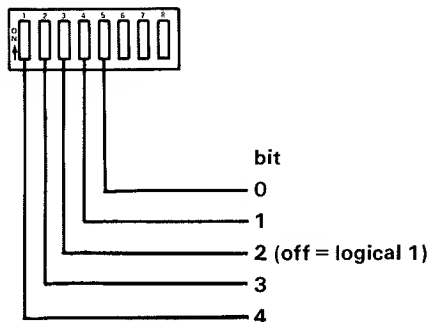
Starting Address = xxxK

32K xxxK =Decimal value

Convert decimal value to binary

Bit.4 3 2 1 0
 Bit value ...16 8 4 2 1

Switch



The following method can be used to determine the switch settings for the 64K memory expansion option.

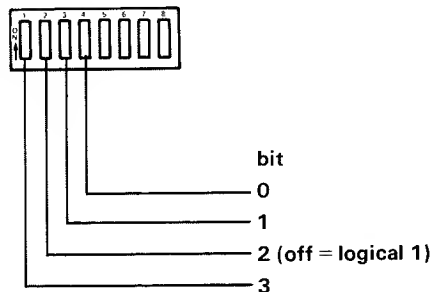
Starting Address = xxxK

64K xxxK =Decimal value

Convert decimal value to binary

Bit.3 2 1 0
 Bit value ...8 4 2 1

Switch



The following method can be used to determine the switch settings for the 64/256K memory expansion option.

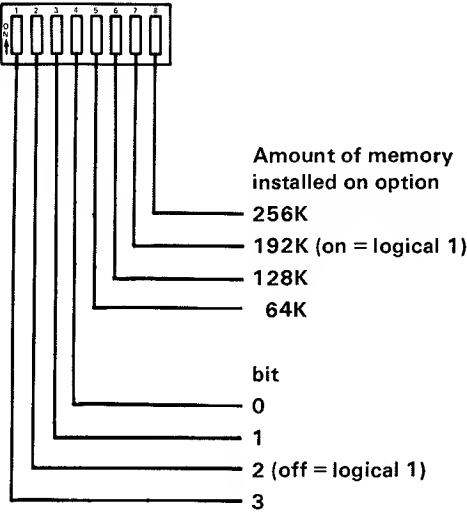
Starting Address = xxxK

64K xxxK =Decimal value

Convert decimal value to binary

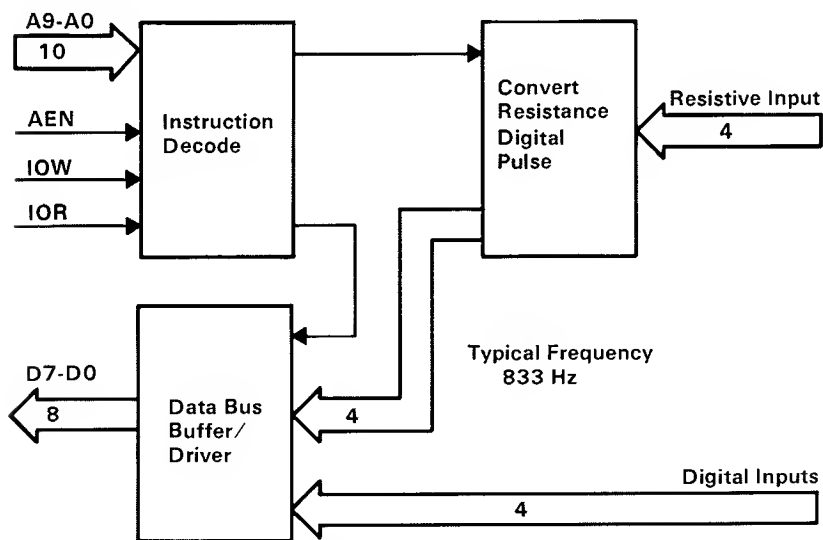
Bit. 3 2 1 0
Bit value. . . 8 4 2 1

Switch



IBM Game Control Adapter

The game control adapter allows up to four paddles or two joy sticks to be attached to the system. This card fits into one of the system board's or expansion board's expansion slots. The game control interface cable attaches to the rear of the adapter. In addition, four inputs for switches are provided. Paddle and joy stick positions are determined by changing resistive values sent to the adapter. The adapter plus system software converts the present resistive value to a relative paddle or joy stick position. On receipt of an output signal, four timing circuits are started. By determining the time required for the circuit to time-out (a function of the resistance), the paddle position can be determined. This adapter could be used as a general purpose I/O card with four analog (resistive) inputs plus four digital input points.



Game Control Adapter Block Diagram

Functional Description

Address Decode

The select on the game control adapter is generated by two 74LS138s as an address decoder. AEN must be inactive while the address is hex 201 in order to generate the select. The select allows a write to fire the one-shots or a read to give the values of the trigger buttons and one-shot outputs.

Data Bus Buffer/Driver

The data bus is buffered by a 74LS244 buffer/driver. For an In from address hex 201, the game control adapter will drive the data bus; at all other times, the buffer is left in the high impedance state.

Trigger Buttons

The trigger button inputs are read by an In from address hex 201. A trigger button is on each joy stick or paddle. These values are seen on data bits 7 through 4. These buttons default to an open state and are read as "1." When a button is pressed, it is read as "0." Software should be aware that these buttons are not debounced in hardware.

Joy Stick Positions

The joy stick position is indicated by a potentiometer for each coordinate. Each potentiometer has a range from 0 to 100 k-ohms that varies the time constant for each of the four one-shots. As this time constant is set at different values, the output of the one-shot will be of varying durations.

All four one-shots are fired at once by an Out to address hex 201. All four one-shot outputs will go true after the fire pulse and will remain high for varying times depending on where each potentiometer is set.

These four one-shot outputs are read by an In from address hex 201 and are seen on data bits 3 through 0.

I/O Channel Description

A9-A0:	Address lines 9 through 0 are used to address the game control adapter.
D7-D0:	Data lines 7 through 0 are the data bus.
IOR, IOW:	I/O read and I/O write are used when reading from or writing to an adapter (In, Out).
AEN:	When active, the adapter must be inactive and the data bus driver inactive.
+5 Vdc:	Power for the game control adapter.
GND:	Common ground.
A19-A10:	Unused.
MEMR, MEMW:	Unused.
DACK0-DACK3:	Unused.
IRQ7-IRQ2:	Unused.
DRQ3-DRQ1:	Unused.
ALE, T/C:	Unused.
CLK, OSC:	Unused.
I/O CH CK:	Unused.
I/O CH RDY:	Unused.
RESET DRV:	Unused.
-5 Vdc, +12 Vdc, -12 Vdc:	Unused.

Interface Description

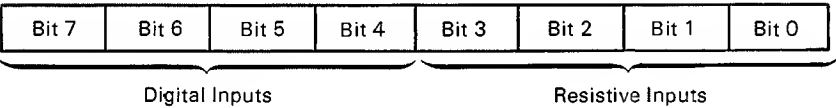
The game control adapter has eight input lines, four of which are digital inputs and 4 of which are resistive inputs. The inputs are read with one In from address hex 201.

The four digital inputs each have a 1 k-ohm pullup resistor +5 Vdc. With no drives on these inputs, a 1 is read. For a 0 reading, the inputs must be pulled to ground.

The four resistive pullups, measured to +5 Vdc, will be converted to a digital pulse with a duration proportional to the resistive load, according to the following equation:

$$\text{Time} = 24.2 \mu\text{sec} + 0.011 (r) \mu\text{sec}$$

The user must first begin the conversation by an Out to address hex 201. An In from address hex 201 will show the digital pulse go high and remain high for the duration according to the resistance value. All four bits (bit 3-bit 0) function in the same manner; their digital pulse will all go high simultaneously and will reset independently according to the input resistance value.



The typical input to the game control adapter is a set of joy sticks or game paddles.

The joy sticks will typically be a set of two (A and B). These will have one or two buttons each with two variable resistances each, with a range from 0 to 100 k-ohms. One variable resistance will indicate the X-coordinate and the other variable resistance will indicate the Y-coordinate. This should be attached to give the following input data:

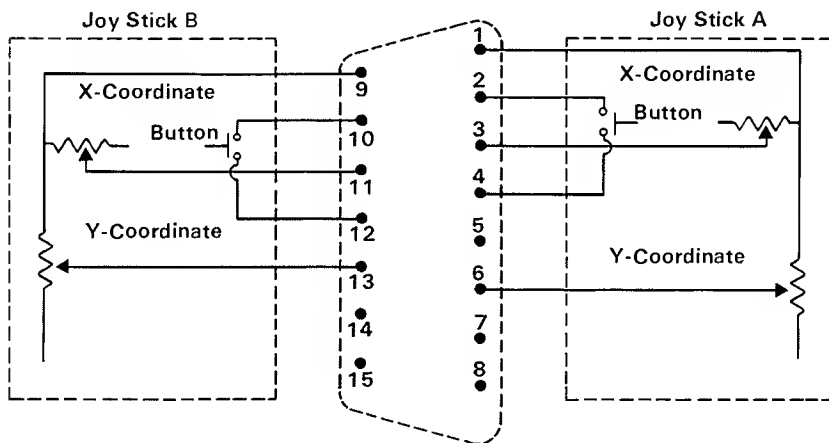
Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
B-#2 Button	B-#1 Button	A-#2 Button	A-#1 Button	B-Y Coordinate	B-X Coordinate	A-Y Coordinate	A-X Coordinate

The game paddles will have a set of two (A and B) or four (A, B, C, and D) paddles. These will have one button each and one variable resistance each, with a range of 0 to 100 k-ohms. This should be attached to give the following input data:

Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
D Button	C Button	B Button	A Button	D Coordinate	C Coordinate	B Coordinate	A Coordinate

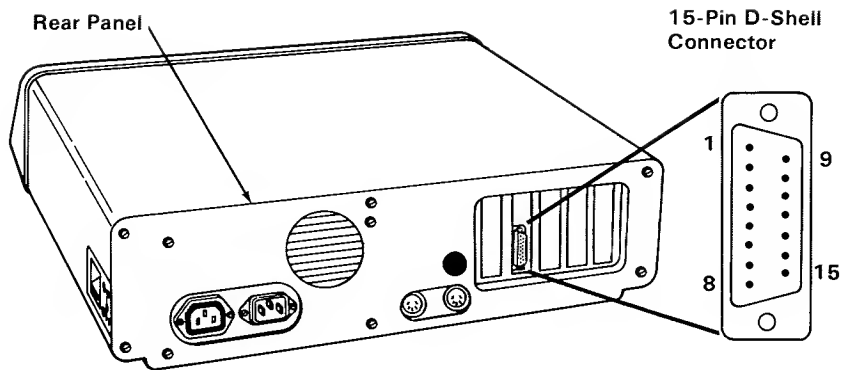
Refer to “Joy Stick Schematic Diagram” for attaching game controllers.

15-Pin Male D-Shell
Connector

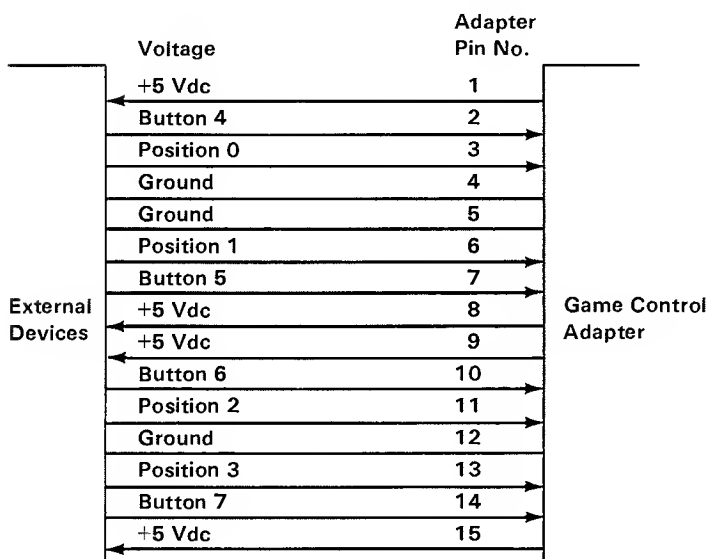


Note: Potentiometer for X- and Y-Coordinates has a range of 0 to 100 k-ohms. Button is normally open; closed when pressed.

Joy Stick Schematic Diagram



At Standard TTL Levels



Connector Specifications

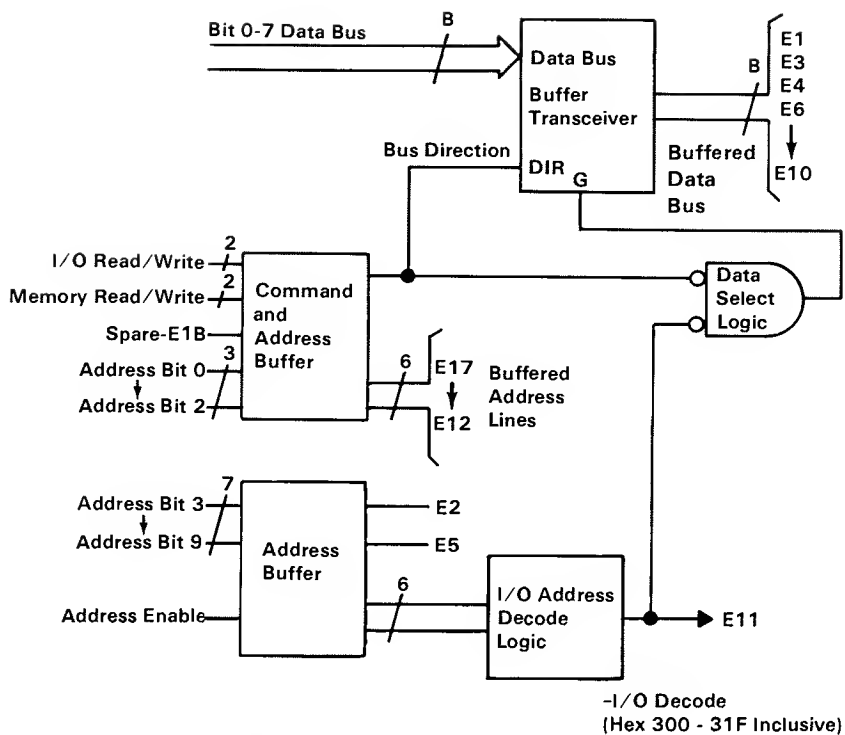
IBM Prototype Card

The prototype card is 4.2 inches (106.7 millimeters) high by 13.2 inches (335.3 millimeters) long and plugs into an expansion unit or system unit expansion slot. All system control signals and voltage requirements are provided through a 2 by 31 position card-edge tab.

The card contains a voltage bus (+5 Vdc) and a ground bus (0 Vdc). Each bus borders the card, with the voltage bus on the back (pin side) and the ground bus on the front (component side). A system interface design is also provided on the prototype card.

The prototype card can also accommodate a D-shell connector if it is needed. The connector size can range from a 9 to a 37 position connector.

Note: Install all components on the component side of the prototype card. The total width of the card including components should not exceed 0.500 inch (12.7 millimeters). If these specifications are not met, components on the prototype card may touch other cards plugged into adjacent slots.



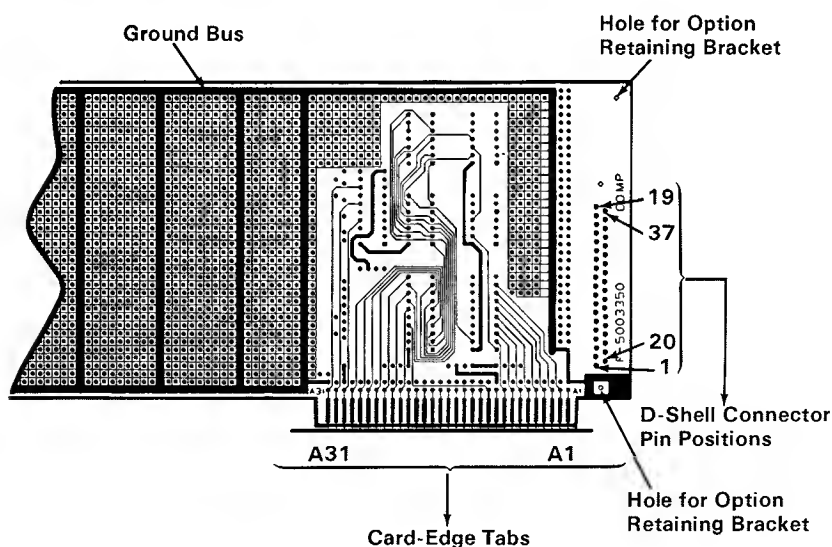
Prototype Card Block Diagram

I/O Channel Interface

The prototype card has two layers screened onto it (one on the front and one on the back). It also has 3,909 plated through-holes that are 0.040 inch (10.1 millimeters) in size and have a 0.060 inch (1.52 millimeters) pad, which is located on a 0.10 inch (2.54 millimeters) grid. There are 37 plated through-holes that are 0.048 inch (1.22 millimeters) in size. These holes are located at the rear of the card (viewed as if installed in the machine). These 37 holes are used for a 9 to 37 position D-shell connector. The card also has 5 holes that are 0.125 inch (3.18 millimeters) in size. One hole is located just above the two rows of D-shell connector holes, and the other four are located in the corners of the board (one in each corner).

Prototype Card Layout

The component side has the ground bus [0.05 inch (1.27 millimeters) wide] screened on it and card-edge tabs that are labeled A1 through A31.



Component Side

Diagram of a gel electrophoresis image showing DNA bands. The lanes are labeled C1, C2, C3, U1, U2, U3, U6, U7, E1, E2, E5, E10, E11, E15, E17, and E18. The bands are numbered 1 through 18. A '+' sign is present below the C1 lane.

The pin side has a +5 Vdc bus [0.05 inch (1.27 millimeters) wide] screened onto it and card-edge tabs that are labeled B1 through B31.



Each card-edged tab is connected to a plated through-hole by a 0.012-inch (0.3-millimeter) land. There are three ground tabs connected to the ground bus by three 0.012-inch (0.3-millimeter) lands. Also, there are two +5 Vdc tabs connected to the voltage bus by two 0.012-inch (0.3-millimeter) lands.

For additional interfacing information, refer to "I/O Channel Description" and "I/O Channel Diagram" in this manual. Also, the "Prototype Card Interface Logic Diagram" is in Appendix D of this manual. If the recommended interface logic is used, the list of TTL type numbers listed below will help you select the necessary components.

Component	TTL Number	Description
U1	74LS245	Octal Bus Transceiver
U2, U5	74LS244	Octal Buffers Line Driver/Line Receivers
U4	74LS04	Hex Inverters
U3	74LS08	Quadruple 2 - Input Positive - AND Gate
U6	74LS02	Quadruple 2 - Input Positive - NOR Gate
U7	74LS21	Dual 4 - Input Positive - AND Gate
C1		10.0 μ F Tantalum Capacitor
C2, C3, C4		0.047 μ F Ceramic Capacitor

System Loading and Power Limitations

Because of the number of options that may be installed in the system, the I/O bus loading should be limited to one Schottky TTL load. If the interface circuitry on the card is used, then this requirement is met.

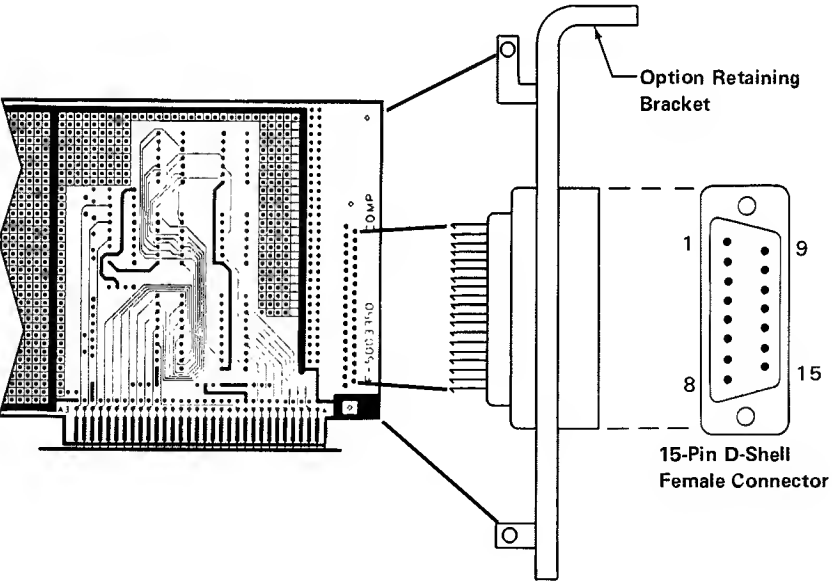
Refer to the power supply information in this manual for the power limitations to be observed.

Prototype Card External Interface

If a connector is required for the card function, then you should purchase one of the recommended connectors (manufactured by Amp) or equivalent listed below:

Connector Size	Part Number (Amp)
9-pin D-shell (Male)	205865-1
9-pin D-shell (Female)	205866-1
15-pin D-shell (Male)	205867-1
15-pin D-shell (Female)	205868-1
25-pin D-shell (Male)	205857-1
25-pin D-shell (Female)	205858-1
37-pin D-shell (Male)	205859-1
37-pin D-shell (Female)	205860-1

The following example shows a 15-pin, D-shell, female connector attached to a prototype card.



Component Side

IBM Asynchronous Communications Adapter

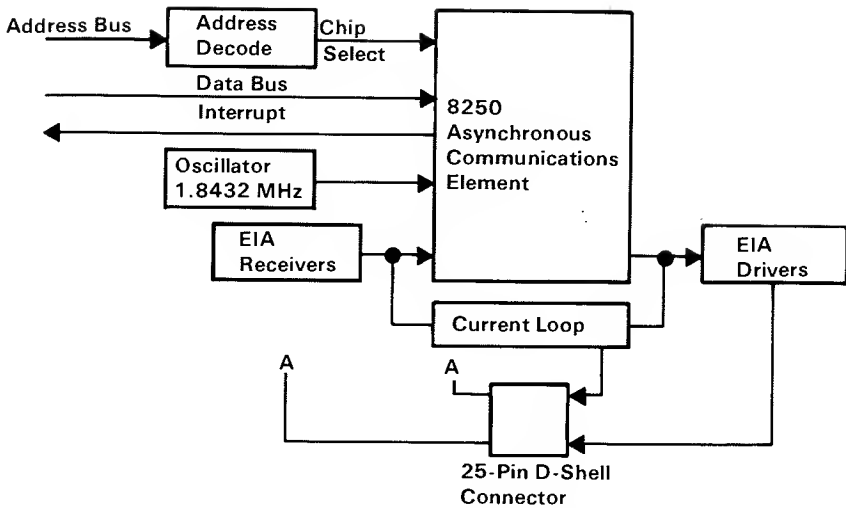
The asynchronous communications adapter system control signals and voltage requirements are provided through a 2 by 31 position card-edge tab. Two jumper modules are provided on the adapter. One jumper module selects either RS-232C or current-loop operation. The other jumper module selects one of two addresses for the adapter, so two adapters may be used in one system.

The adapter is fully programmable and supports asynchronous communications only. It will add and remove start bits, stop bits, and parity bits. A programmable baud rate generator allows operation from 50 baud to 9600 baud. Five, six, seven or eight bit characters with 1, 1-1/2, or 2 stop bits are supported. A fully prioritized interrupt system controls transmit, receive, error, line status and data set interrupts. Diagnostic capabilities provide loopback functions of transmit/receive and input/output signals.

The heart of the adapter is a INS8250 LSI chip or functional equivalent. Features in addition to those listed above are:

- Full double buffering eliminates need for precise synchronization.
- Independent receiver clock input.
- Modem control functions: clear to send (CTS), request to send (RTS), data set ready (DSR), data terminal ready (DTR), ring indicator (RI), and carrier detect.
- False-start bit detection.
- Line-break generation and detection.

All communications protocol is a function of the system microcode and must be loaded before the adapter is operational. All pacing of the interface and control signal status must be handled by the system software. The following figure is a block diagram of the asynchronous communications adapter.



Asynchronous Communications Adapter Block Diagram

Modes of Operation

The different modes of operation are selected by programming the 8250 asynchronous communications element. This is done by selecting the I/O address (hex 3F8 to 3FF primary, and hex 2F8 to 2FF secondary) and writing data out to the card. Address bits A0, A1, and A2 select the different registers that define the modes of operation. Also, the divisor latch access bit (bit 7) of the line control register is used to select certain registers.

I/O Decode (in Hex)		Register Selected	DLAB State
Primary Adapter	Alternate Adapter		
3F8	2F8	TX Buffer	DLAB=0 (Write)
3F8	2F8	RX Buffer	DLAB=0 (Read)
3F8	2F8	Divisor Latch LSB	DLAB=1
3F9	2F9	Divisor Latch MSB	DLAB=1
3F9	2F9	Interrupt Enable Register	
3FA	2FA	Interrupt Identification Registers	
3FB	2FB	Line Control Register	
3FC	2FC	Modem Control Register	
3FD	2FD	Line Status Register	
3FE	2FE	Modem Status Register	

I/O Decodes

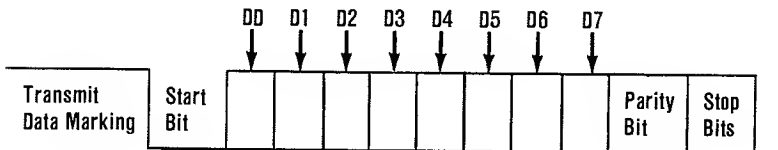
Hex Address 3F8 to 3FF and 2F8 to 2FF											DLAB	Register
A9	A8	A7	A6	A5	A4	A3	A2	A1	A0			
1	1/0	1	1	1	1	1	x	x	x			
							0	0	0		0	Receive Buffer (read), Transmit Holding Reg. (write)
							0	0	1		0	Interrupt Enable
							0	1	0		x	Interrupt Identification
							0	1	1		x	Line Control
							1	0	0		x	Modem Control
							1	0	1		x	Line Status
							1	1	0		x	Modem Status
							1	1	1		x	None
							0	0	0		1	Divisor Latch (LSB)
							0	0	1		1	Divisor Latch (MSB)
<p>Note: Bit 8 will be logical 1 for the adapter designated as primary or a logical 0 for the adapter designated as alternate (as defined by the address jumper module on the adapter).</p> <p>A2, A1 and A0 bits are "don't cares" and are used to select the different register of the communications chip.</p>												

Address Bits

Interrupts

One interrupt line is provided to the system. This interrupt is IRQ4 for a primary adapter or IRQ3 for an alternate adapter, and is positive active. To allow the communications card to send interrupts to the system, bit 3 of the modem control register must be set to 1 (high). At this point, any interrupts allowed by the interrupt enable register will cause an interrupt.

The data format will be as follows:



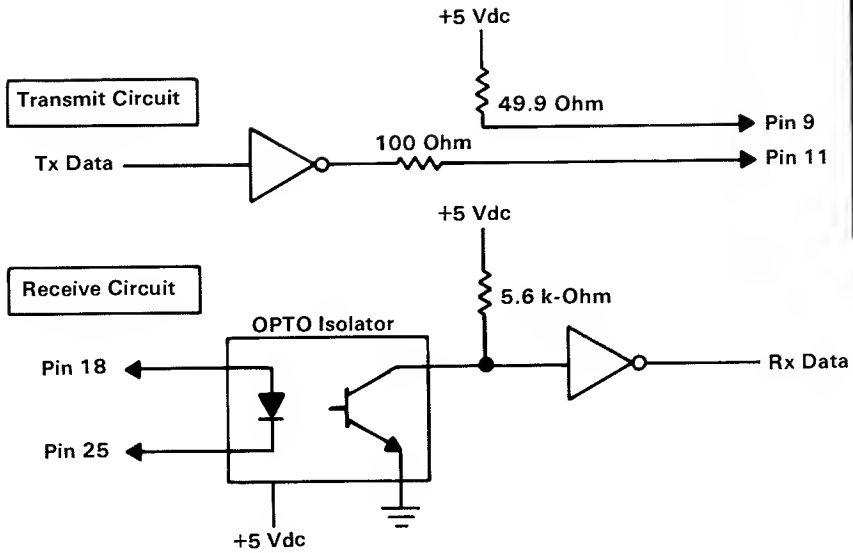
Data bit 0 is the first bit to be transmitted or received. The adapter automatically inserts the start bit, the correct parity bit if programmed to do so, and the stop bit (1, 1-1/2, or 2 depending on the command in the line-control register).

Interface Description

The communications adapter provides an EIA RS-232C-like interface. One 25-pin D-shell, male type connector is provided to attach various peripheral devices. In addition, a current loop interface is also located in this same connector. A jumper block is provided to manually select either the voltage interface, or the current loop interface.

The current loop interface is provided to attach certain printers provided by IBM that use this particular type of interface.

- Pin 18 + receive current loop data
- Pin 25 - receive current loop return
- Pin 9 + transmit current loop return
- Pin 11 - transmit current loop data



Current Loop Interface

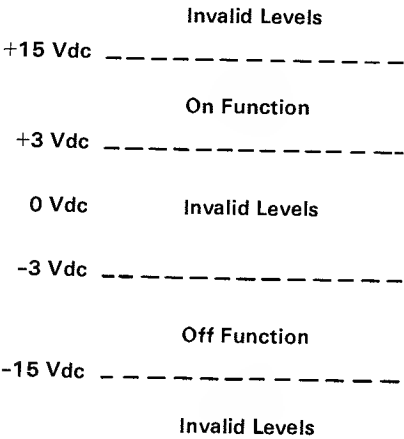
The voltage interface is a serial interface. It supports certain data and control signals, as listed below.

Pin 2	Transmitted Data
Pin 3	Received Data
Pin 4	Request to Send
Pin 5	Clear to Send
Pin 6	Data Set Ready
Pin 7	Signal Ground
Pin 8	Carrier Detect
Pin 20	Data Terminal Ready
Pin 22	Ring Indicator

The adapter converts these signals to/from TTL levels to EIA voltage levels. These signals are sampled or generated by the communications control chip. These signals can then be sensed by the system software to determine the state of the interface or peripheral device.

Voltage Interchange Information

Interchange Voltage	Binary State	Signal Condition	Interface Control Function
Positive Voltage =	Binary (0)	= Spacing	=On
Negative Voltage =	Binary (1)	= Marking	=Off



The signal will be considered in the “marking” condition when the voltage on the interchange circuit, measured at the interface point, is more negative than -3 Vdc with respect to signal ground. The signal will be considered in the “spacing” condition when the voltage is more positive than $+3\text{ Vdc}$ with respect to signal ground. The region between $+3\text{ Vdc}$ and -3 Vdc is defined as the transition region, and considered an invalid level. The voltage that is more negative than -15 Vdc or more positive than $+15\text{ Vdc}$ will also be considered an invalid level.

During the transmission of data, the “marking” condition will be used to denote the binary state “1” and “spacing” condition will be used to denote the binary state “0.”

For interface control circuits, the function is “on” when the voltage is more positive than $+3\text{ Vdc}$ with respect to signal ground and is “off” when the voltage is more negative than -3 Vdc with respect to signal ground.

INS8250 Functional Pin Description

The following describes the function of all INS8250 input/output pins. Some of these descriptions reference internal circuits.

Note: In the following descriptions, a low represents a logical 0 (0 Vdc nominal) and a high represents a logical 1 (+2.4 Vdc nominal).

Input Signals

Chip Select (CS_0 , CS_1 , $\overline{CS_2}$), Pins 12-14: When CS_0 and CS_1 are high and $\overline{CS_2}$ is low, the chip is selected. Chip selection is complete when the decoded chip select signal is latched with an active (low) address strobe (\overline{ADS}) input. This enables communications between the INS8250 and the processor.

Data Input Strobe ($DISTR$, \overline{DISTR}) Pins 22 and 21: When $DISTR$ is high or \overline{DISTR} is low while the chip is selected, allows the processor to read status information or data from a selected register of the INS8250.

Note: Only an active $DISTR$ or \overline{DISTR} input is required to transfer data from the INS8250 during a read operation. Therefore, tie either the $DISTR$ input permanently low or the \overline{DISTR} input permanently high, if not used.

Data Output Strobe ($DOSTR$, \overline{DOSTR}), Pins 19 and 18: When $DOSTR$ is high or \overline{DOSTR} is low while the chip is selected, allows the processor to write data or control words into a selected register of the INS8250.

Note: Only an active $DOSTR$ or \overline{DOSTR} input is required to transfer data to the INS8250 during a write operation. Therefore, tie either the $DOSTR$ input permanently low or the \overline{DOSTR} input permanently high, if not used.

Address Strobe ($\overline{\text{ADS}}$), Pin 25: When low, provides latching for the register select (A0, A1, A2) and chip select (CS0, CS1, CS2) signals.

Note: An active $\overline{\text{ADS}}$ input is required when the register select (A0, A1, A2) signals are not stable for the duration of a read or write operation. If not required, tie the $\overline{\text{ADS}}$ input permanently low.

Register Select (A0, A1, A2), Pins 26-28: These three inputs are used during a read or write operation to select an INS8250 register to read from or write to as indicated in the table below. Note that the state of the divisor latch access bit (DLAB), which is the most significant bit of the line control register, affects the selection of certain INS8250 registers. The DLAB must be set high by the system software to access the baud generator divisor latches.

DLAB	A2	A1	A0	Register
0	0	0	0	Receiver Buffer (Read), Transmitter Holding Register (Write)
0	0	0	1	Interrupt Enable
X	0	1	0	Interrupt Identification (Read Only)
X	0	1	1	Line Control
X	1	0	0	Modem Control
X	1	0	1	Line Status
X	1	1	0	Modem Control Status
X	1	1	1	None
1	0	0	0	Divisor Latch (Least Significant Bit)
1	0	0	1	Divisor Latch (Most Significant Bit)

Master Reset (MR), Pin 35: When high, clears all the registers (except the receiver buffer, transmitter holding, and divisor latches), and the control logic of the INS8250. Also, the state of various output signals (SOUT, INTRPT, $\overline{\text{OUT 1}}$, $\overline{\text{OUT 2}}$, $\overline{\text{RTS}}$, $\overline{\text{DTR}}$) are affected by an active MR input. Refer to the "Asynchronous Communications Reset Functions" table.

Receiver Clock (RCLK), Pin 9: This input is the 16 x baud rate clock for the receiver section of the chip.

Serial Input (SIN), Pin 10: Serial data input from the communications link (peripheral device, modem, or data set).

Clear to Send ($\overline{\text{CTS}}$), Pin 36: The $\overline{\text{CTS}}$ signal is a modem control function input whose condition can be tested by the processor by reading bit 4 (CTS) of the modem status register. Bit 0 (DCTS) of the modem status register indicates whether the $\overline{\text{CTS}}$ input has changed state since the previous reading of the modem status register.

Note: Whenever the CTS bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Data Set Ready ($\overline{\text{DSR}}$), Pin 37: When low, indicates that the modem or data set is ready to establish the communications link and transfer data with the INS8250. The $\overline{\text{DSR}}$ signal is a modem-control function input whose condition can be tested by the processor by reading bit 5 (DSR) of the modem status register. Bit 1 (DDSR) of the modem status register indicates whether the $\overline{\text{DSR}}$ input has changed since the previous reading of the modem status register.

Note: Whenever the DSR bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Received Line Signal Detect ($\overline{\text{RLSD}}$), Pin 38: When low, indicates that the data carrier had been detected by the modem or data set. The $\overline{\text{RLSD}}$ signal is a modem-control function input whose condition can be tested by the processor by reading bit 7 (RLSD) of the modem status register. Bit 3 (DRLSD) of the modem status register indicates whether the $\overline{\text{RLSD}}$ input has changed state since the previous reading of the modem status register.

Note: Whenever the RLSD bit of the modem status register changes state, an interrupt is generated if the modem status interrupt is enabled.

Ring Indicator ($\overline{\text{RI}}$), Pin 39: When low, indicates that a telephone ringing signal has been received by the modem or data set. The $\overline{\text{RI}}$ signal is a modem-control function input whose condition can be tested by the processor by reading bit 6 (RI) of the modem status register. Bit 2 (TERI) of the modem status register indicates whether the $\overline{\text{RI}}$ input has changed from a low to high state since the previous reading of the modem status register.

Note: Whenever the RI bit of the modem status register changes from a high to a low state, an interrupt is generated if the modem status register interrupt is enabled.

VCC, Pin 40: +5 Vdc supply.

VSS, Pin 20: Ground (0 Vdc) reference.

Output Signals

Data Terminal Ready ($\overline{\text{DTR}}$), Pin 33: When low, informs the modem or data set that the INS8250 is ready to communicate. The DTR output signal can be set to an active low by programming bit 0 (DTR) of the modem control register to a high level. The $\overline{\text{DTR}}$ signal is set high upon a master reset operation.

Request to Send ($\overline{\text{RTS}}$), Pin 32: When low, informs the modem or data set that the INS8250 is ready to transmit data. The $\overline{\text{RTS}}$ output signal can be set to an active low by programming bit 1 (RTS) of the modem control register. The $\overline{\text{RTS}}$ signal is set high upon a master reset operation.

Output 1 ($\overline{\text{OUT 1}}$), Pin 34: User-designated output that can be set to an active low by programming bit 2 (OUT 1) of the modem control register to a high level. The $\overline{\text{OUT 1}}$ signal is set high upon a master reset operation.

Output 2 ($\overline{\text{OUT 2}}$), Pin 31: User-designated output that can be set to an active low by programming bit 3 (OUT 2) of the modem control register to a high level. The $\overline{\text{OUT 2}}$ signal is set high upon a master reset operation.

Chip Select Out (CSOUT), Pin 24: When high, indicates that the chip has been selected by active CS0, CS1, and $\overline{\text{CS2}}$ inputs. No data transfer can be initiated until the CSOUT signal is a logical 1.

Driver Disable (DDIS), Pin 23: Goes low whenever the processor is reading data from the INS8250. A high-level DDIS output can be used to disable an external transceiver (if used between the processor and INS8250 on the D7-D0 data bus) at all times, except when the processor is reading data.

Baud Out ($\overline{\text{BAUDOUT}}$), Pin 15: 16 x clock signal for the transmitter section of the INS8250. The clock rate is equal to the main reference oscillator frequency divided by the specified divisor in the baud generator divisor latches. The $\overline{\text{BAUDOUT}}$ may also be used for the receiver section by typing this output to the RCLK input of the chip.

Interrupt (INTRPT), Pin 30: Goes high whenever any one of the following interrupt types has an active high condition and is enabled through the IER: receiver error flag, received data available, transmitter holding register empty, or modem status. The INTRPT signal is reset low upon the appropriate interrupt service or a master reset operation.

Serial Output (SOUT), Pin 11: Composite serial data output to the communications link (peripheral, modem, or data set). The SOUT signal is set to the marking (logical 1) state upon a master reset operation.

Input/Output Signals

Data Bus (D7-D0), Pins 1-8: This bus comprises eight tri-state input/output lines. The bus provides bidirectional communications between the INS8250 and the processor. Data, control words, and status information are transferred through the D7-D0 data bus.

External Clock Input/Output (XTAL1, XTAL2), Pins 16 and 17: These two pins connect the main timing reference (crystal or signal clock) to the INS8250.

Programming Considerations

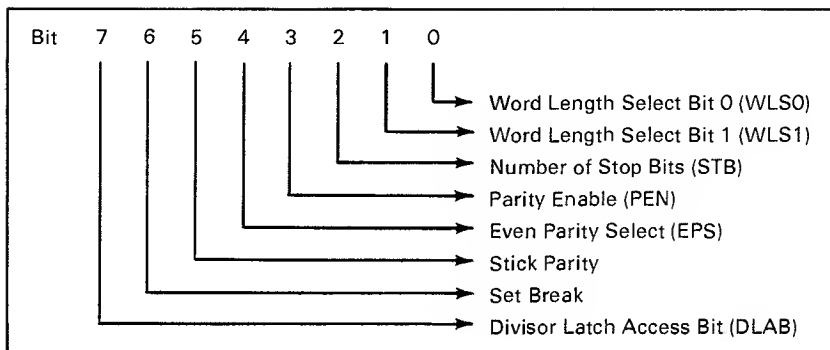
The INS8250 has a number of accessible registers. The system programmer may access or control any of the INS8250 registers through the processor. These registers are used to control INS8250 operations and to transmit and receive data. A table listing and description of the accessible registers follows.

Register/Signal	Reset Control	Reset State
Interrupt Enable Register	Master Reset	All Bits Low (0-3 Forced and 4-7 Permanent)
Interrupt Identification Register	Master Reset	Bit 0 is High, Bits 1 and 2 Low Bits 3-7 are Permanently Low
Line Control Register	Master Reset	All Bits Low
Modem Control Register	Master Reset	All Bits Low
Line Status Register	Master Reset	Except Bits 5 and 6 are High
Modem Status Register	Master Reset	Bits 0-3 Low Bits 4-7 - Input Signal
SOUT	Master Reset	High
INTRPT (RCVR Errors)	Read LSR/MR	Low
INTRPT (RCVR Data Ready)	Read RBR/MR	Low
INTRPT (RCVR Data Ready)	Read IIR/ Write THR/MR	Low
INTRPT (Modem Status Changes)	Read MSR/MR	Low
OUT 2	Master Reset	High
RTS	Master Reset	High
DTR	Master Reset	High
OUT 1	Master Reset	High

Asynchronous Communications Reset Functions

Line-Control Register

The system programmer specifies the format of the asynchronous data communications exchange through the line-control register. In addition to controlling the format, the programmer may retrieve the contents of the line-control register for inspection. This feature simplifies system programming and eliminates the need for separate storage in system memory of the line characteristics. The contents of the line-control register are indicated and described below.



Line-Control Register (LCR)

Bits 0 and 1: These two bits specify the number of bits in each transmitted or received serial character. The encoding of bits 0 and 1 is as follows:

Bit 1	Bit 0	Word Length
0	0	5 Bits
0	1	6 Bits
1	0	7 Bits
1	1	8 Bits

Bit 2: This bit specifies the number of stop bits in each transmitted or received serial character. If bit 2 is a logical 0, one stop bit is generated or checked in the transmit or receive data, respectively. If bit 2 is logical 1 when a 5-bit word length is selected through bits 0 and 1, 1-1/2 stop bits are generated or checked. If bit 2 is logical 1 when either a 6-, 7-, or 8-bit word length is selected, two stop bits are generated or checked.

Bit 3: This bit is the parity enable bit. When bit 3 is a logical 1, a parity bit is generated (transmit data) or checked (receive data) between the last data word bit and stop bit of the serial data. (The parity bit is used to produce an even or odd number of 1's when the data word bits and the parity bit are summed.)

Bit 4: This bit is the even parity select bit. When bit 3 is a logical 1 and bit 4 is a logical 0, an odd number of logical 1's is transmitted or checked in the data word bits and parity bit. When bit 3 is a logical 1 and bit 4 is a logical 1, an even number of bits is transmitted or checked.

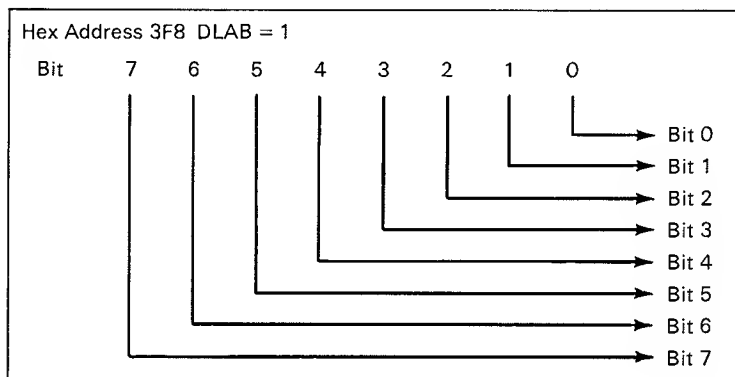
Bit 5: This bit is the stick parity bit. When bit 3 is a logical 1 and bit 5 is a logical 1, the parity bit is transmitted and then detected by the receiver as a logical 0 if bit 4 is a logical 1, or as a logical 1 if bit 4 is a logical 0.

Bit 6: This bit is the set break control bit. When bit 6 is a logical 1, the serial output (SOUT) is forced to the spacing (logical 0) state and remains there regardless of other transmitter activity. The set break is disabled by setting bit 6 to a logical 0. This feature enables the processor to alert a terminal in a computer communications system.

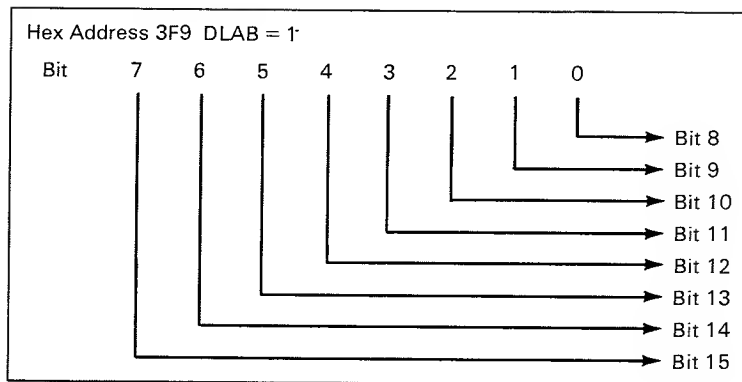
Bit 7: This bit is the divisor latch access bit (DLAB). It must be set high (logical 1) to access the divisor latches of the baud rate generator during a read or write operation. It must be set low (logical 0) to access the receiver buffer, the transmitter holding register, or the interrupt enable register.

Programmable Baud Rate Generator

The INS8250 contains a programmable baud rate generator that is capable of taking the clock input (1.8432 MHz) and dividing it by any divisor from 1 to ($2^{16}-1$). The output frequency of the baud generator is 16 x the baud rate [divisor # = (frequency input)/(baud rate x 16)]. Two 8-bit latches store the divisor in a 16-bit binary format. These divisor latches must be loaded during initialization in order to ensure desired operation of the baud rate generator. Upon loading either of the divisor latches, a 16-bit baud counter is immediately loaded. This prevents long counts on initial load.



Divisor Latch Least Significant Bit (DLL)



Divisor Latch Most Significant Bit (DLM)

The following figure illustrates the use of the baud rate generator with a frequency of 1.8432 MHz. For baud rates of 9600 and below, the error obtained is minimal.

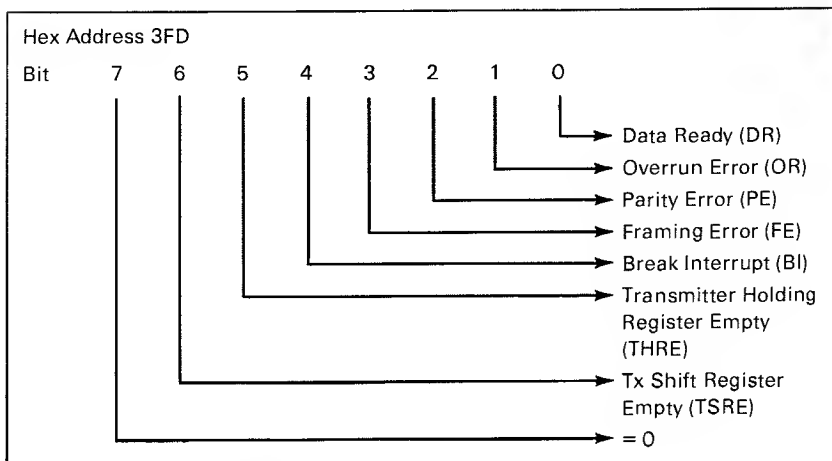
Note: The maximum operating frequency of the baud generator is 3.1 MHz. In no case should the data rate be greater than 9600 baud.

Desired Baud Rate	Divisor Used to Generate 16x Clock		Percent Error Difference Between Desired and Actual
	(Decimal)	(Hex)	
50	2304	900	—
75	1536	600	—
110	1047	417	0.026
134.5	857	359	0.058
150	768	300	—
300	384	180	—
600	192	0C0	—
1200	96	060	—
1800	64	040	—
2000	58	03A	0.69
2400	48	030	—
3600	32	020	—
4800	24	018	—
7200	16	010	—
9600	12	00C	—

Baud Rate at 1.843 MHz

Line Status Register

This 8-bit register provides status information on the processor concerning the data transfer. The contents of the line status register are indicated and described below:



Line Status Register (LSR)

Bit 0: This bit is the receiver data ready (DR) indicator. Bit 0 is set to a logical 1 whenever a complete incoming character has been received and transferred into the receiver buffer register. Bit 0 may be reset to a logical 0 either by the processor reading the data in the receiver buffer register or by writing a logical 0 into it from the processor.

Bit 1: This bit is the overrun error (OE) indicator. Bit 1 indicates that data in the receiver buffer register was not read by the processor before the next character was transferred into the receiver buffer register, thereby destroying the previous character. The OE indicator is reset whenever the processor reads the contents of the line status register.

Bit 2: This bit is the parity error (PE) indicator. Bit 2 indicates that the received data character does not have the correct even or odd parity, as selected by the even parity-select bit. The PE bit is set to a logical 1 upon detection of a parity error and is reset to a logical 0 whenever the processor reads the contents of the line status register.

Bit 3: This bit is the framing error (FE) indicator. Bit 3 indicates that the received character did not have a valid stop bit. Bit 3 is set to a logical 1 whenever the stop bit following the last data bit or parity is detected as a zero bit (spacing level).

Bit 4: This bit is the break interrupt (BI) indicator. Bit 4 is set to a logical 1 whenever the received data input is held in the spacing (logical 0) state for longer than a full word transmission time (that is, the total time of start bit + data bits + parity + stop bits).

Note: Bits 1 through 4 are the error conditions that produce a receiver line status interrupt whenever any of the corresponding conditions are detected.

Bit 5: This bit is the transmitter holding register empty (THRE) indicator. Bit 5 indicates that the INS8250 is ready to accept a new character for transmission. In addition, this bit causes the INS8250 to issue an interrupt to the processor when the transmit holding register empty interrupt enable is set high. The THRE bit is set to a logical 1 when a character is transferred from the transmitter holding register into the transmitter shift register. The bit is reset to logical 0 concurrently with the loading of the transmitter holding register by the processor.

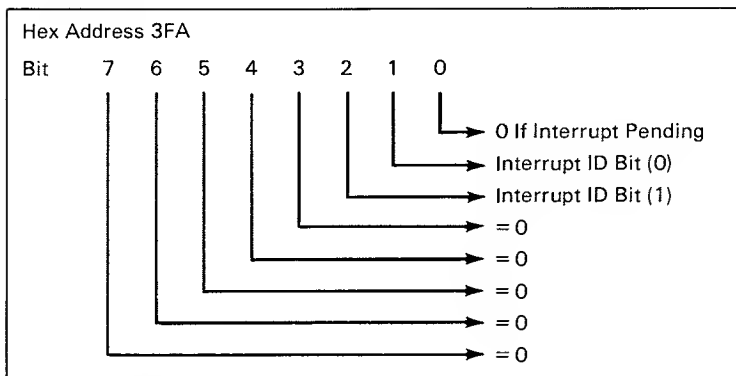
Bit 6: This bit is the transmitter shift register empty (TSRE) indicator. Bit 6 is set to a logical 1 whenever the transmitter shift register is idle. It is reset to logical 0 upon a data transfer from the transmitter holding register to the transmitter shift register. Bit 6 is a read-only bit.

Bit 7: This bit is permanently set to logical 0.

Interrupt Identification Register

The INS8250 has an on-chip interrupt capability that allows for complete flexibility in interfacing to all the popular microprocessors presently available. In order to provide minimum software overhead during data character transfers, the INS8250 prioritizes interrupts into four levels: receiver line status (priority 1), received data ready (priority 2), transmitter holding register empty (priority 3), and modem status (priority 4).

Information indicating that a prioritized interrupt is pending and the type of prioritized interrupt is stored in the interrupt identification register. Refer to the “Interrupt Control Functions” table. The interrupt identification register (IIR), when addressed during chip-select time, freezes the highest priority interrupt pending, and no other interrupts are acknowledged until that particular interrupt is serviced by the processor. The contents of the IIR are indicated and described below.



Interrupt Identification Register (IIR)

Bit 0: This bit can be used in either a hard-wired prioritized or polled environment to indicate whether an interrupt is pending and the IIR contents may be used as a pointer to the appropriate interrupt service routine. When bit 0 is a logical 1, no interrupt is pending and polling (if used) is continued.

Bits 1 and 2: These two bits of the IIR are used to identify the highest priority interrupt pending as indicated in the “Interrupt Control Functions” table.

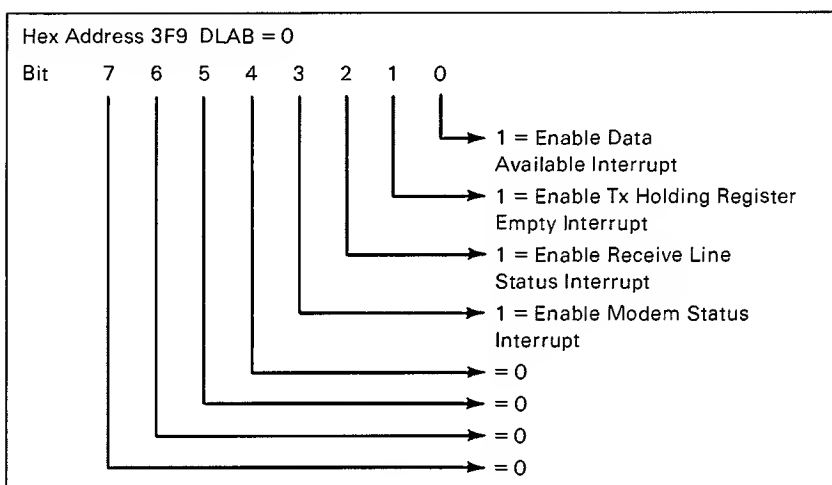
Bits 3 through 7: These five bits of the IIR are always logical 0.

Interrupt ID Register			Interrupt Set and Reset Functions			
Bit 2	Bit 1	Bit 0	Priority Level	Interrupt Type	Interrupt Source	Interrupt Reset Control
0	0	1	—	None	None	—
1	1	0	Highest	Receiver Line Status	Overrun Error or Parity Error or Framing Error or Break Interrupt	Reading the Line Status Register
1	0	0	Second	Received Data Available	Receiver Data Available	Reading the Receiver Buffer Register
0	1	0	Third	Transmitter Holding Register Empty	Transmitter Holding Register Empty	Reading the IIR Register (if source of interrupt) or Writing into the Transmitter Holding Register
0	0	0	Fourth	Modem Status	Clear to Send or Data Set Ready or Ring Indicator or Received Line Signal Direct	Reading the Modem Status Register

Interrupt Control Functions

Interrupt Enable Register

This eight-bit register enables the four types of interrupt of the INS8250 to separately activate the chip interrupt (INTRPT) output signal. It is possible to totally disable the interrupt system by resetting bits 0 through 3 of the interrupt enable register. Similarly, by setting the appropriate bits of this register to a logical 1, selected interrupts can be enabled. Disabling the interrupt system inhibits the interrupt identification register and the active (high) INTRPT output from the chip. All other system functions operate in their normal manner, including the setting of the line status and modem status registers. The contents of the interrupt enable register are indicated and described below:



Interrupt Enable Register (IER)

Bit 0: This bit enables the received data available interrupt when set to logical 1.

Bit 1: This bit enables the transmitter holding register empty interrupt when set to logical 1.

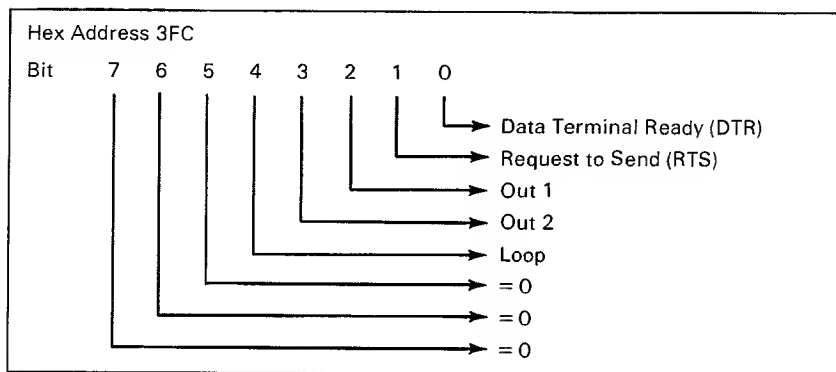
Bit 2: This bit enables the receiver line status interrupt when set to logical 1.

Bit 3: This bit enables the modem status interrupt when set to logical 1.

Bits 4 through 7: These four bits are always logical 0.

Modem Control Register

This eight-bit register controls the interface with the modem or data set (or peripheral device emulating a modem). The contents of the modem control register are indicated and described below:



Modem Control Register (MCR)

Bit 0: This bit controls the data terminal ready ($\overline{\text{DTR}}$) output. When bit 0 is set to logical 1, the $\overline{\text{DTR}}$ output is forced to a logical 0. When bit 0 is reset to a logical 0, the $\overline{\text{DTR}}$ output is forced to a logical 1.

Note: The $\overline{\text{DTR}}$ output of the INS8250 may be applied to an EIA inverting line driver (such as the DS1488) to obtain the proper polarity input at the succeeding modem or data set.

Bit 1: This bit controls the request to send ($\overline{\text{RTS}}$) output. Bit 1 affects the $\overline{\text{RTS}}$ output in a manner identical to that described above for bit 0.

Bit 2: This bit controls the output 1 ($\overline{\text{OUT 1}}$) signal, which is an auxiliary user-designated output. Bit 2 affects the $\overline{\text{OUT 1}}$ output in a manner identical to that described above for bit 0.

Bit 3: This bit controls the output 2 ($\overline{\text{OUT 2}}$) signal, which is an auxiliary user-designated output. Bit 3 affects the $\overline{\text{OUT 2}}$ output in a manner identical to that described above for bit 0.

Bit 4: This bit provides a loopback feature for diagnostic testing of the INS8250. When bit 4 is set to logical 1, the following occurs: the transmitter serial output (SOUT) is set to the marking (logical 1) state; the receiver serial input (SIN) is disconnected; the output of the transmitter shift register is "looped back" into the receiver shift register input; the four modem control inputs ($\overline{\text{CTS}}$, $\overline{\text{DRS}}$, $\overline{\text{RLSD}}$, and $\overline{\text{RI}}$) are disconnected; and the four modem control outputs ($\overline{\text{DTR}}$, $\overline{\text{RTS}}$, $\overline{\text{OUT 1}}$, and $\overline{\text{OUT 2}}$) are internally connected to the four modem control inputs. In the diagnostic mode, data that is transmitted is immediately received. This feature allows the processor to verify the transmit- and receive-data paths of the INS8250.

In the diagnostic mode, the receiver and transmitter interrupts are fully operational. The modem control interrupts are also operational but the interrupts' sources are now the lower four bits of the modem control register instead of the four modem control inputs. The interrupts are still controlled by the interrupt enable register.

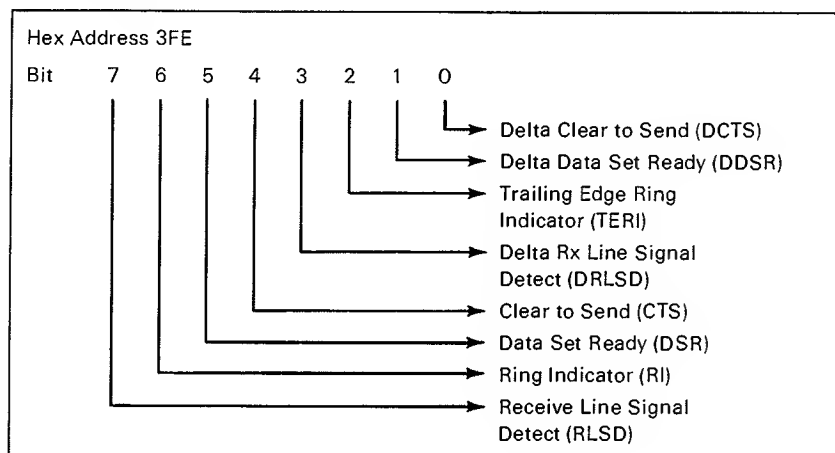
The INS8250 interrupt system can be tested by writing into the lower four bits of the modem status register. Setting any of these bits to a logical 1 generates the appropriate interrupt (if enabled). The resetting of these interrupts is the same as in normal INS8250 operation. To return to normal operation, the registers must be reprogrammed for normal operation and then bit 4 of the modem control register must be reset to logical 0.

Bits 5 through 7: These bits are permanently set to logical 0.

Modem Status Register

This eight-bit register provides the current state of the control lines from the modem (or peripheral device) to the processor. In addition to this current-state information, four bits of the modem status register provide change information. These bits are set to a logical 1 whenever a control input from the modem changes state. They are reset to logical 0 whenever the processor reads the modem status register.

The content of the modem status register are indicated and described below:



Modem Status Register (MSR)

Bit 0: This bit is the delta clear to send (DCTS) indicator. Bit 0 indicates that the $\overline{\text{CTS}}$ input to the chip has changed state since the last time it was read by the processor.

Bit 1: This bit is the delta data set ready (DDSR) indicator. Bit 1 indicates that the $\overline{\text{DRS}}$ input to the chip has changed since the last time it was read by the processor.

Bit 2: This bit is the trailing edge of ring indicator (TERI) detector. Bit 2 indicates that the $\overline{\text{RI}}$ input to the chip has changed from an on (logical 1) to an off (logical 0) condition.

Bit 3: This bit is the delta received line signal detector (DRLSD) indicator. Bit 3 indicates that the RLSD input to the chip has changed state.

Note: Whenever bit 0, 1, 2, or 3 is set to a logical 1, a modem status interrupt is generated.

Bit 4: This bit is the complement of the clear to send ($\overline{\text{CTS}}$) input. If bit 4 (LOOP) of the MCR is set to a logical 1, this is equivalent to RTS in the MCR.

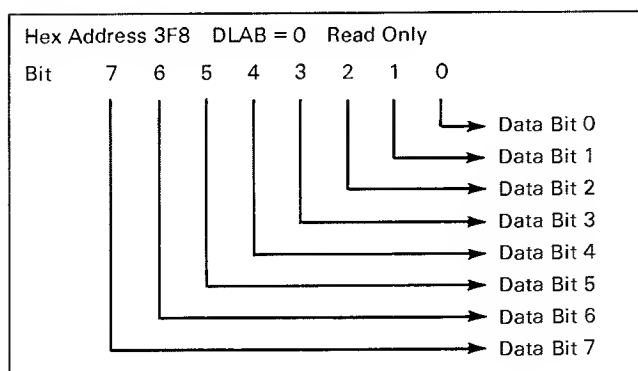
Bit 5: This bit is the complement of the data set ready ($\overline{\text{DSR}}$) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to DTR in the MCR.

Bit 6: This bit is the complement of the ring indicator ($\overline{\text{RI}}$) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to OUT 1 in the MCR.

Bit 7: This bit is the complement of the received line signal detect (RLSD) input. If bit 4 of the MCR is set to a logical 1, this bit is equivalent to OUT 2 of the MCR.

Receiver Buffer Register

The receiver buffer register contains the received character as defined below:

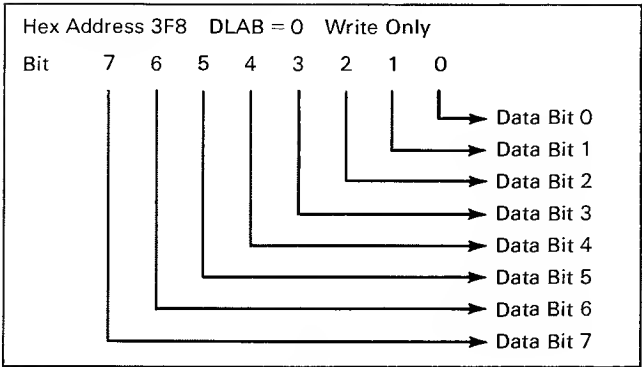


Receiver Buffer Register (RBR)

Bit 0 is the least significant bit and is the first bit serially received.

Transmitter Holding Register

The transmitter holding register contains the character to be serially transmitted and is defined below:



Transmitter Holding Register (THR)

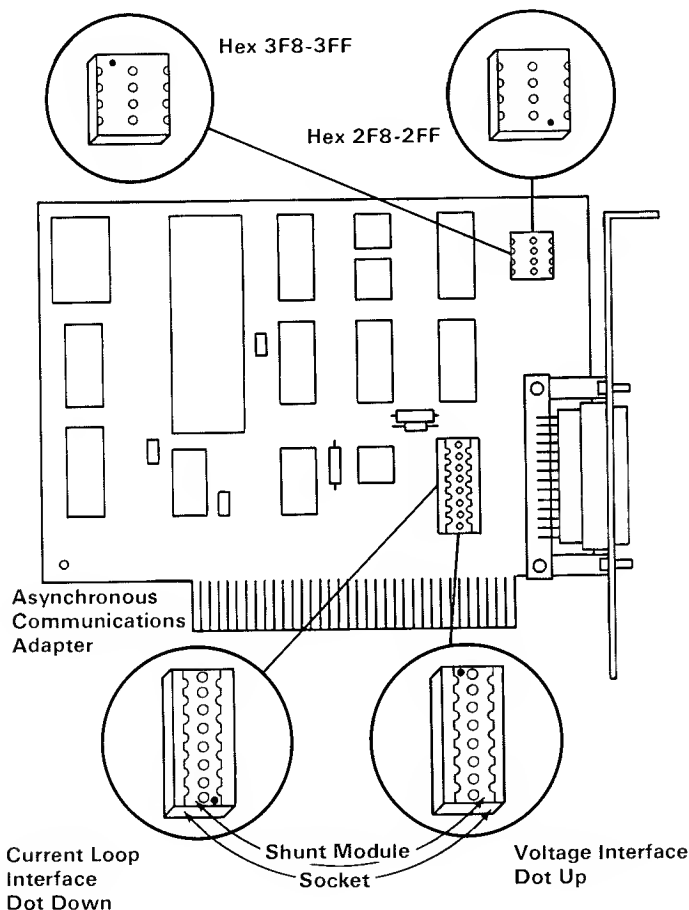
Bit 0 is the least significant bit and is the first bit serially transmitted.

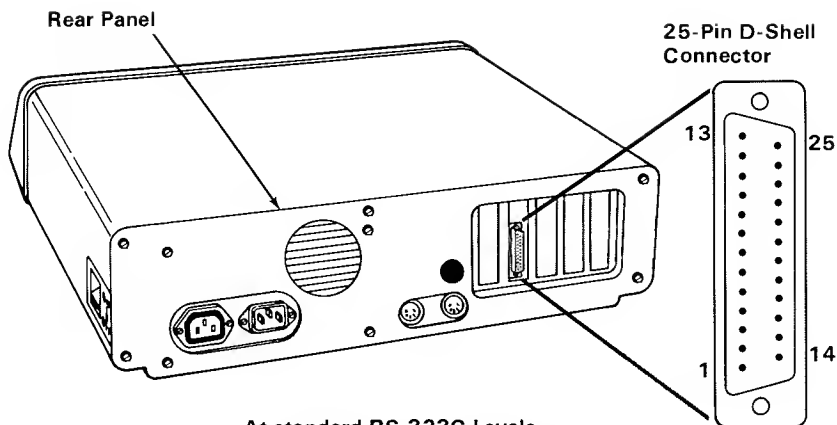
Selecting the Interface Format and Adapter Address

The voltage or current loop interface and adapter address are selected by plugging the programmed shunt modules with the locator dots up or down. See the figure below for the configurations.

Module Position
for Primary Asynchronous
Adapter

Module Position
for Alternate Asynchronous
Adapter





At standard RS-232C Levels
(with exception of current loops)

	Description	Pin	
	NC	1	
←	Transmitted Data	2	
	Received Data	3	→
←	Request to Send	4	
	Clear to Send	5	→
	Data Set Ready	6	→
	Signal Ground	7	
	Received Line Signal Detector	8	→
←	+Transmit Current Loop Data	9	
	NC	10	
←	-Transmit Current Loop Data	11	
	NC	12	
External Device	NC	13	Asynchronous Communications Adapter (RS-232C)
	NC	14	
	NC	15	
	NC	16	
	NC	17	
	+Receive Current Loop Data	18	→
	NC	19	
←	Data Terminal Ready	20	
	NC	21	
	Ring Indicator	22	→
	NC	23	
	NC	24	
	-Receive Current Loop Return	25	→

Note: To avoid inducing voltage surges on interchange circuits, signals from interchange circuits shall be used to drive inductive devices, such as relay coils.

Connector Specifications

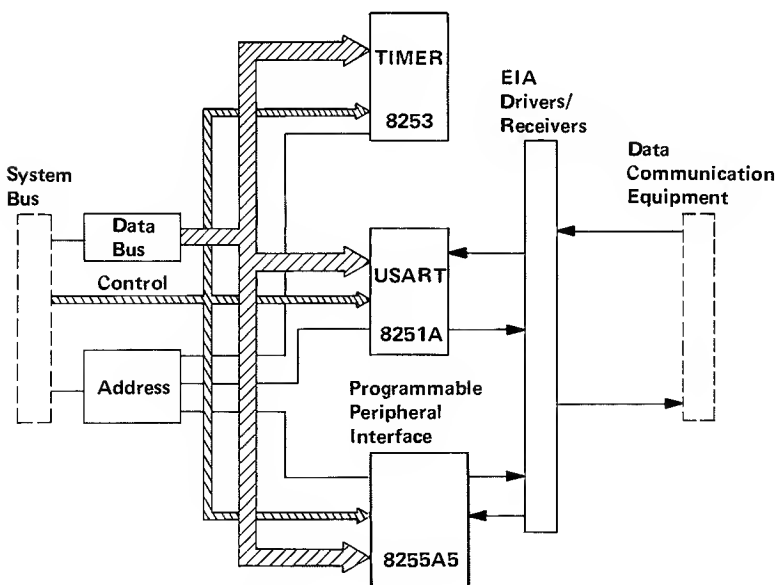
1-250 Asynchronous Adapter

Binary Synchronous Communications Adapter

The binary synchronous communication (BSC) adapter is a 4-inch high by 7.5-inch wide card that provides an RS232C-compatible communication interface for the IBM Personal Computer. All system control, voltage, and data signals are provided through a 2- by 31-position card-edge tab. External interface is in the form of EIA drivers and receivers connected to an RS232C, standard 25-pin, D-shell connector.

The adapter is programmed by communication software to operate in binary synchronous mode. Maximum transmission rate is 9600 bits per second (bps). The heart of the adapter is an Intel 8251A Universal Synchronous/Asynchronous Receiver/Transmitter (USART). An Intel 8255A-5 programmable peripheral interface (PPI) is also used for an expanded modem interface, and an Intel 8253-5 programmable interval timer provides time-outs and generates interrupts.

The following is a block diagram of the BSC adapter.



BSC Adapter Block Diagram

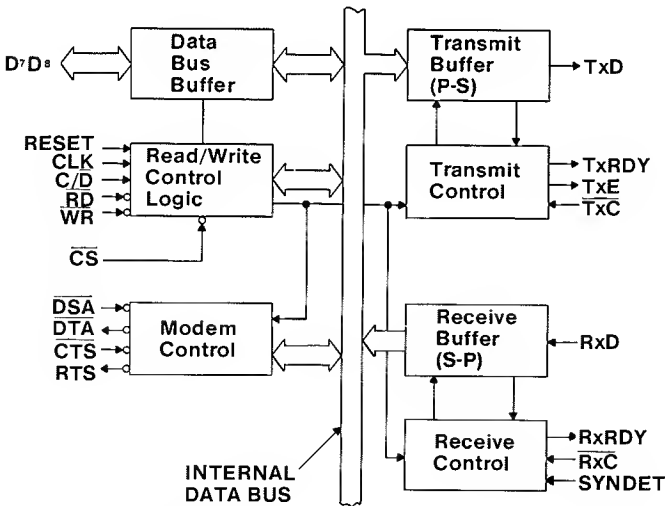
Functional Description

8251A Universal Synchronous/Asynchronous Receiver/Transmitter

The 8251A operational characteristics are programmed by the system unit's software, and it can support virtually any form of synchronous data technique currently in use. In the configuration being described, the 8251A is used for IBM's binary synchronous communications (BSC) protocol in half-duplex mode.

Operation of the 8251A is started by programming the communications format, then entering commands to tell the 8251A what operation is to be performed. In addition, the 8251A can pass device status to the system unit by doing a Status Read operation. The sequence of events to accomplish this are mode instruction, command instruction, and status read. Mode instruction must follow a master reset operation. Commands can be issued in the data block at any time during operation of the 8251A.

A block diagram of the 8251A follows:



8251A Block Diagram

Data Bus Buffer

The system unit's data bus interfaces the 8251A through the data bus buffer. Data is transferred or received by the buffer upon execution of input or output instructions from the system unit. Control words, command words, and status information are also transferred through the data bus buffer.

Read/Write Control Logic

The read/write control logic controls the transfer of information between the system unit and the 8251A. It consists of pins designated as RESET, CLK, WR, RD, C/D, and CS.

RESET: The Reset pin is gated by Port B, bit 4 of the 8255, and performs a master reset of the 8251A. The minimum reset pulse width is 6 clock cycles. Clock-cycle duration is determined by the oscillator speed of the processor.

CLK (Clock): The clock generates internal device timing. No external inputs or outputs are referenced to CLK. The input is the system board's bus clock of 4.77 MHz.

WR (Write): An input to WR informs the 8251A that the system unit is writing data or control words to it. The input is the WR signal from the system-unit bus.

RD (Read): An input to RD informs the 8251A that the processing unit is reading data or status information from it. The input is the RD signal from the system-unit bus.

C/D (Control/Data): An input on this pin, in conjunction with the WR and RD inputs, informs the 8251A that the word on the data bus is either a data character, a control word, or status information. The input is the low-order address bit from the system board's address bus.

CS (Chip Select): A low on the input selects the 8251A. No reading or writing will occur unless the device is selected. An input is decoded at the adapter from the address information on the system-unit bus.

Modem Control

The 8251A has the following input and output control signals which are used to interface the transmission equipment selected by the user.

DSR (Data Set Ready): The DSR input port is a general-purpose, 1-bit, inverting input port. The 8251A can test its condition with a Status Read operation.

CTS (Clear to Send): A low on this input enables the 8251A to transfer serial data if the TxEnable bit in the command byte is set to 1. If either a TxEnable off or CTS off condition occurs while the transmitter is in operation, the transmitter will send all the data in the USART that was written prior to the TxDisable command, before shutting down.

DTR (Data Terminal Ready): The DTR output port is a general-purpose, 1-bit, inverting output port. It can be set low by programming the appropriate bit in the command instruction word.

RTS (Request to Send): The RTS output signal is a general-purpose, 1-bit, inverting output port. It can be set low by programming the appropriate bit in the Command Instruction word.

Transmitter Buffer

The transmitter buffer accepts parallel data from the data-bus buffer, converts it to a serial bit stream, and inserts the appropriate characters or bits for the BSC protocol. The output from the transmit buffer is a composite serial stream of data on the falling edge of Transmit Clock. The transmitter will begin transferring data upon being enabled, if CTS = 0 (active). The transmit data (TxD) line will be set in the marking state upon receipt of a master reset, or when transmit enable/CTS is off and the transmitter is empty (TxEmpty).

Transmitter Control

Transmitter control manages all activities associated with the transfer of serial data. It accepts and issues the following signals, both externally and internally, to accomplish this function:

TxRDY (Transmitter Ready): This output signals the system unit that the transmitter is ready to accept a data character. The TxRDY output pin is used as an interrupt to the system unit (Level 4) and is masked by turning off Transmit Enable. TxRDY is automatically reset by the leading edge of a WR input signal when a data character is loaded from the system unit.

TxE (Transmitter Empty): This signal is used only as a status register input.

TxC (Transmit Clock): The Transmit Clock controls the rate at which the character is to be transmitted. In synchronous mode, the bit-per-second rate is equal to the TxC frequency. The falling edge of TxC shifts the serial data out of the 8251A.

Receiver Buffer

The receiver accepts serial data, converts it to parallel format, checks for bits or characters that are unique to the communication technique, and sends an “assembled” character to the system unit. Serial data input is received on the RxD (Receive Data) pin, and is clocked in on the rising edge of RxC (Receive Clock).

Receiver Control

This control manages all receiver-related activities. The parity-toggle and parity-error flip-flop circuits are used for parity-error detection, and set the corresponding status bit.

RxRDY (Receiver Ready): This output indicates that the 8251A has a character that is ready to be received by the system unit. RxRDY is connected to the interrupt structure of the system unit (Interrupt Level 3). With Receive Enable off, RxRDY is masked and held in the reset mode. To set RxRDY, the receiver must be enabled, and a character must finish assembly and be transferred to the data output register. Failure to read the received character from the RxData output register before the assembly of the next RxData character will set an overrun-condition error, and the previous character will be lost.

RxC (Receiver Clock): The receiver clock controls the rate at which the character is to be received. The bit rate is equal to the actual frequency of RxC.

SYNDET (Synchronization Detect): This pin is used for synchronization detection and may be used as either input or output, programmable through the control word. It is reset to output-mode-low upon reset. When used as an output (internal synchronization mode), the SYNDET pin will go to 1 to indicate that the 8251A has found the synchronization character in the receive mode. If the 8251A is programmed to use double synchronization characters (bisynchronization as in this application), the SYNDET pin will go to 1 in the middle of the last bit of the second synchronization character. SYNDET is automatically reset for a Status Read operation.

8255A-5 Programmable Peripheral Interface

The 8255A-5 is used on the BSC adapter to provide an expanded modem interface and for internal gating and control functions. It has three 8-bit ports, which are defined by the system during initialization of the adapter. All levels are considered plus active unless otherwise indicated. A detailed description of the ports is in "Programming Considerations" in this section.

8253-5 Programmable Interval Timer

The 8253-5 is driven by a divided-by-two system-clock signal. Its outputs are used as clocking signals and to generate inactivity timeout interrupts. These level 4 interrupts occur when either of the timers reaches its programmed terminal counts. The 8253-5 has the following outputs:

Timer 0: Not used for synchronous-mode operation.

Timer 1: Connected to port A, bit 7 of the 8255 and Interrupt Level 4.

Timer 2: Connected to port A, bit 6 of the 8255 and Interrupt Level 4.

Operation

The complete functional definition of the BSC adapter is programmed by the system software. Initialization and control words are sent out by the system to initialize the adapter and program the communications format in which it operates. Once programmed, the BSC Adapter is ready to perform its communication functions.

Transmit

In synchronous transmission, the TxD output is continuously at a mark level until the system sends its first character, which is a synchronization character to the 8251A. When the CTS line goes on, the first character is serially transmitted. All bits are shifted out on the falling edge of TxC. When the 8251A is ready to receive another character from the system for transmission, it raises TxRDY, which causes a level-4 interrupt.

Once transmission has started, the data stream at the TxD output must continue at the TxC rate. If the system does not provide the 8251A with a data character before the 8251A transmit buffers become empty, the synchronization characters will be automatically inserted in the TxD data stream. In this case, the TxE bit in the status register is raised high to signal that the 8251A is empty and that synchronization characters are being sent out. (Note that this TxE bit is in the status register, and is not the TxE pin on the 8251A). TxE does not go low when SYNC is being shifted out. The TxE status bit is internally reset by a data character being written to the 8251A.

Receive

In synchronous reception, the 8251A will achieve character synchronization, because the hardware design of the BSC adapter is intended for internal synchronization. Therefore, the SYNDET pin on the 8251A is not connected to the adapter circuits. For internal synchronization, the Enter Hunt command should be included in the first command instruction word written. Data on the RxD pin is then sampled in on the rising edge of RxC. The content of the RxD buffer is compared at every bit boundary with the first SYNC character until a match occurs. Because the 8251A has been programmed for two synchronization characters (bisynchronization), the next received character is also compared. When both SYNC characters have been detected, the 8251A ends the hunt mode and is in character synchronization. The SYNDET bit in the status register (not the SYNDET pin) is then set high, and is reset automatically by a Status Read.

Once synchronization has occurred, the 8251A begins to assemble received data bytes. When a character is assembled and ready to be transferred to memory from the 8251A, it raises RxRDY, causing an interrupt level 3 to the system.

If the system has not fetched a previous character by the time another received character is assembled (and an interrupt-level 3 issued by the adapter), the old character will be overwritten, and the overrun error flag will be raised. All error flags can be reset by an error reset operation.

Programming Considerations

Before starting data transmission or reception, the BSC adapter is programmed by the system unit to define control and gating ports, timer functions and counts, and the communication environment in which it is to operate.

Typical Programming Sequence

The 8255A-5 programmable peripheral interface (PPI) is initialized for the proper mode by selecting address hex 3A3 and writing the control word. This defines port A as an input, port B as an output for modem control and gating, and port C for 4-bit input and 4-bit output. The bit descriptions for the 8255A-5 are shown in the following figures. Using an output to port C, the adapter is then set to wrap mode, disallow interrupts, and gate external clocks (address=3A2H, data=0DH). The adapter is now isolated from the communication interface, and initialization continues.

Through bit 4 of 8255 Port B, the 8251A reset pin is brought high, held, then dropped. This resets the internal registers of the 8251A.

8255 Port A Assignments Input Port				Address: hex 3A0 for BSC hex 380 for Alternate BSC					
Bit	7	6	5	4	3	2	1	0	
									0 = Ring Indicate is on from Interface
									0 = Data Carrier Defect is on from Interface
									Oscillating = Transmit Clock Active
									0 = Clear-to-Send is on from Interface
									Oscillating = Receive Clock Active
									1 = TxRDY Active
									1 = Timer 2 Output Active
									1 = Timer 1 Output Active

8255 Port B Assignments Output Port				Address: hex 3A1 for BSC hex 381 for Alternate BSC					
Bit	7	6	5	4	3	2	1	0	
									0 = Turn on Data Signal Rate Selector
									0 = Turn on Select Standby
									0 = Turn on Test
									1 = Not Used
									1 = Reset 8251A
									1 = Gate Timer 2
									1 = Gate Timer 1
									1 = Gate Timers 1 and 2 to Interrupt Level 4

8255 Port C Assignments				Address: hex 3A2 for BSC hex 382 for Alternate BSC					
Bit	7	6	5	4	3	2	1	0	
									1 = Gate Internal Clock (Output Bit)
									1 = Gate External Clock (Output Bit)
									1 = Electronic Wrap (Output Bit)
									0 = Enable Timer 1 and 2, Interrupt 6 and Receive Interrupt 3
									Oscillating = Receive Data (Input Bit)
									Oscillating = Timer 0 Output (Input Bit)
									0 = Test Indicate Active (Input Bit)
									0 = BSC Adapter

The 8253-5 programmable interval timer is used in the synchronous mode to provide inactivity time-outs to interrupt the system unit after a preselected period of time has elapsed from the start of a communication operation. Counter 0 is not used for synchronous operation. Counters 1 and 2 are connected to interrupt-level 4, and are programmed to terminal-count values, which will provide the desired time delay before a level-4 interrupt is generated. These interrupts will indicate to the system software that a predetermined period of time has elapsed without a TxRDY (level 4) or RxRDY (level 3) interrupt being sent to the system unit.

The modes for each counter are programmed by selecting each timer-register address and writing the correct control word for counter operation to the adapter. The mode for counters 1 and 2 is set to 0. The terminal-count values are loaded using control-word bits D4 and D5 to select "load." The 8253-5 Control Word format is shown in the following chart.

Control Word Format				Address hex 3A7			
D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
SC1	SC0	RL1	RL0	M2	M1	M0	BCD

Definition of Control

SC — Select Counter:

SC1	SC0	
0	0	Select Counter 0
0	1	Select Counter 1
1	0	Select Counter 2
1	1	Illegal

RL — Read/Load:

RL1	RL0	
0	0	Counter Latching operation
1	0	Read/Load most significant byte only
0	1	Read/Load least significant byte only
1	1	Read/Load least significant byte first, then most significant byte

M — Mode:

M2	M1	M0	
0	0	0	Terminal Count Interrupt

BCD:

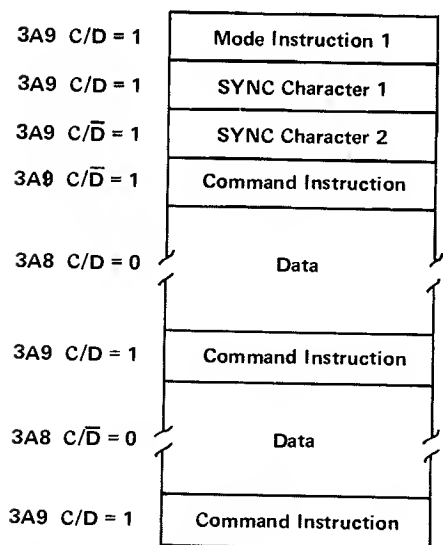
0	Binary Counter 16-bits
1	Binary Coded Decimal (BCD) Counter (4 Decades)

8253-5 Control Word Format

8251A Programming Procedures

After the support devices on the BSC adapter are programmed, the 8251A is loaded with a set of control words that define the communication environment. The control words are split into two formats, mode instruction, and command instruction.

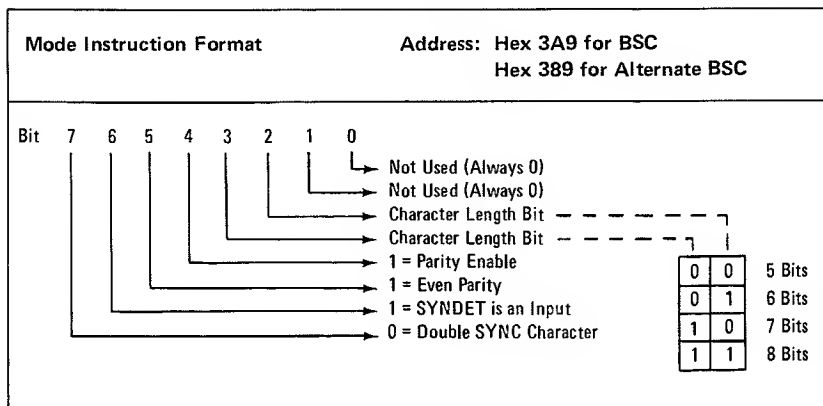
Both the mode and command instructions must conform to a specified sequence for proper device operation. The mode instruction must be inserted immediately after a reset operation, before using the 8251A for data communications. The required synchronization characters for the defined communications technique are next loaded into the 8251A (usually hex 32 for BSC). All control words written to the 8251A after the mode instruction will load the command instruction. Command instructions can be written to the 8251A at any time in the data block during the operation of the 8251A. To return to the mode instruction format, the master reset bit in the command instruction word can be set to start an internal reset operation which automatically places the 8251A back into the mode instruction format. Command instructions must follow the mode instructions or synchronization characters. The following diagram is a typical data block, showing the mode instruction and command instruction.



Typical Data Block

Mode Instruction Definition

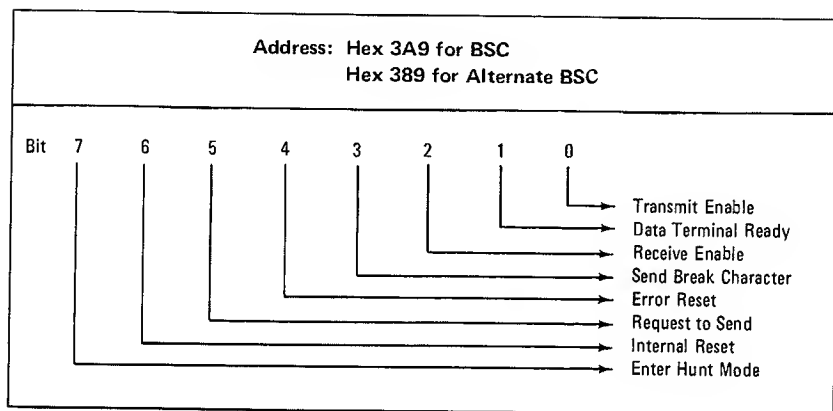
The mode instruction defines the general operational characteristics of the 8251A. It follows a reset operation (internal or external). Once the mode instruction has been written to the 8251A by the system unit, synchronization characters or command instructions may be written to the device. The following figure shows the format for the mode instruction.



Command-Instruction Format

The command-instruction format defines a status word that is used to control the actual operation of the 8251A. Once the mode instruction has been written to the 8251A, and SYNC characters loaded, all further "Control Writes" to I/O address hex 3A9 or hex 389 will load a command instruction.

Data is transferred by accessing two I/O ports on the 8251A, ports 3A8 and 388. A byte of data can be read from port 3A8 and can be written to port 388.



Command Instruction Format

- Bit 0** The Transmit Enable bit sets the function of the 8251A to either enabled (1) or disabled (0).
- Bit 1** The Data Terminal Ready bit, when set to 1 will force the data terminal output to 0. This is a one-bit inverting output port.
- Bit 2** The Receive Enable bit sets the function to either enable the bit (1), or to disable the bit (0).
- Bit 3** The Send Break Character bit is set to 0 for normal BSC operation.
- Bit 4** The Error Reset bit is set to 1 to reset error flags from the command instruction.
- Bit 5** A 1 on the Request to Send bit will set the output to 0. This is a one-bit inverting output port.

- Bit 6** The Internal Reset bit when set to 1 returns the 8251A to mode-instruction format.
- Bit 7** The Enter Hunt bit is set to 1 for BSC to enable a search for synchronization characters.

Status Read Definition

In telecommunication systems, the status of the active device must often be checked to determine if errors or other conditions have occurred that require the processor's attention. The 8251A has a status read facility that allows the system software to read the status of the device at anytime during the functional operation. A normal read command is issued by the processor with I/O address hex 3A9 for BSC, and hex 389 for Alternate BSC to perform a status read operation.

The format for a status read word is shown in the figure below. Some of the bits in the status read format have the same meanings as external output pins so the 8251A can be used in a completely polled environment or in an interrupt-driven environment.

Address: Hex 3A9 for BSC Hex 389 for Alternate BSC	
Bits	0 → TxRDY (See Note Below) 1 → RxRDY 2 → TxEmpty 3 → Parity Error (PE Flag On when a Parity Error Occurs) 4 → Overrun Error (OE Flag On when Overrun Error Occurs) 5 → Framing Error (Not Used for Synchronous Communications) 6 → SYNDET 7 → Data Set Ready (Indicates that DSR is at 0 Level)
Note: TxRDY status bit does not have the same meaning as the 8251A TxRDY output pin. The former is not conditioned by CTS and TxEnable. The latter is conditioned by both CTS and TxEnable.	

Status Read Format

- Bit 0** See the Note in the preceding chart.
- Bit 1** An output on this bit means a character is ready to be received by the computers 8088 microprocessor.

- Bit 2 A 1 on this bit indicates the 8251A has no characters to transmit.
- Bit 3 The Parity Error bit sets a flag when errors are detected. It is reset by the error reset in the command instruction.
- Bit 4 This bit sets a flag when the computers 8088 microprocessor does not read a character before another one is presented. The 8251A operation is not inhibited by this flag, but the overrun character will be lost.
- Bit 5 Not used
- Bit 6 SYNDET goes to 1 when the synchronization character is found in receive mode. For BSC, SYNDET goes high in the middle of the last bit of the second synchronization character.
- Bit 7 The Data Set Ready bit is a one bit inverting input. It is used to check modem conditions, such as data-set ready.

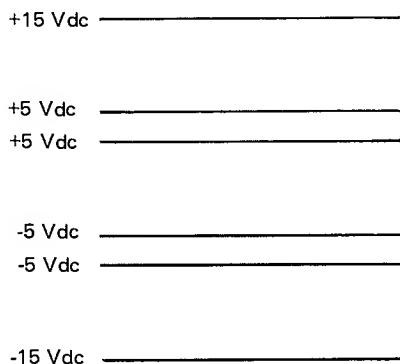
Interface Signal Information

The BSC adapter conforms to interface signal levels standardized by the Electronics Industry Association (EIA) RS232C Standard. These levels are shown in the following figure.

Additional lines, not standardized by the EIA, are pins 11, 18, and 25 on the interface connector. These lines are designated as Select Standby, Test, and Test Indicate. Select Standby is used to support the switched network backup facility of a modem that provides this option. Test and Test Indicate support a modem wrap function on modems that are designated for business-machine, controlled-modem wraps.

Driver

EIA RS232C/CCITT V24-V28 Signal Levels



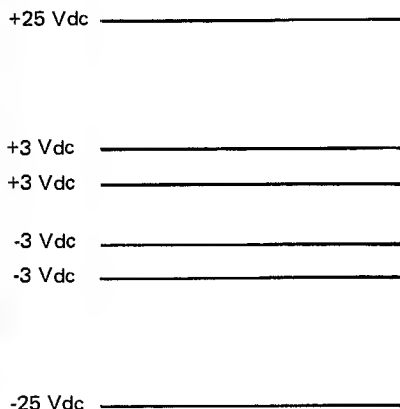
Active/Data = 0

Invalid Level

Inactive/Data = 1

Receiver

EIA RS232C/CCITT V24-V28 Signal Levels



Active/Data = 0

Invalid Level

Inactive/Data = 1

Interface Voltage Levels

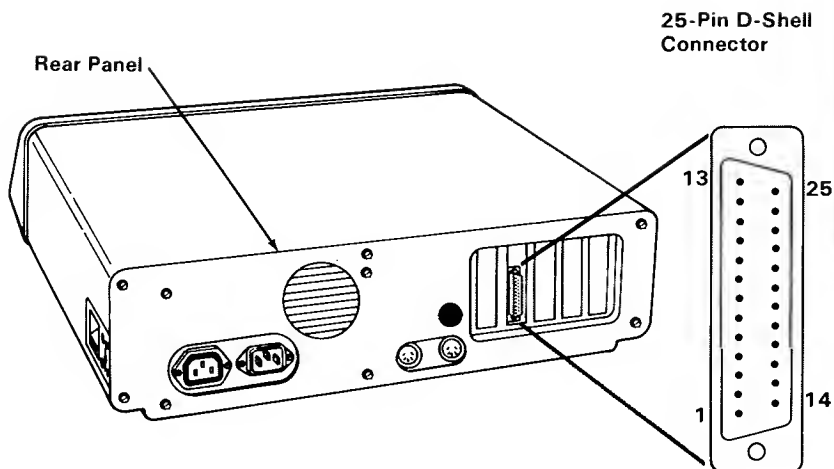
Interrupt Information

Interrupt Level 4: Transmitter Ready
Counter 1
Counter 2

Interrupt Level 3: Receiver Ready

Hex Address		Device	Register Name	Function
Primary	Alternate			
3A0	380	8255	Port A Data	Internal/External Sensing
3A1	381	8255	Port B Data	External Modem Interface
3A2	382	8255	Port C Data	Internal Control
3A3	383	8255	Mode Set	8255 Mode Initialization
3A4	384	8253	Counter 0 LSB	Not Used in Synch Mode
3A4	384	8253	Counter 0 MSB	Not Used in Synch Mode
3A5	385	8253	Counter 1 LSB	Inactivity Time-Outs
3A5	385	8253	Counter 1 MSB	Inactivity Time-Outs
3A6	386	8253	Counter 2 LSB	Inactivity Time-Outs
3A6	386	8253	Counter 2 MSB	Inactivity Time-Outs
3A7	387	8253	Mode Register	8253 Mode Set
3A8	388	8251	Data Select	Data
3A9	389	8251	Command/Status	Mode/Command USART Status

Device Address Summary



Signal Name — Description		Pin
External Device	No Connection	1
	Transmitted Data	2
	Received Data	3
	Request to Send	4
	Clear to Send	5
	Data Set Ready	6
	Signal Ground	7
	Received Line Signal Detector	8
	No Connection	9
	No Connection	10
	Select Standby*	11
	No Connection	12
	No Connection	13
	No Connection	14
	Transmitter Signal Element Timing	15
	No Connection	16
	Receiver Signal Element Timing	17
	Test (IBM Modems Only)*	18
	No Connection	19
	Data Terminal Ready	20
	No Connection	21
	Ring Indicator	22
	Data Signal Rate Selector	23
	No Connection	24
	Test Indicate (IBM Modems Only)*	25
		Binary Synchronous Communications Adapter

*Not standardized by EIA (Electronics Industry Association).

Connector Specifications

Notes:

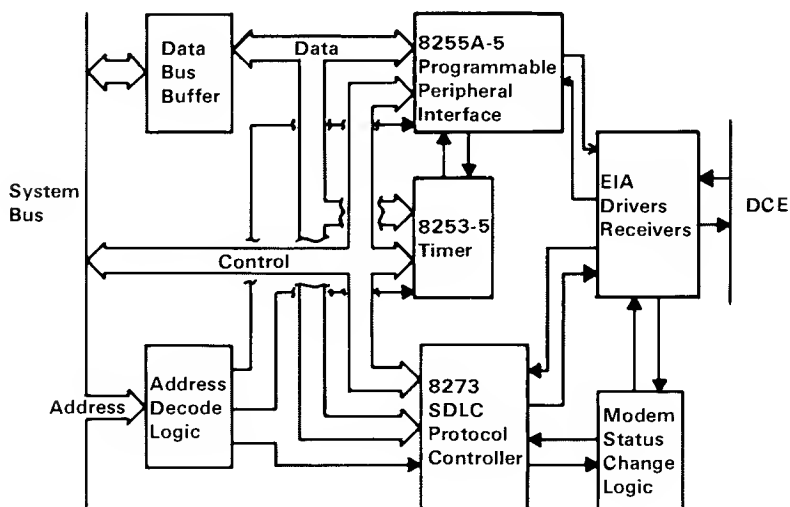
IBM Synchronous Data Link Control (SDLC) Communications Adapter

The SDLC communications adapter system control, voltage, and data signals are provided through a 2 by 31 position card edge tab. Modem interface is in the form of EIA drivers and receivers connecting to an RS232C standard 25-pin, D-shell, male connector.

The adapter is programmed by communications software to operate in a half-duplex synchronous mode. Maximum transmission rate is 9600 bits per second, as generated by the attached modem or other data communication equipment.

The SDLC adapter utilizes an Intel 8273 SDLC protocol controller and an Intel 8255A-5 programmable peripheral interface for an expanded external modem interface. An Intel 8253 programmable interval timer is also provided to generate timing and interrupt signals. Internal test loop capability is provided for diagnostic purposes.

The figure below is a block diagram of the SDLC communications adapter.



SDLC Communications Adapter Block Diagram

The 8273 SDLC protocol control module has the following key features:

- Automatic frame check sequence generation and checking.
- Automatic zero bit insertion and deletion.
- TTL compatibility.
- Dual internal processor architecture, allowing frame level command structure and control of data channel with minimal system processor intervention.

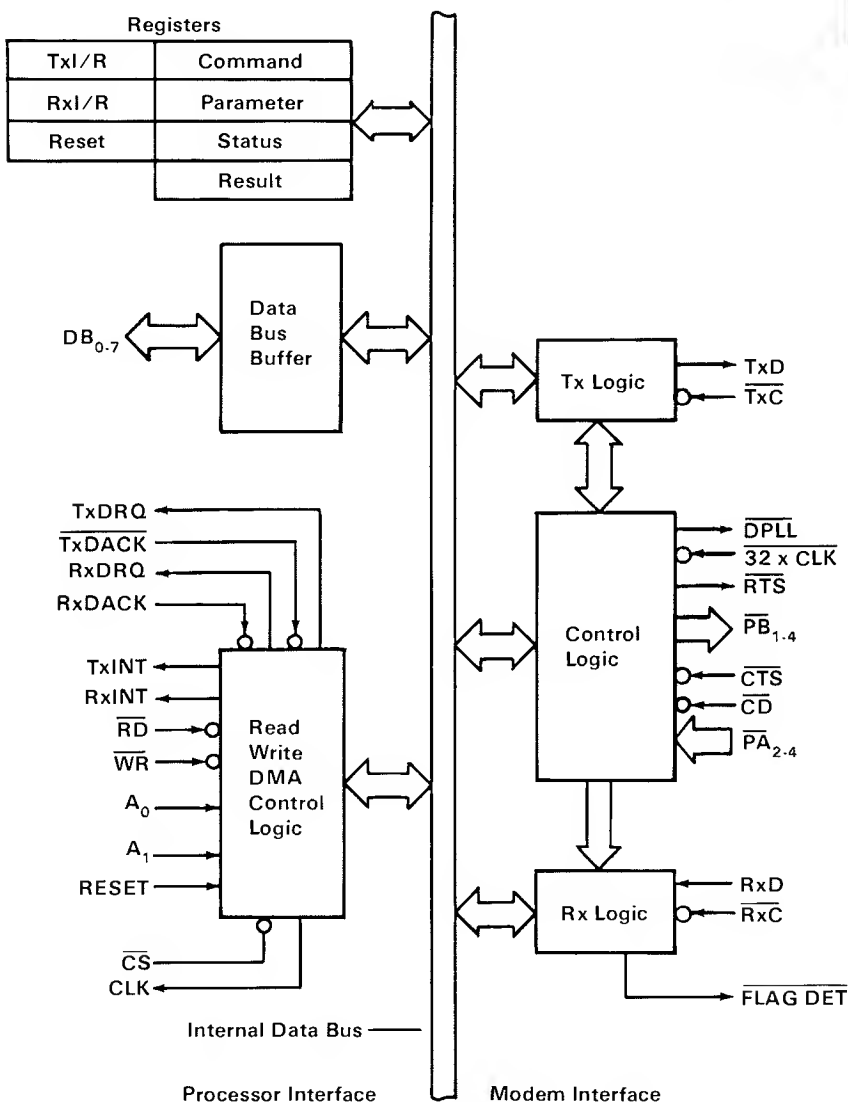
The 8273 SDLC protocol controller operations, whether transmission, reception, or port read, are each comprised of three phases:

Command	Commands and/or parameters for the required operation are issued by the processor.
Execution	Executes the command, manages the data link, and may transfer data to or from memory utilizing direct memory access (DMA), thus freezing the processor except for minimal interruptions.
Result	Returns the outcome of the command by returning interrupt results.

Support of the controller operational phases is through internal registers and control blocks of the 8273 controller.

8273 Protocol Controller Structure

The 8273 module consists of two major interfaces: the processor interface and the modem interface. A block diagram of the 8273 protocol controller module follows.



8273 SDLC Protocol Control Block Diagram

Processor Interface

The processor interface consists of four major blocks: the control/read/write logic (C/R/W), internal registers, data transfer logic, and data bus buffers.

Control/Read/Write Logic

The control/read/write logic is used by the processor to issue commands to the 8273. Once the 8273 receives and executes a command, it returns the results using the C/R/W logic. The logic is supported by seven registers which are addressed by A0, A1, RD, and WR, in addition to CS. A0 and A1 are the two low-order bits of the adapter address-byte. RD and WR are the processor read and write signals present on the system control bus. CS is the chip select, also decoded by the adapter address logic. The table below shows the address of each register using the C/R/W logic.

Address Inputs		Control Inputs			Register
A0	A1	CS	WR	RD	
0	0	0	0	1	Command
0	0	0	1	0	Status
0	1	0	0	1	Parameter
0	1	0	1	0	Result
1	0	0	0	1	Reset
1	0	0	1	0	TxI/R
1	1	0	0	1	None
1	1	0	1	0	RxI/R

8273 SDLC Protocol Controller Register Selection

8273 Control/Read/Write Registers

Command	Operations are initialized by writing the appropriate command byte into this register.
Status	This register provides the general status of the 8273. The status register supplies the processor/adaptor handshaking necessary during various phases of the 8273 operation.
Parameter	Additional information that is required to process the command is written into this register. Some commands require more than one parameter.
Immediate Result (Result)	Commands that execute immediately produce a result byte in this register, to be read by the processor.
Transmit Interrupt Results (TxI/R)	Results of transmit operations are passed to the processor from this register. This result generates an interrupt to the processor when the result becomes available.
Receiver Interrupt Results (Rx/I/R)	Results of receive operations are passed to the processor from this register. This result generates an interrupt to the processor when the result becomes available.
Reset	This register provides a software reset function for the 8273.

The other elements of the C/R/W logic are the interrupt lines (RxINT and TxINT). Interrupt priorities are listed in the "Interrupt Information" table in this section. These lines signal the processor that either the transmitter or the receiver requires service (results should be read from the appropriate register), or a data transfer is required. The status of each interrupt line is also reflected by a bit in the status register, so non-interrupt driven operation is also possible by the communication software examining these bits periodically.

Data Interfaces

The 8273 supports two independent data interfaces through the data transfer logic: received data and transmitted data. These interfaces are programmable for either DMA or non-DMA data transfers. Speeds below 9600 bits-per-second may or may not require DMA, depending on the task load and interrupt response time of the processor. The processor DMA controller is used for management of DMA data transfer timing and addressing. The 8273 handles the transfer requests and actual counts of data-block lengths. DMA level 1 is used to transmit and receive data transfers. Dual DMA support is not provided.

Elements of Data Transfer Interface

TxDRQ/RxDRQ	This line requests a DMA to or from memory and is asserted by the 8273.
TxDACK/RxDACK	This line notifies the 8273 that a request has been granted and provides access to data regions. This line is returned by the DMA controller (DACK1 on the system unit control bus is connected to TxDACK/RxDACK on the 8273).
RD (Read)	This line indicates data is to be read from the 8273 and placed in memory. It is controlled by the processor DMA controller.
WR (Write)	This line indicates if data is to be written to the 8273 from memory and is controlled by the processor DMA controller.

To request a DMA transfer, the 8273 raises the DMA request line. Once the DMA controller obtains control of the system bus, it notifies the 8273 that the DRQ is granted by returning DACK, and WR or RD, for a transmit or receive operation, respectively. The DACK and WR or RD signals transfer data between the 8273 and memory, independent of the 8273 chip-select pin (CS). This “hard select” of data into the transmitter or out of the receiver alleviates the need for the normal transmit and receive data registers, addressed by a combination of address lines, CS, and WR or RD.

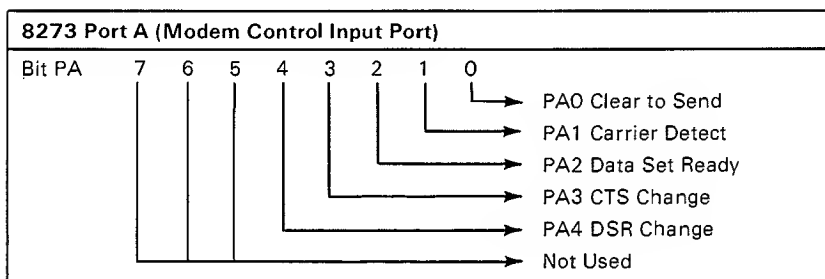
Modem Interface

The modem interface of the 8273 consists of two major blocks: the modem control block and the serial data timing block.

Modem Control Block

The modem control block provides both dedicated and user-defined modem control function. EIA inverting drivers and receivers are used to convert TTL levels to EIA levels.

Port A is a modem control input port. Bits PA0 and PA1 have dedicated functions.



Bit PA0

This bit reflects the logical state of the clear to send (CTS) pin. The 8273 waits until CTS is active before it starts transmitting a frame. If CTS goes inactive while transmitting, the frame is aborted and the processor is interrupted. A CTS failure will be indicated in the appropriate interrupt-result register.

Bit PA1

This bit reflects the logical state of the carrier detect pin (CD). CD must be active in sufficient time for reception of a frame's address field. If CD is lost (goes inactive) while receiving a frame, an interrupt is generated with a CD failure result.

Bit PA2

This bit is a sense bit for data set ready (DSR).

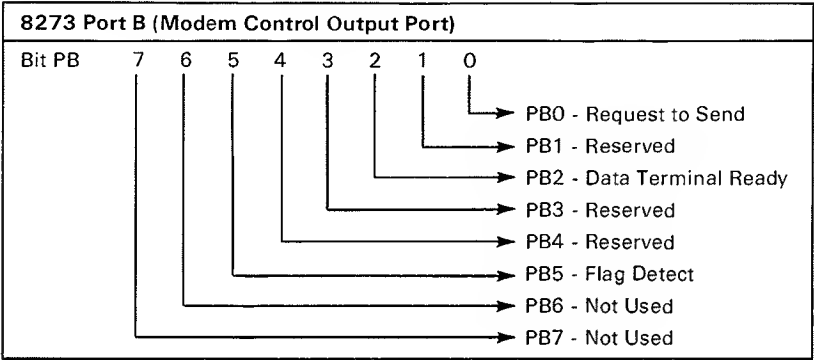
Bit PA3

This bit is a sense bit to detect a change in CTS.

Bit PA4 This bit is a sense bit to detect a change in data set ready.

Bits PA5 to PA7 These bits are not used and each is read as a 1 for a read port A command.

Port B is a modem control output port. Bits PB0 and PB5 are dedicated function pins.



Bit PB0 This bit represents the logical state of request to send (RTS). This function is handled automatically by the 8273.

Bit PB1 Reserved.

Bit PB2 Used for data terminal ready.

Bit PB3 Reserved.

Bit PB4 Reserved.

Bit PB5 This bit reflects the state of the flag detect pin. This pin is activated whenever an active receiver sees a flag character.

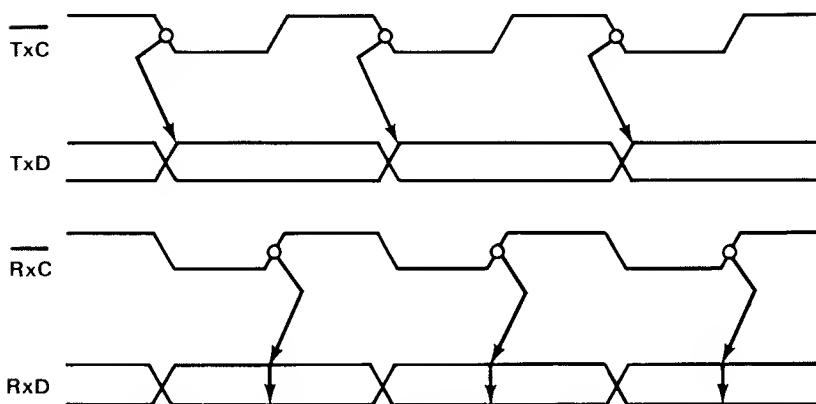
Bit PB6 Not used.

Bit PB7 Not used.

Serial Data Timing Block

The serial data timing block is comprised of two sections: the serial data logic and the digital phase locked loop (DPLL).

Elements of the serial data logic section are the data pins TxD (transmitted data output) and RxD (received data input), and the respective clocks. The leading edge of TxC generates new transmitted data and the trailing edge of RxC is used to capture the received data. The figure below shows the timing for these signals.



8273 SDLC Protocol Controller Transmit/Receive Timing

The digital phase locked loop provided on the 8273 controller module is utilized to capture looped data in proper synchronization during wrap operations performed by diagnostics.

8255A-5 Programmable Peripheral Interface

The 8255A-5 contains three 8-bit ports. Descriptions of each bit of these ports are as follows:

8255A-5 Port A Assignments*								Hex Address 380
Bit	7	6	5	4	3	2	1	0
								0 = Ring Indicator is on from Interface
								0 = Data Carrier Detect is on from Interface
								Oscillating = Transmit Clock Active
								0 = Clear to Send is on from Interface
								Oscillating = Receive Clock Active
								1 = Modem Status Changed
								1 = Timer 2 Output Active
								1 = Timer 1 Output Active
*Port A is defined as an input port								

8255A-5 Port B Assignments*								Hex Address 381
Bit	7	6	5	4	3	2	1	0
								0 = Turn On Data Signal Rate Select at Modem Interface
								0 = Turn On Select Standby at Modem Interface
								0 = Turn On Test
								1 = Reset Modem Status Changed Logic
								1 = Reset 8273
								1 = Gate Timer 2
								1 = Gate Timer 1
								1 = Enable Level 4 Interrupt
*Port B is defined as an output port								

8255A-5 Port C Assignments*								Hex Address 382
Bit	7	6	5	4	3	2	1	0
								1 = Gate Internal Clock (Output Bit)
								1 = Gate External Clock (Output Bit)
								1 = Electronic Wrap (Output Bit)
								0 = Gate Interrupts 3 and 4 (Output Bit)
								Oscillating = Receive Data (Input Bit)
								Oscillating = Timer 0 Output (Input bit)
								0 = Test Indicate Active (Input Bit)
								Not Used

*Port C is defined for internal control and gating functions. It has three input and four output bits. The four output bits are defined during initialization, but only three are used.

8253-5 Programmable Interval Timer

The 8253-5 is driven by a processor clock signal divided by two. It has the following output:

Timer 0 Programmed to generate a square wave signal, used as an input to timer 2. Also connected to 8253 port C, bit 5.

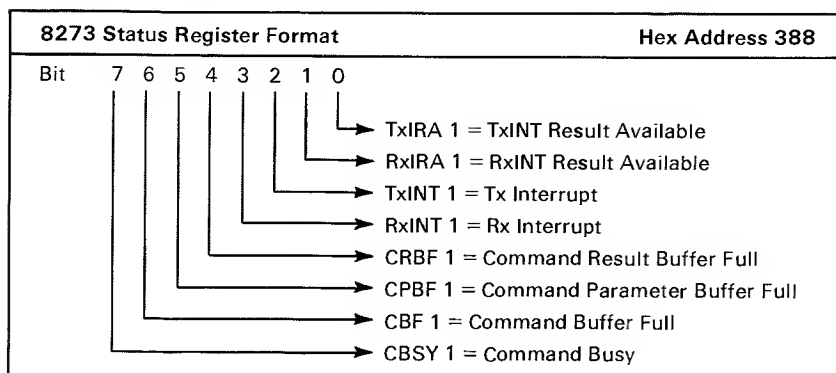
Timer 1 Connected to 8255 port A, bit 7, and interrupt level 4.

Timer 2 Connected to 8255 port A, bit 6, and interrupt level 4.

Programming Considerations

The software aspects of the 8273 involve the communication of both commands from the processor to the 8273 and the return of results of those commands from the 8273 to the processor. Due to the internal processor architecture of the 8273, this system unit/8273 communication is basically a form of interprocessor communication, and must be considered when programming for the SDLC communications adapter.

The protocol for this interprocessor communication is implemented through use of handshaking supplied in the 8273 status register. The bit definitions of this register are shown below.



- Bit 0** This bit is the transmitter interrupt result available (TxIRA) bit. This bit is set when the 8273 places an interrupt-result byte in the TxI/R register, and reset when the processor reads the TxI/R register.
- Bit 1** This bit is the receiver interrupt result available (RxIRA) bit. It is the corresponding result-available bit for the receiver. It is set when the 8273 places an interrupt-result byte in the RxI/R register and reset when the processor reads the register.
- Bit 2** This bit is the transmitter interrupt (TxINT) bit and reflects the state of the TxINT pin. TxINT is set by the 8273 whenever the transmitter needs servicing, and reset when the processor reads the result or performs the data transfer.
- Bit 3** This bit is the receiver interrupt (RxINT) bit and is identical to the TxINT, except action is initiated based on receiver interrupt-sources.
- Bit 4** This bit is the command result buffer full (CRBF) bit. It is set when the 8273 places a result from an immediate-type command in the result register, and reset when the processor reads the result or performs the data transfer.

- Bit 5 This bit is the command parameter buffer full (CPBF) bit and indicates that the parameter register contains a parameter. It is set when the processor deposits a parameter in the parameter register, and reset when the 8273 accepts the parameter.
- Bit 6 This bit is the command buffer full (CBF) bit and, when set, it indicates that a byte is present in the command register. This bit is normally not used.
- Bit 7 This bit is the command busy (CBSY) bit and indicates when the 8273 is in the command phase. It is set when the processor writes a command into the command register, starting the command phase. It is reset when the last parameter is deposited in the parameter register and accepted by the 8273, completing the command phase.

Initializing the Adapter (Typical Sequence)

Before initialization of the 8273 protocol controller, the support devices on the card must be initialized to the proper modes of operation.

Configuration of the 8255A-5 programmable peripheral interface is accomplished by selecting the mode-set address for the 8255 (see the "SDLC Communications Adapter Device Addresses" table later in this section) and writing the appropriate control word to the device (hex 98) to set ports A, B, and C to the modes described previously in this section.

Next, a bit pattern is output to port C which disallows interrupts, sets wrap mode on, and gates the external clock pins (address = hex 382, data = hex 0D). The adapter is now isolated from the communications interface.

Using bit 4 of port B, the 8273 reset line is brought high, held and then dropped. This resets the internal registers of the 8273.

The 8253-5's counter 1 and 2 terminal-count values are now set to values which will provide the desired time delay before a level 4 interrupt is generated. These interrupts may be used to indicate to the communication software that a pre-determined period of time has elapsed without a result interrupt (interrupt level 3). The terminal count-values for these counters are set for any time delay which the programmer requires. Counter 0 is also set at this time to mode 3 (generates square wave signal, used to drive counter 2 input).

To setup the counter modes, the address for the 8253 counter mode register is selected (see the "SDLC Communications Adapter Device Addresses" table, later in this section), and the control word for each individual counter is written to the device separately. The control-word format and bit definitions for the 8253 are shown below. Note that the two most-significant bits of the control word select each individual counter, and each counter mode is defined separately.

Once the support devices have been initialized to the proper modes and the 8273 has been reset, the 8273 protocol controller is ready to be configured for the operating mode that defines the communications environment in which it will be used.

Control Word Format

D ₇	D ₆	D ₅	D ₄	D ₃	D ₂	D ₁	D ₀
SC1	SC0	RL1	RL0	M2	M1	M0	BCD

Definitions of Control**SC - Select Counter:**

SC1 SC0

0	0	Select Counter 0
0	1	Select Counter 1
1	0	Select Counter 2
1	1	Illegal

RL - Read/Load:

RL1 RL0

0	0	Counter Latching operation
1	0	Read/Load most significant byte (MSB)
0	1	Read/Load least significant byte (LSB)
1	1	Read/Load least significant byte first, then most significant byte.

M - Mode:

M2 M1 M0 Mode

0	0	0	Mode 0
0	0	1	Mode 1
X	1	0	Mode 2
X	1	1	Mode 3
1	0	0	Mode 4
1	0	1	Mode 5

BCD:

0	Binary Counter 16-bits
1	Binary Coded Decimal (BCD) Counter (4 Decades)

8253-5 Programmable Interval Timer Control Word

Initialization/Configuration Commands

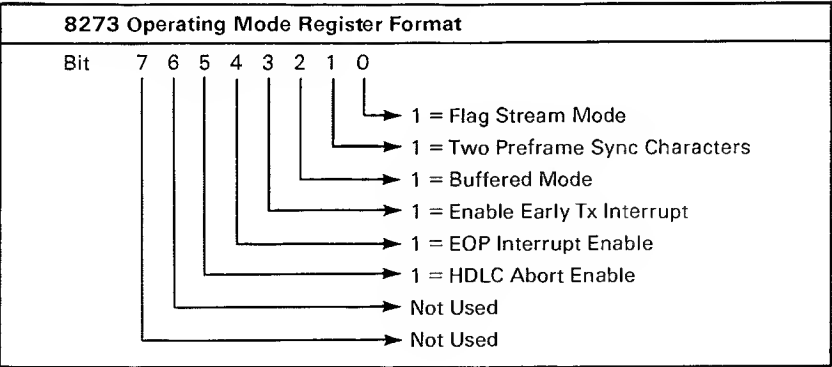
The initialization/configuration commands manipulate internal registers of the 8273, which define operating modes. After chip reset, the 8273 defaults to all 1's in the mode registers. The initialization/configuration commands either set or reset specified bits in the registers depending on the type of command. One parameter is required with the commands. The parameter is actually the bit pattern (mask) used by the set or reset command to manipulate the register bits.

Set commands perform a logical OR operation of the parameter (mask) of the internal register. This mask contains 1's where register bits are to be set. Zero (0's) in the mask cause no change to the corresponding register bit.

Reset commands perform a logical AND operation of the parameter (mask) and internal register. The mask 0 is reset to register bit, and 1 to cause no change.

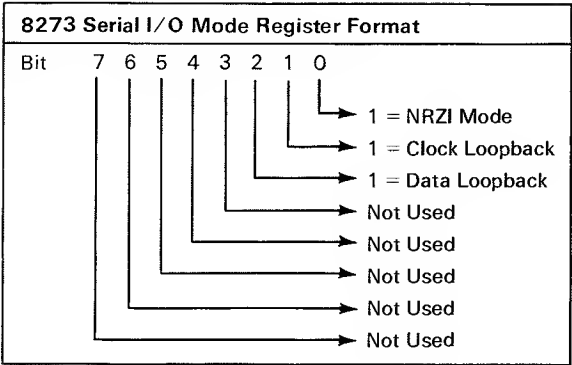
The following are descriptions of each bit of the operating, serial I/O, one-bit delay, and data transfer mode registers.

Operating Mode Register



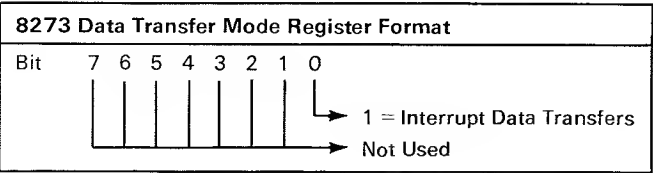
- Bit 0 If bit 0 is set to a 1, flags are sent immediately if the transmitter was idle when the bit was set. If a transmit or transmit-transparent command was active, flags are sent immediately after transmit completion. This mode is ignored if loop transmit is active or the one-bit-delay mode register is set for one-bit delay. If bit 0 is reset (to 0), the transmitter sends idles on the next character boundary if idle or, after transmission is complete, if the transmitter was active at bit-0 reset time.
- Bit 1 If bit 1 is set to a 1, the 8273 sends two characters before the first flag of a frame. These characters are hex 00 if NRZI is set or hex 55 if NRZI is not set. (See "Serial I/O Mode Register," for NRZI encoding mode format.)
- Bit 2 If bit 2 is set to a 1, the 8273 buffers the first two bytes of a received frame (the bytes are not passed to memory). Resetting this bit (to 0) causes these bytes to be passed to and from memory.
- Bit 3 This bit indicates to the 8273 when to generate an end-of-frame interrupt. If bit 3 is set, an early interrupt is generated when the last data character has been passed to the 8273. If the processor responds to the early interrupt with another transmit command before the final flag is sent, the final-flag interrupt will not be generated and a new frame will begin when the current frame is complete. Thus, frames may be sent separated by a single flag. A reset condition causes an interrupt to be generated only following a final flag.
- Bit 4 This is the EOP-interrupt-mode function and is not used on the SDLC communications adapter. This bit should always be in the reset condition.
- Bit 5 This bit is always reset for SDLC operation, which causes the 8273 protocol controller to recognize eight ones (0 1 1 1 1 1 1 1) as an abort character.

Serial I/O Mode Register



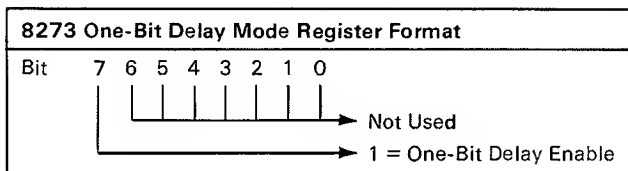
- Bit 0** Set to 1, this bit specifies NRZI encoding and decoding. Resetting this bit specifies that transmit and receive data be treated as a normal positive-logic bit stream.
- Bit 1** When bit 1 is set to 1, the transmit clock is internally routed to the receive-clock circuitry. It is normally used with the loopback bit (bit 2). The reset condition causes the transmit and receive clocks to be routed to their respective 8273 I/O pins.
- Bit 2** When bit 2 is set, the transmitted data is internally routed to the received data circuitry. The reset condition causes the transmitted and received data to be routed to their respective 8273 I/O pins.

Data Transfer Mode Register



When the data transfer mode register is set, the 8273 protocol controller will interrupt when data bytes are required for transmission, or are available from a reception. If a transmit or receive interrupt occurs and the status register indicates that there is no transmit or receive interrupt result, the interrupt is a transmit or receive data request, respectively. Reset of this register causes DMA requests to be performed with no interrupts to the processor.

One-Bit Delay Mode Register



When one-bit delay is set, the 8273 retransmits the received data stream one-bit delayed. Reset of this bit stops the one-bit delay mode.

The table below is a summary of all set and reset commands associated with the 8273 mode registers. The set or reset mask used to define individual bits is treated as a single parameter. No result or interrupt is generated by the 8273 after execution of these commands.

Register	Command	Hex Code	Parameter
One-Bit Delay Mode	Set	A4	Set Mask
	Reset	64	Reset Mask
Data Transfer Mode	Set	97	Set Mask
	Reset	57	Reset Mask
Operating Mode	Set	91	Set Mask
	Reset	51	Reset Mask
Serial I/O Mode	Set	A0	Set Mask
	Reset	60	Reset Mask

8273 SDLC Protocol Controller Mode Register Commands

Command Phase

Although the 8273 is a full duplex device, there is only one command register. Thus, the command register must be used for only one command sequence at a time and the transmitter and receiver may never be simultaneously in a command phase.

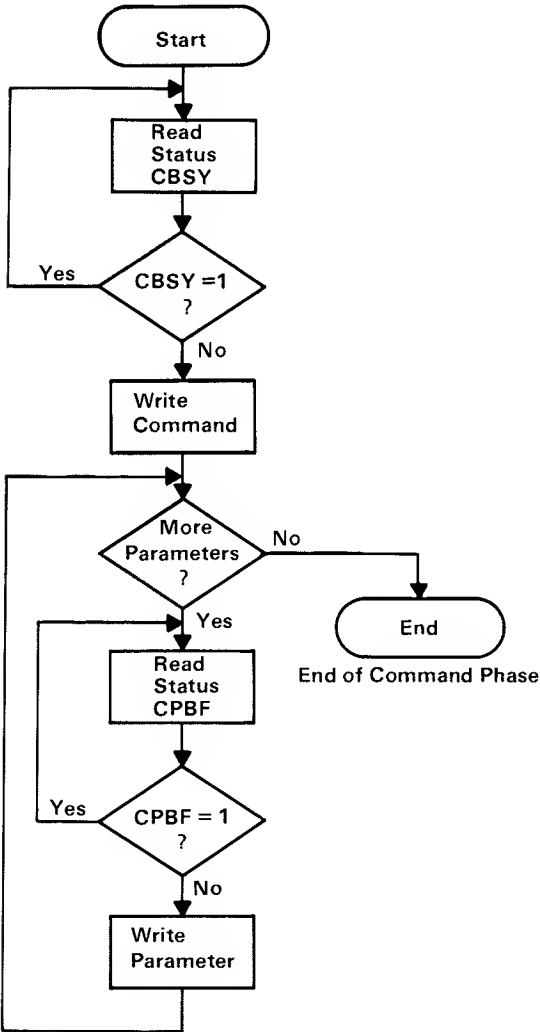
The system software starts the command phase by selecting the 8273 command register address and writing a command byte into the register. The following table lists command and parameter information for the 8273 protocol controller. If further information is required by the 8273 prior to execution of the command, the system software must write this information into the parameter register.

Command Description	Command (Hex)	Parameter	Results	Result Port	Completion Interrupt
Set One-Bit Delay	A4	Set Mask	None	—	No
Reset One-Bit Delay	64	Reset Mask	None	—	No
Set Data Transfer Mode	97	Set Mask	None	—	No
Reset Data Transfer Mode	57	Reset Mask	None	—	No
Set Operating Mode	91	Set Mask	None	—	No
Reset Operating Mode	51	Reset Mask	None	—	No
Set Serial I/O Mode	A0	Set Mask	None	—	No
Reset Serial I/O Mode	60	Reset Mask	None	—	No
General Receive	C0	80,81	RIC,R0,R1, A,C	RXI/R	Yes
Selective Receive	C1	80,81,A1, A2	RIC,R0,R1, A,C	RXI/R	Yes
Receive Disable	C5	None	None	—	No
Transmit Frame	C8	L0,L1,A,C	TIC	TXI/R	Yes
Transmit Transparent	C9	L0,L1	TIC	TXI/R	Yes
Abort Transmit Frame	CC	None	TIC	TXI/R	Yes
Abort Transmit Transparent	CD	None	TIC	TXI/R	Yes
Read Port A	22	None	Port Value	Result	No
Read Port B	23	None	Port Value	Result	No
Set Port B Bit	A3	Set Mask	None	—	No
Reset Port B Bit	63	Reset Mask	None	—	No

8273 Command Summary Key

- B0** — Least significant byte of the receiver buffer length.
B1 — Most significant byte of the receiver buffer length.
L0 — Least significant byte of the Tx frame length.
L1 — Most significant byte of the Tx frame length.
A1 — Receive frame address match field one.
A2 — Receive frame address match field two.
A — Address field of received frame. If non-buffered mode is specified, this result is not provided.
C — Control field of received frame. If non-buffered mode is specified, this result is not provided.
RXI/R — Receive interrupt result register.
TXI/R — Transmit interrupt result register.
RD — Least significant byte of the length of the frame received.
R1 — Most significant byte of the length of the frame received.
RIC — Receiver interrupt result code.
TIC — Transmitter interrupt result code.

A flowchart of the command phase is shown below. Handshaking of the command and parameter bytes is accomplished by the CBSY and CPBF bits of the status register. A command may not be written if the 8273 is busy (CBSY = 1). The original command will be overwritten if a second command is issued while CBSY = 1. The flowchart also indicates a parameter buffer full check. The processor must wait until CPBF = 0 before writing a parameter to the parameter register. Previous parameters are overwritten and lost if a parameter is written while CPBF = 1.



8273 SDLC Protocol Controller Command Phase Flowchart

Execution Phase

During the execution phase, the operation specified by the command phase is performed. If DMA is utilized for data transfers, no processor involvement is required.

For interrupt-driven transfers the 8273 raises the appropriate INT pin (TxINT or RxINT). When the processor responds to the interrupt, it must determine the cause by examining the status register and the associated IRA (interrupt result available) bit of the status register. If $IRA = 0$, the interrupt is a data transfer request. If $IRA = 1$, an operation is complete and the associated interrupt result register must be read to determine completion status.

Result Phase

During the result phase, the 8273 notifies the processor of the outcome of a command execution. This phase is initiated by either a successful completion or error detection during execution.

Some commands such as reading or writing the I/O ports provide immediate results. These results are made available to the processor in the 8273 result register. Presence of a valid immediate result is indicated by the CRBF (command result buffer full) bit of the status register.

Non-immediate results deal with the transmitter and receiver. These results are provided in the TxI/R (transmit interrupt result) or RxI/R (receiver interrupt result) registers, respectively. The 8273 notifies the processor that a result is available with the TxIRA and RxIRA bits of the status register. Results consist of one-byte result interrupt code indicating the condition for the interrupt and, if required, one or more bytes supplying additional information. The "Result Code Summary" table later in this section provides information on the format and decode of the transmitter and receiver results.

The following are typical frame transmit and receive sequences. These examples assume DMA is utilized for data transfer operations.

Transmit

Before a frame can be transmitted, the DMA controller is supplied, by the communication software, the starting address for the desired information field. The 8273 is then commanded to transmit a frame (by issuing a transmit frame command).

After a command, but before transmission begins, the 8273 needs some more information (parameters). Four parameters are required for the transmit frame command; the frame address field byte, the frame control field byte, and two bytes which are the least significant and most significant bytes of the information field byte length. Once all four parameters are loaded, the 8273 makes RTS (request to send) active and waits for CTS (clear to send) to go active from the modem interface. Once CTS is active, the 8273 starts the frame transmission. While the 8273 is transmitting the opening flag, address field, and control field, it starts making transmitter DMA requests. These requests continue at character (byte) boundaries until the pre-loaded number of bytes of information field have been transmitted. At this point, the requests stop, the FCS (frame check sequence) and closing flag are transmitted, and the TxINT line is raised, signaling the processor the frame transmission is complete and the result should be read. Note that after the initial command and parameter loading, no processor intervention was required (since DMA is used for data transfers) until the entire frame was transmitted.

General Receive

Receiver operation is very similar. Like the initial transmit sequence, the processor's DMA controller is loaded with a starting address for a receive data buffer and the 8273 is commanded to receive. Unlike the transmitter, there are two different receive commands; a general receive, where all received frames are transferred to memory, and selective receive, where only frames having an address field matching one of two preprogrammed 8273 address fields are transferred to memory.

(This example covers a general receive operation.) After the receive command, two parameters are required before the receiver becomes active; the least significant and most significant bytes of the receiver buffer length. Once these bytes are loaded, the receiver is active and the processor may return to other tasks. The next frame appearing at the receiver input is transferred to memory using receiver DMA requests. When the closing flag is received, the 8273 checks the FCS and raises its RxINT line. The processor can then read the results, which indicate if the frame was error-free or not. (If the received frame had been longer than the pre-loaded buffer length, the processor would have been notified of that occurrence earlier with a receiver error interrupt. Like the transmit example, after the initial command, the processor is free for other tasks until a frame is completely received.

Selective Receive

In selective receive, two parameters (A1 and A2) are required in addition to those for general receive. These parameters are two address match bytes. When commanded to selective receive, the 8273 passes to memory or the processor only those frames having an address field matching either A1 or A2. This command is usually used for secondary stations with A1 designating the secondary address and A2 being the "all parties" address. If only one match byte is needed, A1 and A2 should be equal. As in general receive, the 8273 counts the incoming data bytes and interrupts the processor if the received frame is larger than the preset receive buffer length.

Result Code Summary

	Hex Code	Result	Status After Interrupt
T r a n s m i t	0C	Early Transmit Interrupt	Transmitter Active
	0D	Frame Transmit Complete	Idle or Flags
	0E	DMA Underrun	Abort
	0F	Clear to Send Error	Abort
	10	Abort Complete	Idle or Flags
R e c e i v e	X0	A1 Match or General Receive	Active
	X1	A2 Match	Active
	03	CRC Error	Active
	04	Abort Detected	Active
	05	Idle Detected	Disabled
	06	EOP Detected	Disabled
	07	Frame Less Than 32 Bits	Active
	08	DMA Overrun	Disabled
	09	Memory Buffer Overflow	Disabled
	0A	Carrier Detect Failure	Disabled
	0B	Receiver Interrupt Overrun	Disabled
Note: X decodes to number of bits in partial byte received.			

The first two codes in the receive result code table result from the error free reception of a frame. Since SDLC allows frames of arbitrary length (>32 bits), the high order bits of the receive result report the number of valid received bits in the last received information field byte. The chart below shows the decode of this receive result bit.

X	Bits Received in Last Byte
E	All Eight Bits of Last Byte
0	Bit0 Only
8	Bit1-Bit0
4	Bit2-Bit0
C	Bit3-Bit0
2	Bit4-Bit0
A	Bit5-Bit0
6	Bit6-Bit0

Address and Interrupt Information

The following tables provide address and interrupt information for the SDLC adapter:

Hex Code	Device	Register Name	Function
380	8255	Port A Data	Internal/External Sensing
381	8255	Port B Data	External Modem Interface
382	8255	Port C Data	Internal Control
383	8255	Mode Set	8255 Mode Initialization
384	8253	Counter 0 LSB	Square Wave Generator
384	8253	Counter 0 MSB	Square Wave Generator
385	8253	Counter 1 LSB	Inactivity Time-Outs
385	8253	Counter 1 MSB	Inactivity Time-Outs
386	8253	Counter 2 LSB	Inactivity Time-Outs
386	8253	Counter 2 MSB	Inactivity Time-Outs
387	8253	Mode Register	8253 Mode Set
388	8273	Command/Status	Out=Command In=Status
389	8273	Parameter/Result	Out=Parameter In=Status
38A	8273	Transmit INT Status	DMA/INT
38B	8273	Receive INT Status	DMA/INT
38C	8273	Data	DPC (Direct Program Control)

SDLC Communications Adapter Device Addresses

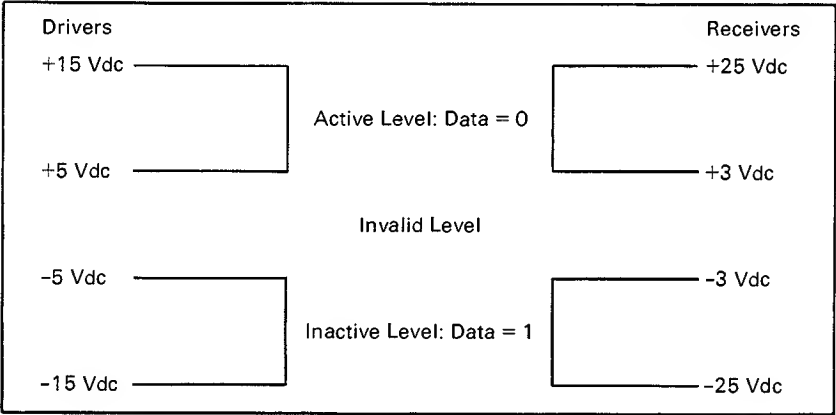
Interrupt Level 3	Transmit/Receive Interrupt
Interrupt Level 4	Timer 1 Interrupt Timer 2 Interrupt Clear to Send Changed Data Set Ready Changed
DMA Level One is used for Transmit and Receive	

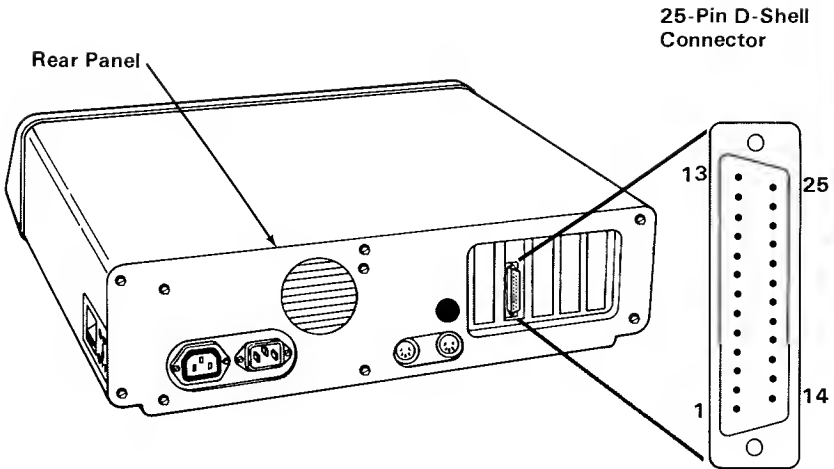
Interrupt Information

Interface Information

The SDLC communications adapter conforms to interface signal levels standardized by the Electronics Industries Association RS-232C Standard. These levels are shown in the figure below.

Additional lines used but not standardized by EIA are pins 11, 18, and 25. These lines are designated as select standby, test and test indicate, respectively. Select Standby is used to support the switched network backup facility of a modem providing this option. Test and test indicate support a modem wrap function on modems which are designed for business machine controlled modem wraps. Two jumpers on the adapter (P1 and P2) are used to connect test and test indicate to the interface, if required (see Appendix D for these jumpers).





Signal Name — Description		Pin
No Connection		1
Transmitted Data		2
Received Data		3
Request to Send		4
Clear to Send		5
Data Set Ready		6
Signal Ground		7
Received Line Signal Detector		8
No Connection		9
No Connection		10
Select Standby*		11
No Connection		12
No Connection		13
No Connection		14
Transmitter Signal Element Timing		15
No Connection		16
Receiver Signal Element Timing		17
Test (IBM Modems Only)*		18
No Connection		19
Data Terminal Ready		20
No Connection		21
Ring Indicator		22
Data Signal Rate Selector		23
No Connection		24
Test Indicate (IBM Modems Only)*		25

*Not standardized by EIA (Electronics Industry Association).

Connector Specifications

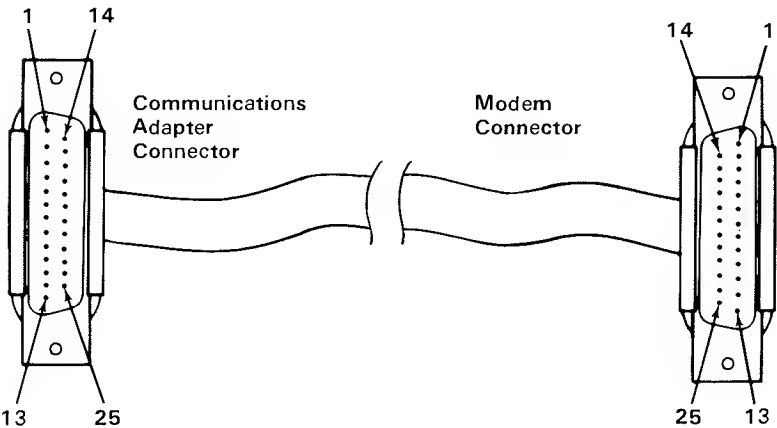
Notes:

IBM Communications Adapter Cable

The IBM Communications Adapter Cable is a ten foot cable for connection of an IBM communications adapter to a modem or other RS-232C DCE (data communications equipment). It is fully shielded and provides a high quality, low noise channel for interface between the communications adapter and DCE.

The connector ends are 25-pin D-shell connectors. All pin connections conform with the EIA RS-232C standard. In addition, connection is provided on pins 11, 18 and 25. These pins are designated as select standby, test and test indicate, respectively, on some modems. Select standby is used to support the switched network backup facility, if applicable. Test and test indicate support a modem wrap function on modems designed for business machine controlled modem wraps.

The IBM Communications Adapter Cable connects the following pins on the 25-pin D-shell connectors.



Communications Adapter Connector Pin #	Name	Modem Connector Pin #
NC	Outer Cable Shield	1
2	Transmitted Data	2
3	Received Data	3
4	Request to Send	4
5	Clear to Send	5
6	Data Set Ready	6
7	Signal Ground (Inner Lead Shields)	7
8	Received Line Signal Detector	8
NC		NC
NC		NC
11	Select Standby	11
NC		NC
NC		NC
NC		NC
15	Transmitter Signal Element Timing	15
NC		NC
17	Receiver Signal Element Timing	17
18	Test	18
NC		NC
20	Data Terminal Ready	20
NC		NC
22	Ring Indicator	22
23	Data Signal Rate Selector	23
NC		NC
25	Test Indicate	25

Connector Specifications

SECTION 2: ROM BIOS AND SYSTEM USAGE

ROM BIOS	2-2
Keyboard Encoding and Usage	2-11
BIOS Cassette Logic	2-21

Notes:

ROM BIOS

The basic input/output system (BIOS) resides in ROM on the system board and provides device level control for the major I/O devices in the system. Additional ROM modules may be located on option adapters to provide device level control for that option adapter. BIOS routines enable the assembly language programmer to perform block (disk and diskette) or character-level I/O operations without concern for device address and operating characteristics. System services, such as time-of-day and memory size determination, are provided by the BIOS.

The goal is to provide an operational interface to the system and relieve the programmer of the concern about the characteristics of hardware devices. The BIOS interface insulates the user from the hardware, thus allowing new devices to be added to the system, yet retaining the BIOS level interface to the device. In this manner, user programs become transparent to hardware modifications and enhancements.

The IBM Personal Computer MACRO Assembler manual and the IBM Personal Computer Disk Operating System (DOS) manual provide useful programming information related to this section. A complete listing of the BIOS is given in Appendix A.

Use of BIOS

Access to BIOS is through the 8088 software interrupts. Each BIOS entry point is available through its own interrupt, which can be found in the "8088 Software Interrupt Listing."

The software interrupts, hex 10 through hex 1A, each access a different BIOS routine. For example, to determine the amount of memory available in the system,

INT 12H

will invoke the BIOS routine for determining memory size and will return the value to the caller.

Parameter Passing

All parameters passed to and from the BIOS routines go through the 8088 registers. The prolog of each BIOS function indicates the registers used on the call and the return. For the memory size example, no parameters are passed. The memory size, in 1K byte increments, is returned in the AX register.

If a BIOS function has several possible operations, the AH register is used at input to indicate the desired operation. For example, to set the time of day, the following code is required:

```
MOV  AH,1           ;function is to set time of day.
MOV  CX,HIGH_COUNT ;establish the current time.
MOV  DX,LOW_COUNT
INT  1AH           ;set the time.
```

To read the time of day:

```
MOV  AH,0           ;function is to read time of
                    ;day.
INT  1AH           ;read the timer.
```

Generally, the BIOS routines save all registers except for AX and the flags. Other registers are modified on return only if they are returning a value to the caller. The exact register usage can be seen in the prolog of each BIOS function.

Address (Hex)	Interrupt Number	Name	BIOS Entry
0-3	0	Divide by Zero	D_EOI
4-7	1	Single Step	D_EOI
8-B	2	Nonmaskable	NMI_INT
C-F	3	Breakpoint	D_EOI
10-13	4	Overflow	D_EOI
14-17	5	Print Screen	PRINT_SCREEN
18-1B	6	Reserved	D_EOI
1D-1F	7	Reserved	D_EOI
20-23	8	Time of Day	TIMER_INT
24-27	9	Keyboard	KB_INT
28-2B	A	Reserved	D_EOI
2C-2F	B	Communications	D_EOI
30-33	C	Communications	D_EOI
34-37	D	Disk	D_EOI
38-3B	E	Diskette	DISK_INT
3C-3F	F	Printer	D_EOI
40-43	10	Video	VIDEO_IO
44-47	11	Equipment Check	EQUIPMENT
48-4B	12	Memory	MEMORY_SIZE_DETERMINE
4C-4F	13	Diskette/Disk	DISKETTE_IO
50-53	14	Communications	RS232_IO
54-57	15	Cassette	CASSETTE_IO
58-5B	16	Keyboard	KEYBOARD_IO
5C-5F	17	Printer	PRINTER_IO
60-63	18	Resident BASIC	F600:0000
64-67	19	Bootstrap	BOOT_STRAP
68-6B	1A	Time of Day	TIME_OF_DAY
6C-6F	1B	Keyboard Break	DUMMY_RETURN
70-73	1C	Timer Tick	DUMMY_RETURN
74-77	1D	Video Initialization	VIDEO_PARMS
78-7B	1E	Diskette Parameters	DISK_BASE
7C-7F	1F	Video Graphics Chars	0

8088 Software Interrupt Listing

Vectors with Special Meanings

Interrupt Hex 1B – Keyboard Break Address

This vector points to the code to be exercised when the Ctrl and Break keys are pressed on the keyboard. The vector is invoked while responding to the keyboard interrupt, and control should be returned through an IRET instruction. The power-on routines initialize this vector to point to an IRET instruction, so that nothing will occur when the Ctrl and Break keys are pressed unless the application program sets a different value.

Control may be retained by this routine, with the following problems. The Break may have occurred during interrupt processing, so that one or more End of Interrupt commands must be sent to the 8259 controller. Also, all I/O devices should be reset in case an operation was underway at that time.

Interrupt Hex 1C – Timer Tick

This vector points to the code to be executed on every system-clock tick. This vector is invoked while responding to the timer interrupt, and control should be returned through an IRET instruction. The power-on routines initialize this vector to point to an IRET instruction, so that nothing will occur unless the application modifies the pointer. It is the responsibility of the application to save and restore all registers that will be modified.

Interrupt Hex 1D – Video Parameters

This vector points to a data region containing the parameters required for the initialization of the 6845 on the video card. Note that there are four separate tables, and all four must be reproduced if all modes of operation are to be supported. The power-on routines initialize this vector to point to the parameters contained in the ROM video routines.

Interrupt Hex 1E – Diskette Parameters

This vector points to a data region containing the parameters required for the diskette drive. The power-on routines initialize the vector to point to the parameters contained in the ROM diskette routine. These default parameters represent the specified values for any IBM drives attached to the machine. Changing this parameter block may be necessary to reflect the specifications of the other drives attached.

Interrupt Hex 1F – Graphics Character Extensions

When operating in the graphics modes of the IBM Color/Graphics Monitor Adapter (320 by 200 or 640 by 200), the read/write character interface will form the character from the ASCII code point, using a set of dot patterns. The dot patterns for the first 128 code points are contained in ROM. To access the second 128 code points, this vector must be established to point at a table of up to 1K bytes, where each code point is represented by eight bytes of graphic information. At power-on, this vector is initialized to 000:0, and it is the responsibility of the user to change this vector if the additional code points are required.

Interrupt Hex 40 – Reserved

When an IBM Fixed Disk Drive Adapter is installed, the BIOS routines use interrupt hex 40 to revector the diskette pointer.

Interrupt Hex 41 – Fixed Disk Parameters

This vector points to a data region containing the parameters required for the fixed disk drive. The power-on routines initialize the vector to point to the parameters contained in the ROM disk routine. These default parameters represent the specified values for any IBM Fixed Disk Drives attached to the machine. Changing this parameter block may be necessary to reflect the specifications of the other fixed disk drives attached.

Other Read/Write Memory Usage

The IBM BIOS routines use 256 bytes of memory starting at absolute hex 400 to hex 4FF. Locations hex 400 to 407 contain the base addresses of any RS-232C cards attached to the system. Locations hex 408 to 40F contain the base addresses of the printer adapter.

Memory locations hex 300 to 3FF are used as a stack area during the power-on initialization, and bootstrap, when control is passed to it from power-on. If the user desires the stack in a different area, the area must be set by the application.

Address (Hex)	Interrupt (Hex)	Function
80-83	20	DOS Program Terminate
84-87	21	DOS Function Call
88-8B	22	DOS Terminate Address
8C-8F	23	DOS Ctrl Break Exit Address
90-93	24	DOS Fatal Error Vector
94-97	25	DOS Absolute Disk Read
98-9B	26	DOS Absolute Disk Write
9C-9F	27	DOS Terminate, Fix In Storage
A0-FF	28-3F	Reserved for DOS
100-17F	40-5F	Reserved
180-19F	60-67	Reserved for User Software Interrupts
1A0-1FF	68-7F	Not Used
200-217	80-85	Reserved by BASIC
218-3C3	86-F0	Used by BASIC Interpreter while BASIC is running
3C4-3FF	F1-FF	Not Used

BASIC and DOS Reserved Interrupts

Address (Hex)	Mode	Function
400-48F	ROM BIOS	See BIOS Listing
490-4EF		Reserved
4F0-4FF		Reserved as Intra-Application Communication Area for any application
500-5FF	DOS	Reserved for DOS and BASIC
500		Print Screen Status Flag Store
		0-Print Screen Not Active or Successful
		Print Screen Operation
		1-Print Screen In Progress
	DOS	255-Error Encountered during Print Screen Operation
504		Single Drive Mode Status Byte
510-511		BASIC's Segment Address Store
512-515	BASIC	Clock Interrupt Vector Segment: Offset Store
516-519	BASIC	Break Key Interrupt Vector Segment: Offset Store
51A-51D	BASIC	Disk Error Interrupt Vector Segment: Offset Store

Reserved Memory Locations

If you do DEF SEG (Default workspace segment):

	Offset (Hex Value)	Length
Line number of current line being executed	2E	2
Line number of last error	347	2
Offset into segment of start of program text	30	2
Offset into segment of start of variables (end of program text 1-1)	358	2
Keyboard buffer contents	6A	1
if 0-no characters in buffer		
if 1-characters in buffer		
Character color in graphics mode	4E	1
Set to 1, 2, or 3 to get text in colors 1 to 3.		
Do not set to 0.		
(Default = 3)		
<p>Example</p> <p>100 Print PEEK (&H2E) + 256*PEEK (&H2F)</p> <p style="margin-left: 40px;"> \int <div style="display: inline-block; text-align: center; margin: 0 10px;">L</div> <div style="display: inline-block; text-align: center; margin: 0 10px;">H</div> </p> <p style="margin-left: 40px;">100</p> <div style="display: flex; justify-content: space-around; width: 150px; margin-left: 40px;"> <div style="border: 1px solid black; padding: 2px 10px;">Hex 64</div> <div style="border: 1px solid black; padding: 2px 10px;">Hex 00</div> </div>		

BASIC Workspace Variables

Starting Address in Hex

00000	BIOS Interrupt Vectors
00080	Available Interrupt Vectors
00400	BIOS Data Area
00500	User Read/Write Memory
C8000	Disk Adapter
F0000	Read Only Memory
FE000	Bios Program Area

BIOS Memory Map

BIOS Programming Hints

The BIOS code is invoked through software interrupts. The programmer should not “hard code” BIOS addresses into applications. The internal workings and absolute addresses within BIOS are subject to change without notice.

If an error is reported by the disk or diskette code, you should reset the drive adapter and retry the operation. A specified number of retries should be required on diskette reads to ensure the problem is not due to motor start-up.

When altering I/O port bit values, the programmer should change only those bits which are necessary to the current task. Upon completion, the programmer should restore the original environment. Failure to adhere to this practice may be incompatible with present and future applications.

Adapter Cards with System-Accessible ROM Modules

The ROM BIOS provides a facility to integrate adapter cards with on board ROM code into the system. During the POST, interrupt vectors are established for the BIOS calls. After the default vectors are in place, a scan for additional ROM modules takes place. At this point, a ROM routine on the adapter card may gain control. The routine may establish or intercept interrupt vectors to hook themselves into the system.

The absolute addresses hex C8000 through hex F4000 are scanned in 2K blocks in search of a valid adapter card ROM. A valid ROM is defined as follows:

- Byte 0: Hex 55
- Byte 1: Hex AA
- Byte 2: A length indicator representing the number of 512 byte blocks in the ROM (length/512).
A checksum is also done to test the integrity of the ROM module. Each byte in the defined ROM is summed modulo hex 100. This sum must be 0 for the module to be deemed valid.

When the POST identifies a valid ROM, it does a far call to byte 3 of the ROM (which should be executable code). The adapter card may now perform its power-on initialization tasks. The feature ROM should return control to the BIOS routines by executing a far return.

Notes:

Keyboard Encoding and Usage

Encoding

The keyboard routine provided by IBM in the ROM BIOS is responsible for converting the keyboard scan codes into what will be termed “Extended ASCII.”

Extended ASCII encompasses one-byte character codes with possible values of 0 to 255, an extended code for certain extended keyboard functions, and functions handled within the keyboard routine or through interrupts.

Character Codes

The following character codes are passed through the BIOS keyboard routine to the system or application program. A “-1” means the combination is suppressed in the keyboard routine. The codes are returned in AL. See Appendix C for the exact codes. Also, see “Keyboard Scan Code Diagram” in Section 1.

Key Number	Base Case	Upper Case	Ctrl	Alt
1	Esc	Esc	Esc	-1
2	1	!	-1	Note 1
3	2	@	Nul (000) Note 1	Note 1
4	3	#	-1	Note 1
5	4	\$	-1	Note 1
6	5	%	-1	Note 1
7	6	^	RS(030)	Note 1
8	7	&	-1	Note 1
9	8	*	-1	Note 1
10	9	(-1	Note 1
11	0)	-1	Note 1
12	-	_	US(031)	Note 1
13	=	+	-1	Note 1
14	Backspace (008)	Backspace (008)	Del (127)	-1
15	→ (009)	← (Note 1)	-1	-1
16	q	Q	DC1 (017)	Note 1
17	w	W	ETB (023)	Note 1

Key Number	Base Case	Upper Case	Ctrl	Alt
18	e	E	ENQ (005)	Note 1
19	r	R	DC2 (018)	Note 1
20	t	T	DC4 (020)	Note 1
21	y	Y	EM (025)	Note 1
22	u	U	NAK (021)	Note 1
23	i	I	HT (009)	Note 1
24	o	O	SI (015)	Note 1
25	p	P	DLE (016)	Note 1
26	[{	Esc (027)	-1
27]	}	GS (029)	-1
28	CR	CR	LF (010)	-1
29 Ctrl	-1	-1	-1	-1
30	a	A	SOH (001)	Note 1
31	s	S	DC3 (019)	Note 1
32	d	D	EOT (004)	Note 1
33	f	F	ACK (006)	Note 1
34	g	G	BEL (007)	Note 1
35	h	H	BS (008)	Note 1
36	j	J	LF (010)	Note 1
37	k	K	VT (011)	Note 1
38	l	L	FF (012)	Note 1
39	;	:	-1	-1
40	'	"	-1	-1
41	`	~	-1	-1
42 Shift	-1	-1	-1	-1
43	\		FS (028)	-1
44	z	Z	SUB (026)	Note 1
45	x	X	CAN (024)	Note 1
46	c	C	ETX (003)	Note 1
47	v	V	SYN (022)	Note 1
48	b	B	STX (002)	Note 1
49	n	N	SO (014)	Note 1
50	m	M	CR (013)	Note 1
51	,	<	-1	-1
52	.	>	-1	-1
53	/	?	-1	-1
54 Shift	-1	-1	-1	-1
55	*	(Note 2)	(Note 1)	-1
56 Alt	-1	-1	-1	-1
57	SP	SP	SP	SP
58 Caps Lock	-1	-1	-1	-1
59	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
60	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
61	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
62	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
63	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
64	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)

Character Codes (Part 2 of 3)

2-14 Keyboard Encoding

Key Number	Base Case	Upper Case	Ctrl	Alt
65	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
66	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
67	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
68	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)	Nul (Note 1)
69 Num Lock	-1	-1	Pause (Note 2)	-1
70 Scroll Lock	-1	-1	Break (Note 2)	-1
Notes: 1. Refer to "Extended Codes" in this section. 2. Refer to "Special Handling" in this section.				

Character Codes (Part 3 of 3)

Keys 71 to 83 have meaning only in base case, in Num Lock (or shifted) states, or in Ctrl state. It should be noted that the shift key temporarily reverses the current Num Lock state.

Key Number	Num Lock	Base Case	Alt	Ctrl
71	7	Home (Note 1)	-1	Clear Screen
72	8	↑ (Note 1)	-1	-1
73	9	Page Up (Note 1)	-1	Top of Text and Home
74	-	-----	-1	-1
75	4	← (Note 1)	-1	Reverse Word (Note 1)
76	5	-1	-1	-1
77	6	→ (Note 1)	-1	Advance Word (Note 1)
78	+	+	-1	-1
79	1	End (Note 1)	-1	Erase to EOL (Note 1)
80	2	↓ (Note 1)	-1	-1
81	3	Page Down (Note 1)	-1	Erase to EOS (Note 1)
82	0	Ins	-1	-1
83	.	Del (Notes 1,2)	Note 2	Note 2
Notes: 1. Refer to "Extended Codes" in this section. 2. Refer to "Special Handling" in this section.				

Extended Codes

Extended Functions

For certain functions that cannot be represented in the standard ASCII code, an extended code is used. A character code of 000 (Nul) is returned in AL. This indicates that the system or application program should examine a second code that will indicate the actual function. Usually, but not always, this second code is the scan code of the primary key that was pressed. This code is returned in AH.

Second Code	Function
3	Nul Character
15	←
16-25	Alt Q, W, E, R, T, Y, U, I, O, P
30-38	Alt A, S, D, F, G, H, J, K, L
44-50	Alt Z, X, C, V, B, N, M
59-68	F1 to F10 Function Keys Base Case
71	Home
72	↑
73	Page Up and Home Cursor
75	←
77	→
79	End
80	↓
81	Page Down and Home Cursor
82	Ins (Insert)
83	Del (Delete)
84-93	F11 to F20 (Uppercase F1 to F10)
94-103	F21 to F30 (Ctrl F1 to F10)
104-113	F31 to F40 (Alt F1 to F10)
114	Ctrl PrtSc (Start/Stop Echo to Printer)
115	Ctrl ← (Reverse Word)
116	Ctrl → (Advance Word)
117	Ctrl End [Erase to End of Line (EOL)]
118	Ctrl PgDn [Erase to End of Screen (EOS)]
119	Ctrl Home (Clear Screen and Home)
120-131	Alt 1, 2, 3, 4, 5, 6, 7, 8, 9, 0, -, = (Keys 2-13)
132	Ctrl PgUp (Top 25 Lines of Text and Home Cursor)

Keyboard Extended Functions

Shift States

Most shift states are handled within the keyboard routine, transparent to the system or application program. In any case, the current set of active shift states are available by calling an entry point in the ROM keyboard routine. The following keys result in altered shift states:

Shift

This key temporarily shifts keys 2-13, 15-27, 30-41, 43-53, 55, and 59-68 to upper case (base case if in Caps Lock state). Also, the Shift key temporarily reverses the Num Lock or non-Num-Lock state of keys 71-73, 75, 77, and 79-83.

Ctrl

This key temporarily shifts keys 3, 7, 12, 14, 16-28, 30-38, 43-50, 55, 59-71, 73, 75, 77, 79, and 81 to the Ctrl state. Also, the Ctrl key is used with the Alt and Del keys to cause the “system reset” function, with the Scroll Lock key to cause the “break” function, and with the Num Lock key to cause the “pause” function. The system reset, break, and pause functions are described in “Special Handling” on the following pages.

Alt

This key temporarily shifts keys 2-13, 16-25, 30-38, 44-50, and 59-68 to the Alt state. Also, the Alt key is used with the Ctrl and Del keys to cause the “system reset” function described in “Special Handling” on the following pages.

The Alt key has another use. This key allows the user to enter any character code from 0 to 255 into the system from the keyboard. The user holds down the Alt key and types the decimal value of the characters desired using the numeric keypad (keys 71-73, 75-77, and 79-82). The Alt key is then released. If more than three digits are typed, a modulo-256 result is created. These three digits are interpreted as a character code and are transmitted through the keyboard routine to the system or application program. Alt is handled internal to the keyboard routine.

Caps Lock

This key shifts keys 16-25, 30-38, and 44-50 to upper case. A second depression of the Caps Lock key reverses the action. Caps Lock is handled internal to the keyboard routine.

Scroll Lock

This key is interpreted by appropriate application programs as indicating use of the cursor-control keys should cause windowing over the text rather than cursor movement. A second depression of the Scroll Lock key reverses the action. The keyboard routine simply records the current shift state of the Scroll Lock key. It is the responsibility of the system or application program to perform the function.

Shift Key Priorities and Combinations

If combinations of the Alt, Ctrl, and Shift keys are pressed and only one is valid, the precedence is as follows: the Alt key is first, the Ctrl key is second, and the Shift key is third. The only valid combination is Alt and Ctrl, which is used in the “system reset” function.

Special Handling

System Reset

The combination of the Alt, Ctrl, and Del keys will result in the keyboard routine initiating the equivalent of a “system reset” or “reboot.” System reset is handled internal to the keyboard.

Break

The combination of the Ctrl and Break keys will result in the keyboard routine signaling interrupt hex 1A. Also, the extended characters (AL = hex 00, AH = hex 00) will be returned.

Pause

The combination of the Ctrl and Num Lock keys will cause the keyboard interrupt routine to loop, waiting for any key except the Num Lock key to be pressed. This provides a system- or application-transparent method of temporarily suspending list, print, and so on, and then resuming the operation. The “unpause” key is thrown away. Pause is handled internal to the keyboard routine.

Print Screen

The combination of the Shift and PrtSc (key 55) keys will result in an interrupt invoking the print screen routine. This routine works in the alphanumeric or graphics mode, with unrecognizable characters printing as blanks.

Other Characteristics

The keyboard routine does its own buffering. The keyboard buffer is large enough to support a fast typist. However, if a key is entered when the buffer is full, the key will be ignored and the “bell” will be sounded.

Also, the keyboard routine suppresses the typematic action of the following keys: Ctrl, Shift, Alt, Num Lock, Scroll Lock, Caps Lock, and Ins.

Keyboard Usage

This section is intended to outline a set of guidelines of key usage when performing commonly used functions.

Function	Key(s)	Comment
Home Cursor	Home	Editors; word processors
Return to outermost menu	Home	Menu driven applications
Move cursor up	↑	Full screen editor, word processor
Page up, scroll backward 25 lines and home	PgUp	Editors; word processors
Move cursor left	← Key 75	Text, command entry
Move cursor right	→	Text, command entry
Scroll to end of text Place cursor at end of line	End	Editors; word processors
Move cursor down	↓	Full screen editor, word processor
Page down, scroll forward 25 lines and home	Pg Dn	Editors; word processors
Start/Stop insert text at cursor, shift text right in buffer	Ins	Text, command entry
Delete character at cursor	Del	Text, command entry
Destructive backspace	← Key 14	Text, command entry
Tab forward	→	Text entry
Tab reverse	←	Text entry
Clear screen and home	Ctrl Home	Command entry
Scroll up	↑	In scroll lock mode
Scroll down	↓	In scroll lock mode
Scroll left	←	In scroll lock mode
Scroll right	→	In scroll lock mode
Delete from cursor to EOL	Ctrl End	Text, command entry
Exit/Escape	Esc	Editor, 1 level of menu, and so on
Start/Stop Echo screen to printer	Ctrl Prt Sc (Key 55)	Any time
Delete from cursor to EOS	Ctrl PgDn	Text, command entry
Advance word	Ctrl →	Text entry
Reverse word	Ctrl ←	Text entry
Window Right	Ctrl →	When text is too wide to fit screen
Window Left	Ctrl ←	When text is too wide to fit screen
Enter insert mode	Ins	Line editor

Keyboard - Commonly Used Functions (Part 1 of 2)

2-20 Keyboard Encoding

Function	Key(s)	Comment
Exit insert mode	Ins	Line editor
Cancel current line	Esc	Command entry, text entry
Suspend system (pause)	Ctrl Num Lock	Stop list, stop program, and so on Resumes on any key
Break interrupt	Ctrl Break	Interrupt current process
System reset	Alt Ctrl Del	Reboot
Top of document and home cursor	Ctrl PgUp	Editors, word processors
Standard function keys	F1-F10	Primary function keys
Secondary function keys	Shift F1-F10 Ctrl F1-F10 Alt F1-F10	Extra function keys if 10 are not sufficient
Extra function keys	Alt Keys 2-13 (1-9,0,-,=)	Used when stickers are put along top of keyboard
Extra function keys	Alt A-Z	Used when function starts with same letter as one of the alpha keys

Keyboard - Commonly Used Functions (Part 2 of 2)

Function	Key
Carriage return	↵
Line feed	Ctrl ↵
Bell	Ctrl G
Home	Home
Cursor up	↑
Cursor down	↓
Cursor left	←
Cursor right	→
Advance one word	Ctrl →
Reverse one word	Ctrl ←
Insert	Ins
Delete	Del
Clear screen	Ctrl Home
Freeze output	Ctrl Num Lock
Tab advance	→
Stop execution (break)	Ctrl Break
Delete current line	Esc
Delete to end of line	Ctrl End
Position cursor to end of line	End

BASIC Screen Editor Special Functions

Function	Key
Suspend	Ctrl Num Lock
Echo to printer	Ctrl PrtSc (Key 55 any case)
Stop echo to printer	Ctrl PrtSc (Key 55 any case)
Exit current function (break)	Ctrl Break
Backspace	← Key 14
Line feed	Ctrl ↵
Cancel line	Esc
Copy character	F1 or →
Copy until match	F2
Copy remaining	F3
Skip character	Del
Skip until match	F4
Enter skip mode	Ins
Exit insert mode	Ins
Make new line the template	F5
String separator in REPLACE	F6
End of file in keyboard input	F6

DOS Special Functions

BIOS Cassette Logic

Software Algorithms – Interrupt Hex 15

The cassette routine will be called by the request type in AH. The address of the bytes to be read from or written to the tape will be specified by ES:BX and the number of bytes to be read or written will be specified by CX. The actual number of bytes read will be returned in DX. The read block and write block will automatically turn the cassette motor on at the start and off at the end. The request types in AH and the cassette status descriptions follow:

Request Type	Function
AH = 0	Turn Cassette Motor On
AH = 1	Turn Cassette Motor Off
AH = 2	Read Tape Block Read CX bytes into memory starting at Address ES:BX Return actual number of bytes read in DX Return Cassette Status in AH
AH = 3	Write Tape Block Write CX bytes onto cassette starting at Address DS:BX Return Cassette Status in AH

Cassette Status	Description
AH = 00	No Errors
AH = 01	Cyclic Redundancy Check (CRC) Error in Read Block
AH = 02	No Data Transitions
AH = 04	No Leader
AH = 80	Invalid Command

Note: The carry flag will be set on any error.

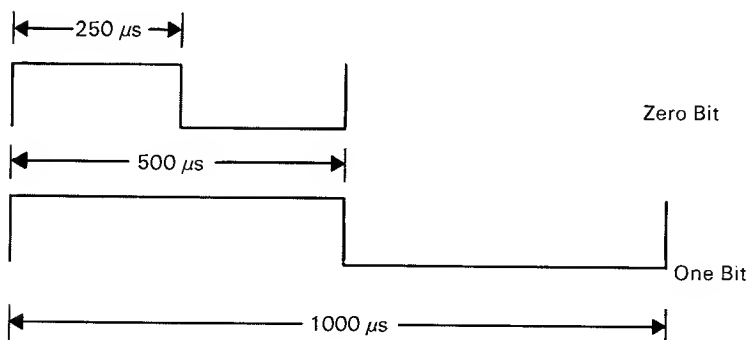
Cassette Write

The write-block routine writes a tape block onto the cassette tape. The block is described in “Data Record Architecture” later in this section.

The write-block routine turns on the cassette drive motor and a synchronization bit (0) and then writes the leader (256 bytes of all 1's) to the tape. Next, the routine writes the number of data blocks specified by CX. After each data block of 256 bytes, a 2-byte cyclic redundancy check (CRC) is written. The data bytes are taken from the memory location pointed at by ES.

The write-byte routine disassembles and writes the byte a bit at a time to the cassette. The method used is to set Timer 2 to the period of the desired data bit. The timer is set to a period of 1.0 millisecond for a 1 bit and 0.5 millisecond for a 0 bit.

The timer is set to mode 3, which means the timer outputs a square wave with a period given by its counter register. The timer's period is changed on the fly for each data bit written to the cassette. If the number of data bytes to be written is not an integral multiple of 256, then, after the last desired data byte from memory has been written, the data block is extended to 256 bytes of writing multiples of the last data byte. The last block is closed with two CRC bytes as usual. After the last data block, a trailer consisting of four bytes of all 1 bits is written. Finally, the cassette motor is turned off, if there are no errors reported by the routine.



Cassette Read

The read-block routine turns on the cassette drive motor and then delays for approximately 0.5 second to allow the motor to come up to speed.

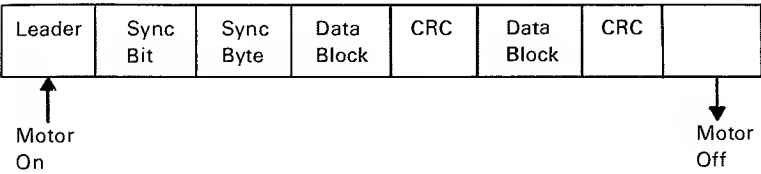
The read-block routine then searches for the leader and must detect all 1 bits for approximately 1/4 of the leader length before it can look for the sync (0) bit. After the sync bit is detected, the sync byte (ASCII character hex 16) is read. If the sync byte is read correctly, the data portion can be read. If a correct sync byte is not found, the routine goes back and searches for the leader again. The data is read a bit at a time and assembled into bytes. After each byte is assembled, it is written into memory at location ES:BX and BX is incremented by 1.

After each multiple of 256 data bytes is read, the CRC is read and compared to the CRC generated. If a CRC error is detected, the routine will exit with the carry flag set to indicate an error and the status of AH set to hex 01. DX will contain the number of bytes written memory.

The time of day interrupt (IRQ0) is disabled during the cassette-read operation.

Data Record Architecture

The write-block routine uses the following format to record a tape block onto a cassette tape:



Component	Description
Leader	256 Bytes (of All 1's)
Sync Bit	One 0 Bit
Sync Byte	ASCII Character Hex 16
Data Blocks	256 Bytes in Length
CRC	2 Bytes for each Data Block

Data Record Components

Error Recovery

Error recovery is handled through software. A CRC is used to detect errors. The polynomial used is $G(X) = X^{16} + X^{12} + X^5 + 1$, which is the polynomial used by the synchronous data link control interface. Essentially, as bits are written to or read from the cassette tape, they are passed through the CRC register in software. After a block of data is written, the complemented value of the calculated CRC register is written on the tape. Upon reading the cassette data, the CRC bytes are read and compared to the generated CRC value. If the read CRC does not equal the generated CRC, the processor's carry flag is set and the status of AH is set to hex 01, which indicates a CRC error has occurred. Also, the routine is exited on a CRC error.

APPENDIX A: ROM BIOS LISTINGS

	Page	Line Number
System ROM BIOS		
Equates	A-2	12
8088 Interrupt Locations	A-2	34
Stack	A-2	66
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Power-On Self-Test	A-5	229
Boot Strap Loader	A-21	1493
I/O Support		
Asynchronous Communications		
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Keyboard	A-26	1818
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System Configuration Analysis		
Memory Size Determination	A-73	5177
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Time of Day	A-82	5903
Print Screen	A-84	6077

Fixed Disk ROM BIOS

Fixed Disk I/O Interface	A-87	1
Boot Strap Loader	A-92	399

```

1  $TITLE(BIOS FOR IBM PERSONAL COMPUTER)
2
3  ;-----
4  ;   THE BIOS ROUTINES ARE MEANT TO BE ACCESSED THROUGH   :
5  ;   SOFTWARE INTERRUPTS ONLY.  ANY ADDRESSES PRESENT IN   :
6  ;   THE LISTINGS ARE INCLUDED ONLY FOR COMPLETENESS,      :
7  ;   NOT FOR REFERENCE.  APPLICATIONS WHICH REFERENCE      :
8  ;   ABSOLUTE ADDRESSES WITHIN THE CODE SEGMENT           :
9  ;   VIOLATE THE STRUCTURE AND DESIGN OF BIOS.             :
10 ;-----
11
12 ;-----
13 ;               EQUATES                                   :
14 ;-----
0060 15  PORT_A      EQU    60H      ; 8255 PORT A ADDR
0061 16  PORT_B      EQU    61H      ; 8255 PORT B ADDR
0062 17  PORT_C      EQU    62H      ; 8255 PORT C ADDR
0063 18  CMD_PORT    EQU    63H
0020 19  INTA00      EQU    20H      ; 8259 PORT
0021 20  INTA01      EQU    21H      ; 8259 PORT
0020 21  EDI         EQU    20H
0040 22  TIMER       EQU    40H
0043 23  TIM_CTL     EQU    43H      ; 8253 TIMER CONTROL PORT ADDR
0040 24  TIMER0      EQU    40H      ; 8253 TIMER/CNTR 0 PORT ADDR
0001 25  THINT       EQU    D1      ; TIMER 0 INTR RECD MASK
0008 26  DMA00       EQU    D0      ; DMA STATUS REG PORT ADDR
0000 27  DMA         EQU    00      ; DMA CHANNEL 0 ADDR REG PORT ADDR
0540 28  MAX_PERIOD  EQU    540H
0410 29  MIN_PERIOD  EQU    410H
0060 30  KBD_IN       EQU    60H      ; KEYBOARD DATA IN ADDR PORT
0002 31  KBDINT       EQU    D2      ; KEYBOARD INTR MASK
0060 32  KB_DATA     EQU    60H      ; KEYBOARD SCAN CODE PORT
0061 33  KB_CTL       EQU    61H      ; CONTROL BITS FOR KB SENSE DATA
34 ;-----
35 ;               8086 INTERRUPT LOCATIONS                 :
36 ;-----
---- 37  ABS0          SEGMENT AT 0
0000 38  STG_LOCO     LABEL  BYTE
0008 39              ORG    2*4
0008 40  NMI_PTR      LABEL  WORD
0014 41              DRG    5*4
0014 42  INT5_PTR     LABEL  WORD
0020 43              ORG    8*4
0020 44  INT_ADDR     LABEL  WORD
0020 45  INT_PTR      LABEL  QWORD
0040 46              ORG    10H*4
0040 47  VIDED_INT    LABEL  WORD
0074 48              DRG    10H*4
0074 49  PARM_PTR      LABEL  DWORD      ; POINTER TO VIDED PARMS
0060 50              DRG    18H*4
0060 51  BASIC_PTR    LABEL  WORD      ; ENTRY POINT FOR CASSETTE BASIC
0076 52              ORG    01EH*4      ; INTERRUPT 1EH
0078 53  DISK_POINTER  LABEL  DWORD
007C 54              ORG    01FH*4      ; LOCATION OF POINTER
007C 55  EXT_PTR LABEL  DWORD      ; POINTER TO EXTENSION
0100 56              DRG    040H*4      ; ROUTINE
0100 57  IO_ROM_INIT  DW    ?          ;
0102 58  IO_ROM_SEG  DW    ?          ; OPTIONAL ROM SEGMENT
0400 59              DRG    400H
0400 60  DATA_AREA   LABEL  BYTE      ; ABSOLUTE LOCATION OF DATA SEGMENT
0400 61  DATA_WORD   LABEL  WORD
7C00 62              DRG    7C00H
7C00 63  BOOT_LDCN   LABEL  FAR
---- 64  ABS0          ENDS
65
66 ;-----
67 ;   STACK -- USED DURING INITIALIZATION ONLY             :
68 ;-----
0000 69  STACK        SEGMENT AT 30H
---- 70              DW    128 DUP(?)
0100 71  TDS          LABEL  WORD
---- 72  STACK          ENDS
73
74 ;-----
75 ;   ROM BIOS DATA AREAS                                 :
76 ;-----
---- 77  DATA          SEGMENT AT 40H

```


LOC OBJ	LINE	SOURCE			
0000 (4 ????)	78	RS232_BASE	OW	4 DUP(?)	ADDRESSES OF RS232 ADAPTERS
0008 (4 ????)	79	PRINTER_BASE	OW	4 DUP(?)	ADDRESSES OF PRINTERS
0010 ???? 0012 ?? 0013 ???? 0015 ???? 0017 ??	80 81 82 83 84 85 86 87 88 89 90	EQUIP_FLAG HFG_TST MEMORY_SIZE TO_RAM_SIZE ----- KEYBOARD DATA AREAS ----- KB_FLAG	OW OB OW OW ----- ----- OB	? ? ? ? ----- ----- ?	INSTALLED HARDWARE INITIALIZATION FLAG MEMORY SIZE IN K BYTES MEMORY IN I/O CHANNEL ----- ----- SHIFT FLAG EQUATES WITHIN KB_FLAG
0080 0040 0020 0010 0008 0004 0002 0001	91 92 93 94 95 96 97 98 99	INS_STATE CAPS_STATE NUM_STATE SCROLL_STATE ALT_SHIFT CTL_SHIFT LEFT_SHIFT RIGHT_SHIFT	EQU EQU EQU EQU EQU EQU EQU EQU	80H 40H 20H 10H 08H 04H 02H 01H	INSERT STATE IS ACTIVE CAPS LOCK STATE HAS BEEN TOGGLED NUM LOCK STATE HAS BEEN TOGGLED SCROLL LOCK STATE HAS BEEN TOGGLED ALTERNATE SHIFT KEY DEPRESSED CONTROL SHIFT KEY DEPRESSED LEFT SHIFT KEY DEPRESSED RIGHT SHIFT KEY DEPRESSED
0018 ?? 0080 0040 0020 0010 0008	100 101 102 103 104 105 106 107	KB_FLAG_1 INS_SHIFT CAPS_SHIFT NUM_SHIFT SCROLL_SHIFT HOLD_STATE	OB EQU EQU EQU EQU EQU	? 60H 40H 20H 10H 08H	SECOND BYTE OF KEYBOARD STATUS INSERT KEY IS DEPRESSED CAPS LOCK KEY IS DEPRESSED NUM LOCK KEY IS DEPRESSED SCROLL LOCK KEY IS DEPRESSED SUSPEND KEY HAS BEEN TOGGLED
0019 ?? 001A ???? 001C ???? 001E (16 ????)	108 109 110 111	ALT_INPUT BUFFER_HEAD BUFFER_TAIL KB_BUFFER	OB OW OW OW	? ? ? 16 DUP(?)	STORAGE FOR ALTERNATE KEYPAO ENTRY POINTER TO HEAD OF KEYBOARD BUFFER POINTER TO TAIL OF KEYBOARD BUFFER ROOM FOR 15 ENTRIES
003E	112 113 114 115	KB_BUFFER_END ----- HEAD = TAIL INDICATES THAT THE BUFFER IS EMPTY	LABEL ----- -----	WORD ----- -----	
0045 0046 0038 0010 003A 002A 0036 0052 0053	116 117 118 119 120 121 122 123 124 125	NUM_KEY SCROLL_KEY ALT_KEY CTL_KEY CAPS_KEY LEFT_KEY RIGHT_KEY INS_KEY DEL_KEY	EQU EQU EQU EQU EQU EQU EQU EQU EQU	69 70 56 29 56 42 54 82 63	SCAN CODE FOR NUMBER LOCK SCROLL LOCK KEY ALTERNATE SHIFT KEY SCAN CODE SCAN CODE FOR CONTROL KEY SCAN CODE FOR SHIFT LOCK SCAN CODE FOR LEFT SHIFT SCAN CODE FOR RIGHT SHIFT SCAN CODE FOR INSERT KEY SCAN CODE FOR DELETE KEY
003E ?? 0080 003F ?? 0040 ?? 0025	126 127 128 129 130 131 132 133 134 135 136 137 138	----- DISKETTE DATA AREAS ----- SEEK_STATUS INT_FLAG HOTOR_STATUS HOTOR_COUNT HOTOR_WAIT	OB EQU OB OB EQU	? 080H ? ? 37	DRIVE RECALIBRATION STATUS DRIVE 3-0 NEEDS RECAL BEFORE NEXT SEEK IF BIT IS = 0 INTERRUPT OCCURRENCE FLAG HOTOR STATUS DRIVE 3-0 IS CURRENTLY RUNNING CURRENT OP IS A WRITE, REQUIRES DELAY TIME OUT COUNTER FOR DRIVE TURN OFF TWO SEC OF COUNT FOR HOTOR TURN OFF
0041 ?? 0080 0040 0020 0010 0009 0008 0004 0003 0002	139 140 141 142 143 144 145 146 147 148	DISKETTE_STATUS TIME_OUT BAD_SEEK BAD_NEC BAD_CRC DMA_BOUNDARY BAD_DMA RECORD_NOT_FND WRITE_PROTECT BAD_ADOR_MARK	OB EQU EQU EQU EQU EQU EQU EQU EQU EQU EQU	? 80H 40H 20H 10H 09H 08H 04H 03H 02H	BYTE OF RETURN CODE INFO FOR STATUS ATTACHMENT FAILED TO RESPOND SEEK OPERATION FAILED NEC CONTROLLER HAS FAILED BAD CRC ON DISKETTE READ ATTEMPT TO DMA ACROSS 64K BOUNDARY DMA OVERRUN ON OPERATION REQUESTED SECTOR NOT FOUND WRITE ATTEMPTED ON WRITE PROT DISK ADDRESS MARK NOT FOUND

LOC OBJ	LINE	SOURCE
0001	149	BAD_CMD EQU DIH ; BAD COMMAND PASSED TO DISKETTE I/O
	150	
0042 7 ??)	151	NEC_STATUS DB 7 DUP(?) ; STATUS BYTES FROM NEC
	152	
	153	;
	154	VIDEO DISPLAY DATA AREA :
	155	;
0049 ??	156	CRT_MODE DB ? ; CURRENT CRT MODE
004A ???? 004C ???? 004E ???? 0050 8 ????)	157	CRT_COLS DW ? ; NUMBER OF COLUMNS ON SCREEN
	158	CRT_LEN DW ? ; LENGTH OF REGEN IN BYTES
	159	CRT_START DW ? ; STARTING ADDRESS IN REGEN BUFFER
	160	CURSOR_POSN DW 8 DUP(?) ; CURSOR FOR EACH OF UP TO 8 PAGES
0060 ???? 0062 ?? 0063 ???? 0065 ?? 0066 ??	161	CURSOR_MODE DW ? ; CURRENT CURSOR MODE SETTING
	162	ACTIVE_PAGE DB ? ; CURRENT PAGE BEING DISPLAYED
	163	ADDR_6845 DW ? ; BASE ADDRESS FOR ACTIVE DISPLAY CARD
	164	CRT_MODE_SET DB ? ; CURRENT SETTING OF THE 3X8 REGISTER
	165	CRT_PALETTE DB ? ; CURRENT PALETTE SETTING COLOR CARD
	166	
	167	;
	168	CASSETTE DATA AREA :
	169	;
0067 ???? 0069 ???? 006B ??	170	EDGE_CNT DW ? ; TIME COUNT AT DATA EDGE
	171	CRC_REG DW ? ; CRC REGISTER
	172	LAST_VAL DB ? ; LAST INPUT VALUE
	173	
	174	;
	175	TIMER DATA AREA :
	176	;
006C ???? 006E ???? 0070 ??	177	TIMER_LOW DW ? ; LOW WORD OF TIMER COUNT
	178	TIMER_HIGH DW ? ; HIGH WORD OF TIMER COUNT
	179	TIMER_OFL DB ? ; TIMER HAS ROLLED OVER SINCE LAST READ
	180	ICOUNTS_SEC EQU 18
	181	ICOUNTS_MIN EQU 1092
	182	ICOUNTS_HOUR EQU 65543
	183	ICOUNTS_DAY EQU 1573040 = 180080N
	184	
	185	;
	186	SYSTEM DATA AREA :
	187	;
0071 ?? 0072 ???? 0073 ???? 0074 ???? 0076 ???? 0077 ???? 0078 4 ??) 007C 4 ??)	188	BIOS_BREAK DB ? ; BIT 7 = 1 IF BREAK KEY WAS DEPRESSED
	189	RESET_FLAG DW ? ; WORD = 1234H IF K8 RESET UNDERWAY
	190	;
	191	FIXED DISK DATA AREA :
	192	;
	193	DW ? ;
	194	DW ? ;
	195	;
	196	PRINTER AND RS232 TIMEOUT CTXPS :
	197	;
	198	PRINT_TIM_OUT DB 4 DUP(?) ; PRINTER TIME OUT COUNTER
	199	RS232_TIM_OUT DB 4 DUP(?) ; RS232 TIME OUT COUNTER
	200	;
	201	EXTRA KEYBOARD DATA AREA :
	202	;
0080 ???? 0082 ???? ----	203	BUFFER_START DW ?
	204	BUFFER_END DW ?
	205	DATA ENDS
	206	;
	207	EXTRA DATA AREA :
	208	;
0000 ?? ----	209	XXDATA SEGMENT AT 50H
	210	STATUS_BYTE DB ?
	211	XXDATA ENDS
	212	
	213	;
	214	VIDEO DISPLAY BUFFER :
	215	;
	216	VIDEO_RAM SEGMENT AT DB800N

```

LOC OBJ          LINE   SOURCE

0000             217   REGEN          LABEL   BYTE
0000             218   REGENM        LABEL   WORD
0000 (16384      219   OB            I6384 OUP(?)
??
)
-----
220   VIDEO_RAH      ENDS
221   ;-----
222   ;           ROM RESIDENT CODE           ;
223   ;-----
224   CODE            SEGMENT AT DF000H
0000 (57344      225   OB            57344 OUP(?)           ; FILL LOWEST 56K
??
)

E000 31353031343736
20434F50522E20
49424D20313938
32

226
227   OB            'ISDI476 CDPR. IBM 1951'           ; COPYRIGHT NOTICE

228
229   ;-----
230   ;           INITIAL RELIABILITY TESTS -- PHASE I           ;
231   ;-----
232   ASSUME          CS:CODE,SS:CODE,ES:ABS0,OS:DATA
233   ;-----
234   ;           DATA DEFINITIONS           ;
235   ;-----
E016 D1E0        236   C1          OW          C11           ; RETURN ADDRESS
237
238   ;-----
239   ;           THIS SUBROUTINE PERFORMS A READ/WRITE STORAGE TEST ON           ;
240   ;           A 16K BLOCK OF STORAGE.                                           ;
241   ; ENTRY REQUIREMENTS:                                                         ;
242   ; ES = ADDRESS OF STORAGE SEGMENT BEING TESTED                             ;
243   ; OS = ADDRESS OF STORAGE SEGMENT BEING TESTED                             ;
244   ; WHEN ENTERING AT STGTST_CNT, CX MUST BE LOADED WITH                       ;
245   ; THE BYTE COUNT.                                                            ;
246   ; EXIT PARAMETERS:                                                            ;
247   ; ZERO FLAG = 0 IF STORAGE ERROR (DATA COMPARE OR PARITY CHECK.             ;
248   ; AL = 0 DENOTES A PARITY CHECK. ELSE AL=XOR'ED BIT                         ;
249   ; PATTERN OF THE EXPECTED DATA PATTERN VS THE                             ;
250   ; ACTUAL DATA READ.                                                         ;
251   ; AX,BX,CX,DX,DI, AND SI ARE ALL DESTROYED.                               ;
252   ;-----
253
E018             254   STGTST   PROC          NEAR
E01B B90040      255   MOV          CX,4000H           ; SETUP CNT TO TEST A 16K BLK
E01B             256   STGTST_CNT:
E01B FC          257   CLO                     ; SET DIR FLAG TO INCREMENT
E01C BB09        258   MOV          BX,CX           ; SAVE BYTE CNT (4K FOR VIDEO OR 16K)
E01E B8AAAA      259   MOV          AX,DAAAAH          ; GET DATA PATTERN TO WRITE
E021 BASSFF      260   MOV          0X,OFFSSH          ; SETUP OTHER DATA PATTERNS TO USE
E024 2BFF        261   SUB          01,01           ; 01 = OFFSET 0 RELATIVE TO ES REG
E026 F3          262   REP          STOSB           ; WRITE STORAGE LOCATIONS
E027 AA
E028             263   C3:                     ; ST60I
E02B 4F          264   DEC          01           ; POINT TO LAST BYTE JUST WRITTEN
E029 F0          265   STO                     ; SET DIR FLAG TO GO BACKWARDS
E02A             266   C4:
E02A 8BF7        267   MOV          SI,01
E02C 8BCB        268   MOV          CX,BX
E02E             269   C5:
E02E AC          270   LOOSB           ; SETUP BYTE CNT
E02F 52C4        271   XOR          AL,AN           ; INNER TEST LOOP
E031 7525        272   JNE          C7           ; READ OLD TST BYTE FROM STORAGE [SI]+
E033 8AC2        273   MOV          AL,0L           ; DATA READ AS EXPECTED ?
E035 AA          274   STOSB           ; NO - GO TO ERROR ROUTINE
E036 E2F6        275   LOOP          CS           ; GET NEXT DATA PATTERN TO WRITE
E038             276   ; WRITE INTO LOCATION JUST READ [DI]+
E038 22E4        277   AND          AH,AH           ; DECREMENT BYTE COUNT AND LOOP CX
E03A 7416        278   JZ          C6X          ; ENDING ZERO PATTERN WRITTEN TO STB ?
E03C 8AE0        279   MOV          AH,AL           ; YES - RETURN TO CALLER WITH AL=0
E03E 86F2        280   XCHG          0H,0L           ; SETUP NEW VALUE FOR COMPARE
E040 22E4        281   AND          AH,AH           ; MOVE NEXT DATA PATTERN TO DL
E042 7504        282   JNZ          C6           ; READING ZERO PATTERN THIS PASS ?
E044 8AD4        283   MOV          0L,AH           ; CONTINUE TEST SEQUENCE TILL ZERO DATA
E046 EBE0        284   JMP          C3           ; ELSE SET ZERO FOR END READ PATTERN
E048             285   C6:

```

LOC OBJ	LINE	SOURCE
E048 FC	286	CLD ; SET OIR FLAG TO GO FORWARD
E049 47	287	INC 01 ; SET POINTER TO BEG LOCATION
E04A 740E	288	JZ C4 ; READ/WRITE FORWARD IN STG
E04C 4F	289	DEC 01 ; ADJUST POINTER
E04D BA0100	290	MOV 0X,00001H ; SETUP 01 FOR PARITY BIT
	291	; AND 00 FOR END
E050 EB06	292	JMP C3 ; READ/WRITE BACKWARD IN STG
E052	293	C6X:
E052 E462	294	IN AL,PORT_C ; OIO A PARITY ERROR OCCUR ?
E054 24C0	295	AND AL,0C0H ; ZERO FLAG WILL BE OFF PARITY ERROR
E056 B000	296	MOV AL,000H ; AL=0 DATA COMPARE OK
E058	297	C7:
E058 FC	298	CLD ; SET DEFAULT OIRCTN FLAG BACK TO INC
E059 C3	299	RET
	300	STG1ST ENDP
	301	;
	302	; 8088 PROCESSOR TEST :
	303	; DESCRIPTION :
	304	; VERIFY 8088 FLAGS, REGISTERS AND CONDITIONAL JUMPS :
	305	;
E05B	306	ASSUME CS:CODE,DS:NOTHING,ES:NOTHING,SS:NOTHING
E05B	307	ORG 0E05BH
E05B	308	RESET LABEL FAR
E05B FA	309	START:
E05C B405	310	CLI ; DISABLE INTERRUPTS
E05E 9E	311	MOV AN,005H ; SET SF, CF, ZF, AND AF FLAGS ON
E05F 73AC	312	SAHF
E061 754A	313	JNC ERR01 ; GO TO ERR ROUTINE IF CF NOT SET
E063 7B48	314	JNZ ERR01 ; GO TO ERR ROUTINE IF ZF NOT SET
E065 7946	315	JNP ERR01 ; GO TO ERR ROUTINE IF PF NOT SET
E066 7F46	316	JNS ERR01 ; GO TO ERR ROUTINE IF SF NOT SET
E067 9F	317	LAHF ; LOAD FLAG IMAGE TO AH
E068 B105	318	MOV CL,S ; LOAD CNT REG WITH SHIFT CNT
E06A D2EC	319	SHR AN,CL ; SHIFT AF INTO CARRY BIT POS
E06C 733F	320	JNC ERR01 ; GO TO ERR ROUTINE IF AF NOT SET
E06E B040	321	MOV AL,40H ; SET THE OF FLAG ON
E070 D0E0	322	SHL AL,1 ; SETUP FOR TESTING
E072 7139	323	JNO ERR01 ; GO TO ERR ROUTINE IF OF NOT SET
E074 32E4	324	XOR AH,AH ; SET AH = 0
E076 9E	325	SAHF ; CLEAR SF, CF, ZF, AND PF
E077 7634	326	JBE ERR01 ; GO TO ERR ROUTINE IF CF ON
	327	; OR TO TO ERR ROUTINE IF ZF ON
E079 7632	328	JS ERR01 ; GO TO ERR ROUTINE IF SF ON
E07B 7A30	329	JP ERR01 ; GO TO ERR ROUTINE IF PF ON
E07D 9F	330	LAHF ; LOAD FLAG IMAGE TO AH
E07E B105	331	MOV CL,S ; LOAD CNT REG WITH SHIFT CNT
E080 D2EC	332	SHR AH,CL ; SHIFT 'AF' INTO CARRY BIT POS
E082 7229	333	JC ERR01 ; GO TO ERR ROUTINE IF ON
E084 D0E4	334	SHL AH,1 ; CHECK THAT 'OF' IS CLEAR
E086 7625	335	JO ERR01 ; GO TO ERR ROUTINE IF ON
	336	
	337	;----- READ/WRITE THE 8088 GENERAL AND SEGMENTATION REGISTERS
	338	; WITH ALL ONE'S AND ZEROES'S.
	339	
E088 B0FFFF	340	MOV AX,0FFFFH ; SETUP ONE'S PATTERN IN AX
E08B F9	341	STC
E08C	342	C8:
E08C 8ED8	343	MOV DS,AX ; WRITE PATTERN TO ALL REGS
E08E 8CDB	344	MOV BX,DS
E090 8EC3	345	MOV ES,BX
E092 8CC1	346	MOV CX,ES
E094 8ED1	347	MOV SS,CX
E096 8CD2	348	MOV DX,SS
E098 8BE2	349	MOV SP,DX
E09A 8BEC	350	MOV BP,SP
E09C 8BF5	351	MOV SI,BP
E09E 8BFE	352	MOV DI,SI
E0A0 7307	353	JNC C9 ; TSTIA
E0A2 33C7	354	XOR AX,01 ; PATTERN MAKE IT THRU ALL REGS
E0A4 7507	355	JNZ ERR01 ; NO - GO TO ERR ROUTINE
E0A6 F8	356	CLC
E0A7 EBE3	357	JMP C8
E0A9	358	C9:
E0A9 0BC7	359	OR AX,01 ; TSTIA
E0AB 7401	360	JZ C10 ; ZERO PATTERN MAKE IT THRU?
E0AD F4	361	ERR01: HLT ; YES - GO TO NEXT TEST
	362	; HALT SYSTEM
		;

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363      ;      RDS CHECKSUM TEST 1      :
364      ; DESCRIPTION      :
365      ;      A CHECKSUM IS DONE FOR THE 6K RDS MODULE      :
366      ;      CONTAINING PCO AND BIOS.      :
367      ;-----:
EOAE      368      C10:
369      ; ZERD IN AL ALREADY
EOAE E6A0      370      OUT      0A0H,AL      ; DISABLE NMI INTERRUPTS
EOB0 E6B3      371      OUT      B3H,AL      ; INITIALIZE DMA PAGE REG
EOB2 BADB03      372      MOV      DX,0B0H
EOB5 EE      373      OUT      DX,AL      ; DISABLE COLOR VIDEO
EOB6 FEC0      374      INC      AL
EOB8 B2B8      375      MOV      DL,0B0H
EOBA EE      376      OUT      DX,AL      ; DISABLE B/W VIDEO,EN HIGH RES
EOBB B099      377      MOV      AL,99H      ; SET 8255 A,C-INPUT,B-OUTPUT
EOBD E663      378      OUT      CHD_PORT,AL      ; WRITE 82SS CHD/MODE REG
EOBF B0FC      379      MOV      AL,0FCH      ; DISABLE PARITY CHECKERS AND
EOC1 E661      380      OUT      PORT_B,AL      ; GATE SNS SNS,CASS MOTOR OFF
EOC3 8CC8      381      MOV      AX,CS      ; SETUP SS SEG REG
EOCS 8ED0      382      MOV      SS,AX
EOC7 8ED8      383      MOV      DS,AX      ; SET UP DATA SEG TO POINT TO
384      ; ROM ADDRESS
385      ASSUME      SS:CODE
EOC9 B7E0      386      MOV      BH,0E0H      ; SETUP STARTING RDS ADDR (E0000)
EOCB BC16E0      387      MOV      SP,0FFSET C1      ; SETUP RETURN ADDRESS
EOCE E97B0B      388      JMP      RDS_CHECKSUM
EOD1      389
EOD1 75DA      390      C11:      JNE      ERR01      ; HALT SYSTEM IF ERROR
391      ;-----:
392      ;      8237 DMA INITIALIZATION CHANNEL REGISTER TEST      :
393      ; DESCRIPTION      :
394      ;      DISABLE THE 8237 DMA CONTROLLER. VERIFY THAT TIMER 1      :
395      ;      FUNCTIONS OK. WRITE/READ THE CURRENT ADDRESS AND WORD      :
396      ;      COUNT REGISTERS FOR ALL CHANNELS. INITIALIZE AND      :
397      ;      START DMA FOR MEMORY REFRESH.      :
398      ;-----:
EOD3 B004      399      MOV      AL,04      ; DISABLE DMA CONTROLLER
EOD5 E60B      400      OUT      DMA0B,AL
401
402      ;----- VERIFY THAT TIMER 1 FUNCTIONS OK
403
EOD7 B054      404      MOV      AL,54H      ; SEL TIMER 1,LSB,MODE 2
EOD9 E643      405      OUT      TIMER+3,AL
EODB 8AC1      406      MOV      AL,CL      ; SET INITIAL TIMER CNT TO 0
EODD E641      407      OUT      TIMER+1,AL
EODF      408      C12:
EODF B040      409      MOV      AL,40H      ; TIMER1_BITS_ON
EOE1 E643      410      OUT      TIMER+3,AL      ; LATCH TIMER 1 COUNT
EOE3 80FBFF      411      CMP      BL,0FFH      ; YES - SEE IF ALL BITS GO OFF
EOE6 7407      412      JE      C13      ; TIMER1_BITS_OFF
EOE8 E441      413      IN      AL,TIMER+1      ; READ TIMER 1 COUNT
EOEA 0A0B      414      OR      BL,AL      ; ALL BITS ON IN TIMER
EOEC E2F1      415      LOOP      C12      ; TIMER1_BITS_ON
EOEE F4      416      HLT      ; TIMER 1 FAILURE, HALT SYS
EOEF      417      C13:
EOEF 8AC3      418      MOV      AL,BL      ; TIMER1_BITS_OFF
EOF1 2BC9      419      SUB      CX,CX      ; SET TIMER 1 CNT
EOF3 E641      420      OUT      TIMER+1,AL
EOF5      421      C14:
EOF5 B040      422      MOV      AL,40H      ; TIMER_LOOP
EOF7 E643      423      OUT      TIMER+3,AL      ; LATCH TIMER 1 COUNT
EOF9 90      424      NOP
EOFA 90      425      NOP      ; DELAY FOR TIMER
EOFB E441      426      IN      AL,TIMER+1      ; READ TIMER 1 COUNT
EOD 22D8      427      AND      BL,AL
EOFF 7403      428      JZ      C15      ; GO TO WRAP_DMA_REG
E101 E2F2      429      LOOP      C14      ; TIMER_LOOP
E103 F4      430      HLT      ; TIMER ERROR - HALT SYSTEM
431
432      ;----- INITIALIZE TIMER 1 TO REFRESH MEMORY
433
E104      434      C15:
E104 B012      435      MOV      AL,1B      ; WRAP_DMA_REG
E106 E641      436      OUT      TIMER+1,AL      ; SETUP DIVISOR FOR REFRESH
E108 E60D      437      OUT      DMA+0DH,AL      ; WRITE TIMER 1 CNT REG
438      ; SEND MASTER CLEAR TO DMA

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LOC OBJ	LINE	SOURCE
	439	;----- WRAP DMA CHANNELS ADDRESS AND COUNT REGISTERS
	440	
E10A B0FF	441	MOV AL,0FFH ; WRITE PATTERN FF TO ALL REGS
E10C	442	
E10C 8A08	443	C16: MOV BL,AL ; SAVE PATTERN FOR CMPARE
E10E 8AF8	444	MOV BH,AL
E110 B90800	445	MOV CX,8 ; SETUP LOOP CNT
E113 2B02	446	SUB DX,DX ; SETUP I/O PORT ADDR DF REG (0000)
E115	447	
E115 EE	448	C17: OUT DX,AL ; WRITE PATTERN TO REG, LSB
E116 50	449	PUSH AX
E117 EE	450	OUT DX,AL ; MSB DF 16 BIT REG
E118 B80101	451	MOV AX,0101H ; AX TO ANOTHER PAT BEFORE RD
E11B EC	452	IN AL,DX ; READ 16-BIT DMA CN REG, LSB
E11C 8AE0	453	MOV AH,AL ; SAVE LSB DF 16-BIT REG
E11E EC	454	IN AL,DX ; READ MSB OF DMA CN REG
E11F 3B08	455	CMP BX,AX ; PATTERN READ AS WRITTEN?
E121 7401	456	JE C18 ; YES - CHECK NEXT REG
E123 F4	457	NLT ; NO - NALT THE SYSTEM
E124	458	C18: ; NEXT_DMA_CN
E124 42	459	INC DX ; SET I/O PORT TO NEXT CN REG
E125 E2EE	460	LOOP C17 ; WRITE PATTERN TO NEXT REG
E127 FEC0	461	INC AL ; SET PATTERN TO 0
E129 74E1	462	JZ C16 ; WRITE TO CHANNEL REGS
	463	
	464	;----- INITIALIZE AND START DMA FOR MEMORY REFRESH.
	465	
E12B 8EDB	466	MOV DS,BX ; SET UP ABS0 INTO OS AND ES
E12D 8EC3	467	MOV ES,BX
	468	ASSUME OS:ABS0,ES:ABS0
	469	
E12F B0FF	470	MOV AL,0FFH ; SET CNT OF 64K FOR RAM REFRESH
E131 E601	471	OUT OMA+1,AL
E133 50	472	PUSH AX
E134 E601	473	OUT OMA+1,AL
E136 B20B	474	MOV OL,0BH ; DX=000B
E13B B056	475	MOV AL,056H ; SET OMA MOOE,CH 0,READ,AUTOINT
E13A EE	476	OUT DX,AL ; WRITE OMA MOOE REG
E13B B000	477	MOV AL,0 ; ENABLE OMA CONTROLLER
E130 E60B	478	OUT DMA+8,AL ; SETUP OMA COMMAND REG
E13F 50	479	PUSH AX
E140 E60A	480	OUT OMA+1D,AL ; ENABLE CHANNEL 0 FOR REFRESH
E142 B103	481	MOV CL,3
E144 B041	482	MOV AL,41H ; SET MODE FOR CHANNEL 1
E146	483	C18A: ;
E146 EE	484	OUT OX,AL
E147 FEC0	485	INC AL ; POINT TO NEXT CHANNEL
E149 E2FB	486	LOOP C18A
	487	;-----
	488	; BASE 16K READ/WRITE STORAGE TEST ;
	489	; DESCRIPTION ;
	490	; WRITE/READ/VERIFY DATA PATTERNS FF,SS,AA,01, AND 00 ;
	491	; TO 1ST 16K DF STORAGE. VERIFY STORAGE ADDRESSABILITT. ;
	492	; INITIALIZE THE B259 INTERRUPT CONTROLLER CHIP FOR ;
	493	; CHECKING MANUFACTURING TEST 2 MODE. ;
	494	;-----
	495	
	496	;----- DETERMINE MEMORY SIZE AND FILL MEMORY WITH DATA
	497	
E14B BAI302	498	MOV OX,D213H ; ENABLE EXPANSION BOX
E14E B001	499	MOV AL,01H
E150 EE	500	OUT DX,AL
E151 8B2E7204	501	MOV BP,DATA_WORD[OFFSET RESET_FLAG] ; SAVE 'RESET_FLAG' IN BP
E155 81FD3412	502	CNP BP,1234H ; WARM START?
E159 740A	503	JE C18B ; BYPASS STG TST.
E15B BC41F090	504	MOV SP,OFFSET C2
E15F E9B6FE	505	JNP STGTST
E162	506	
E162 7401	507	C24: JE C18B ; PROCEED IF STGTST OK
E164 F4	508	NLT ; NALT IF NOT
E165	509	C18B: ;
E165 2BFF	510	SUB DI,DI
E167 E460	511	IN AL,PORT_A ; DETERMINE BASE RAM SIZE
E169 240C	512	AND AL,0CH ; ISOLATE RAM SIZE SHS
E16B 0404	513	ADD AL, 4 ; CALCULATE MEMORY SIZE
E16D B10C	514	MOV CL, 12

LOC OBJ	LINE	SOURCE
E16F D3E0	515	SHL AX, CL
E171 8BC6	516	MOV CX, AX
E173 FC	517	CID
E174	518	C19: ; SET DIR FLAG TO INCR
E174 AA	519	STOSB ; FILL BASE RAM WITH DATA
E175 E2F0	520	LOOP C19 ; LOOP TIL ALL ZERO
E177 892E7204	521	MOV DATA_MORIOFFSET RESET_FLAG},BP
	522	
	523	;----- DETERMINE IO CHANNEL RAM SIZE
	524	
E17B B0F8	525	MOV AL,0F8H ; ENABLE SWITCH 5
E17D E661	526	OUT PORT_B,AL
E17F E462	527	IN AL,PORT_C ; READ SWITCHES
E181 2401	528	AND AL,00000001B ; ISOLATE SWITCH 5
E183 B10C	529	MOV CL,12D
E185 03C0	530	ROL AX,CL
E187 B0FC	531	MOV AL,0FCH ; OISABLE SW. 5
E189 E661	532	OUT PORT_B,AL
E18B E462	533	IN AL,PORT_C
E18D 240F	534	AND AL,0FH
E18F DAC4	535	OR AL,AH ; COMBINE SWITCH VALUES
E191 8A08	536	MOV BL,AL ; SAVE
E193 B420	537	MOV AH,32
E195 F6E4	538	MUL AH ; CALC. LENGTH
E197 A31504	539	MOV DATA_MORIOFFSET IO_RAM_SIZE1,AX ;SAVE IT
E19A 7418	540	JZ C21
E19C BA0010	541	MOV DX,1000H ; SEGMENT FOR I/O RAM
E19F 8AE0	542	MOV AH,AL
E1A1 B000	543	MOV AL,0
E1A3	544	C20: ; FILL_IO:
E1A3 8EC2	545	MOV ES,0X
E1A5 B90080	546	MOV CX,8000H ; FILL 32K BYTES
E1A8 2BFF	547	SUB DI,DI
E1AA F3	548	REP STOSB
E1AB AA		
E1AC 81C20000	549	ADD DX,800H ; NEXT SEGMENT VALUE
E1B0 FECB	550	DEC BL
E1B2 75EF	551	JNZ C20 ; FILL_ID
	552	;-----
	553	; INITIALIZE THE 8259 INTERRUPT CONTROLLER CHIP ;
	554	;-----
E1B4	555	C21:
E1B4 B013	556	MOV AL,13H ; ICW1 - EDGE, SNGL, ICW4
E1B6 E620	557	OUT INTA00,AL
E1B8 B008	558	MOV AL,8 ; SETUP ICW2 - INT TYPE 8 (8-F)
E1BA E621	559	OUT INTA01,AL
E1BC B009	560	MOV AL,9 ; SETUP ICW4 - BUFFRD,8086 MODE
E1BE E621	561	OUT INTA01,AL
E1C0 2BC0	562	SUB AX,AX
E1C2 8EC0	563	MOV ES,AX ; POINT ES TO BEGIN ; OF R/W STORAGE
	564	;-----
	565	; CHECK FOR MANUFACTURING TEST 2 TO LOAD TEST PROGRAMS FROM KEYBOARD. ;
	566	;-----
	567	
	568	;----- SETUP STACK SEG AND SP
	569	
E1C4 B83000	570	MOV AX,STACK ; GET STACK VALUE
E1C7 8ED0	571	MOV SS,AX
E1C9 BC0001	572	MOV SP,OFFSET YOS ; SET THE STACK UP
E1CC 81FD3412	573	CHP BP,1234H ; STACK IS READY TO GO
E1D0 7425	574	JE C25 ; RESET_FLAG SET?
E1D2 2BFF	575	SUB DI,DI ; YES - SKIP MFG TEST
E1D4 8EDF	576	MOV DS,01
E1D6 BB2400	577	MOV BX,24H
E1D9 C70747FF	578	MOV WORD PTR [BX],OFFSET 011 ; SET UP KB INTERRUPT
E1DD 43	579	INC BX
E1DE 43	580	INC BX
E1DF 8C0F	581	MOV [BX],C5
E1E1 E85F04	582	CALL KBD_RESET ; READ IN KB RESET CODE TO BL
E1E4 80FB65	583	CHP BL,065H ; IS THIS MANUFACTURING TEST 2?
E1E7 750E	584	JNZ C25 ; JUMP IF NOT MAN. TEST
E1E9 B2FF	585	MOV OL,255 ; READ IN TEST PROGRAM
E1EB	586	C22:
E1EB E86204	587	CALL SP_TEST
E1EE 8AC3	588	MOV AL,BL
E1F0 AA	589	STOSB

LOC	OBJ	LINE	SOURCE
E1F1	FECA	590	DEC DL
E1F3	75F6	591	JNZ C22
E1F5	CD3E	592	INT 3EH
E1F7		593	C25: ; SET INTERRUPT TYPE 62 ADDRESS F8H
		594	
		595	;----- SET UP THE BIOS INTERRUPT VECTORS TO TEMP INTERRUPT
		596	
E1F7	B92000	597	MOV CX,32 ; FILL ALL 32 INTERRUPTS
E1FA	2BFF	598	SUB 01,D1 ; FIRST INTERRUPT LOCATON
E1FC		599	D3: ;
E1FC	B847FF	600	MOV AX,OFFSET D11 ; MOVE ADDR OF INTR PROC TO TBL
E1FF	AB	601	STOSW
E200	8CC8	602	MOV AX,CS ; GET ADDR OF INTR PROC SEG
E202	AB	603	STOSW
E203	E2F7	604	LOOP D3 ; VECTBL0
		605	
		606	;----- SET UP OTHER INTERRUPTS AS NECESSARY
		607	
E205	C7060800C3E2	608	MOV NMI_PTR,OFFSET NMI_INT ; NMI INTERRUPT
E20B	C706140054FF	609	MOV INT5_PTR,OFFSET PRINT_SCREEN ; PRINT SCREEN
E211	C706620000F6	610	MOV BASIC_PTR+2,DF600H ; SEGMENT FOR CASSETTE BASIC
		611	
		612	;
		613	; 8259 INTERRUPT CONTROLLER TEST ;
		614	; DESCRIPTION ;
		615	; READ/WRITE THE INTERRUPT MASK REGISTER (IMR) WITH ALL ;
		616	; ONES AND ZEROES. ENABLE SYSTEM INTERRUPTS. MASK DEVICE ;
		617	; INTERRUPTS OFF. CHECK FOR NOT INTERRUPTS (UNEXPECTED). ;
		618	;
		619	
		620	;----- TEST THE IMR REGISTER
		621	
E217	BA2100	622	MOV 0X,0021H ; POINT INTR. CHIP ADDR 21
E21A	8000	623	MOV AL,0 ; SET IMR TO ZERO
E21C	EE	624	OUT 0X,AL
E210	EC	625	IN AL,0X ; READ IMR
E21E	0AC0	626	OR AL,AL ; IMR = 0?
E220	7515	627	JNZ 06 ; GO TO ERR ROUTINE IF NOT 0
E222	80FF	628	MOV AL,OFFH ; DISABLE DEVICE INTERRUPTS
E224	EE	629	OUT 0X,AL ; WRITE TO IMR
E225	EC	630	IN AL,0X ; READ IMR
E226	0401	631	ADD AL,1 ; ALL IMR BIT ON?
E228	7500	632	JNZ 06 ; NO - GO TO ERR ROUTINE
		633	
		634	;----- CHECK FOR NOT INTERRUPTS
		635	
		636	;----- INTERRUPTS ARE MASKED OFF. CHECK THAT NO INTERRUPTS OCCUR.
		637	
E22A	32E4	638	XOR AH,AH ; CLEAR AN REG
E22C	FB	639	STI ; ENABLE EXTERNAL INTERRUPTS
E220	2BC9	640	SUB CX,CX ; WAIT 1 SEC FOR ANY INTRs THAT
E22F	E2FE	641	04: ;
E22F	E2FE	642	LOOP 04 ; MIGHT OCCUR
E231		643	D5: ;
E231	E2FE	644	LOOP 05 ;
E233	0AE4	645	OR AN,AH ; DID ANY INTERRUPTS OCCUR?
E235	7408	646	JZ 07 ; NO - GO TO NEXT TEST
E237		647	06: ;
E237	DA0101	648	MOV 0X,101H ; BEEP SPEAKER IF ERROR
E23A	E89203	649	CALL ERR_BEEP ; GO TO BEEP SUBROUTINE
E230	FA	650	CLI
E23E	F4	651	HLT ; HALT THE SYSTEM
		652	;
		653	; 8253 TIMER CKECKOUT ;
		654	; DESCRIPTION ;
		655	; VERIFY THAT THE SYSTEM TIMER (D) ;
		656	; DOESN'T COUNT TOO FAST OR TOO SLOW. ;
		657	;
E23F		658	07: ;
E23F	80FE	659	MOV AL,0FH ; MASK ALL INTRs EXCEPT LVL 0
E241	EE	660	OUT 0X,AL ; WRITE THE 8259 IMR
E242	D010	661	MOV AL,00010000B ; SET TIM D, LSB, MODE 0, BINARY
E244	E643	662	OUT TIM_CTL,AL ; WRITE TIMER CONTROL MODE REG
E246	B91600	663	MOV CX,16H ; SET PGH LOOP CNT
E249	8AC1	664	MOV AL,CL ; SET TIMER 0 CNT REG
E24B	E640	665	DUT TIMERO,AL ; WRITE TIMER 0 CNT REG


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LOC OBJ          LINE    SOURCE

E24D             666      DB:
E24D F6C4FF      667
E250 7504        668          TEST    AH,OFFH          ; DID TIMER 0 INTERRUPT OCCUR?
E252 E2F9        669          JNZ     D9              ; YES - CHECK TIMER 0P FOR SLOW TIME
E254 EBE1        670          LOOP    D8              ; WAIT FOR INTR FOR SPECIFIED TIME
E256             671          JMP     D6              ; TIMER 0 INTR DIDN'T OCCUR - ERR
E256 8112        672          D9:      MOV     CL,18          ; SET PGM LOOP CNT
E258 80FF        673          MOV     AL,OFFH          ; WRITE TIMER 0 CNT REG
E25A E640        674          OUT     TIMERD,AL
E25C 80FE00      675          MOV     AX,DFEN
E25F EE          676          OUT     DX,AL
E260             677          D10:     TEST    AH,OFFH          ; DID TIMER 0 INTERRUPT OCCUR?
E260 F6C4FF      678          JNZ     D6              ; YES - TIMER CNTING TOO FAST, ERR
E263 75D2        679          LOOP    D1D              ; WAIT FOR INTR FOR SPECIFIED TIME
E265 E2F9        680
E267             681
E267             682      I----- ESTABLISH 8IDS SUBROUTINE CALL INTERRUPT VECTORS
E267             683
E267 1E          684          PUSH    DS          ; SAVE POINTER TO DATA AREA
E268 BF4000      685          MOV     DI,OFFSET VIEDD_INT ; SETUP ADDR TO INTR AREA
E268 0E          686          PUSH    CS
E26C 1F          687          POP     DS          ; SETUP ADDR OF VECTDR TABLE
E26D 0E03FF90    688          MOV     SI,OFFSET VECTOR_TABLE+16 ; START WITH VIEDD ENTRY
E271 B91000      689          MOV     CX,16
E272             690
E272             691      I----- SETUP TIMER D TO MODE 3
E272             692
E274 80FF        693          MOV     AL,OFFH          ; DISABLE ALL DEVICE INTERRUPTS
E276 EE          694          OUT     DX,AL
E277 8036        695          MOV     AL,36H          ; SEL TIM 0,LSB,MSB,MODE 3
E279 E643        696          OUT     TIMER+3,AL      ; WRITE TIMER MODE REG
E27B 8000        697          MOV     AL,0
E27D E640        698          OUT     TIMER,AL       ; WRITE LSB TO TIMER 0 REG
E27F             699          E1A:      MOVSW          ; MOVE VECTOR TABLE TO RAM
E27F AS          700          INC     DI              ; MOVE PAST SEGMENT POINTER
E280 47          701          INC     DI
E281 47          702          LOOP    E1A
E282 E2FB        703          DUT     TIMER,AL       ; WRITE MSB TO TIMER 0 REG
E284 E640        704          PDP     DS              ; RECOVER DATA SEG POINTER
E286 1F          705
E287             706
E287             707      I----- SETUP TIMER 0 TO BLINK LED IF MANUFACTURING TEST MODE
E287             708
E287 E8B903      709          CALL    KBD_RESET          ; SEND SOFTWARE RESET TO KEYBRD
E28A 80FBAJ      710          CMP     BL,0AAH          ; SCAN CODE 'AA' RETURNED?
E28D 741E        711          JE      E6              ; YES - CONTINUE (NON MFG MODE)
E28F B03C        712          MOV     AL,3CH          ; EN KBD, SET KBD CLK LINE LOW
E291 E661        713          OUT     PORT_B,AL         ; WRITE 8255 PORT B
E293 90          714          NOP
E294 90          715          NOP
E295 E460        716          IN      AL,PORT_A         ; WAS A BIT CLOCKED IN?
E297 24FF        717          AND     AL,OFFH
E299 750E        718          JNZ     E2              ; YES - CONTINUE (NON MFG MODE)
E29B FE061204    719          INC     DATA_AREA[OFFSET MFG_TST] ; ELSE SET SW FOR MFG TEST MODE
E29F C7062006DE6 720          MOV     INT_ADDR,OFFSET BLINK_INT ; SETUP TIMER INTR TO BLINK LED
E2A5 80FE        721          MOV     AL,0FH          ; ENABLE TIMER INTERRUPT
E2A7 E621        722          OUT     INTA01,AL
E2A9             723          E2:      JUMPER_NOT_IN: ; JUMPER_NOT_IN:
E2A9 B0CC        724          MOV     AL,0CCH          ; RESET THE KEYBOARD
E2AB E661        725          OUT     PORT_0,AL
E2AC             726
E2AC             727      I-----
E2AC             728      ; INITIALIZE AND START CRT CONTROLLER (6845) :
E2AC             729      ; TEST VIEDD READ/WRITE STORAGE. :
E2AC             730      ; DESCRIPTION :
E2AC             731      ; RESET THE VIDEO ENABLE SIGNAL. :
E2AC             732      ; SELECT ALPHANUMERIC MODE, 40 = 25, B & M. :
E2AC             733      ; READ/WRITE DATA PATTERNS TO STG. CHECK STG :
E2AC             734      ; ADDRESSABILITY. :
E2AC             735      I-----
E2AD             736      E6:
E2AD E460        737          IN      AL,PORT_A         ; READ SENSE SWITCHES
E2AF 8400        738          MOV     AH,D
E2B1 A31004      739          MOV     DATA_WORD[OFFSET EQUIP_FLAG],AX ; STORE SENSE SW INFO
E2B4             740          E6A:
E2B4 2430        741          AND     AL,30H          ; ISOLATE VIDEO SMS
E2B6 7529        742          JNZ     E7              ; VIEDD SMS SET TO 0?

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LOC OBJ	LINE	SOURCE
E2B8 C704400053FF	743	MOV VIDEO_INT,OFFSET DUMMY_RETURN
E2BE E9A200	744	JMP E10_1 ; SKIP VIDEO TESTS FOR BURH-IN
	745	
E2C3	746	ORG 0E2C3H
E2C3	747	NMI_INT PROC HEAR
E2C3 50	748	PUSH AX ; SAVE ORIG CONTENTS OF AX
E2C4 E462	749	IN AL,PORT_C
E2C6 ABC0	750	TEST AL,0C0H ; PARITY CHECK?
E2C8 7415	751	JZ D14 ; NO, EXIT FROM ROUTINE
E2CA BEDAFF90	752	MOV SI,OFFSET D1 ; ADDR OF ERROR MSG
E2CE AB40	753	TEST AL,40H ; I/O PARITY CHECK
E2D0 7504	754	JNZ D13 ; DISPLAY ERROR MSG
E2D2 BE23FF90	755	MOV SI,OFFSET D2 ; MUST BE PLANAR
E2D6	756	D13: SUB AX,AX ; INIT AND SET MODE FOR VIDEO
E2D6 2BC0	757	INT 10H ; CALL VIDEO_IO PROCEDURE
E2D8 CD10	758	CALL P_MSG ; PRINT ERROR MSG
E2DA E80003	759	CLI
E2DD FA	760	HLT ; HALT SYSTEM
E2DE F4	761	
E2DF	762	D14: POP AX ; RESTORE ORIG CONTENTS OF AX
E2DF 58	763	IRET
E2E0 CF	764	NMI_INT ENDP
E2E1	765	E7: ; TEST_VIDEO:
E2E1 3C30	767	CMP AL,30H ; B/W CARD ATTACHED?
E2E3 7408	768	JE E8 ; YES - SET MODE FOR B/W CARD
E2E5 FEC4	769	INC AH ; SET COLOR MODE FOR COLOR CD
E2E7 3C20	770	CMP AL,20H ; 80X25 MODE SELECTED?
E2E9 7502	771	JNE E8 ; NO - SET MODE FOR 40X25
E2EB 8403	772	MOV AH,3 ; SET MODE FOR 80X25
E2ED	773	E8: ; SET_MODE
E2ED 86E0	774	XCHG AH,AL ; SET_VIDEO
E2EF 50	775	PUSH AX ; SAVE VIDEO MODE ON STACK
E2F0 2AE4	776	SUB AH,AN ; INITIALIZE TO ALPHANUMERIC MD
E2F2 CD10	777	INT 10H ; CALL VIDEO_IO
E2F4 58	778	POP AX ; RESTORE VIDEO SENSE SMS IN AH
E2F5 50	779	PUSH AX ; RESAVE VALUE
E2F6 880080	780	MOV 8X,08DDH ; B6G VIDEO RAM ADDR B/W CD
E2F9 8A8803	781	MOV DX,3B8H ; MODE REG FOR B/W
E2FC 890010	782	MOV CX,4D96 ; RAM BYTE CNT FOR B/W CD
E2FF 8001	783	MOV AL,1 ; SET MODE FOR BW CARD
E301 80FC30	784	CHP AH,30H ; B/W VIDEO CARD ATTACHED?
E304 7408	785	JE E9 ; YES - SO TEST VIDEO STG
E306 87B8	786	MOV 8H,088H ; B6G VIDEO RAM ADDR COLOR CD
E308 82D8	787	MOV DL,088H ; MODE REG FOR CDOR CD
E30A B540	788	MOV CH,40H ; RAM BYTE CNT FOR COLOR CD
E30C FEC8	789	DEC AL ; SET MODE TO 0 FOR COLOR CD
E30E	790	E9: ; TEST_VIDEO_STG:
E30E EE	791	OUT DX,AL ; DISABLE VIDEO FOR COLOR CD
E30F 81FD3412	792	CHP 8P,1234H ; POS INITIATED BY K80 RESET?
E313 8EC3	793	MOV ES,8X ; POINT ES TO VIDEO RAM STG
E315 7407	794	JE E10 ; YES - SKIP VIDEO RAM TEST
E317 8ED8	795	MOV DS,8X ; POINT DS TO VIDEO RAM STG
	796	ASSUME DS:NOTHING,ES:NOTHING
E319 E8FFFC	797	CALL STGTST_CNT ; GO TEST VIDEO R/W STG
E31C 7532	798	JNE E17 ; R/W STG FAILURE - BEEP SPK
	799	;
	800	; SETUP VIDEO DATA ON SCREEN FOR VIDEO LINE TEST. ;
	801	; DESCRIPTION ;
	802	; ENABLE VIDEO SIGNAL AND SET MODE. ;
	803	; DISPLAY A HORIZONTAL BAR ON SCREEN. ;
	804	;
E31E	805	E10: ;
E31E 58	806	POP AX ; GET VIDEO SENSE SMS (AH)
E31F 50	807	PUSH AX ; SAVE IT
E320 B400	808	MOV AH,0 ; ENABLE VIDEO AND SET MODE
E322 CD10	809	INT 10H ; VIDEO
E324 862070	810	MOV AX,7020H ; WRT BLANKS IN REVERSE VIDEO
E327 2BFF	811	SUB DI,DI ; SETUP STARTING LOC
E329 B92800	812	MOV CX,40 ; NO. OF BLANKS TO DISPLAY
E32C F3	813	REP STOSW ; WRITE VIDEO STORAGE
E32D AB		
	814	;
	815	; CRT INTERFACE LINES TEST ;
	816	; DESCRIPTION ;
	817	; SENSE ON/OFF TRANSITION OF THE VIDEO ENABLE ;

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LOC OBJ          LINE    SOURCE

010      ;      AND HORIZONTAL SYNC LINES.
019      ;-----
E32E 50          020      POP     AX      ; GET VIDEO SENSE SW INFO
E32F 50          021      PUSH    AX      ; SAVE IT
E330 80FC30      022      CMP     AH,30H   ; 8/M CARD ATTACHEO?
E333 BABA03      023      MOV     CX,03BAH ; SETUP ADDR OF 8H STATUS PORT
E336 7402        024      JE      E11     ; YES - GO TEST LINES
E338 B2DA        025      MOV     CX,00A0H ; COLOR CARD IS ATTACHED
E33A             026      E11:         ; LINE_TST:
E33A B408        027      MOV     AH,8     ;
E33C             028      E12:         ; OFLOOP_CNT:
E33C 2BC9        029      SUB     CX,CX
E33E             030      E13:         ;
E33E EC          031      IN      AL,CX   ; READ CRT STATUS PORT
E33F 22C4        032      AND     AL,AH   ; CHECK VIDEO/HORZ LINE
E341 7504        033      JNZ     E14     ; ITS ON - CHECK IF IT GOES OFF
E343 E2F9        034      LOOP    E13     ; LOOP TILL ON OR TIMEOUT
E345 EB09        035      JHP     SHORT E17   ; GO PRINT ERROR MSG
E347             036      E14:         ;
E347 2BC9        037      SUB     CX,CX
E349             038      E15:         ;
E349 EC          039      IN      AL,CX   ; READ CRT STATUS PORT
E34A 22C4        040      AND     AL,AH   ; CHECK VIDEO/HORZ LINE
E34C 740A        041      JZ      E16     ; ITS ON - CHECK NEXT LINE
E34E E2F9        042      LOOP    E15     ; LOOP IF OFF TILL IT GOES ON
E350             043      E17:         ; CRT_ERR
E350 BA0201      044      MOV     CX,102H
E353 E87902      045      CALL    ERR_BEEP      ; GO BEEP SPEAKER
E356 EB06        046      JHP     SHORT E18
E358             047      E16:         ; NXT_LINE
E358 B103        048      MOV     CL,3     ; GET NEXT BIT TO CNECK
E35A 02EC        049      SHR     AN,CL
E35C 75DE        050      JNZ     E12     ; GO CHECK HORIZONTAL LINE
E35E             051      E18:         ; DISPLAY_CURSOR:
E35E 58          052      POP     AX      ; GET VIDEO SENSE SWS (AH)
E35F B400        053      MOV     AH,0     ; SET MODE AND DISPLAY CURSOR
E361 CD10        054      INT     10H     ; CALL VIDEO I/O PROCEDURE
E363             055
E363 BA00C0      056      E18_1:
E363             057      MOV     CX,0C000H
E366             058      E18A:
E366 B5DA        059      MOV     DS,DX
E368 280B        060      SUB     BX,BX
E36A 8B07        061      MOV     AX,[BX]
E36C 53          062      PUSH    BX      ; GET FIRST 2 LOCATIONS
E36D 5B          063      POP     BX      ; LET BUS SETTLE
E36E 3D55AA      064      CMP     AX,0A55H   ; PRESENT?
E371 7505        065      JNZ     E18B     ; NO? GO LOOK FOR OTHER MODULES
E373 E80E03      066      CALL    ROM_CHECK ; GO SCAN MODULE
E376 EB04        067      JHP     SHORT E18C
E378             068      E18B:
E378 81C28000     069      ADD     CX,00B0H   ; POINT TO NEXT 2K BLOCK
E37C             070      E18C:
E37C 81FA00C8     071      CMP     CX,0C800H  ; TOP OF VIDEO ROM AREA YET?
E380 7CE4        072      JL      E18A     ; GO SCAN FOR ANOTHER MODULE
E382             073
E382             074      ; EXPANSION I/O BOX TEST
E382             075      ; CHECK TO SEE IF EXPANSION BOX PRESENT - IF INSTALLED,
E382             076      ; TEST DATA AND ADDRESS BUSES TO I/O BOX.
E382             077      ; ERROR='1801'
E382             078      ;-----
E382             079
E382             080      ;----- DETERMINE IF BOX IS PRESENT
E382             081
E382             082      EXP_ID:
E382 B1A1002      083      MOV     CX,0210H   ; (CARD WAS ENABLED EARLIER)
E385 B85555      084      MOV     AX,5555H   ; CONTROL PORT ADDRESS
E388 EE          085      OUT     CX,AL      ; SET DATA PATTERN
E389 0001        086      MOV     AL,01H
E38B EC          087      IN      AL,CX     ; RECOVER DATA
E38C 3AC4        088      CMP     AL,AH     ; REPLY?
E38E 7534        089      JNE     E19       ; NO RESPONSE, GO TO NEXT TEST
E390 F700        090      NDT     AX      ; MAKE DATA=AAAA
E392 EE          091      OUT     CX,AL
E393 0001        092      MOV     AL,01H
E395 EC          093      IN      AL,CX     ; RECOVER DATA
E396 3AC4        094      CMP     AL,AH

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LOC OBJ	LINE	SOURCE	
E396 752A	895	JNE E19	; NO ANSWER=NEXT TEST
	896		
	897	----- CHECK ADDRESS AND DATA BUS	
	898		
E39A	899	EXP1:	
E39A 8B08	900	MOV BX,AX	
E39C 8A1402	901	MOV DX,0214H	; LOAD DATA REG ADDRESS
E39F 2E6807	902	MOV CS:[BX],AL	; WRITE ADDRESS F0000+BX
E3A2 EE	903	OUT DX,AL	; WRITE DATA
E3A3 90	904	NOP	
E3A4 EC	905	IN AL,DX	; READ DATA
E3A5 3AC7	906	CHP AL,BH	
E3A7 7514	907	JNE EXP_ERR	
E3A9 42	908	INC DX	; DX=215H (ADDR. NI REG)
E3AA EC	909	IN AL,DX	
E3AB 3AC4	910	CHP AL,AH	; COMPARE TO NI ADDRESS
E3AD 750E	911	JNE EXP_ERR	
E3AF 42	912	INC DX	; DX=216H (ADDR. LOW REG)
E3B0 EC	913	IN AL,DX	
E3B1 3AC4	914	CHP AL,AH	; ADDR. LOW OK?
E3B3 7508	915	JNE EXP_ERR	
E3B5 F700	916	NOT AX	; INVERT AX
E3B7 3CAA	917	CHP AL,0AAH	; BACK TO STARTING VALUE (AAAA) YET
E3B9 7409	918	JE E19	; GO ON TO NEXT TEST IF SO
E3BB EBD0	919	JMP EXP1	; LOOP BACK THROUGH WITH DATA DF 5555
E3BD	920	EXP_ERR:	
E3BD BEE0FE90	921	MOV SI,OFFSET F3B	
E3C1 E8F602	922	CALL P_MSG	
	923	-----	
	924	; ADDITIONAL READ/WRITE STORAGE TEST	
	925	; DESCRIPTION	
	926	; WRITE/READ DATA PATTERNS TO ANY READ/WRITE STORAGE	
	927	; AFTER THE BASIC 16K. STORAGE ADDRESSABILITY IS CHECKED.	
	928	-----	
	929	ASSUME DS:DATA	
E3C4	930	E19:	
	931		
	932	----- DETERMINE RAM SIZE ON PLANAR BOARD	
	933		
E3C4 E87718	934	CALL DOS	
E3C7 A01000	935	MOV AL,BYTE PTR EQUIP_FLAG	; GET SENSE SWS INFO
E3CA 240C	936	AND AL,0CH	; ISOLATE RAM SIZE SWS
E3CC 8404	937	MOV AH,4	
E3CE F6E4	938	MUL AH	
E3D0 0410	939	ADD AL,16	; ADD BASIC 16K
E3D2 8B00	940	MOV DX,AX	; SAVE PLANAR RAM SIZE IN DX
E3D4 8B08	941	MOV BX,AX	; AND IN BX
	942		
	943	----- DETERMINE ID CHANNEL RAM SIZE	
	944		
E3D6 A11500	945	MOV AX,ID_RAM_SIZE	; GET ID CHANNEL RAM SIZE
E3D9 83F840	946	CHP BX,40H	; PLANAR RAM SIZE = 64K?
E3DC 7402	947	JE E20	; YES - ADD ID CHN RAM SIZE
E3DE 2BC0	948	SUB AX,AX	; NO - DON'T ADD ANY ID RAM
E3E0	949	E20:	; ADD_ID_SIZE:
E3E0 03C3	950	ADD AX,BX	; SUM TOTAL RAM SIZE
E3E2 A31300	951	MOV MEMORY_SIZE,AX	; SETUP MEMORY SIZE PARAM
E3E5 81FD3412	952	CHP BP,1234H	; P00 INITIATED BY K80 RESET?
E3E9 1E	953	PUSH DS	; SAVE DATA SEGMENT
E3EA 744F	954	JE TST12	; YES - SKIP MEMORY TEST
	955		
	956	----- TEST ANY OTHER READ/WRITE STORAGE AVAILABLE	
	957		
E3EC 8B0004	958	MOV BX,40DH	
E3EF B91000	959	MOV CX,16	
E3F2	960	E21:	
E3F2 3B01	961	CHP DX,CX	; ANY MORE STG TO BE TESTED?
E3F4 7620	962	JBE E23	; NO - GO TO NEXT TEST
E3F6 8ED8	963	MOV DS,BX	; SETUP STG ADDR IN DS AND ES
E3F8 8EC3	964	MOV ES,BX	
E3FA 03C110	965	ADD CX,16	; INCREMENT STG BYTE COUNTER
E3FD 01C30004	966	ADD BX,40DH	; SET POINTER TO NEXT 16K BLK
E401 51	967	PUSH CX	; SAVE REGS
E402 53	968	PUSH BX	
E403 52	969	PUSH DX	
E404 E811FC	970	CALL STGTST	; GO TEST A 16K BLK DF STG
E407 5A	971	POP DX	

LOC	OBJ	LINE	SOURCE
E408 5B		972	POP BX ; RESTORE REGS
E409 59		973	POP CX
E40A 74E6		974	JE E21 ; CHECK IF MORE STG TO TEST
		975	
		976	;----- PRINT FAILING ADDRESS AND XOR'ED PATTERN IF DATA COMPARE ERROR
		977	
E40C 8CDA		978	MOV DX,05 ; CONVERT FAILING HIGH-ORDER
E40E 8AE8		979	MOV CH,AL ; SAVE FAILING BIT PATTERN
E410 8AC6		980	MOV AL,0H ; GET FAILING AODR
E412 E61002		981	CALL XPC_BYTE ; CONVERT AND PRINT CODE
E415 8AC5		982	MOV AL,CH ; GET FAILING BIT PATTERN
E417 E60B02		983	CALL XPC_BYTE ; CONVERT AND PRINT CODE
E41A BE67FA90		984	MOV SI,OFFSET E1 ; SETUP ADDRESS OF ERROR MSG
E41E E69902		985	CALL P_MSG ; PRINT ERROR MSG
E421		986	E22:
E421 EB18		987	JMP SHORT TST12 ; GO TO NEXT TEST
E423		988	E23:
E423 1F		989	POP DS ; STG_TEST_00NE
E424 1E		990	PUSH DS ; POINT OS TO DATA SEGMENT
E425 8B161500		991	MOV OX,IO_RAM_SIZE ; GET IO CHANNEL RAM SIZE
E429 0BD2		992	OR OX,OX ; SET FLAG RESULT
E42B 740E		993	JZ TST12 ; NO IO RAM, GO TO NEXT TEST
E420 B90000		994	MOV CX,0
E430 81FB0010		995	CMP BX,1000H ; HAS IO RAM BEEN TESTED
E434 7705		996	JA TST12 ; YES - GO TO NEXT TEST
E436 BB0010		997	MOV BX,1000H ; SETUP BEG LOC FOR IO RAM
E439 EBB7		998	JMP E21 ; GO TEST IO CHANNEL RAM
		999	;
		1000	;
		1001	;
		1002	;
		1003	;
		1004	;
		1005	;
		1006	ASSUME OS:DATA
		1007	TST12:
E43B 1F		1008	POP OS
E43C 603E120001		1009	CMP HFG_TST,1 ; MANUFACTURING TEST MODE?
E441 742A		1010	JE F7 ; YES - SKIP KEYBOARD TEST
E443 EBF001		1011	CALL KBD_RESET ; ISSUE SOFTWARE RESET TO KEYBOD
E446 E31E		1012	JCXZ F6 ; PRINT ERR MSG IF NO INTERRUPT
E44B B040		1013	MOV AL,40H ; ENABLE KEYBOARD
E44A E661		1014	OUT PORT_B,AL
E44C 80FBAA		1015	CMP BL,0AAH ; SCAN CODE AS EXPECTED?
E44F 7515		1016	JNE F6 ; NO - DISPLAY ERROR MSG
		1017	
		1018	;
		1019	;
		1020	;
E451 B0CC		1020	MOV AL,0CCH ; CLR KBD, SET CLK LINE HIGH
E453 E661		1021	OUT PORT_B,AL
E455 B04C		1022	MOV AL,4CH ; ENABLE KBD,CLK IN NEXT BYTE
E457 E661		1023	OUT PORT_B,AL
E459 2BC9		1024	SUB CX,CX
E45B		1025	F5:
E45B E2FE		1026	LOOP F5 ; KBD_WAIT
E45D E460		1027	IN AL,KBD_IN ; OELAY FOR A WHILE
E45F 3C00		1028	CMP AL,0 ; CHECK FOR STUCK KEYS
E461 740A		1029	JE F7 ; SCAN CODE = 0?
E463 E8BF01		1030	CALL XPC_BYTE ; YES - CONTINUE TESTING
E466 BE33FF90		1031	F6: MOV SI,OFFSET F1 ; CONVERT AND PRINT
E46A E84002		1032	CALL P_MSG ; GET MSG AODR
		1033	PRINT MSG ON SCREEN
		1034	;
		1035	;
		1036	;
E46D 2BC0		1037	SUB AX,AX ; SETUP_INT_TABLE:
E46F 8EC0		1038	MOV ES,AX
E471 B90800		1039	MOV CX,8
E474 1E		1040	PUSH DS ; GET VECTOR CNT
E475 0E		1041	PUSH CS ; SAVE DATA SEGMENT
E476 1F		1042	POP DS ; SETUP DS SEG REG
E477 BEF3FE90		1043	MOV SI,OFFSET VECTOR_TABLE
E47B BF2000		1044	MOV DI,OFFSET INT_PTR
E47E		1045	F7A:
E47E AS		1046	MOVSI
E47F 47		1047	INC DI ; SKIP OVER SEGMENT
E480 47		1048	INC DI

LOC OBJ	LINE	SOURCE
E481 E2FB	1049	LOOP F7A
	1050	-----
	1051	; CASSETTE DATA WRAP TEST ;
	1052	; DESCRIPTION ;
	1053	; TURN CASSETTE MOTOR OFF. WRITE A BIT OUT TO THE ;
	1054	; CASSETTE DATA BUS. VERIFY THAT CASSETTE DATA ;
	1055	; READ IS WITHIN A VALID RANGE. ;
	1056	-----
	1057	
	1058	;----- TURN THE CASSETTE MOTOR OFF
	1059	
E483	1060	TST13:
E483 1F	1061	POP DS
E484 1E	1062	PUSH DS
E485 804D	1063	MOV AL,D4DH ; SET TIMER 2 SPK OUT, AND CASST
E487 E661	1064	OUT PORT_B,AL ; OUT BITS ON, CASSETTE MOT OFF
	1065	
	1066	;----- WRITE A BIT
	1067	
E489 B0FF	1068	MOV AL,OFFH ; DISABLE TIMER INTERRUPTS
E48B E621	1069	OUT INTA01,AL
E48D B0B6	1070	MOV AL,0B6H ; SEL TIM 2, LSB, MSB, MD 3
E48F E643	1071	OUT TIMER+3,AL ; WRITE 8253 CH0/MODE REG
E491 88D304	1072	MOV AX,1235 ; SET TIMER 2 CNT FOR 1000 USEC
E494 E642	1073	OUT TIMER+2,AL ; WRITE TIMER 2 COUNTER REG
E496 8AC4	1074	MOV AL,AH ; WRITE MSB
E498 E642	1075	OUT TIMER+2,AL
	1076	
	1077	;----- READ CASSETTE INPUT
	1078	
E49A E462	1079	IN AL,PORT_C ; READ VALUE OF CASS IN BIT
E49C 2410	1080	AND AL,10H ; ISOLATE FROM OTHER BITS
E49E A26B00	1081	MOV LAST_VAL,AL
E4A1 E8D514	1082	CALL READ_HALF_BIT
E4A4 E8D214	1083	CALL READ_HALF_BIT
E4A7 E30C	1084	JCXZ F8 ; CAS_ERR
E4A9 81FB4005	1085	CMF BX,MAX_PERIOD
E4AD 7306	1086	JNC F8 ; CAS_ERR
E4AF 81FB1004	1087	CMF BX,MIN_PERIOD
E4B3 7307	1088	JNC ROM_SCAN ; GO TO NEXT TEST IF OK
E4B5	1089	F8: ; CAS_ERR
E4B5 BE39FF90	1090	MOV SI,OFFSET F2 ; CASSETTE WRAP FAILED
E4B9 E8FE01	1091	CALL P_MSG ; GO PRINT ERROR MSG
	1092	-----
	1093	; CHECK FOR OPTIONAL ROM FROM C800D->F4000 IN 2K INCREMENTS ;
	1094	; (A VALID MODULE HAS 'SSAA' IN THE FIRST 2 LOCATIONS, LENGTH ;
	1095	; INDICATOR (LENGTH/512) IN THE 3RD LOCATION AND TEST/INIT. ;
	1096	; CODE STARTING IN THE 4TH LOCATION.) ;
	1097	-----
E4BC	1098	ROM_SCAN:
E4BC BA00C8	1099	MOV DX,0C800H ; SET BEGINNING ADDRESS
E4BF 8EDA	1100	ROM_SCAN_1:
E4C1 2BDB	1101	MOV OS,OX
E4C3 8B07	1102	SUB BX,BX ; SET BX=0000
E4C5 3D55AA	1103	MOV AX,IBX1 ; GET 1ST WORD FROM MODULE
E4C8 7505	1104	CMF AX,0AA55H ; = TO 10 WORD?
E4CA E88701	1105	JNZ NEXT_ROM ; PROCEED TO NEXT ROM IF NOT
E4CD EB04	1106	CALL ROM_CHECK ; GO DD CHECKSUM AND CALL
E4CF	1107	JMP SHORT ARE_WE_DONE ; CHECK FOR END OF ROM SPACE
E4CF 81C28000	1108	NEXT_ROM:
E4D3	1109	ADD DX,0080H ; POINT TO NEXT 2K ADDRESS
E4D3 81FA00F6	1110	ARE_WE_DONE:
E4D7 7CE6	1111	CMF OX,0F600H ; AT F60DD YET?
E4D9 EB0190	1112	JL ROM_SCAN_1 ; GO CHECK ANOTHER ADD. IF NOT
	1113	JMP BASE_ROM_CHK ; GO CHECK BASIC ROM
	1114	-----
	1115	; ROS CHECKSUM II ;
	1116	; DESCRIPTION ;
	1117	; A CHECKSUM IS DONE FOR THE 4 ROS ;
	1118	; MODULES CONTAINING BASIC CODE ;
	1119	-----
E4DC	1120	BASE_ROM_CHK:
E4DC	1121	E4:
E4DC 28DB	1122	SUB BX,BX ; SETUP STARTING ROS ADDR
E4DE 8EDA	1123	MOV OS,OX
E4E0 E86907	1124	CALL ROS_CHECKSUM ; CHECK ROS

LOC OBJ	LINE	SOURCE
E4E3 7403	1125	JE ES ; CONTINUE IF OK
E4E5 E82103	1126	CALL ROM_ERR ; POST ERROR
E4E8	1127	E5:
E4E8 80C602	1128	ADD 0H,02H ; POINT TO NEXT 8K MOCOULE
E4EB 80FEFE	1129	CNP DN,DFEH
E4EE 75EC	1130	JNZ E4 ; YES - CONTINUE
E4F0 1F	1131	POP OS ; RECOVER DATA SEG PTR
	1132	;
	1133	DISKETTE ATTACHMENT TEST ;
	1134	DESCRIPTION ;
	1135	CHECK IF IPL DISKETTE DRIVE IS ATTACHED TO SYSTEM. IF ATTACHED, ;
	1136	VERIFY STATUS OF NEC FDC AFTER A RESET. ISSUE A RECAL AND SEEK ;
	1137	CHD TO FDC AND CHECK STATUS. COMPLETE SYSTEM INITIALIZATION ;
	1138	THEN PASS CONTROL TO THE BOOT LOADER PROGRAM. ;
	1139	;
E4F1	1140	F9:
E4F1 A01000	1141	MOV AL,BYTE PTR EQUIP_FLAG ; GET SENSE SMS INFO
E4F4 A801	1142	TEST AL,D1H ; IPL DISKETTE DRIVE ATTON?
E4F6 750A	1143	JNZ F1D ; NO -SKIP THIS TEST
E4F8 803E120001	1144	CNP NFG_TST,1 ; MANUFACTURING TEST MODE?
E4FD 753D	1145	JNE F15A ; NO - GO TO BOOT LOADER
E4FF E959FB	1146	JNP START ; YES - LOOP POWER-ON-DIAGS
E502	1147	F10:
E502 E421	1148	IN AL,INTA01 ; DISK_TEST
E504 24BF	1149	AND AL,0BFH ; ENABLE DISKETTE INTERRUPTS
E506 E621	1150	OUT INTAD1,AL
E508 B400	1151	MOV AH,0 ; RESET NEC FDC
E50A 8AD4	1152	MOV DL,AH ; (POINT TO DISKETTE)
E50C C013	1153	INT 13H ; VERIFY STATUS AFTER RESET
E50E 7221	1154	JC F13
	1155	;
	1156	----- TURN DRIVE 0 MOTOR ON
	1157	;
E510 BAF203	1158	MOV DX,03F2H ; GET ADDR OF FDC CARD
E513 52	1159	PUSH DX ; SAVE IT
E514 B01C	1160	MOV AL,1CH ; TURN MOTOR ON, EN DMA/INT
E516 EE	1161	OUT DX,AL ; WRITE FDC CONTROL REG
E517 2BC9	1162	SUB CX,CX
E519	1163	F11:
E519 E2FE	1164	LOOP F11 ; MOTOR_WAIT:
E51B	1165	F12:
E51B E2FE	1166	LOOP F12 ; WAIT FOR 1 SECOND
E51D 3302	1167	XOR DX,DX ; MOTOR_WAIT1:
E51F B501	1168	MOV CN,1 ; SELECT DRIVE 0
E521 86143E00	1169	MOV SEEK_STATUS,0L ; SELECT TRACK 1
E525 E05509	1170	CALL SEEK
E528 7207	1171	JC F13 ; RECALIBRATE DISKETTE
E52A B522	1172	MOV CN,34 ; GO TO ERR SUBROUTINE IF ERR
E52C E84E09	1173	CALL SEEK ; SELECT TRACK 34
E52F 7307	1174	JNC F14 ; SEEK TO TRACK 34
E531	1175	F13:
E531 BEEAFF90	1176	MOV SI,OFFSET F3 ; OK, TURN MOTOR OFF
E535 E68201	1177	CALL P_MSG ; OSK_ERR:
	1178	;
	1179	----- TURN DRIVE D MOTOR OFF
	1180	;
E538	1181	F14:
E538 B00C	1182	MOV AL,0CH ; DRQ_OFF:
E53A 5A	1183	POP DX ; TURN DRIVE 0 MOTOR OFF
E53B EE	1184	OUT DX,AL ; RECOVER FDC CTL ADDRESS
	1185	;
	1186	----- SETUP PRINTER AND RS232 BASE ADDRESSES IF DEVICE ATTACHED
	1187	;
E53C	1188	F15A:
E53C 8E1E00	1189	MOV SI,OFFSET KB_BUFFER
E53F 89361A00	1190	MOV BUFFER_HEAD,SI ; SETUP KEYBOARD PARAMETERS
E543 89361C00	1191	MOV BUFFER_TAIL,SI
E547 89368000	1192	MOV BUFFER_START,SI ; DEFAULT TO STANDARD BUFFER
E54B 83C620	1193	ADD SI,32 ; (32 BYTES LONG)
E54E 89368200	1194	MOV BUFFER_END,SI
E552 E421	1195	IN AL,INTAD1
E554 24FC	1196	AND AL,DFCH ; ENABLE TIMER AND KBD INTS
E556 E621	1197	OUT INTAD1,AL
E558 BD3DE690	1198	MOV BP,OFFSET F4 ; PRT_SRC_TBL
E55C 2BF6	1199	SUB SI,SI
E55E	1200	F16:
E55E 2E8856DD	1201	MOV DX,CS:[BP] ; PRT_BASE:
		;
		GET PRINTER BASE ADDR

LOC OBJ	LINE	SOURCE	
E562 B0AA	1202	MOV	AL,0AAH ; WRITE DATA TO PORT A
E564 EE	1203	DUT	DX,AL
E565 52	1204	PUSH	DX
E566 EC	1205	IN	AL,DX ; READ PORT A
E567 5A	1206	POP	DX
E568 3CAA	1207	CMF	AL,0AAH ; DATA PATTERN SAME
E56A 7505	1208	JHE	F17 ; NO - CHECK NEXT PRT CD
E56C 895408	1209	MOV	PRINTER_BASE[SI],DX ; YES - STORE PRT BASE ADDR
E56F 46	1210	INC	SI ; INCREMENT TO NEXT WORD
E570 46	1211	INC	SI
E571	1212	F17:	NO_STORE:
E571 45	1213	INC	BP ; POINT TO NEXT BASE ADDR
E572 45	1214	INC	BP
E573 81FD43E6	1215	CMF	BP,OFFSET F4E ; ALL POSSIBLE ADDRS CHECKED?
E577 75E5	1216	JHE	F16 ; PRT_BASE
E579 2BDB	1217	SUB	BX,BX ; POINTER TO RS232 TABLE
E57B BAF403	1218	MOV	DX,3FAH ; CHECK IF RS232 CD 1 ATTCH?
E57E EC	1219	IN	AL,DX ; READ INTR ID REG
E57F A8F8	1220	TEST	AL,0F8H
E581 7506	1221	JNZ	F18
E583 C707F803	1222	MOV	RS232_BASE[BX],3F6H ; SETUP RS232 CD #1 ADDR
E587 43	1223	INC	BX
E588 43	1224	INC	BX
E589	1225	F18:	
E589 B602	1226	MOV	DX,02H ; CHECK IF RS232 CD 2 ATTCH (AT 2FA)
E58B EC	1227	IN	AL,DX ; READ INTERRUPT ID REG
E58C A8F8	1228	TEST	AL,0F8H
E58E 7506	1229	JNZ	F19 ; BASE_END
E590 C707FB02	1230	MOV	RS232_BASE[BX],2F6H ; SETUP RS232 CD #2
E594 43	1231	INC	BX
E595 43	1232	INC	BX
	1233		
	1234		;----- SET UP EQUIP FLAG TO INDICATE NUMBER OF PRINTERS AND RS232 CARDS
	1235		
E596	1236	F19:	BASE_END:
E596 0BC6	1237	MOV	AX,SI ; SI HAS 2* NUMBER OF RS232
E598 B103	1238	MOV	CL,3 ; SHIFT COUNT
E59A 02C8	1239	ROR	AL,CL ; ROTATE RIGHT 3 POSITIONS
E59C 0AC3	1240	OR	AL,BL ; OR IN THE PRINTER COUNT
E59E A21100	1241	MOV	BYTE PTR EQUIP_FLAG+1,AL ; STORE AS SECOND BYTE
E5A1 B201	1242	MOV	DL,01H ; OX=201
E5A3 EC	1243	IN	AL,DX
E5A4 A80F	1244	TEST	AL,0FH
E5A6 7505	1245	JNZ	F20 ; NO_GAME_CARD
E5A8 800E110010	1246	OR	BYTE PTR EQUIP_FLAG+1,16
E5AA	1247	F20:	
	1248		
	1249		;----- SET DEFAULT TIMEOUT VALUES FOR PRINTER AND RS232
	1250		
E5A0 1E	1251	PUSH	DS
E5AE 07	1252	POP	ES
E5AF BF7800	1253	MOV	DI,OFFSET PRINT_YIM_OUT
E5B2 B81414	1254	MOV	AX,1414H ; PRINTER DEFAULTS (COUNT=20)
E5B5 AB	1255	STOSW	
E5B6 AB	1256	STOSW	
E5B7 B80101	1257	MOV	AX,0101H ; RS232 DEFAULTS=01
E5BA AB	1258	STOSW	
E5BB AB	1259	STOSW	
	1260		
	1261		;----- ENABLE NMI INTERRUPTS
	1262		
E5BC B080	1263	MOV	AL,80H ; ENABLE NMI INTERRUPTS
E5BE E6A0	1264	DUT	0A0H,AL
E5C0 803E120001	1265	CMF	MFG_TST,1 ; MFG MOOE?
E5C5 7406	1266	JE	F21 ; LOAD_BOOT_STRAP
E5C7 BA0100	1267	MOV	DX,1
E5CA E80200	1268	CALL	ERR_BEEP ; BEEP 1 SHORT TONE
	1269		
E5CD	1270	F21:	LOAD_BOOT_STRAP:
E5CD CD19	1271	INT	19H ; BOOTSTRAP
	1272		
	1273		-----
	1274		INITIAL RELIABILITY TEST -- SUBROUTINES
	1275		-----
	1276		ASSUME CS:CODE,DS:DATA
	1277		-----
	1278		SUBROUTINES FOR POWER ON DIAGNOSTICS


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1279 ; THIS PROCEDURE WILL ISSUE ONE LONG TONE (3 SECS) AND ONE OR
1280 ; MORE SHORT TONES (1 SEC) TO INDICATE A FAILURE ON THE PLANAR
1281 ; BOARD, A BAD RAM MODULE, OR A PROBLEM WITH THE CRT.
1282 ; ENTRY PARAMETERS:
1283 ; OH = NUMBER DF LONG TONES TO BEEP
1284 ; DL = NUMBER DF SHORT TONES TO BEEP
1285 ;-----
E603 1286 ERR_BEEP PROC NEAR
E603 1287 ; PUSHF ; SAVE FLAGS
E603 1288 CLI ; DISABLE SYSTEM INTERRUPTS
E603 1289 PUSH OS ; SAVE DS REG CONTENTS
E603 1290 CALL DDS
E603 1291 OR DH,DH ; ANY LONG ONES TO BEEP
E603 1292 JZ G3 ; NO, DO THE SHORT ONES
E603 1293 G1: ; LONG_BEEP:
E603 1294 MOV BL,6 ; COUNTER FOR BEEPS
E603 1295 CALL BEEP ; DO THE BEEP
E603 1296 LOOP G2 ; DELAY BETWEEN BEEPS
E603 1297 DEC DH ; ANY MORE TO DO
E603 1298 JNZ G1 ; DO IT
E603 1299 CMP HFG_TST,1 ; HFG TEST MODE?
E603 1300 JNE G3 ; YES - CONTINUE BEEPING SPEAKER
E603 1301 MOV AL,0CDH ; STOP BLINKING LED
E603 1302 OUT PORT_B,AL
E603 1303 JNP SHORT G1
E603 1304 G3: ; SHORT_BEEP:
E603 1305 MOV BL,1 ; COUNTER FOR A SHORT BEEP
E603 1306 CALL BEEP ; DO THE SOUND
E603 1307 G4:
E603 1308 LOOP G4 ; DELAY BETWEEN BEEPS
E603 1309 DEC DL ; DONE WITH SHORTS
E603 1310 JNZ G3 ; DO SOME MORE
E603 1311 G5:
E603 1312 LOOP G5 ; LONG DELAY BEFORE RETURN
E603 1313 G6:
E603 1314 LOOP G6
E603 1315 POP OS ; RESTORE ORIG CONTENTS OF OS
E603 1316 POPF ; RESTORE FLAGS TO ORIG SETTINGS
E603 1317 RET ; RETURN TO CALLER
E603 1318 ERR_BEEP ENDP
E603 1319
E603 1320 ;----- ROUTINE TO SOUND BEEPER
E603 1321
E603 1322 BEEP PROC NEAR
E603 1323 MOV AL,10110110B ; SET TIM 2,LSB,MSB,BINARY
E603 1324 OUT TIMER+3,AL ; WRITE THE TIMER MODE REG
E603 1325 MOV AX,533H ; DIVISOR FOR 1000 HZ
E603 1326 OUT TIMER+2,AL ; WRITE TIMER 2 CNT - LSB
E603 1327 MOV AL,AH
E603 1328 OUT TIMER+2,AL ; WRITE TIMER 2 CNT - MSB
E603 1329 IN AL,PORT_B ; GET CURRENT SETTINGS DF PORT
E603 1330 MOV AH,AL ; SAVE THAT SETTING
E603 1331 OR AL,03 ; TURN SPEAKER ON
E603 1332 OUT PORT_B,AL
E603 1333 SUB CX,CX ; SET CNT TO WAIT 500 MS
E603 1334 G7:
E603 1335 LOOP G7 ; DELAY BEFORE TURNING OFF
E603 1336 DEC BL ; DELAY CNT EXPIRED?
E603 1337 JNZ G7 ; NO - CONTINUE BEEPING 5PK
E603 1338 MOV AL,AH ; RECOVER VALUE DF PORT
E603 1339 OUT PORT_B,AL
E603 1340 RET ; RETURN TO CALLER
E603 1341 BEEP ENDP
E603 1342
E603 1343 ;-----
E603 1344 ; CONVERT AND PRINT ASCII CODE
E603 1345 ; AL MUST CONTAIN NUMBER TO BE CONVERTED.
E603 1346 ; AX AND BX DESTROYED.
E603 1347 ;-----
E625 1348 XPC_BYTE PROC NEAR
E625 1349 PUSH AX ; RESAVE FOR LOW NIBBLE DISPLAY
E625 1350 MOV CL,4 ; SHIFT COUNT
E625 1351 SHR AL,CL ; NIBBLE SWAP
E625 1352 CALL XLAT_PR ; DO THE HIGH NIBBLE DISPLAY
E625 1353 POP AX ; RECOVER THE NIBBLE
E625 1354 AND AL,0FH ; ISOLATE TO LOW NIBBLE
E625 1355 ; FALL INTO LOW NIBBLE CONVERSION

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LOC OBJ	LINE	SOURCE	
E630	1356	XLAT_PR PROC NEAR	; CONVERT 00-DF TO ASCII CHARACTER
E630 0490	1357	ADD AL,D90H	; ADD FIRST CONVERSION FACTOR
E632 27	1358	DAA	; ADJUST FOR NUMERIC AND ALPHA RANGE
E633 1440	1359	ADC AL,040H	; ADD CONVERSION AND ADJUST LOW NIBBLE
E635 27	1360	DAA	; ADJUST HI NIBBLE TO ASCII RANGE
E636	1361	PRT_HEX PROC NEAR	
E636 B40E	1362	MOV AH,14	; DISPLAY CHAR. IN AL
E638 B700	1363	MOV BH,0	
E63A CD10	1364	INT 10H	; CALL VIDEO_ID
E63C C3	1365	RET	
	1366	PRT_HEX ENDP	
	1367	XLAT_PR ENDP	
	1368	XPC_BYTE ENDP	
	1369		
E63D	1370	F4 LABEL WORD	; PRINTER SOURCE TABLE
E63D BC03	1371	DW 38CH	
E63F 7803	1372	DW 378H	
E641 7802	1373	DW 278H	
E643	1374	F4E LABEL WORD	
	1375		
	1376		
	1377	;----- THIS PROCEDURE WILL SEND A SOFTWARE RESET TO THE KEYBOARD. ;	
	1378	; SCAN CODE 'AA' SHOULD BE RETURNED TO THE CPU. ;	
	1379	;-----	
E643	1380	KBD_RESET PROC NEAR	
E643 B09C	1381	MOV AL,0CH	; SET KBD CLK LINE LOW
E645 E661	1382	OUT PORT_B,AL	; WRITE 0255 PORT B
E647 B95629	1383	MOV CX,1D582	; HOLD KBD CLK LOW FOR 20 MS
E64A	1384	56:	
E64A E2FE	1385	LOOP 56	; LOOP FOR 20 MS
E64C B0CC	1386	MOV AL,0CCH	; SET CLK, ENABLE LINES HIGH
E64E E661	1387	OUT PORT_B,AL	
E650	1388	SP_TEST:	; ENTRY FOR MANUFACTURING TEST 2
E650 B04C	1389	MOV AL,4CH	; SET KBD CLK HIGH, ENABLE LOW
E652 E661	1390	OUT PORT_B,AL	
E654 B0F0	1391	MOV AL,0F0H	; ENABLE KEYBOARD INTERRUPTS
E656 E621	1392	OUT INTA01,AL	; WRITE 0259 IHR
E658 FB	1393	STI	; ENABLE SYSTEM INTERRUPTS
E659 B400	1394	MOV AN,0	; RESET INTERRUPT INDICATOR
E65B 2BC9	1395	SUB CX,CX	; SETUP INTERRUPT TIMEOUT CNT
E65D	1396	59:	
E65D F6C4FF	1397	TEST AH,DFH	; DID A KEYBOARD INTR OCCUR?
E660 7502	1398	JNZ G10	; YES - READ SCAN CODE RETURNED
E662 E2F9	1399	LOOP 59	; NO - LOOP TILL TIMEOUT
E664	1400	610:	
E664 E460	1401	IN AL,PORT_A	; READ KEYBOARD SCAN CODE
E666 0A08	1402	MOV BL,AL	; SAVE SCAN CODE JUST READ
E668 B0CC	1403	MOV AL,0CCH	; CLEAR KEYBOARD
E66A E661	1404	OUT PORT_B,AL	
E66C C3	1405	RET	; RETURN TO CALLER
	1406	KBD_RESET ENDP	
	1407		
	1408		
	1409	;----- BLINK LED PROCEDURE FOR MFG BURN-IN AND RUN-IN TESTS ;	
	1410	; IF LED IS ON, TURN IT OFF. IF OFF, TURN ON. ;	
	1411	;-----	
E66D	1412	BLINK_INT PROC NEAR	
E66D FB	1413	STI	
E66E 50	1414	PUSH AX	; SAVE AX REG CONTENTS
E66F E461	1415	IN AL,PORT_B	; READ CURRENT VAL OF PORT B
E671 8AE0	1416	MOV AN,AL	
E673 F6D0	1417	XOR AL,AL	; FLIP ALL BITS
E675 2440	1418	AND AL,D1000D00B	; ISOLATE CONTRL BIT
E677 80E4BF	1419	AND AN,10111111B	; MASK OUT OF ORIGINAL VAL
E67A 0AC4	1420	OR AL,AH	; OR NEW CONTRL BIT IN
E67C E661	1421	OUT PORT_B,AL	
E67E B020	1422	MOV AL,EDI	
E680 E620	1423	OUT INTA00,AL	
E682 58	1424	PDP AX	; RESTORE AX REG
E683 CF	1425	IRET	
	1426	BLINK_INT ENDP	
	1427		
	1428	;----- CHECKSUM AND CALL INIT CODE IN OPTIONAL ROMS	
	1429		
E684	1430	ROM_CHECK PROC NEAR	
E684 B940D0	1431	MOV AX,DATA	; SET ES=DATA
E687 8EC0	1432	MOV ES,AX	

LOC OBJ	LINE	SOURCE
E689 2AE4	1433	SUB AH,AH ; ZERO OUT AH
E688 8A4702	1434	MOV AL,IBX*2J ; GET LENGTH INDICATOR
E68E B109	1435	MOV CL,09H ; MULTIPLY BY SIZ
E690 D3E0	1436	SHL AX,CL
E692 88C8	1437	MOV CX,AX ; SET COUNT
E694 S1	1438	PUSH CX
E69S B104	1439	MOV CL,4
E697 D3E8	1440	SHR AX,CL
E699 03D0	1441	ADD QX,AX ; SET POINTER TO NEXT MODULE
E69B S9	1442	POP CX
	1443	
E69C E88005	1444	CALL ROS_CHECKSUM_CNT ; DO CHECKSUM
E69F 7405	1445	JZ ROM_CHECK_1
E6A1 E86S01	1446	CALL ROM_ERR ; PRINT ERROR INFO
E6A4 EB13	1447	JMP SHORT ROM_CHECK_END
E6A6	1448	ROM_CHECK_1:
E6A6 S2	1449	PUSH DX ; SAVE POINTER
E6A7 26C70600010300	1450	MOV ES:IO_ROM_INIT,0003H ; LOAD OFFSET
E6AE 268C1E0201	1451	MOV ES:IO_ROM_SEG,05 ; LOAD SEGMENT
E6B3 26FF1E0001	1452	CALL DWORD PTR ES:IO_ROM_INIT ; CALL INIT RTN.
E6B8 SA	1453	POP DX
E6B9	1454	ROM_CHECK_END:
E6B9 C3	1455	RET
	1456	ROM_CHECK ENDP
	1457	
	1458	;
	1459	; THIS SUBROUTINE WILL PRINT A MESSAGE ON THE DISPLAY ;
	1460	;
	1461	; ENTRY REQUIREMENTS: ;
	1462	; SI = OFFSET(ADDRESS) OF MESSAGE BUFFER ;
	1463	; CX = MESSAGE BYTE COUNT ;
	1464	; MAXIMUM MESSAGE LENGTH IS 36 CHARACTERS ;
	1465	;
E6BA	1466	P_MSG PROC NEAR
E6BA E88118	1467	CALL DOS
E6BD 803E120001	1468	CHP HFG_TST,1 ; HFG TEST MODE?
E6C2 7B05	1469	JNE G12 ; NO - DISPLAY ERROR MSG
E6C4 B601	1470	MOV DH,1 ; YES - SETUP TO BEEP SPEAKER
E6C6 E906FF	1471	JMP ERR_BEEP ; YES - BEEP SPEAKER
E6C9	1472	G12: ; WRITE MSG:
E6C9 2E8A04	1473	MOV AL,CS:[SI] ; PUT CHAR IN AL
E6CC 46	1474	INC SI ; POINT TO NEXT CHAR
E6CD 50	1475	PUSH AX ; SAVE PRINT CHAR
E6CE E86SFF	1476	CALL PRT_NEX ; CALL VIDEO_IO
E6D1 58	1477	POP AX ; RECOVER PRINT CHAR
E6D2 3C0A	1478	CHP AL,10 ; WAS IT LINE FEED
E6D4 7BF3	1479	JNE G12 ; NO,KEEP PRINTING STRING
E6D6 C3	1480	RET
	1481	P_MSG ENDP
	1482	
E6D7 29524F40	1483	F3A DB ' ROM',13,10
E6DB 0D		
E6DC 0A		
	1484	
E6DD	1485	D_EOI PROC NEAR
E6DD 50	1486	PUSH AX
E6DE B020	1487	MOV AL,20H
E6E0 E620	1488	OUT 20H,AL
E6E2 58	1489	POP AX
E6E3 CF	1490	IRET
	1491	O_EOI ENDP
	1492	
	1493	;
	1494	; INT 19
	1495	; BOOT STRAP LOADER ;
	1496	; IF A 5 1/4" DISKETTE DRIVE IS AVAILABLE ON THE SYSTEM, ;
	1497	; TRACK 0, SECTOR 1 IS READ INTO THE BOOT LOCATION ;
	1498	; (SEGMENT 0, OFFSET 7C00) AND CONTROL IS TRANSFERRED ;
	1499	; THERE. ;
	1500	; IF THERE IS NO DISKETTE DRIVE, OR IF THERE IS A ;
	1501	; HARDWARE ERROR CONTROL IS TRANSFERRED TO THE RESIDENT ;
	1502	; BASIC ENTRY POINT. ;
	1503	; ;
	1504	; IPL ASSUMPTIONS: ;
	1505	; 8255 PORT 60H BIT 0 = 1 IF IPL FROM DISKETTE ;
	1506	;
	1507	ASSUME CS:CODE,DS:ABS0

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LOC OBJ          LINE  SOURCE

1508
1509 1----- IPL HAS SUCCESSFUL
1510
E6E4             1511 H4:
E6E4 EA007C0000  1512     JNP     BOOT_LOCN
E6F2             1513     ORG     0E6F2N
E6F2             1514 BOOT_STRAP  PROC     NEAR
E6F2 FB         1515     STI                     ; ENABLE INTERRUPTS
E6F3 2BC0       1516     SUB     AX,AX
E6F5 0ED8       1517     NDV     DS,AX
1518
1519 1----- RESET DISKETTE PARAMETER TABLE VECTOR
1520
E6F7 C7067800C7EF 1521     MOV     WORD PTR DISK_POINTER,OFFSET DISK_BASE
E6FD 8C0E7A00     1522     NDV     WORD PTR DISK_POINTER+2,CS
E701 A11004       1523     MOV     AX,DATA_WORD[OFFSET EQUIP_FLAG] ; GET THE EQUIPMENT SWITCHES
E704 A801         1524     TEST    AL,1                     ; ISLDATE IPL SENSE SWITCH
E706 741E         1525     JZ      H3                      ; GO TO CASSETTE BASIC ENTRY POINT
1526
1527 1----- MUST LOAD SYSTEM FROM DISKETTE -- CX HAS RETRY COUNT
1528
E708 B90400       1529     MOV     CX,4                     ; SET RETRY COUNT
E708             1530 H1:                     ; IPL_SYSTEM
E708 51           1531     PUSH    CX                     ; SAVE RETRY COUNT
E70C B400         1532     MOV     AN,0                   ; RESET THE DISKETTE SYSTEM
E70E C013         1533     INT     13H                  ; DISKETTE_IO
E710 720F         1534     JC      H2                     ; IF ERROR, TRY AGAIN
E712 B80102       1535     MOV     AX,201H                ; READ IN THE SINGLE SECTOR
E715 2B02         1536     SUB     0X,0X
E717 0EC2         1537     MOV     ES,DX
E719 BB007C       1538     MOV     BX,OFFSET BOOT_LOCN
E71C B90100       1539     MOV     CX,1                     ; SECTOR 1, TRACK 0
E71F C013         1540     INT     13H                  ; DISKETTE_IO
E721 59           1541 H2:     POP     CX                     ; RECOVER RETRY COUNT
E722 73C0         1542     JNC     H4                     ; CF SET BY UNSUCCESSFUL READ
E724 E2E5         1543     LOOP    H1                     ; DO IT FOR RETRY TIMES
1544
1545 1----- UNABLE TO IPL FROM THE DISKETTE
1546
E726             1547 H3:                     ; CASSETTE_JUMP:
E726 C018         1548     INT     18H                     ; USE INTERRUPT VECTOR TO GET TO BASIC
1549 BOOT_STRAP    1549     ENDP
1550
1551 1-----INT 14-----
1552 ; RS232_IO
1553 ; THIS ROUTINE PROVIDES BYTE STREAM I/O TO THE COMMUNICATIONS
1554 ; PORT ACCORDING TO THE PARAMETERS:
1555 ; (AH)=0 INITIALIZE THE COMMUNICATIONS PORT
1556 ; (AL) HAS PARAMETERS FOR INITIALIZATION
1557 ;
1558 ; 7 6 5 4 3 2 1 0
1559 ; ----- BAUD RATE -- -PARITY-- STOPBIT --WORD LENGTH--
1560 ; 000 - 110 X0 - NONE 0 - 1 10 - 7 BITS
1561 ; 001 - 150 01 - 000 1 - 2 11 - 8 BITS
1562 ; 010 - 300 11 - EVEN
1563 ; 011 - 600
1564 ; 100 - 1200
1565 ; 101 - 2400
1566 ; 110 - 4800
1567 ; 111 - 9600
1568 ;
1569 ; ON RETURN, CONDITIONS SET AS IN CALL TO COMMO STATUS (AH=3)
1570 ; (AN)=1 SEND THE CHARACTER IN (AL) OVER THE COMMO LINE
1571 ; (AL) REGISTER IS PRESERVED
1572 ; ON EXIT, BIT 7 OF AH IS SET IF THE ROUTINE WAS UNABLE
1573 ; TO TRANSMIT THE BYTE OF DATA OVER THE LINE.
1574 ; IF BIT 7 OF AH IS NOT SET, THE REMAINDER OF AH
1575 ; IS SET AS IN A STATUS REQUEST, REFLECTING THE
1576 ; CURRENT STATUS OF THE LINE.
1577 ; (AH)=2 RECEIVE A CHARACTER IN (AL) FROM COMMO LINE BEFORE
1578 ; RETURNING TO CALLER
1579 ; ON EXIT, AH HAS THE CURRENT LINE STATUS, AS SET BY THE
1580 ; STATUS ROUTINE, EXCEPT THAT THE ONLY BITS
1581 ; LEFT ON ARE THE ERROR BITS (7,4,3,2,1)
1582 ; IF AH HAS BIT 7 ON (TIME OUT) THE REMAINING
1583 ; BITS ARE NOT PREDICTABLE.
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1585      OCCURRED.
1586      (AH)=3 RETURN THE COMPTON PORT STATUS IN (AX)
1587      AH CONTAINS THE LINE STATUS
1588      BIT 7 = TIME OUT
1589      BIT 6 = TRANS SHIFT REGISTER EMPTY
1590      BIT 5 = TRAH HOLDING REGISTER EMPTY
1591      BIT 4 = BREAK DETECT
1592      BIT 3 = FRAMING ERROR
1593      BIT 2 = PARITY ERROR
1594      BIT 1 = OVERRUN ERROR
1595      BIT 0 = DATA READY
1596      AL CONTAINS THE MODEM STATUS
1597      BIT 7 = RECEIVED LINE SIGNAL DETECT
1598      BIT 6 = RING INDICATOR
1599      BIT 5 = DATA SET READY
1600      BIT 4 = CLEAR TO SEND
1601      BIT 3 = DELTA RECEIVE LINE SIGNAL DETECT
1602      BIT 2 = TRAILING EDGE RING DETECTOR
1603      BIT 1 = DELTA DATA SET READY
1604      BIT 0 = DELTA CLEAR TO SEND
1605
1606      (DX) = PARAMETER INDICATING WHICH RS232 CARD (0,1 ALLOWED)
1607
1608      DATA AREA RS232_BASE CONTAINS THE BASE ADDRESS OF THE 8250 ON THE
1609      CARD LOCATION 400H CONTAINS UP TO 4 RS232 ADDRESSES POSSIBLE
1610      DATA AREA LABEL RS232_TIM_OUT (BYTE) CONTAINS OUTER LOOP COUNT
1611      VALUE FOR TIMEOUT (DEFAULT=1)
1612      OUTPUT
1613      AX MODIFIED ACCORDING TO PARMS OF CALL
1614      ALL OTHERS UNCHANGED
1615      -----
1616      ASSUME CS:CODE,DS:DATA
1617      DRG DE729H
1618      LABEL WORD
1619      OW 1047
1620      OW 768
1621      OW 384
1622      DW 192
1623      OW 96
1624      OW 48
1625      OW 24
1626      OW 12
1627
1628      RS232_IO PROC FAR
1629
1630      ;----- VECTOR TO APPROPRIATE ROUTINE
1631
1632      STI
1633      PUSH OS
1634      PUSH OX
1635      PUSH SI
1636      PUSH OI
1637      PUSH CX
1638      PUSH BX
1639      MOV SI,DX
1640      MOV DI,DX
1641      SHL SI,1
1642      CALL DDS
1643      MOV OX,RS232_BASE(SI)
1644      OR DX,OX
1645      JZ A3
1646      OR AH,AH
1647      JZ A4
1648      DEC AH
1649      JZ A5
1650      DEC AH
1651      JZ A12
1652      A2:
1653      DEC AH
1654      JNZ A3
1655      JMP A18
1656      A3:
1657      POP BX
1658      POP CX
1659      POP DI
1660      POP SI
1661      POP DX

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LOC	OBJ	LINE	SOURCE
E767	1F	1662	POP DS
E768	CF	1663	IRET
		1664	;
		1665	;
		1666	;
		1667	;
E769		1667	A4:
E769	8AE0	1668	MOV AH,AL
E76B	83C203	1669	ADD DX,3
E76E	B080	1670	MOV AL,80H
E770	EE	1671	OUT DX,AL
		1672	;
		1673	;
		1674	;
E771	8AD4	1675	MOV DL,AH
E773	B104	1676	MOV CL,4
E775	D2C2	1677	ROL DL,CL
E777	81E20E00	1678	AND DX,0EH
E77B	BF29E7	1679	MOV DI,OFFSET A1
E77E	03FA	1680	ADD DI,DX
E780	8B14	1681	MOV DX,RS232_BASE[SI]
E782	42	1682	INC DX
E783	2E8A4501	1683	MOV AL,CS:[DI]*1
E787	EE	1684	OUT DX,AL
E788	4A	1685	DEC DX
E789	2E8A05	1686	MOV AL,CS:[DI]
E78C	EE	1687	OUT DX,AL
E78D	83C203	1688	ADD DX,3
E790	8AC4	1689	MOV AL,AH
E792	241F	1690	AND AL,01FH
E794	EE	1691	OUT DX,AL
E795	4A	1692	DEC DX
E796	4A	1693	DEC DX
E797	B000	1694	MOV AL,0
E799	EE	1695	OUT DX,AL
E79A	EB49	1696	JMP SHORT A18
		1697	;
		1698	;
		1699	;
E79C		1700	A5:
E79C	50	1701	PUSH AX
E79D	83C204	1702	ADD DX,4
E7A0	B003	1703	MOV AL,3
E7A2	EE	1704	OUT DX,AL
E7A3	42	1705	INC DX
E7A4	42	1706	INC DX
E7A5	B730	1707	MOV BN,30H
E7A7	E84800	1708	CALL WAIT_FOR_STATUS
E7AA	740B	1709	JE A9
E7AC		1710	A7:
E7AC	59	1711	POP CX
E7AD	8AC1	1712	MOV AL,CL
E7AF		1713	A8:
E7AF	80CC80	1714	OR AH,80H
E7B2	EBAE	1715	JMP A3
E7B4		1716	A9:
E7B4	4A	1717	DEC DX
E7B5		1718	A10:
E7B5	B720	1719	MOV BN,20H
E7B7	E83800	1720	CALL WAIT_FOR_STATUS
E7BA	75F0	1721	JNZ A7
E7BC		1722	A11:
E7BC	83EA05	1723	SUB DX,5
E7BF	59	1724	POP CX
E7C0	8AC1	1725	MOV AL,CL
E7C2	EE	1726	OUT DX,AL
E7C3	EB9D	1727	JMP A3
		1728	;
		1729	;
		1730	;
E7C5		1731	A12:
E7C5	83C204	1732	ADD DX,4
E7C8	B001	1733	MOV AL,1
E7CA	EE	1734	OUT DX,AL
E7CB	42	1735	INC DX
E7CC	42	1736	INC DX
E7CD		1737	A13:
E7CD	B720	1738	MOV BH,20H

LOC OBJ	LINE	SOURCE	
E7CF E02000	1739	CALL	WAIT_FOR_STATUS ; TEST FOR DSR
E7D2 75DB	1740	JNZ	A6 ; RETURN WITH ERROR
E7D4	1741	A15:	WAIT_DSR_END ;
E7D4 4A	1742	DEC	0X ; LINE STATUS REGISTER
E7D5	1743	A16:	WAIT_RECV ;
E7D5 B701	1744	MOV	BM,1 ; RECEIVE BUFFER FULL
E7D7 E01800	1745	CALL	WAIT_FOR_STATUS ; TEST FOR REC. BUFF. FULL
E7DA 75D3	1746	JNZ	AB ; SET TIME OUT ERROR
E7DC	1747	A17:	GET_CHAR ;
E7DC 00E41E	1748	AND	AH,00D11110B ; TEST FOR ERR CONDITIONS ON RECV CHAR
E7DF 0B14	1749	MOV	DX,RS232_BASE[51] ; DATA PORT
E7E1 EC	1750	IN	AL,0X ; GET CHARACTER FROM LINE
E7E2 E970FF	1751	JMP	A3 ; RETURN
	1752		
	1753	;----- COMMO PORT STATUS ROUTINE	
	1754		
E7E5	1755	A1B:	
E7E5 0B14	1756	MOV	DX,RS232_BASE[51] ;
E7E7 83C205	1757	ADD	0X,5 ; CONTRDL PORT
E7EA EC	1758	IN	AL,0X ; GET LINE CONTROL STATUS
E7EB 8AE0	1759	MOV	AN,AL ; PUT IN AN FOR RETURN
E7ED 42	1760	INC	0X ; POINT TO MODEM STATUS REGISTER
E7EE EC	1761	IN	AL,0X ; GET MODEM CONTROL STATUS
E7EF E970FF	1762	JMP	A3 ; RETURN
	1763	;-----	
	1764	; WAIT FOR STATUS ROUTINE ;	
	1765	; ;	
	1766	; ENTRY: ;	
	1767	; BN=STATUS BIT(S) TO LOOK FOR, ;	
	1768	; 0X=ADDR. OF STATUS REG ;	
	1769	; EXIT: ;	
	1770	; ZERO FLAG ON = STATUS FOUND ;	
	1771	; ZERO FLAG OFF = TIMEOUT. ;	
	1772	; AN=LAST STATUS READ ;	
	1773	;-----	
E7F2	1774	WAIT_FOR_STATUS PROC	NEAR
E7F2 6A5D7C	1775	MOV	BL,RS232_TIR_OUT[01] ; LOAD OUTER LOOP COUNT
E7F5	1776	WFS0:	
E7F5 2BC9	1777	SUB	CX,CX
E7F7	1778	WFS1:	
E7F7 EC	1779	IN	AL,0X ; GET STATUS
E7F8 8AE0	1780	MOV	AN,AL ; MOVE TO AN
E7FA 22C7	1781	AND	AL,BN ; ISOLATE BITS TO TEST
E7FC 3AC7	1782	CMF	AL,BN ; EXACTLY = TO MASK
E7FE 7408	1783	JE	WFS_END ; RETURN WITH ZERO FLAG ON
E800 E2F5	1784	LOOP	WFS1 ; TRY AGAIN
E802 FECB	1785	DEC	BL
E804 75EF	1786	JNZ	WFS0
E806 0AFF	1787	OR	BN,BN ; SET ZERO FLAG OFF
E808	1788	WFS_END:	
E808 C3	1789	RET	
	1790	WAIT_FOR_STATUS ENDP	
	1791	RS232_IO	ENDP
	1792		
	1793	;-----	
	1794	; PRINT ADDRESS AND ERROR MESSAGE FOR ROM CHECKSUM ERRORS ;	
	1795	;-----	
E809	1796	ROM_ERR PROC	NEAR
E809 52	1797	PUSH	0X ; SAVE POINTER
E80A 50	1798	PUSH	AX
E80B 0CDA	1799	MOV	DX,D5 ; GET ADDRESS POINTER
E80D 01FA00C8	1800	CMF	DX,0CB000H
E811 7E13	1801	JLE	ROM_ERR_BEEP ; SPECIAL ERROR INDICATION
E813 8AC6	1802	MOV	AL,BN
E815 E80DFE	1803	CALL	XPC_BYTE ; DISPLAY ADDRESS
E818 8AC2	1804	MOV	AL,D1
E81A E808FE	1805	CALL	XPC_BYTE
E81D 0E07E6	1806	MOV	SI,OFF5EY F3A ; DISPLAY ERROR MSG
E820 E897FE	1807	CALL	P_MSG
E823	1808	ROM_ERR_END:	
E823 58	1809	POP	AX
E824 5A	1810	POP	DX
E825 C3	1811	RET	
E826	1812	ROM_ERR_BEEP:	
E826 BA0201	1813	MOV	DX,0102N ; BEEP 1 LONG, 2 SHORT
E829 E8A3FD	1814	CALL	ERR_BEEP
E82C EBF5	1815	JMP	SHORT ROM_ERR_END

LOC OBJ	LINE	SOURCE
	1816	ROM_ERR ENDP
	1817	
	1818	;----- INT 16 -----
	1819	; KEYBOARD I/O
	1820	; THESE ROUTINES PROVIDE KEYBOARD SUPPORT
	1821	; INPUT
	1822	; (AH)=0 READ THE NEXT ASCII CHARACTER STRUCK FROM THE KEYBOARD
	1823	; RETURN THE RESULT IN (AL), SCAN CODE IN (AH)
	1824	; (AH)=1 SET THE Z FLAG TO INDICATE IF AN ASCII CHARACTER IS
	1825	; AVAILABLE TO BE READ.
	1826	; (ZF)=1 -- NO CODE AVAILABLE
	1827	; (ZF)=0 -- CODE IS AVAILABLE
	1828	; IF ZF = 0, THE NEXT CHARACTER IN THE BUFFER TO BE READ
	1829	; IS IN AX, AND THE ENTRY REMAINS IN THE BUFFER
	1830	; (AH)=2 RETURN THE CURRENT SHIFT STATUS IN AL REGISTER
	1831	; THE BIT SETTINGS FOR THIS CODE ARE INDICATED IN THE
	1832	; THE EQUATES FOR KB_FLAG
	1833	; OUTPUT
	1834	; AS NOTED ABOVE, ONLY AX AND FLAGS CHANGED
	1835	; ALL REGISTERS PRESERVED
	1836	;-----
	1837	ASSUME CS:CODE,DS:DATA
E82E	1838	ORG 0E82EH
E82E	1839	KEYBOARD_TO PROC FAR
E82E FB	1840	STI ; INTERRUPTS BACK ON
E82F 1E	1841	PUSH D5 ; SAVE CURRENT D5
E830 53	1842	PUSH BX ; SAVE BX TEMPORARILY
E831 E80A17	1843	CALL DOS
E834 0AE4	1844	DR AH,AH ; AH=0
E836 740A	1845	JZ K1 ; ASCII_READ
E838 FECC	1846	DEC AH ; AH=1
E83A 741E	1847	JZ K2 ; ASCII_STATUS
E83C FECC	1848	DEC AH ; AH=2
E83E 742B	1849	JZ K3 ; SHIFT_STATUS
E840 EB2C	1850	JMP SHORT INT10_END ; EXIT
	1851	
	1852	;----- READ THE KEY TO FIGURE OUT WHAT TO DO
	1853	
E842	1854	K1:
E842 FB	1855	STI ; ASCII READ
E843 90	1856	HDP ; INTERRUPTS BACK ON DURING LOOP
E844 FA	1857	CLI ; ALLOW AN INTERRUPT TO OCCUR
E845 8B1E1A00	1858	MOV BX,BUFFER_HEAD ; GET POINTER TO HEAD OF BUFFER
E849 3B1E1C00	1859	CMPL BX,BUFFER_TAIL ; TEST END OF BUFFER
E84D 74F3	1860	JZ K1 ; LOOP UNTIL SOMETHING IN BUFFER
E84F 8B07	1861	MOV AX,[BX] ; GET SCAN CODE AND ASCII CODE
E851 E81D00	1862	CALL K4 ; MOVE POINTER TO NEXT POSITION
E854 891E1A00	1863	MOV BUFFER_HEAD,BX ; STORE VALUE IN VARIABLE
E856 EB14	1864	JMP SHORT INT10_END ; RETURN
	1865	
	1866	;----- ASCII STATUS
	1867	
E85A	1868	K2:
E85A FA	1869	CLI ; INTERRUPTS OFF
E85B 8B1E1A00	1870	MOV BX,BUFFER_HEAD ; GET HEAD POINTER
E85F 3B1E1C00	1871	CMPL BX,BUFFER_TAIL ; IF EQUAL (Z=1) THEN NOTHING THERE
E863 8B07	1872	MOV AX,[BX]
E865 FB	1873	STI ; INTERRUPTS BACK ON
E866 5B	1874	POP BX ; RECOVER REGISTER
E867 1F	1875	POP DS ; RECOVER SEGMENT
E868 CA0200	1876	RET 2 ; THROW AWAY FLAGS
	1877	
	1878	;----- SHIFT STATUS
	1879	
E86B	1880	K3:
E86B A01700	1881	MOV AL,KB_FLAG ; GET THE SHIFT STATUS FLAGS
E86E	1882	INT10_END:
E86E 5B	1883	POP BX ; RECOVER REGISTER
E86F 1F	1884	POP DS ; RECOVER REGISTERS
E870 CF	1885	IRET ; RETURN TO CALLER
	1886	KEYBOARD_IO ENDP
	1887	
	1888	;----- INCREMENT A BUFFER POINTER
	1889	
E871	1890	K4
E871 43	1891	PROC NEAR
E872 43	1892	INC BX ; MOVE TO NEXT WORD IN LIST
		INC BX

LOC	OBJ	LINE	SOURCE
E873	301E8200	1893	CMF BX,BUFFER_END ; AY END OF BUFFER?
E877	7504	1894	JNE K5 ; NO, CONTINUE
E879	881E8000	1895	MOV BX,BUFFER_STARTY ; YES, RESET TO BUFFER BEGINNING
E87D		1896	K5:
E87D	C3	1897	REY
		1898	K4 ENDP
		1899	
		1900	;----- YABLE OF SHIFT KEYS AND MASK VALUES
		1901	
E87E		1902	K6 LABEL BYTE
E87E	52	1903	DB INS_KEY ; INSERT KEY
E87F	3A	1904	DB CAPS_KEY,NUM_KEY,SCROLL_KEY,ALT_KEY,CTL_KEY
E880	45		
E881	46		
E882	38		
E883	10		
E884	2A	1905	DB LEFTY_KEY,RIGHT_KEY
E885	36		
	0008	1906	K6L EQU \$-K6
		1907	
		1908	;----- SHIFT MASK YABLE
		1909	
E886		1910	K7 LABEL BYTE
E886	80	1911	DB INS_SHIFT ; INSERT MOOE SHIFT
E887	40	1912	DB CAPS_SHIFT,NUM_SHIFT,SCROLL_SHIFT,ALT_SHIFT,CTL_SHIFT
E888	20		
E889	10		
E88A	08		
E88B	04		
E88C	02	1913	DB LEFT_SHIFT,RIGHT_SHIFT
E88D	01		
		1914	
		1915	;----- SCAN CODE TABLES
		1916	
E88E	1B	1917	K8 DB 27,-1,0,-1,-1,-1,30,-1
E88F	FF		
E890	00		
E891	FF		
E892	FF		
E893	FF		
E894	1E		
E895	FF		
E896	FF	1918	DB -1,-1,-1,31,-1,127,-1,17
E897	FF		
E898	FF		
E899	1F		
E89A	FF		
E89B	7F		
E89C	FF		
E89D	11		
E89E	17	1919	DB 23,5,18,20,25,21,9,15
E89F	05		
E8A0	12		
E8A1	14		
E8A2	19		
E8A3	15		
E8A4	09		
E8A5	0F		
E8A6	10	1920	DB 16,27,29,10,-1,1,19
E8A7	1B		
E8A8	10		
E8A9	0A		
E8AA	FF		
E8AB	01		
E8AC	13		
E8AD	04	1921	DB 4,6,7,8,10,11,12,-1,-1
E8AE	06		
E8AF	07		
E8B0	08		
E8B1	0A		
E8B2	0B		
E8B3	0C		
E8B4	FF		
E8B5	FF		
E8B6	FF	1922	DB -1,-1,28,26,24,3,22,2
E8B7	FF		
E8B8	1C		

LOC	OBJ	LINE	SOURCE
E0B9	1A		
E0BA	18		
E0BB	03		
E0BC	16		
E0BD	02		
E0BE	0E	1923	DB 14,13,-1,-1,-1,-1,-1
E0BF	0D		
E0C0	FF		
E0C1	FF		
E0C2	FF		
E0C3	FF		
E0C4	FF		
E0C5	FF		
E0C6	20	1924	DB ' ', -1
E0C7	FF		
E0C8		1925	i----- CTL TABLE SCAN
E0C8	5E	1926	K9 LABEL BYTE
E0C9	5F	1927	DB 94,95,96,97,98,99,100,101
E0CA	60		
E0CB	61		
E0CC	62		
E0CD	63		
E0CE	64		
E0CF	65		
E0D0	66	1928	DB 102,103,-1,-1,119,-1,132,-1
E0D1	67		
E0D2	FF		
E0D3	FF		
E0D4	77		
E0D5	FF		
E0D6	84		
E0D7	FF		
E0D8	73	1929	DB 115,-1,116,-1,117,-1,118,-1
E0D9	FF		
E0DA	74		
E0DB	FF		
E0DC	75		
E0DD	FF		
E0DE	76		
E0DF	FF		
E0E0	FF	1930	DB -1
E0E1		1931	i----- LC TABLE
E0E1	1B	1932	K10 LABEL BYTE
E0E2	31323334353637 3839302030	1933	DB 018H, '1234567890=-', 08H, 09H
E0EE	08		
E0EF	09		
E0F0	71776572747975 696F705B50	1934	DB 'qwertyuiop[]', 0DH, -1, 'asdfghjkl;', 027H
E0FC	DD		
E0FD	FF		
E0FE	6173646667686A 6B6C3B		
E908	27		
E909	60	1935	DB 60H, -1, 5CH, 'zxcvbnm,.,/ ', -1, ' ', -1, ' '
E90A	FF		
E90B	5C		
E90C	7A786376626E6D 2C2E2F		
E916	FF		
E917	2A		
E918	FF		
E919	20		
E91A	FF	1936	DB -1
E91B		1937	i----- UC TABLE
E91B	1B	1938	K11 LABEL BYTE
E91C	21402324	1939	DB 27, '1234', 37, 05EH, '&#()_+', 08H, 0
E920	25		
E921	5E		
E922	262A28295F2B		
E928	08		
E929	00		
E92A	51574552545955 494F507B7D	1940	DB 'QWERTYUIOP[]', 00H, -1, 'ASDFGHJKL:=""

LOC OBJ	LINE	SOURCE
E936 00		
E937 FF		
E938 4153446647484A		
4B4C3A22		
E943 7E	1941	DB 07EH,-1,' ZXCVBNM >?',-1,0,-1,' ',-1
E944 FF		
E945 7C5A584356424E		
4D3C3E3F		
E950 FF		
E951 00		
E952 FF		
E953 20		
E954 FF		
E955	1942	;----- UC TABLE SCAN
E955 54	1943	K12 LABEL BYTE
E956 55	1944	DB B9,85,86,87,88,89,90
E957 56		
E958 57		
E959 58		
E95A 59		
E95B 5A		
E95C 5B	1945	DB 91,92,93
E95D 5C		
E95E 5D		
E95F	1946	;----- ALT TABLE SCAN
E95F 6B	1947	K13 LABEL BYTE
E960 69	1948	DB 104,105,106,107,108
E961 6A		
E962 6B		
E963 6C		
E964 6D	1949	DB 109,110,111,112,113
E965 6E		
E966 6F		
E967 70		
E968 71		
E969	1950	;----- MM STATE TABLE
E969 373B392D343536	1951	K14 LABEL BYTE
2B313E33302E	1952	DB '7B9-456+1230.'
E976	1953	;----- BASE CASE TABLE
E976 47	1954	K15 LABEL BYTE
E977 4B	1955	DB 71,72,73,-1,75,-1,77
E978 49		
E979 FF		
E97A 4B		
E97B FF		
E97C 4D		
E97D FF	1956	DB -1,79,80,81,82,83
E97E 4F		
E97F 50		
E980 51		
E981 52		
E982 53		
E987	1957	
E987	1958	;----- KEYBOARD INTERRUPT ROUTINE
E987	1959	
E987 FB	1960	ORG 0E9B7H
E988 50	1961	KB_INT PROC FAR
E989 53	1962	STI ; ALLOW FURTHER INTERRUPTS
E98A 51	1963	PUSH AX
E98B 52	1964	PUSH BX
E98C 56	1965	PUSH CX
E98D 57	1966	PUSH DX
E98E 1E	1967	PUSH SI
E98F 06	1968	PUSH DI
E990 FC	1969	PUSH DS
E991 E8AA15	1970	PUSH ES
E994 E460	1971	CLO ; FORWARD DIRECTION
E996 50	1972	CALL DDS
E997 E461	1973	IN AL,KB_DATA ; READ IN THE CHARACTER
E999 8AE0	1974	PUSH AX ; SAVE IT
E99B 0C80	1975	IN AL,KB_CTL ; GET THE CONTROL PORT
	1976	MOV AH,AL ; SAVE VALUE
	1977	OR AL,B0H ; RESET BIT FOR KEYBOARD

LOC OBJ	LINE	SOURCE
E990 E661	1978	OUT KB_CTL,AL
E99F 86E0	1979	XCHG AH,AL ; GET BACK ORIGINAL CONTROL
E9A1 E661	1980	OUT KB_CTL,AL ; KB HAS BEEN RESET
E9A3 58	1981	POP AX ; RECOVER SCAN CODE
E9A4 8AE0	1982	MOV AH,AL ; SAVE SCAN CODE IN AH ALSO
	1983	
	1984	;
	1985	;----- TEST FOR OVERRUN SCAN CODE FROM KEYBOARD
E9A6 3CFF	1986	CHP AL,0FFH ; IS THIS AH OVERRUN CHAR
E9A8 7503	1987	JNZ K16 ; NO, TEST FOR SHIFT KEY
E9AA E97A02	1988	JMP K62 ; BUFFER_FULL_BEEP
	1989	
	1990	;----- TEST FOR SHIFT KEYS
	1991	
E9A0	1992	K16: ; TEST_SHIFT
E9A0 247F	1993	AND AL,07FH ; TURN OFF THE BREAK BIT
E9AF 0E	1994	PUSH CS
E9B0 07	1995	POP ES
E9B1 8F7EE8	1996	MOV DI,OFFSET K6 ; ESTABLISH ADDRESS OF SHIFT TABLE
E9B4 B90800	1997	MOV CX,K6L ; SHIFT KEY TABLE
E9B7 F2	1998	REPNE SCASB ; LENGTH
E9B8 AE		
E9B9 8AC4	1999	MOV AL,AH ; LOOK THROUGH THE TABLE FOR A MATCH
E9BB 7403	2000	JE K17 ; RECOVER SCAN CODE
E9BD E98500	2001	JMP K25 ; JUMP IF MATCH FOUND
	2002	; IF NO MATCH, THEN SHIFT NOT FOUND
	2003	;
	2004	;----- SHIFT KEY FOUND
E9C0 81EF7FE8	2005	K17: SUB DI,OFFSET K6+1 ; ADJUST PTR TO SCAN CODE MTCH
E9C4 2E8AAS86E8	2006	MOV AH,CS:K7(OI) ; GET MASK INTO AH
E9C9 A880	2007	TEST AL,80H ; TEST FOR BREAK KEY
E9CB 7551	2008	JNZ K23 ; BREAK_SHIFT_FOUND
	2009	
	2010	;----- SHIFT MAKE FOUND, DETERMINE SET OR TOGGLE
	2011	
E9C0 80FC10	2012	CHP AH,SCROLL_SHIFT
E9D0 7307	2013	JAE K18 ; IF SCROLL SHIFT OR ABOVE, TOGGLE KEY
	2014	
	2015	;----- PLAIN SHIFT KEY, SET SHIFT ON
	2016	
E9D2 08261700	2017	OR KB_FLAG,AH ; TURN ON SHIFT BIT
E9D6 E98000	2018	JMP K26 ; INTERRUPT_RETURN
	2019	
	2020	;----- TOGGLE SHIFT KEY, TEST FOR 1ST MAKE OR HOT
	2021	
E9D9	2022	K18: ; SHIFT-TOGGLE
E9D9 F606170004	2023	TEST KB_FLAG, CTL_SHIFT ; CHECK CTL SHIFT STATE
E9DE 7565	2024	JNZ K25 ; JUMP IF CTL STATE
E9E0 3C82	2025	CHP AL, IHS_KEY ; CHECK FOR INSERT KEY
E9E2 7522	2026	JNZ K22 ; JUMP IF NOT INSERT KEY
E9E4 F606170008	2027	TEST KB_FLAG, ALT_SHIFT ; CHECK FOR ALTERNATE SHIFT
E9E9 755A	2028	JNZ K25 ; JUMP IF ALTERNATE SHIFT
E9EB F606170020	2029	K19: TEST KB_FLAG, NUM_STATE ; CHECK FOR BASE STATE
E9F0 7500	2030	JNZ K21 ; JUMP IF NUM LOCK IS ON
E9F2 F606170003	2031	TEST KB_FLAG, LEFT_SHIFT+ RIGHT_SHIFT
E9F7 7400	2032	JZ K22 ; JUMP IF BASE STATE
	2033	
E9F9	2034	K20: ; NUMERIC ZERO, NOT INSERT KEY
E9F9 B83052	2035	MOV AX, 5230H ; PUT OUT AH ASCII ZERO
E9FC E9D601	2036	JMP K57 ; BUFFER_FILL
E9FF	2037	K21: ; MIGHT BE NUMERIC
E9FF F606170003	2038	TEST KB_FLAG, LEFT_SHIFT+ RIGHT_SHIFT
EA04 74F3	2039	JZ K20 ; JUMP NUMERIC, NOT INSERT
	2040	
EA06	2041	K22: ; SHIFT TOGGLE KEY HIT; PROCESS IT
EA06 84261800	2042	TEST AH,KB_FLAG_1 ; IS KEY ALREADY DEPRESSED
EA0A 7540	2043	JNZ K26 ; JUMP IF KEY ALREADY DEPRESSED
EA0C 08261800	2044	OR KB_FLAG_1,AH ; INDICATE THAT THE KEY IS DEPRESSED
EA10 30261700	2045	XOR KB_FLAG,AH ; TOGGLE THE SHIFT STATE
EA14 3C82	2046	CHP AL,INS_KEY ; TEST FOR 1ST MAKE OF INSERT KEY
EA16 7541	2047	JNE K26 ; JUMP IF NOT INSERT KEY
EA18 B80052	2048	MOV AX,INS_KEY*256 ; SET SCAN CODE INTO AH, 0 INTO AL
EA1B E9B701	2049	JMP K57 ; PUT INTO OUTPUT BUFFER
	2050	
	2051	;
	2052	;----- BREAK SHIFT FOUND
EA1E	2053	K23: ; BREAK-SHIFT-FOUND

LOC	OBJ	LINE	SOURCE
EA1E	80FC10	2054	CHP AH,SCRDLL_SHIFT ; IS THIS A TOGGLE KEY
EA21	731A	2055	JAE K24 ; YES, HANDLE BREAK TOGGLE
EA23	F6D4	2056	NOT AH ; INVERT MASK
EA25	20261700	2057	AND KB_FLAG,AH ; TURN OFF SHIFT BIT
EA29	3CB8	2058	CHP AL,ALT_KEY+B0H ; IS THIS ALTERNATE SHIFT RELEASE
EA2B	752C	2059	JNE K26 ; INTERRUPT_RETURN
		2060	
		2061	;----- ALTERNATE SHIFT KEY RELEASED, GET THE VALUE INTO BUFFER
		2062	
EA2D	A01900	2063	MOV AL,ALT_INPUT
EA30	B400	2064	MOV AH,0 ; SCAN CODE OF 0
EA32	08261900	2065	MOV ALT_INPUT,AH ; ZERD OUT THE FIELD
EA36	3C00	2066	CHP AL,0 ; WAS THE INPUT=0
EA38	741F	2067	JE K26 ; INTERRUPT_RETURN
EA3A	E9A101	2068	JMP K58 ; IT WASN'T, SO PUT IN BUFFER
EA3D		2069	K24: ; BREAK-TOGGLE
EA3D	F6D4	2070	NOT AH ; INVERT MASK
EA3F	20261800	2071	AND KB_FLAG_I,AH ; INDICATE NO LONGER DEPRESSED
EA43	EB14	2072	JMP SHORT K26 ; INTERRUPT_RETURN
		2073	
		2074	;----- TEST FOR HOLD STATE
		2075	
EA45		2076	K25: ; NO-SHIFT-FOUND
EA45	3C80	2077	CHP AL,B0H ; TEST FOR BREAK KEY
EA47	7310	2078	JAE K26 ; NOTHING FOR BREAK CHARS FROM HERE ON
EA49	F606180008	2079	TEST KB_FLAG_I,HOLD_STATE ; ARE WE IN HOLD STATE
EA4E	7417	2080	JZ K28 ; BRANCH AROUND TEST IF NOT
EA50	3C45	2081	CHP AL,HUM_KEY
EA52	7405	2082	JE K26 ; CAN'T END HOLD ON HUM_LOCK
EA54	60261800F7	2083	AND KB_FLAG_I,NOT_HOLD_STATE ; TURN OFF THE HOLD STATE BIT
EA59		2084	K26: ; INTERRUPT_RETURN
EA59	FA	2085	CLI ; TURN OFF INTERRUPTS
EA5A	B020	2086	MOV AL,EDI ; END OF INTERRUPT COMMAND
EA5C	E620	2087	OUT 020H,AL ; SEND COMMAND TO INT CONTROL PORT
EA5E		2088	K27: ; INTERRUPT_RETURN-NO-EOI
EA5E	07	2089	POP ES
EA5F	1F	2090	POP DS
EA60	5F	2091	POP DI
EA61	5E	2092	POP SI
EA62	5A	2093	POP DX
EA63	59	2094	POP CX
EA64	5B	2095	POP BX
EA65	58	2096	POP AX ; RESTORE STATE
EA66	CF	2097	IRET ; RETURN, INTERRUPTS BACK ON
		2098	; WITH FLAG CHANGE
		2099	
		2100	;----- NOT IN HOLD STATE, TEST FOR SPECIAL CHARS
		2101	
EA67		2102	K28: ; NO-HOLD-STATE
EA67	F606170008	2103	TEST KB_FLAG,ALT_SHIFT ; ARE WE IN ALTERNATE SHIFT
EA6C	7503	2104	JNZ K29 ; JUMP IF ALTERNATE SHIFT
EA6E	E99100	2105	JMP K38 ; JUMP IF NOT ALTERNATE
		2106	
		2107	;----- TEST FOR RESET KEY SEQUENCE (CTL ALT DEL)
		2108	
EA71		2109	K29: ; TEST-RESET
EA71	F606170004	2110	TEST KB_FLAG,CTL_SHIFT ; ARE WE IN CONTROL SHIFT ALSO
EA76	7433	2111	JZ K31 ; NO_RESET
EA78	3C53	2112	CHP AL,DEL_KEY ; SHIFT STATE IS THERE, TEST KEY
EA7A	752F	2113	JNE K31 ; NO_RESET
		2114	
		2115	;----- CTL-ALT-DEL HAS BEEN FOUND, DO I/O CLEANUP
		2116	
EA7C	C70672003412	2117	MOV RESET_FLAG, 1234H ; SET FLAG FOR RESET FUNCTION
EA82	EA5BE000F0	2118	JMP RESET ; JUMP TO POWER ON DIAGNOSTICS
		2119	
		2120	;----- ALT-INPUT-TABLE
EA87		2121	K30 LABEL BYTE
EA87	52	2122	DB 82,79,80,B1,75,76,77
EA88	4F		
EA89	50		
EA8A	51		
EA8B	4B		
EA8C	4C		
EA8D	4D		
EA8E	47	2123	DB 71,72,73 ; IO NUMBERS ON KEYPAD
EA8F	48		

LOC OBJ	LINE	SOURCE
EA90 49		
EA91 10	2124	;----- SUPER-SHIFT-TABLE
EA92 11	2125	DB 16,17,18,19,20,21,22,23 ; A-Z TYPEWRITER CHARS
EA93 12		
EA94 13		
EA95 14		
EA96 15		
EA97 16		
EA98 17		
EA99 18	2126	DB 24,25,30,31,32,33,34,35
EA9A 19		
EA9B 1E		
EA9C 1F		
EA9D 20		
EA9E 21		
EA9F 22		
EAA0 23		
EAA1 24	2127	DB 36,37,38,44,45,46,47,48
EAA2 25		
EAA3 26		
EAA4 2C		
EAA5 20		
EAA6 2E		
EAA7 2F		
EAA8 30		
EAA9 31	2128	DB 49,50
EAAA 32		
	2129	
	2130	;----- IN ALTERNATE SHIFT, RESET NOT FOUND
	2131	
EAAB	2132	K31: ; NO-RESET
EAAB 3C39	2133	CHP AL,57 ; TEST FOR SPACE KEY
EAAD 7505	2134	JNE K32 ; NOT THERE
EAAF B020	2135	MOV AL,' ' ; SET SPACE CHAR
EAB1 E92101	2136	JMP K57 ; BUFFER_FILL
	2137	
	2138	;----- LOOK FOR KEY PAO ENTRY
	2139	
EAB4	2140	K32: ; ALT-KEY-PAD
EAB4 BF87EA	2141	MOV OI,OFFSET K30 ; ALT-INPUT-TABLE
EAB7 B90A00	2142	MOV CX,10 ; LOOK FOR ENTRY USING KEYPAD
EABA F2	2143	REPNE SCASB ; LOOK FOR MATCH
EAB8 AE		
EABC 7512	2144	JNE K33 ; NO_ALT_KEYPAD
EABE 61EF88EA	2145	SUB OI,OFFSET K30+1 ; OI NOW HAS ENTRY VALUE
EAC2 A01900	2146	MOV AL,ALT_INPUT ; GET THE CURRENT BYTE
EAC5 B40A	2147	MOV AH,10 ; MULTIPLY BY 10
EAC7 F6E4	2148	MUL AH
EAC9 03C7	2149	ADD AX,OI ; ADD IN THE LATEST ENTRY
EACB A21900	2150	MOV ALT_INPUT,AL ; STORE IT AWAY
EACE EB89	2151	JMP K26 ; THROW AWAY THAT KEYSTROKE
	2152	
	2153	;----- LOOK FOR SUPERSHIFT ENTRY
	2154	
EAD0	2155	K33: ; NO-ALT-KEYPAD
EAD0 C606190000	2156	MOV ALT_INPUT,0 ; ZERO ANY PREVIOUS ENTRY INTO INPUT
EAD5 B91A00	2157	MOV CX,26 ; OI,ES ALREADY POINTING
EAD8 F2	2158	REPNE SCASB ; LOOK FOR MATCH IN ALPHABET
EAD9 AE		
EADA 7505	2159	JNE K34 ; NOT FOUND, FUNCTION KEY OR OTHER
EADC B000	2160	MOV AL,D ; ASCII CODE OF ZERO
EADE E9F400	2161	JMP K57 ; PUT IT IN THE BUFFER
	2162	
	2163	;----- LOOK FOR TOP ROW OF ALTERNATE SHIFT
	2164	
EAE1	2165	K34: ; ALT-TOP-ROW
EAE1 3C02	2166	CHP AL,2 ; KEY WITH '1' ON IT
EAE3 720C	2167	JB K35 ; NOT ONE OF INTERESTING KEYS
EAE5 3C0E	2168	CHP AL,14 ; IS IT IN THE REGION
EAE7 7308	2169	JAE K35 ; ALT-FUNCTION
EAE9 80C476	2170	ADD AH,118 ; CONVERT PSEUDO SCAN CODE TO RANGE
EAE C B000	2171	MOV AL,0 ; INDICATE AS SUCH
EAE E E9E400	2172	JMP K57 ; BUFFER_FILL
	2173	
	2174	;----- TRANSLATE ALTERNATE SHIFT PSEUDO SCAN CODES
	2175	

LOC	OBJ	LINE	SOURCE	
EAF1		2176	K35:	; ALT-FUNCTION
EAF1 3C3B		2177	CMF AL,59	; TEST FOR IN TABLE
EAF3 7303		2178	JAE K37	; ALT-CONTINUE
EAF5		2179	K36:	; CLOSE-RETURN
EAF5 E961FF		2180	JMP K26	; IGNORE THE KEY
EAF8		2181	K37:	; ALT-CONTINUE
EAF8 3C47		2182	CMF AL,71	; IN KEYPAD REGION
EAF8 73F9		2183	JAE K36	; IF 50, IGNORE
EAPC BB5FE9		2184	MOV BX,OFFSET K13	; ALT SHIFT PSEUDO SCAN TABLE
EAPF E91B01		2185	JMP K63	; TRANSLATE THAT
		2186		
		2187	;	NOT IN ALTERNATE SHIFT
		2188		
EB02		2189	K38:	; NOT-ALT-SHIFT
EB02 F606170004		2190	TEST KB_FLAG,CTL_SHIFT	; ARE WE IN CONTROL SHIFT
EB07 7458		2191	JZ K44	; NOT-CTL-SHIFT
		2192		
		2193	;	CONTROL SHIFT, TEST SPECIAL CHARACTERS
		2194	;	TEST FOR BREAK AND PAUSE KEYS
		2195		
EB09 3C46		2196	CMF AL,SCROLL_KEY	; TEST FOR BREAK
EB0B 7518		2197	JNE K39	; NO-BREAK
EB0D 881E8000		2198	MOV BX,BUFFER_START	; RESET BUFFER TO EMPTY
EB11 891E1A00		2199	MOV BUFFER_NEAD,BX	
EB15 891E1C00		2200	MOV BUFFER_TAIL,BX	
EB19 C606710080		2201	MOV BIOS_BREAK,80H	; TURN ON BIOS_BREAK BIT
EB1E CD18		2202	INT 1BH	; BREAK INTERRUPT VECTOR
EB20 28C0		2203	SUB AX,AX	; PUT OUT CUMMY CHARACTER
EB22 E9B000		2204	JNP K57	; BUFFER_FILL
EB25		2205	K39:	; NO-BREAK
EB25 3C45		2206	CMP AL,NUM_KEY	; LOOK FOR PAUSE KEY
EB27 7521		2207	JNE K41	; NO-PAUSE
EB29 800E180008		2208	OR KB_FLAG_1,NOLD_STATE	; TURN ON THE NOLD FLAG
EB2E B020		2209	MOV AL,EOI	; END OF INTERRUPT TO CONTROL PORT
EB30 E620		2210	OUT 020H,AL	; ALLOW FURTHER KEYSTROKE INTS
		2211		
		2212	;	DURING PAUSE INTERVAL, TURN CRT BACK ON
		2213		
EB32 803E490007		2214	CMF CRT_MODE,7	; IS THIS BLACK AND WHITE CARD
EB37 7407		2215	JE K40	; YES, NOTHING TO DO
EB39 BAD803		2216	MOV DX,8308H	; PORT FOR COLOR CARD
EB3C A06500		2217	MOV AL,CRT_MODE_SET	; GET THE VALUE OF THE CURRENT MODE
EB3F EE		2218	OUT DX,AL	; SET THE CRT MODE, SO THAT CRT IS ON
EB40		2219	K40:	; PAUSE-LOOP
EB40 F606180008		2220	TEST KB_FLAG_1,NOLD_STATE	
EB45 75F9		2221	JNZ K40	; LOOP UNTIL FLAG TURNED OFF
EB47 E914FF		2222	JNP K27	; INTERRUPT_RETURN_NO_EOI
EB4A		2223	K41:	; NO-PAUSE
		2224		
		2225	;	TEST SPECIAL CASE KEY 55
		2226		
EB4A 3C37		2227	CMF AL,55	
EB4C 7506		2228	JNE K42	; NOT-KEY-55
EB4E B80072		2229	MOV AX,114*256	; START/STOP PRINTING SWITCH
EB51 E98100		2230	JMP K57	; BUFFER_FILL
		2231		
		2232	;	SET UP TO TRANSLATE CONTROL SHIFT
		2233		
EB54		2234	K42:	; NOT-KEY-55
EB54 BB8EE8		2235	MOV BX,OFFSET K8	; SET UP TO TRANSLATE CTL
EB57 3C3B		2236	CMF AL,59	; IS IT IN TABLE
		2237		; CTL-TABLE-TRANSLATE
EB59 7276		2238	JB K56	; YES, GO TRANSLATE CHAR
EB5B		2239	K43:	; CTL-TABLE-TRANSLATE
EB5B BBC8E8		2240	MOV BX,OFFSET K9	; CTL TABLE SCAN
EB5E E9BC00		2241	JMP K63	; TRANSLATE_SCAN
		2242		
		2243	;	NOT IN CONTROL SHIFT
		2244		
EB61		2245	K44:	; NOT-CTL-SHIFT
EB61 3C47		2246	CMF AL,71	; TEST FOR KEYPAD REGION
EB63 732C		2247	JAE K48	; HANDLE KEYPAD REGION
EB65 F606170003		2248	TEST KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT	
EB6A 745A		2249	JZ K54	; TEST FOR SHIFT STATE
		2250		
		2251	;	UPPER CASE, HANDLE SPECIAL CASES
		2252		

LOC OBJ	LINE	SOURCE
EB6C 3C0F	2253	CHP AL,15 ; BACK TAB KEY
EB6E 7505	2254	JNE K45 ; NOT-BACK-TAB
EB70 B8000F	2255	MOV AX,15*256 ; SET PSEUDO SCAN CODE
EB73 EB60	2256	JMP SHORT K57 ; BUFFER_FILL
EB75	2257	K45: ; NOT-BACK-TAB
EB75 3C37	2258	CHP AL,55 ; PRINT SCREEN KEY
EB77 7509	2259	JNE K46 ; NOT-PRINT-SCREEN
	2260	
	2261	;----- ISSUE INTERRUPT TO INDICATE PRINT SCREEN FUNCTION
	2262	
EB79 B020	2263	MOV AL,EOI ; END OF CURRENT INTERRUPT
EB7B E620	2264	OUT 020H,AL ; SO FURTHER THINGS CAN HAPPEN
EB70 C005	2265	INT 5H ; ISSUE PRINT SCREEN INTERRUPT
EB7F E90CFE	2266	JMP K27 ; GO BACK WITHOUT EOI OCCURRING
EB82	2267	K46: ; NOT-PRINT-SCREEN
EB82 3C3B	2268	CHP AL,59 ; FUNCTION KEYS
EB84 7206	2269	JB K47 ; NOT-UPPER-FUNCTION
EB86 B855E9	2270	MOV BX,OFFSET K12 ; UPPER CASE PSEUDO SCAN CODES
EB89 E99100	2271	JMP K63 ; TRANSLATE_SCAN
EB8C	2272	K47: ; NOT-UPPER-FUNCTION
EB8C B81BE9	2273	MOV BX,OFFSET K11 ; POINT TO UPPER CASE TABLE
EB8F EB40	2274	JMP SHORT K56 ; OK, TRANSLATE THE CHAR
	2275	
	2276	;----- KEYPAD KEYS, MUST TEST NUM LOCK FOR DETERMINATION
	2277	
EB91	2278	K48: ; KEYPAD-REGION
EB91 F606170020	2279	TEST KB_FLAG,NUM_STATE ; ARE WE IN NUM_LOCK
EB96 7520	2280	JNZ K52 ; TEST FOR SURE
EB98 F606170003	2281	TEST KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT ; ARE WE IN SHIFT STATE
EB90 7520	2282	JNZ K53 ; IF SHIFTED, REALLY NUM STATE
	2283	
	2284	;----- BASE CASE FOR KEYPAD
	2285	
EB9F	2286	K49: ; BASE-CASE
EB9F 3C4A	2287	CHP AL,74 ; SPECIAL CASE FOR A COUPLE OF KEYS
EBA1 740B	2288	JE K50 ; MINUS
EBA3 3C4E	2289	CHP AL,78
EBA5 740C	2290	JE K51
EBA7 2C47	2291	SUB AL,71 ; CONVERT ORIGIN
EBA9 B876E9	2292	MOV BX,OFFSET K15 ; BASE CASE TABLE
EBAC EB71	2293	JMP SHORT K64 ; CONVERT TO PSEUDO SCAN
EBAE	2294	K50: ;
EBAE B82D4A	2295	MOV AX,74*256+ '-' ; MINUS
EBB1 EB22	2296	JMP SHORT K57 ; BUFFER_FILL
EBB3	2297	K51: ;
EBB3 B82B4E	2298	MOV AX,78*256+ '*' ; PLUS
EBB6 EB10	2299	JMP SHORT K57 ; BUFFER_FILL
	2300	
	2301	;----- MIGHT BE NUM LOCK, TEST SHIFT STATUS
	2302	
EBB8	2303	K52: ; ALMOST-NUM-STATE
EBB8 F606170003	2304	TEST KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT
EBB0 75E0	2305	JNZ K49 ; SHIFTED TEMP OUT OF NUM STATE
EBBF	2306	K53: ; REALLY_NUM_STATE
EBBF 2C46	2307	SUB AL,70 ; CONVERT ORIGIN
EBC1 B869E9	2308	MOV BX,OFFSET K14 ; NUM STATE TABLE
EBC4 EB0B	2309	JMP SHORT K56 ; TRANSLATE_CHAR
	2310	
	2311	;----- PLAIN OLD LOWER CASE
	2312	
EBC6	2313	K54: ; NOT-SHIFT
EBC6 3C3B	2314	CHP AL,59 ; TEST FOR FUNCTION KEYS
EBC8 7204	2315	JB K55 ; NOT-LOWER-FUNCTION
EBCA B000	2316	MOV AL,0 ; SCAN CODE IN AH ALREADY
EBCC EB07	2317	JMP SHORT K57 ; BUFFER_FILL
EBCE	2318	K55: ; NOT-LOWER-FUNCTION
EBCE BBE1E8	2319	MOV BX,OFFSET K10 ; LC TABLE
	2320	
	2321	;----- TRANSLATE THE CHARACTER
	2322	
EBD1	2323	K56: ; TRANSLATE-CHAR
EBD1 FEC8	2324	DEC AL ; CONVERT ORIGIN
EBD3 2E07	2325	XLAT CS:K11 ; CONVERT THE SCAN CODE TO ASCII
	2326	
	2327	;----- PUT CHARACTER INTO BUFFER
	2328	
EBD5	2329	K57: ; BUFFER-FILL

LOC OBJ	LINE	SOURCE	
EB05 3CFF	2330	CMP AL,-1	; IS THIS AN IGNORE CHAR
EB07 741F	2331	JE K59	; YES, DO NOTHING WITH IT
EB09 80FCFF	2332	CMP AH,-1	; LOOK FOR -1 PSEUDO SCAN
EB0C 741A	2333	JE K59	; NEAR_INTERRUPT_RETURN
	2334		
	2335	;----- HANDLE THE CAPS LOCK PROBLEM	
	2336		
EB0E	2337	K58:	; BUFFER-FILL-NOTEST
EB0E F606170040	2338	TEST KB_FLAG,CAPS_STATE	; ARE WE IN CAPS LOCK STATE
EBE3 7420	2339	JZ K61	; SKIP IF NOT
	2340		
	2341	;----- IN CAPS LOCK STATE	
	2342		
EBE5 F606170003	2343	TEST KB_FLAG,LEFT_SHIFT+RIGHT_SHIFT	; TEST FOR SHIFT STATE
EBEA 740F	2344	JZ K60	; IF NOT SHIFT, CONVERT LOWER TO UPPER
	2345		
	2346	;----- CONVERT ANY UPPER CASE TO LOWER CASE	
	2347		
EBEC 3C41	2348	CMP AL,'A'	; FIND OUT IF ALPHABETIC
EBEE 7215	2349	JB K61	; NOT_CAPS_STATE
EBF0 3C5A	2350	CMP AL,'Z'	
EBF2 7711	2351	JA K61	; NOT_CAPS_STATE
EBF4 0420	2352	ADD AL,'a'-'A'	; CONVERT TO LOWER CASE
EBF6 EB0D	2353	JMP SHORT K61	; NOT_CAPS_STATE
EBFB	2354	K59:	; NEAR-INTERRUPT-RETURN
EBF8 E9SEFE	2355	JMP K26	; INTERRUPT_RETURN
	2356		
	2357	;----- CONVERT ANY LOWER CASE TO UPPER CASE	
	2358		
EBFB	2359	K60:	; LOWER-TO-UPPER
EBFB 3C61	2360	CMP AL,'a'	; FIND OUT IF ALPHABETIC
EBF0 7206	2361	JB K61	; NOT_CAPS_STATE
EBFF 3C7A	2362	CMP AL,'z'	
EC01 7702	2363	JA K61	; NOT_CAPS_STATE
EC03 EC20	2364	SUB AL,'a'-'A'	; CONVERT TO UPPER CASE
EC05	2365	K61:	; NOT-CAPS-STATE
EC05 8B1E1C00	2366	MOV BX,BUFFER_TAIL	; GET THE END POINTER TO THE BUFFER
EC09 BBF3	2367	MOV SI,BX	; SAVE THE VALUE
EC0B EB63FC	2368	CALL K4	; ADVANCE THE TAIL
EC0E 3B1E1A00	2369	CMPI BX,BUFFER_HEAD	; HAS THE BUFFER WRAPPED AROUND
EC12 7413	2370	JE K62	; BUFFER_FULL_BEEP
EC14 8904	2371	MOV [SI],AX	; STORE THE VALUE
EC16 891E1C00	2372	MOV BUFFER_TAIL,BX	; MOVE THE POINTER UP
EC1A E93CFE	2373	JMP K26	; INTERRUPT_RETURN
	2374		
	2375	;----- TRANSLATE SCAN FOR PSEUDO SCAN CODES	
	2376		
EC1D	2377	K63:	; TRANSLATE-SCAN
EC1D 2C3B	2378	SUB AL,S9	; CONVERT ORIGIN TO FUNCTION KEYS
EC1F	2379	K64:	; TRANSLATE-SCAN-ORGD
EC1F 2E07	2380	XLAT CS:K9	; CTL TABLE SCAN
EC21 8AE0	2381	MOV AH,AL	; PUT VALUE INTO AH
EC23 B000	2382	MOV AL,0	; ZERO ASCII CODE
EC25 EBAE	2383	JMP K57	; PUT IT INTO THE BUFFER
	2384		
	2385	KB_INT ENDP	
	2386		
	2387	;----- BUFFER IS FULL, SOUND THE BEEPER	
	2388		
EC27	2389	K62:	; BUFFER-FULL-BEEP
EC27 B020	2390	MOV AL,E01	; END OF INTERRUPT COMMAND
EC29 E620	2391	OUT 20H,AL	; SEND COMMAND TO INT CONTROL PORT
EC2B B88000	2392	MOV BX,080H	; NUMBER OF CYCLES FOR 1/12 SECOND TONE
EC2E E461	2393	IN AL,KB_CTL	; GET CONTROL INFORMATION
EC30 50	2394	PUSH AX	; SAVE
EC31	2395	K65:	; BEEP-CYCLE
EC31 24FC	2396	AND AL,0FCH	; TURN OFF TIMER GATE AND SPEAKER DATA
EC33 E661	2397	OUT KB_CTL,AL	; OUTPUT TO CONTROL
EC35 B94800	2398	MOV CX,48H	; HALF CYCLE TIME FOR TONE
EC38	2399	K66:	
EC38 E2FE	2400	LOOP K66	; SPEAKER OFF
EC3A 0C02	2401	OR AL,2	; TURN ON SPEAKER BIT
EC3C E661	2402	OUT KB_CTL,AL	; OUTPUT TO CONTROL
EC3E B94800	2403	MOV CX,48H	; SET UP COUNT
EC41	2404	K67:	
EC41 E2FE	2405	LOOP K67	; ANOTHER HALF CYCLE
EC43 4B	2406	DEC BX	; TOTAL TIME COUNT

LOC OBJ	LINE	SOURCE
EC44 75EB	2407	JNZ K65 ; 00 ANOTHER CYCLE
EC46 58	2408	POP AX ; RECOVER CONTROL
EC47 E661	2409	OUT KB_CTL,AL ; OUTPUT THE CONTROL
EC49 E912FE	2410	JMP K27
	2411	-----
	2412	; ROS CHECKSUM SUBROUTINE ;
	2413	-----
EC4C	2414	ROS_CHECKSUM PROC NEAR ; NEXT ROS_MODULE
EC4C B90020	2415	MOV CX,0192 ; NUMBER OF BYTES TO ADD
EC4F	2416	ROS_CHECKSUM_CNT: ; ENTRY FOR OPTIONAL ROS TEST
EC4F 32C0	2417	XOR AL,AL
EC51	2418	C26:
EC51 0207	2419	ADD AL,05:[BX]
EC53 43	2420	INC BX ; POINT TO NEXT BYTE
EC54 E2FB	2421	LOOP C26 ; ADD ALL BYTES IN ROS MODULE
EC56 0AC0	2422	OR AL,AL ; SUM = 0?
EC58 C3	2423	RET
	2424	ROS_CHECKSUM ENDP
	2425	
	2426	;-- INT 13 -----
	2427	; DISKETTE I/O ;
	2428	; THIS INTERFACE PROVIDES ACCESS TO THE 5 1/4" DISKETTE DRIVES ;
	2429	; INPUT ;
	2430	; (AH)=0 RESET DISKETTE SYSTEM ;
	2431	; HARD RESET TO NEC, PREPARE COMMAND, RECAL REQUIRED ;
	2432	; ON ALL DRIVES ;
	2433	; (AH)=1 READ THE STATUS OF THE SYSTEM INTO (AL) ;
	2434	; DISKETTE_STATUS FROM LAST OPERATION IS USED ;
	2435	; ;
	2436	; REGISTERS FOR READ/WRITE/VERIFY/FORMAT ;
	2437	; (DL) - DRIVE NUMBER (0-3 ALLOWED, VALUE CHECKED) ;
	2438	; (DH) - HEAD NUMBER (0-1 ALLOWED, NOT VALUE CHECKED) ;
	2439	; (CH) - TRACK NUMBER (0-39, NOT VALUE CHECKED) ;
	2440	; (CL) - SECTOR NUMBER (1-8, NOT VALUE CHECKED, ;
	2441	; NOT USED FOR FORMAT) ;
	2442	; (AL) - NUMBER OF SECTORS (MAX = 8, NOT VALUE CHECKED, NOT USED ;
	2443	; FOR FORMAT) ;
	2444	; (ES:BX) - ADDRESS OF BUFFER (NOT REQUIRED FOR VERIFY) ;
	2445	; ;
	2446	; (AH)=2 READ THE DESIRED SECTORS INTO MEMORY ;
	2447	; (AH)=3 WRITE THE DESIRED SECTORS FROM MEMORY ;
	2448	; (AH)=4 VERIFY THE DESIRED SECTORS ;
	2449	; (AH)=5 FORMAT THE DESIRED TRACK ;
	2450	; FOR THE FORMAT OPERATION, THE BUFFER POINTER (ES,BX) ;
	2451	; MUST POINT TO THE COLLECTION OF DESIRED ADDRESS FIELDS ;
	2452	; FOR THE TRACK. EACH FIELD IS COMPOSED OF 4 BYTES, ;
	2453	; (C,H,R,N), WHERE C = TRACK NUMBER, H=HEAD NUMBER, ;
	2454	; R = SECTOR NUMBER, N= NUMBER OF BYTES PER SECTOR ;
	2455	; (00=128, 01=256, 02=512, 03=1024). THERE MUST BE ONE ;
	2456	; ENTRY FOR EVERY SECTOR ON THE TRACK. THIS INFORMATION ;
	2457	; IS USED TO FIND THE REQUESTED SECTOR DURING READ/WRITE ;
	2458	; ACCESS. ;
	2459	; ;
	2460	; DATA VARIABLE -- DISK_POINTER ;
	2461	; DOUBLE WORD POINTER TO THE CURRENT SET OF DISKETTE PARAMETERS ;
	2462	; OUTPUT ;
	2463	; AH = STATUS OF OPERATION ;
	2464	; STATUS BITS ARE DEFINED IN THE EQUATES FOR ;
	2465	; DISKETTE_STATUS VARIABLE IN THE DATA SEGMENT OF THIS ;
	2466	; MODULE. ;
	2467	; CY = 0 SUCCESSFUL OPERATION (AH=0 ON RETURN) ;
	2468	; CY = 1 FAILED OPERATION (AH HAS ERROR REASON) ;
	2469	; FOR READ/WRITE/VERIFY ;
	2470	; DS,BX,DX,CH,CL PRESERVED ;
	2471	; AL = NUMBER OF SECTORS ACTUALLY READ ;
	2472	; ***** AL MAY NOT BE CORRECT IF TIME OUT ERROR OCCURS ;
	2473	; NOTE: IF AN ERROR IS REPORTED BY THE DISKETTE CODE, THE ;
	2474	; APPROPRIATE ACTION IS TO RESET THE DISKETTE, THEN RETRY ;
	2475	; THE OPERATION. ON READ ACCESSES, NO MOTOR START DELAY ;
	2476	; IS TAKEN, SO THAT THREE RETRIES ARE REQUIRED ON READS ;
	2477	; TO ENSURE THAT THE PROBLEM IS NOT DUE TO MOTOR ;
	2478	; START-UP. ;
	2479	-----
	2480	ASSUME CS:CODE,DS:DATA,ES:DATA
EC59	2481	ORG 0EC59H
EC59	2482	DISKETTE_IO PROC FAR
EC59 FB	2483	STI ; INTERRUPTS BACK ON

LOC	OBJ	LINE	SOURCE	
EC5A	53	2484	PUSH BX	; SAVE ADDRESS
EC5B	51	2485	PUSH CX	
EC5C	1E	2486	PUSH DS	; SAVE SEGMENT REGISTER VALUE
EC5D	56	2487	PUSH SI	; SAVE ALL REGISTERS DURING OPERATION
EC5E	57	2488	PUSH DI	
EC5F	55	2489	PUSH BP	
EC60	52	2490	PUSH DX	
EC61	88EC	2491	MOV BP,SP	; SET UP POINTER TO HEAD PARK
EC63	E8D812	2492	CALL DOS	
EC66	E81C00	2493	CALL JI	; CALL THE REST TO ENSURE OS RESTORED
EC69	8B0400	2494	MOV BX,4	; GET THE MOTOR WAIT PARAMETER
EC6C	E8FD01	2495	CALL GET_PARK	
EC6F	8B264000	2496	MOV MOTOR_COUNT,AH	; SET THE TIMER COUNT FOR THE MOTOR
EC73	8A264100	2497	MOV AH,DISKETTE_STATUS	; GET STATUS OF OPERATION
EC77	80FC01	2498	CMP AH,I	; SET THE CARRY FLAG TO INDICATE
EC7A	F5	2499	CNC	; SUCCESS OR FAILURE
EC7B	5A	2500	POP DX	; RESTORE ALL REGISTERS
EC7C	5D	2501	POP BP	
EC7D	5F	2502	POP DI	
EC7E	5E	2503	POP SI	
EC7F	1F	2504	POP DS	
EC80	59	2505	POP CX	
EC81	5B	2506	POP BX	; RECOVER ADDRESS
EC82	CA0200	2507	RET 2	; THROW AWAY SAVED FLAGS
		2508	DISKETTE_IO	
		2509	ENDP	
EC85		2510	J1 PROC NEAR	
EC85	8AF0	2511	MOV DH,AL	; SAVE 8 SECTORS IN DH
EC87	80263F007F	2512	AND MOTOR_STATUS,07FH	; INDICATE A READ OPERATION
EC8C	0AE4	2513	OR AH,AH	; AH=0
EC8E	7427	2514	JZ DISK_RESET	
EC90	FECC	2515	DEC AH	; AH=1
EC92	7473	2516	JZ DISK_STATUS	
EC94	C606410000	2517	MOV DISKETTE_STATUS,0	; RESET THE STATUS INDICATOR
EC99	80FA04	2518	CMP DL,4	; TEST FOR DRIVE IN 0-3 RANGE
EC9C	7313	2519	JAE J3	; ERROR IF ABOVE
EC9E	FECC	2520	DEC AH	; AH=2
ECA0	7469	2521	JZ DISK_READ	
ECA2	FECC	2522	DEC AH	; AH=3
ECA4	7503	2523	JNZ J2	; TEST_DISK_VERF
ECA6	E99500	2524	JMP DISK_WRITE	
ECA9		2525	J2:	; TEST_DISK_VERF
ECA9	FECC	2526	DEC AH	; AH=4
ECAB	7467	2527	JZ DISK_VERF	
ECAD	FECC	2528	DEC AH	; AH=5
ECAF	7467	2529	JZ DISK_FORMAT	
ECB1		2530	J3:	; BAD_COMMAND
ECB1	C606410001	2531	MOV DISKETTE_STATUS,BAD_CMD	; ERROR CODE, NO SECTORS TRANSFERRED
ECB6	C3	2532	RET	; UNDEFINED OPERATION
		2533	J1 ENDP	
		2534		
		2535	;----- RESET THE DISKETTE SYSTEM	
		2536		
ECB7		2537	DISK_RESET PROC NEAR	
ECB7	BAF203	2538	MOV DX,D3F2H	; ADAPTER CONTROL PORT
ECBA	FA	2539	CLI	; NO INTERRUPTS
ECBB	A03F00	2540	MOV AL,MOTOR_STATUS	; WHICH MOTOR IS ON
ECBE	B104	2541	MOV CL,4	; SHIFT COUNT
ECC0	D2E0	2542	SAL AL,CL	; MOVE MOTOR VALUE TO HIGH HYBBLE
ECC2	A820	2543	TEST AL,20H	; SELECT CORRESPONDING DRIVE
ECC4	750C	2544	JNZ J5	; JUMP IF MOTOR ONE IS ON
ECC6	A840	2545	TEST AL,40H	
ECC8	7506	2546	JNZ J4	; JUMP IF MOTOR TWO IS ON
ECCA	A880	2547	TEST AL,B0H	
ECCC	7406	2548	JZ J6	; JUMP IF MOTOR ZERO IS ON
ECCF	FEC0	2549	INC AL	
ECD0		2550	J4:	
ECD0	FEC0	2551	INC AL	
ECD2		2552	J5:	
ECD2	FEC0	2553	INC AL	
ECD4		2554	J6:	
ECD4	0C08	2555	OR AL,8	; TURN ON INTERRUPT ENABLE
ECD6	EE	2556	OUT DX,AL	; RESET THE ADAPTER
ECD7	C6063E0000	2557	MOV SEEK_STATUS,0	; SET RECAL REQUIRED ON ALL DRIVES
ECD8	C606410000	2558	MOV DISKETTE_STATUS,0	; SET OK STATUS FOR DISKETTE
ECE1	0C04	2559	OR AL,4	; TURN OFF RESET
ECE3	EE	2560	OUT DX,AL	; TURN OFF THE RESET

LOC OBJ	LINE	SOURCE
ECE4 FB	2561	STI ; REENABLE THE INTERRUPTS
ECE5 E82A02	2562	CALL CHK_STAT_2 ; 00 SENSE INTERRUPT STATUS
	2563	
ECE8 A04200	2564	MOV AL,NEC_STATUS ; FOLLOWING RESET
ECEB 3CC0	2565	CMV AL,0C0H ; IGNORE ERROR RETURN AND DO OWN TEST
ECEB 7406	2566	JZ J7 ; TEST FOR DRIVE READY TRANSITION
ECEF 800E410020	2567	DR DISKETTE_STATUS,BAQ_NEC ; EVERYTHING OK
ECF4 C3	2568	RET ; SET ERROR CODE
	2569	
	2570	;----- SEND SPECIFY COMMAND TO NEC
	2571	
ECF5	2572	J7: ; DRIVE_READY
ECF5 B403	2573	MOV AH,03H ; SPECIFY COMMAND
ECF7 E84701	2574	CALL NEC_OUTPUT ; OUTPUT THE COMMAND
ECFA BB0100	2575	MOV BX,1 ; FIRST BYTE PARM IN BLOCK
ECFD E86C01	2576	CALL GET_PARM ; TO THE NEC CONTROLLER
ED00 BB0300	2577	MOV BX,3 ; SECOND BYTE PARM IN BLOCK
ED03 E86601	2578	CALL GET_PARM ; TO THE NEC CONTROLLER
ED06	2579	J8: ; RESET_RET
ED06 C3	2580	RET ; RETURN TO CALLER
	2581	DISK_RESET ENDP
	2582	
	2583	;----- DISKETTE STATUS ROUTINE
	2584	
ED07	2585	DISK_STATUS PROC NEAR
ED07 A04100	2586	MOV AL,DISKETTE_STATUS
ED0A C3	2587	RET
	2588	DISK_STATUS ENDP
	2589	
	2590	;----- DISKETTE READ
	2591	
ED0B	2592	DISK_READ PROC NEAR
ED0B B046	2593	MOV AL,046H ; READ COMMAND FOR DMA
ED0D	2594	J9: ; DISK_READ_CDNT
ED0D E8DB01	2595	CALL DMA_SETUP ; SET UP THE DMA
ED10 B4E6	2596	MOV AH,0E6H ; SET UP RD COMMAND FOR NEC CONTROLLER
ED12 EB36	2597	JMP SHORT RM_OPN ; GO DO THE OPERATION
	2598	DISK_READ ENDP
	2599	
	2600	;----- DISKETTE VERIFY
	2601	
ED14	2602	DISK_VERF PROC NEAR
ED14 B042	2603	MOV AL,042H ; VERIFY COMMAND FOR DMA
ED16 EBF5	2604	JMP J9 ; DO AS IF DISK READ
	2605	DISK_VERF ENDP
	2606	
	2607	;----- DISKETTE FDMAT
	2608	
ED1B	2609	DISK_FDMAT PROC NEAR
ED1B 800E3F0080	2610	DR MOTOR_STATUS,80H ; INDICATE WRITE OPERATION
ED1D B04A	2611	MOV AL,04AH ; WILL WRITE TO THE DISKETTE
ED1F E8A601	2612	CALL DMA_SETUP ; SET UP THE DMA
ED22 B44D	2613	MOV AH,04DH ; ESTABLISH THE FORMAT COMMAND
ED24 EB24	2614	JMP SHORT RM_OPN ; DO THE OPERATION
ED26	2615	J10: ; CONTINUATION OF RM_OPN FOR FMT
ED26 BB0700	2616	MOV BX,7 ; GET THE
ED29 E84001	2617	CALL GET_PARM ; BYTES/SECTOR VALUE TO NEC
ED2C BB0900	2618	MOV BX,9 ; GET THE
ED2F E83A01	2619	CALL GET_PARM ; SECTORS/TRACK VALUE TO NEC
ED32 BB0F00	2620	MOV BX,15 ; GET THE
ED35 E83401	2621	CALL GET_PARM ; GAP LENGTH VALUE TO NEC
ED38 BB1100	2622	MOV BX,17 ; GET THE FILLER BYTE
ED3B E9AB00	2623	JMP J16 ; TO THE CONTROLLER
	2624	DISK_FORMAT ENDP
	2625	
	2626	;----- DISKETTE WRITE ROUTINE
	2627	
ED3E	2628	DISK_WRITE PROC NEAR
ED3E 800E3F0080	2629	DR MOTOR_STATUS,80H ; INDICATE WRITE OPERATION
ED43 B04A	2630	MOV AL,04AH ; DMA WRITE COMMAND
ED45 E88001	2631	CALL DMA_SETUP
ED48 B4C5	2632	MOV AN,0C5H ; NEC COMMAND TO WRITE TO DISKETTE
	2633	DISK_WRITE ENDP
	2634	
	2635	;----- ALLOW WRITE ROUTINE TO FALL INTO RM_OPN
	2636	
	2637	;-----

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2638 ; RH_OPN
2639 ; THIS ROUTINE PERFORMS THE READ/WRITE/VERIFY OPERATION ;
2640 ; -----
ED4A 2641 RH_OPN PROC MEAR
ED4A 7308 2642 JMC J11 ; TEST FOR DMA ERROR
ED4C C606410009 2643 MOV OISKETTE_STATUS,DMA_BOUNDARY ; SET ERROR
ED51 B000 2644 MOV AL,0 ; NO SECTORS TRANSFERRED
ED53 C3 2645 RET ; RETURN TO MAIN ROUTINE
ED54 2646 J11: ; DD_RH_OPN
ED54 50 2647 PUSH AX ; SAVE THE COMMAND
2648
2649 ;----- TURN ON THE MOTOR AND SELECT THE DRIVE
2650
ED55 S1 2651 PUSH CX ; SAVE THE T/S PARMS
ED56 8ACA 2652 MOV CL,DL ; GET DRIVE NUMBER AS SHIFT COUNT
ED58 B001 2653 MOV AL,1 ; MASK FOR DETERMINING MOTOR BIT
ED5A D2E0 2654 SAL AL,CL ; SHIFT THE MASK BIT
ED5C FA 2655 CLI ; NO INTERRUPTS WHILE DETERMINING
2656 ; MOTOR STATUS
ED5D C6064000FF 2657 MOV MOTOR_COUNT,0FFH ; SET LARGE COUNT DURING OPERATION
ED62 84063F00 2658 TEST AL,MOTOR_STATUS ; TEST THAT MOTOR FOR OPERATING
ED66 7531 2659 JNZ J14 ; IF RUNNING, SKIP THE WAIT
ED68 80263F00F0 2660 AND MOTOR_STATUS,0F0H ; TURN OFF ALL MOTOR BITS
ED6D 0A063F00 2661 OR MOTOR_STATUS,AL ; TURN ON THE CURRENT MOTOR
ED71 FB 2662 STI ; INTERRUPTS BACK ON
ED72 8010 2663 MOV AL,10H ; MASK BIT
ED74 D2E0 2664 SAL AL,CL ; DEVELOP BIT MASK FOR MOTOR ENABLE
ED76 0AC2 2665 OR AL,OL ; GET DRIVE SELECT BITS IN
ED78 0C0C 2666 OR AL,0CH ; NO RESET, ENABLE DMA/INT
ED7A 52 2667 PUSH DX ; SAVE REG
ED7B 8AF203 2668 MOV DX,03F2H ; CONTROL PORT ADDRESS
ED7E EE 2669 OUT DX,AL
ED7F 5A 2670 POP DX ; RECOVER REGISTERS
2671
2672 ;----- WAIT FOR MOTOR IF WRITE OPERATION
2673
ED80 F6063F0080 2674 TEST MOTOR_STATUS,80H ; IS THIS A WRITE
ED85 7412 2675 JZ J14 ; NO, CONTINUE WITHOUT WAIT
ED87 8B1400 2676 MOV BX,20 ; GET THE MOTOR WAIT
ED8A E0DF00 2677 CALL GET_PARM ; PARAMETER
ED8D 0AE4 2678 OR AH,AH ; TEST FOR NO WAIT
ED8F 2679 J12: ; TEST_WAIT_TIME
ED8F 7408 2680 JZ J14 ; EXIT WITH TIME EXPIRED
ED91 2BC9 2681 SUB CX,CX ; SET UP 1/8 SECOND LOOP TIME
ED93 2682 J13:
ED93 E2FE 2683 LOOP J13 ; WAIT FOR THE REQUIRED TIME
ED95 FECC 2684 DEC AH ; DECREMENT TIME VALUE
ED97 E8F6 2685 JMP J12 ; ARE WE DONE YET
ED99 2686 J14: ; MOTOR_RUNNING
ED99 FB 2687 STI ; INTERRUPTS BACK ON FOR BYPASS WAIT
ED9A 59 2688 POP CX
2689
2690 ;----- DO THE SEEK OPERATION
2691
ED9B E8DF00 2692 CALL SEEK ; MOVE TO CORRECT TRACK
ED9E 58 2693 POP AX ; RECOVER COMMAND
ED9F 8AFC 2694 MOV BH,AH ; SAVE COMMAND IN BH
EOA1 B600 2695 MOV OH,0 ; SET NO SECTORS READ IN CASE OF ERROR
EOA3 724B 2696 JC J17 ; IF ERROR, THEN EXIT AFTER MOTOR OFF
EOA5 BEF0ED90 2697 MOV SI,OFFSET J17 ; DUMMY RETURN ON STACK FOR NEC_OUTPUT
EOA9 56 2698 PUSH SI ; SO THAT IT WILL RETURN TO MOTOR OFF
2699 ; LOCATION
2700
2701 ;----- SEND OUT THE PARAMETERS TO THE CONTROLLER
2702
EDAA E89400 2703 CALL NEC_OUTPUT ; OUTPUT THE OPERATION COMMAND
EOAD 8A6601 2704 MOV AH,[BP+1] ; GET THE CURRENT HEAD NUMBER
EDB0 D0E4 2705 SAL AH,1 ; MOVE IT TO BIT 2
EDB2 D0E4 2706 SAL AH,1
EDB4 80E404 2707 AND AH,4 ; ISOLATE THAT BIT
EDB7 0AE2 2708 OR AH,OL ; OR IN THE DRIVE NUMBER
EDB9 E88500 2709 CALL NEC_OUTPUT
2710
2711 ;----- TEST FOR FORMAT COMMAND
2712
EDBC 80FF4D 2713 CMP BH,040H ; IS THIS A FORMAT OPERATION
EDBF 7503 2714 JNE J15 ; NO. CONTINUE WITH R/W/V

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LOC OBJ	LINE	SOURCE
EDC1 E962FF	2715	JMP J10 ; IF 50, HANDLE SPECIAL
EDC4	2716	J15:
EDC4 8AE5	2717	MOV AH,CH ; CYLINDER NUMBER
EDC6 E87800	2718	CALL NEC_OUTPUT
EDC9 8A6601	2719	MOV AH,IBP+11 ; HEAD NUMBER FROM STACK
EDCC E87200	2720	CALL NEC_OUTPUT
EDCF 8AE1	2721	MOV AH,CL ; SECTOR NUMBER
EDD1 E86000	2722	CALL NEC_OUTPUT
EDD4 BB0700	2723	MOV BX,7 ; BYTES/SECTOR PARM FROM BLOCK
EDD7 E89200	2724	CALL GET_PARM ; TO THE NEC
EDDA BB0900	2725	MOV BX,9 ; EOT PARM FROM BLOCK
EDDD E88C00	2726	CALL GET_PARM ; TO THE NEC
EDE0 BB0800	2727	MOV BX,11 ; GAP LENGTH PARM FROM BLOCK
EDE3 E88400	2728	CALL GET_PARM ; TO THE NEC
EDE6 BB0D00	2729	MOV BX,13 ; DTL PARM FROM BLOCK
EDE9	2730	J16: ; RM_OPN_FINISH
EDE9 E88000	2731	CALL GET_PARM ; TO THE NEC
EDEC 5E	2732	POP SI ; CAN NOW DISCARD THAT DUMPHY
	2733	; RETURN ADDRESS
	2734	
	2735	I----- LET THE OPERATION HAPPEN
	2736	
EDED E84301	2737	CALL WAIT_INT ; WAIT FOR THE INTERRUPT
EDF0	2738	J17: ; MOTOR_OFF
EDF0 7245	2739	JC J21 ; LOOK FOR ERROR
EDF2 E87401	2740	CALL RESULTS ; GET THE NEC STATUS
EDF5 723F	2741	JC J2D ; LOOK FOR ERROR
	2742	
	2743	I----- CNECK THE RESULTS RETURNED BY THE CONTROLLER
	2744	
EDF7 FC	2745	CLD ; SET THE CORRECT DIRECTION
EDF8 BE4200	2746	MOV SI,OFFSET NEC_STATUS ; POINT TO STATUS FIELD
EDFB AC	2747	LDOS NEC_STATUS ; GET STD
EDFC 24C0	2748	AND AL,0CON ; TEST FOR NORMAL TERMINATION
EDFE 743B	2749	JZ J22 ; DPM_OK
EE00 3C40	2750	CMP AL,040H ; TEST FOR ABNORMAL TERMINATION
EE02 7529	2751	JNZ J18 ; NOT ABNORMAL, BAD NEC
	2752	
	2753	I----- ABNORMAL TERMINATION, FIND OUT WHY
	2754	
EE04 AC	2755	LDOS NEC_STATUS ; GET ST1
EE05 D0E0	2756	SAL AL,1 ; TEST FOR EOT FOUND
EE07 B404	2757	MOV AH,RECORD_NOT_FND
EE09 7224	2758	JC J19 ; RM_FAIL
EE0B D0E0	2759	SAL AL,1
EE0D D0E0	2760	SAL AL,1 ; TEST FOR CRC ERROR
EE0F B410	2761	MOV AH,BAD_CRC
EE11 721C	2762	JC J19 ; RM_FAIL
EE13 D0E0	2763	SAL AL,1 ; TEST FOR DMA OVERRUN
EE15 B408	2764	MOV AH,BAD_DMA
EE17 7216	2765	JC J19 ; RM_FAIL
EE19 D0E0	2766	SAL AL,1
EE1B D0E0	2767	SAL AL,1 ; TEST FOR RECORD NOT FOUND
EE1D B404	2768	MOV AH,RECORD_NOT_FND
EE1F 720E	2769	JC J19 ; RM_FAIL
EE21 D0E0	2770	SAL AL,1
EE23 B403	2771	MOV AH,WRITE_PROTECT ; TEST FOR WRITE_PROTECT
EE25 7208	2772	JC J19 ; RM_FAIL
EE27 D0E0	2773	SAL AL,1 ; TEST MISSING ADDRESS MARK
EE29 B402	2774	MOV AH,BAD_ADDR_MARK
EE2B 7202	2775	JC J19 ; RM_FAIL
	2776	
	2777	I----- NEC MUST HAVE FAILED
	2778	
EE2D	2779	J18: ; RM-NEC-FAIL
EE2D B420	2780	MOV AH,BAD_NEC
EE2F	2781	J19: ; RM-FAIL
EE2F 08264100	2782	OR DISKETTE_STATUS,AH
EE33 E87801	2783	CALL NUM_TRANS ; HOW MANY WERE REALLY TRANSFERRED
EE36	2784	J20: ; RM_ERR
EE36 C3	2785	RET ; RETURN TO CALLER
EE37	2786	J21: ; RM_ERR_RES
EE37 E82F01	2787	CALL RESULTS ; FLUSH THE RESULTS BUFFER
EE3A C3	2788	RET
	2789	
	2790	I----- OPERATION WAS SUCCESSFUL
	2791	

LOC	OBJ	LINE	SOURCE
EE3B		2792	J22:
EE3B E67001		2793	CALL MM_TRANS ; OPN_OK
EE3E 32E4		2794	XOR AH,AH ; HOW MANY GOT MOVED
EE40 C3		2795	RET ; NO ERRORS
		2796	RM_OPN ENDP
		2797	-----
		2798	; NEC_OUTPUT ;
		2799	; THIS ROUTINE SENDS A BYTE TO THE NEC CONTROLLER AFTER TESTING ;
		2800	; FOR CORRECT DIRECTION AND CONTROLLER READY THIS ROUTINE WILL ;
		2801	; TIME OUT IF THE BYTE IS NOT ACCEPTED WITHIN A REASONABLE ;
		2802	; AMOUNT OF TIME, SETTING THE DISKETTE STATUS ON COMPLETION. ;
		2803	; INPUT ;
		2804	; (AH) BYTE TO BE OUTPUT ;
		2805	; OUTPUT ;
		2806	; CY = 0 SUCCESS ;
		2807	; CY = 1 FAILURE -- DISKETTE STATUS UPDATED ;
		2808	; IF A FAILURE HAS OCCURRED, THE RETURN IS MADE ONE LEVEL ;
		2809	; HIGHER THAN THE CALLER OF NEC_OUTPUT. ;
		2810	; THIS REMOVES THE REQUIREMENT OF TESTING AFTER EVERY ;
		2811	; CALL OF NEC_OUTPUT. ;
		2812	; (AL) DESTROYED ;
		2813	-----
EE41		2814	NEC_OUTPUT PROC NEAR
EE41 52		2815	PUSH OX ; SAVE REGISTERS
EE42 51		2816	PUSH CX
EE43 BAF403		2817	MOV DX,D3F4H ; STATUS PORT
EE46 33C9		2818	XOR CX,CX ; COUNT FOR TIME OUT
EE48		2819	J23:
EE48 EC		2820	IN AL,DX ; GET STATUS
EE49 A840		2821	TEST AL,040H ; TEST DIRECTION BIT
EE4B 740C		2822	JZ J25 ; DIRECTION OK
EE4D E2F9		2823	LOOP J23
EE4F		2824	J24: ; TIME_ERROR
EE4F 800E410080		2825	OR DISKETTE_STATUS,TIME_OUT
EE54 59		2826	POP CX
EE55 5A		2827	POP DX ; SET ERROR CODE AND RESTORE REGS
EE56 58		2828	POP AX ; DISCARD THE RETURN ADDRESS
EE57 F9		2829	STC ; INDICATE ERROR TO CALLER
EE58 C3		2830	RET
EE59		2831	J25:
EE59 33C9		2832	XOR CX,CX ; RESET THE COUNT
EE5B		2833	J26:
EE5B EC		2834	IN AL,DX ; GET THE STATUS
EE5C A880		2835	TEST AL,080H ; IS IT READY
EE5E 7504		2836	JNZ J27 ; YES, GO OUTPUT
EE60 E2F9		2837	LOOP J26 ; COUNT DOWN AND TRY AGAIN
EE62 E8EB		2838	JMP J24 ; ERROR CONDITION
EE64		2839	J27: ; OUTPUT
EE64 8AC4		2840	MOV AL,AH ; GET BYTE TO OUTPUT
EE66 B2F5		2841	MOV DL,0F5H ; DATA PORT (3F5)
EE6A EE		2842	OUT DX,AL ; OUTPUT THE BYTE
EE69 59		2843	POP CX ; RECOVER REGISTERS
EE6A 5A		2844	POP OX
EE6B C3		2845	RET ; CY = 0 FROM TEST INSTRUCTION
		2846	NEC_OUTPUT ENDP
		2847	-----
		2848	; GET_PARM ;
		2849	; THIS ROUTINE FETCHES THE INDEXED POINTER FROM THE DISK_BASE ;
		2850	; BLOCK POINTED AT BY THE DATA VARIABLE DISK_POINTER. A BYTE FROM ;
		2851	; THAT TABLE IS THEN MOVED INTO AH, THE INDEX OF THAT BYTE BEING ;
		2852	; THE PARM IN BX ;
		2853	; ENTRY -- ;
		2854	; BX = INDEX OF BYTE TO BE FETCHED * 2 ;
		2855	; IF THE LOW BIT OF BX IS ON, THE BYTE IS IMMEDIATELY OUTPUT ;
		2856	; TO THE NEC CONTROLLER ;
		2857	; EXIT -- ;
		2858	; AH = THAT BYTE FROM BLOCK ;
		2859	-----
EE6C		2860	GET_PARM PROC NEAR
EE6C 1E		2861	PUSH DS ; SAVE SEGMENT
EE6D 2BC0		2862	SUB AX,AX ; ZERO TO AX
EE6F 8ED8		2863	MOV OS,AX
		2864	ASSUME DS:ABS0
EE71 C5367800		2865	LDS SI,DISK_POINTER ; POINT TO BLOCK
EE75 D1EB		2866	SHR BX,1 ; DIVIDE BX BY 2, AND SET FLAG
		2867	; FOR EXIT
EE77 8A20		2868	MOV AH,[SI+BX] ; GET THE WORD

LOC OBJ	LINE	SOURCE
EE79 1F	2869	POP DS ; RESTORE SEGMENT
EE7A 72C5	2870	ASSUME DS:DATA
EE7C C3	2871	JC NEC_OUTPUT ; IF FLAG SET, OUTPUT TO CONTROLLER
	2872	RET ; RETURN TO CALLER
	2873	GET_PARM ENDP
	2874	;
	2875	; SEEK ;
	2876	; THIS ROUTINE WILL MOVE THE HEAD ON THE NAMED DRIVE TO THE ;
	2877	; NAMED TRACK. IF THE DRIVE HAS NOT BEEN ACCESSED SINCE THE ;
	2878	; DRIVE RESET COMMAND HAS ISSUED, THE DRIVE WILL BE RECALIBRATED. ;
	2879	; INPUT ;
	2880	; (DL) = DRIVE TO SEEK ON ;
	2881	; (CH) = TRACK TO SEEK TO ;
	2882	; OUTPUT ;
	2883	; CT = 0 SUCCESS ;
	2884	; CT = 1 FAILURE -- DISKETTE_STATUS SET ACCORDINGLY ;
	2885	; (AX) DESTROYED ;
	2886	;
EE7D	2887	SEEK PROC NEAR
EE7D B001	2888	MOV AL,1 ; ESTABLISH MASK FOR RECAL TEST
EE7F 51	2889	PUSH CX ; SAVE INPUT VALUES
EE80 8ACA	2890	MOV CL,DL ; GET DRIVE VALUE INTO CL
EE82 D2C0	2891	ROL AL,CL ; SHIFT IT BY THE DRIVE VALUE
EE84 59	2892	POP CX ; RECOVER TRACK VALUE
EE85 84063E00	2893	TEST AL,SEEK_STATUS ; TEST FOR RECAL REQUIRED
EE89 7513	2894	JNZ J28 ; NO_RECAL
EE8B 08063E00	2895	OR SEEK_STATUS,AL ; TURN ON THE NO RECAL BIT IN FLAG
EE8F 8407	2896	MOV AH,07H ; RECALIBRATE COMMAND
EE91 E8ADFF	2897	CALL NEC_OUTPUT
EE94 8AE2	2898	MOV AH,0L
EE96 E8A8FF	2899	CALL NEC_OUTPUT ; OUTPUT THE DRIVE NUMBER
EE99 E87600	2900	CALL CHK_STAT_2 ; GET THE INTERRUPT AND SENSE INT STATUS
EE9C 7229	2901	JC J32 ; SEEK_ERROR
	2902	
	2903	;----- DRIVE IS IN STNCH WITH CONTROLLER, SEEK TO TRACK
	2904	
EE9E	2905	J28:
EE9E 840F	2906	MOV AH,0FH ; SEEK COMMAND TO HEC
EEA0 E89EFF	2907	CALL NEC_OUTPUT
EEA3 8AE2	2908	MOV AH,0L ; DRIVE NUMBER
EEA5 E899FF	2909	CALL NEC_OUTPUT
EEA8 8AE5	2910	MOV AH,CH ; TRACK NUMBER
EEAA E894FF	2911	CALL NEC_OUTPUT
EEAD E86200	2912	CALL CHK_STAT_2 ; GET ENDING INTERRUPT AND
	2913	; SENSE STATUS
	2914	
	2915	;----- WAIT FOR HEAD SETTLE
	2916	
EEB0 9C	2917	PUSHF ; SAVE STATUS FLAGS
EEB1 881200	2918	MOV BX,18 ; GET HEAD SETTLE PARAMETER
EEB4 E8B5FF	2919	CALL GET_PARM
EEB7 51	2920	PUSH CX ; SAVE REGISTER
EEB8	2921	J29: ; HEAD_SETTLE
EEB8 892602	2922	MOV CX,550 ; 1 MS LOOP
EEBB 0AE4	2923	OR AH,AH ; TEST FOR TIME EXPIRED
EEBD 7406	2924	JZ J31
EEBF	2925	J30: ;
EEBF E2FE	2926	LOOP J30 ; DELAY FOR 1 MS
EEC1 FECC	2927	DEC AN ; DECREMENT THE COUNT
EEC3 EBF3	2928	JMP J29 ; DO IT SOME MORE
EEC5	2929	J31: ;
EEC5 59	2930	POP CX ; RECOVER STATE
EEC6 90	2931	POPF ;
EEC7	2932	J32: ; SEEK_ERROR
EEC7 C3	2933	RET ; RETURN TO CALLER
	2934	SEEK ENDP
	2935	;
	2936	; DMA_SETUP ;
	2937	; THIS ROUTINE SETS UP THE DMA FOR READ/WRITE/VERIFY OPERATIONS. ;
	2938	; INPUT ;
	2939	; (AL) = MODE BYTE FOR THE DMA ;
	2940	; (ES:BX) = ADDRESS TO READ/WRITE THE DATA ;
	2941	; OUTPUT ;
	2942	; (AX) DESTROYED ;
	2943	;
EEC8	2944	DMA_SETUP PROC NEAR
EEC8 51	2945	PUSH CX ; SAVE THE REGISTER

LOC OBJ	LINE	SOURCE	
EEC9 FA	2946	CLI	: NO MORE INTERRUPTS
EECA E60C	2947	OUT	: OMA+12,AL
EECC 50	2948	PUSH	: SET THE FIRST/LAST F/F
EECD 58	2949	POP	AX
EECE E60B	2950	OUT	: OMA+11,AL
EEED 8CC0	2951	MOV	: AX,ES
EE02 B104	2952	MOV	: CL,4
EE04 03C0	2953	ROL	: AX,CL
EE06 8AE8	2954	MOV	: CH,AL
EE08 24F0	2955	AND	: AL,0F0H
EE0A 03C3	2956	ADD	: AX,BX
EE0C 7302	2957	JNC	: J33
EE0E FEC5	2958	JNC	: CH
EEF0	2959		: CARRY MEANS HIGH 4 BITS MUST BE INC
EE00 50	2960	J33:	
EEE1 E604	2961	PUSH	: AX
EEE3 8AC4	2962	OUT	: DMA+4,AL
EEE5 E604	2963	MOV	: AL,AH
EEE7 8AC5	2964	OUT	: DMA+4,AL
EEE9 240F	2965	MOV	: AL,CH
EEEB E681	2966	AND	: AL,0FH
	2967	OUT	: 081H,AL
	2968		: OUTPUT THE HIGH 4 BITS TO
	2969		: THE PAGE REGISTER
	2970		
	2971		:----- DETERMINE COUNT
EEED 8AE6	2971	MOV	: AH,CH
EEEF 2AC0	2972	SUB	: AL,AL
EEF1 01E8	2973	SHR	: AX,1
EEF3 50	2974	PUSH	: AX
EEF4 8B0600	2975	MOV	: BX,6
EEF7 E072FF	2976	CALL	: GET_PARM
EEFA 8ACC	2977	MOV	: CL,AH
EEFC 58	2978	POP	: AX
EEFO 03E0	2979	SHL	: AX,CL
EEFF 48	2980	DEC	: AX
EF00 50	2981	PUSH	: AX
EF01 E605	2982	OUT	: DMA+5,AL
EF03 8AC4	2983	MOV	: AL,AH
EF05 E605	2984	OUT	: DMA+5,AL
EF07 F8	2985	STI	: HIGH BYTE OF COUNT
EF08 59	2986	POP	: CX
EF09 58	2987	POP	: AX
EF0A 03C1	2988	ADD	: AX,CX
EF0C 59	2989	POP	: CX
EF00 8002	2990	MOV	: AL,2
EF0F E60A	2991	OUT	: OMA+10,AL
EF11 C3	2992	RET	: RETURN TO CALLER,
	2993		: CFL SET BY ABOVE IF ERROR
	2994		
	2995	OMA_SETUP	ENDP
	2996		:-----
	2997	: CHK_STAT_2	:
	2998	: THIS ROUTINE HANDLES THE INTERRUPT RECEIVED AFTER A	:
	2999	: RECALIBRATE, SEEK, OR RESET TO THE ADAPTER.	:
	3000	: THE INTERRUPT IS WAITED FOR, THE INTERRUPT STATUS SENSED,	:
	3001	: AND THE RESULT RETURNED TO THE CALLER.	:
	3002	: INPUT	:
	3003	: NONE	:
	3004	: OUTPUT	:
	3005	: CY = 0 SUCCESS	:
	3006	: CY = 1 FAILURE -- ERROR IS IN DISKETTE_STATUS	:
	3007	: (AX) DESTROYED	:
	3008	:-----	:
EF12	3008	CHK_STAT_2	PROC NEAR
EF12 E01E00	3009	CALL	: WAIT_INT
EF15 7214	3010	JC	: J34
EF17 B408	3011	MOV	: AH,08H
EF19 E825FF	3012	CALL	: NEC_OUTPUT
EF1C E84A00	3013	CALL	: RESULTS
EF1F 720A	3014	JC	: J34
EF21 A04200	3015	MOV	: AL,NEC_STATUS
EF24 2460	3016	AND	: AL,060H
EF26 3C60	3017	CHP	: AL,060H
EF28 7402	3018	JZ	: J35
EF2A F8	3019	CLC	: GOOD RETURN
EF2B	3020	J34:	
EF2B C3	3021	RET	: RETURN TO CALLER
EF2C	3022	J35:	: CHK2_ERROR

LOC OBJ	LINE	SOURCE
EF2C 800E410040	3023	OR DISKETTE_STATUS,BAD_SEEK
EF31 F9	3024	STC ; ERROR RETURN CODE
EF32 C3	3025	RET
	3026	CHK_STAT_2 ENDP
	3027	;
	3028	; WAIT INT
	3029	; THIS ROUTINE WAITS FOR AN INTERRUPT TO OCCUR. A TIME OUT
	3030	; ROUTINE TAKES PLACE DURING THE WAIT, SO THAT AN ERROR MAY BE
	3031	; RETURNED IF THE DRIVE IS NOT READY.
	3032	; INPUT
	3033	; NONE
	3034	; OUTPUT
	3035	; CY = 0 SUCCESS
	3036	; CY = 1 FAILURE -- DISKETTE_STATUS IS SET ACCORDINGLY
	3037	; (AX) DESTROYED
	3038	;
EF33	3039	WAIT_INT PROC NEAR
EF33 F8	3040	STI ; TURN ON INTERRUPTS, JUST IN CASE
EF34 53	3041	PUSH BX
EF35 51	3042	PUSH CX ; SAVE REGISTERS
EF36 8302	3043	MOV BL,2 ; CLEAR THE COUNTERS
EF38 33C9	3044	XDR CX,CX ; FOR 2 SECOND WAIT
EF3A	3045	J36:
EF3A F6063E0080	3046	TEST SEEK_STATUS,INT_FLAG ; TEST FOR INTERRUPT OCCURRING
EF3F 750C	3047	JNZ J37
EF41 E2F7	3048	LODP J36 ; COUNT DOWN WHILE WAITING
EF43 FECB	3049	DEC BL ; SECOND LEVEL COUNTER
EF45 75F3	3050	JNZ J36
EF47 800E410080	3051	OR DISKETTE_STATUS,TIME_OUT ; NOTHING HAPPENED
EF4C F9	3052	STC ; ERROR RETURN
EF40	3053	J37:
EF40 9C	3054	PUSHF ; SAVE CURRENT CARRY
EF4E 80263E007F	3055	AND SEEK_STATUS,NOT INT_FLAG ; TURN OFF INTERRUPT FLAG
EF53 90	3056	POPF ; RECOVER CARRY
EF54 59	3057	POP CX
EF55 58	3058	PDP BX ; RECOVER REGISTERS
EF56 C3	3059	RET ; GOOD RETURN CODE COMES FROM TEST INST
	3060	
	3061	WAIT_INT ENDP
	3062	;
	3063	; DISK_INT
	3064	; THIS ROUTINE HANDLES THE DISKETTE INTERRUPT
	3065	; INPUT
	3066	; NONE
	3067	; OUTPUT
	3068	; THE INTERRUPT FLAG IS SET IS SEEK_STATUS
	3069	;
EF57	3070	ORG 0EF57H
EF57	3071	DISK_INT PROC FAR
EF57 FB	3072	STI ; RE ENABLE INTERRUPTS
EF58 1E	3073	PUSH OS
EF59 50	3074	PUSH AX
EF5A E8E10F	3075	CALL DDS
EF5D 800E3E0080	3076	OR SEEK_STATUS,INT_FLAG
EF62 B020	3077	MOV AL,20H ; END OF INTERRUPT MARKER
EF64 E620	3078	OUT 20H,AL ; INTERRUPT CONTROL PORT
EF66 58	3079	POP AX
EF67 1F	3080	POP OS ; RECOVER SYSTEM
EF68 CF	3081	IRET ; RETURN FROM INTERRUPT
	3082	DISK_INT ENDP
	3083	;
	3084	; RESULTS
	3085	; THIS ROUTINE WILL READ ANYTHING THAT THE NEC CONTROLLER HAS
	3086	; TO SAY FOLLOWING AN INTERRUPT.
	3087	; INPUT
	3088	; NONE
	3089	; OUTPUT
	3090	; CY = 0 SUCCESSFUL TRANSFER
	3091	; CT = 1 FAILURE -- TIME OUT IN WAITING FOR STATUS
	3092	; NEC_STATUS AREA HAS STATUS BYTE LOADED INTO IT
	3093	; (AN) DESTROYED
	3094	;
EF69	3095	RESULTS PROC NEAR
EF69 FC	3096	CLO
EF6A BF4200	3097	MOV DI,OFFSET NEC_STATUS ; POINTER TO DATA AREA
EF6D 51	3098	PUSH CX ; SAVE COUNTER
EF6E 52	3099	PUSH DX

LOC OBJ	LINE	SOURCE
EF6F 53	3100	PUSH BX
EF70 B307	3101	MOV BL,7
	3102	
	3103	;----- WAIT FOR REQUEST FOR MASTER
	3104	
EF72	3105	J30: ; INPUT_LOOP
EF72 33C9	3106	XOR CX,CX ; COUNTER
EF74 8AF403	3107	MOV DX,03F4H ; STATUS PORT
EF77	3108	J39: ; WAIT FOR MASTER
EF77 EC	3109	IN AL,DX ; GET STATUS
EF78 A880	3110	TEST AL,080H ; MASTER READY
EF7A 750C	3111	JNZ J40A ; TEST_OIR
EF7C E2F9	3112	LOOP J39 ; WAIT_MASTER
EF7E 800E410080	3113	OR OISKETTE_STATUS,TIME_OUT
EF83	3114	J40: ; RESULTS_ERROR
EF83 F9	3115	STC ; SET ERROR RETURN
EF84 5B	3116	POP BX
EF85 5A	3117	POP DX
EF86 59	3118	POP CX
EF87 C3	3119	RET
	3120	
	3121	;----- TEST THE OIRECTION BIT
	3122	
EF88	3123	J40A: ; GET STATUS REG AGAIN
EF88 EC	3124	IN AL,DX ; TEST OIRECTION BIT
EF89 A840	3125	TEST AL,040H ; OK TO READ STATUS
EF8B 7507	3126	JNZ J41 ; NEC_FAIL
EF8D	3127	J41: ; RESULTS_ERROR
EF8D 800E410020	3128	OR OISKETTE_STATUS,BAD_NEC
EF92 EBEF	3129	JMP J40
	3130	
	3131	;----- READ IN THE STATUS
	3132	
EF94	3133	J42: ; INPUT_STAT
EF94 42	3134	INC DX ; POINT AT DATA PORT
EF95 EC	3135	IN AL,DX ; GET THE DATA
EF96 0605	3136	MOV [DI],AL ; STORE THE BYTE
EF98 47	3137	INC DI ; INCREMENT THE POINTER
EF99 B90A00	3138	MOV CX,10 ; LOOP TO KILL TIME FOR NEC
EF9C E2FE	3139	J43: LOOP J43
EF9E 4A	3140	DEC DX ; POINT AT STATUS PORT
EF9F EC	3141	IN AL,DX ; GET STATUS
EFA0 A810	3142	TEST AL,010H ; TEST FOR NEC STILL BUSY
EFA2 7406	3143	JZ J44 ; RESULTS DONE
EFA4 FECB	3144	DEC BL ; DECREMENT THE STATUS COUNTER
EFA6 75CA	3145	JNZ J38 ; GO BACK FOR MORE
EFA8 EBE3	3146	JMP J41 ; CHIP HAS FAILED
	3147	
	3148	;----- RESULT OPERATION IS DONE
	3149	
EFAA	3150	J44: ; RECOVER REGISTERS
EFAA 5B	3151	POP BX
EFA8 5A	3152	POP DX
EFA8 59	3153	POP CX
EFA0 C3	3154	RET ; GOOD RETURN CODE FROM TEST INST
	3155	;-----
	3156	NUM_TRANS ;
	3157	THIS ROUTINE CALCULATES THE NUMBER OF SECTORS THAT ;
	3158	WERE ACTUALLY TRANSFERRED TO/FROM THE OISKETTE ;
	3159	INPUT ;
	3160	(CH) = CYLINDER OF OPERATION ;
	3161	(CL) = START SECTOR OF OPERATION ;
	3162	OUTPUT ;
	3163	(AL) = NUMBER ACTUALLY TRANSFERRED ;
	3164	NO OTHER REGISTERS MODIFIED ;
	3165	;-----
EFAE	3166	NUM_TRANS PROC NEAR
EFAE A04500	3167	MOV AL,NEC_STATUS+3 ; GET CYLINDER ENDED UP ON
EFB1 3AC5	3168	CHP AL,CN ; SAME AS WE STARTED
EFB3 A04700	3169	MOV AL,NEC_STATUS+5 ; GET ENDING SECTOR
EFB6 740A	3170	JZ J45 ; IF ON SAME CYL, THEN NO ADJUST
EFB8 BB0800	3171	MOV BX,B
EFB8 BBAEFE	3172	CALL GET_PARM ; GET EOT VALUE
EFBE 8AC4	3173	MOV AL,AH ; INTO AL
EFCE FEC0	3174	INC AL ; USE EOT+1 FOR CALCULATION
EFCE	3175	J45: ; SUBTRACT START FROM END
EFCE 2AC1	3176	SUB AL,CL

LOC OBJ	LINE	SOURCE
EFC4 C3	3177	RET
	3178	MUM_TRANS ENDP
	3179	RESULTS ENDP
	3180	-----
	3181	; DISK_BASE
	3182	; THIS IS THE SET OF PARAMETERS REQUIRED FOR DISKETTE OPERATION.
	3183	; THEY ARE POINTED AT BY THE DATA VARIABLE DISK_POINTER. TO
	3184	; MODIFY THE PARAMETERS, BUILD ANOTHER PARAMETER BLOCK AND POINT
	3185	; DISK_POINTER TO IT.
	3186	-----
EFC7	3187	ORG 0EFC7H
EFC7	3188	DISK_BASE LABEL BTTE
EFC7 CF	3189	DB 11001111B ; SRT=C, NO UNLOAD=0F - 1ST SPECIFY BYTE
EFC8 02	3190	DB 2 ; NO LOAD=1. MODE=DMA - 2ND SPECIFY RYTF
EFC9 25	3191	DB MOTOR_WAIT ; WAIT AFTER OPN TIL MOTOR OFF
EFCA D2	3192	DB 2 ; SIZ BYTES/SECTOR
EFCB 08	3193	DB 8 ; EOT (LAST SECTOR ON TRACK)
EFCC 2A	3194	DB 02AH ; GAP LENGTH
EFCF FF	3195	DB 0FFH ; OTL
EFCE 50	3196	DB 050H ; GAP LENGTH FOR FORMAT
EFCF F6	3197	DB 0F6H ; FILL BTTE FOR FORMAT
EFDD 19	3198	DB 25 ; HEAD SETTLE TIME (MILLISECONDS)
EFDD 04	3199	DB 4 ; MOTOR START TIME (1/8 SECONDS)
	3200	-----
	3201	;--- INT 17 -----
	3202	; PRINTER_IO
	3203	; THIS ROUTINE PROVIDES COMMUNICATION WITH THE PRINTER
	3204	; INPUT
	3205	; (AH)=0 PRINT THE CHARACTER IN (AL)
	3206	; ON RETURN, AH=1 IF CHARACTER COULD NOT BE PRINTED
	3207	; (TIME OUT). OTHER BITS SET AS ON NORMAL STATUS CALL
	3208	; (AH)=1 INITIALIZE THE PRINTER PORT
	3209	; RETURNS WITH (AH) SET WITH PRINTER STATUS
	3210	; (AH)=2 READ THE PRINTER STATUS INTO (AH)
	3211	; 7 6 5 4 3 2-1 0
	3212	; TIME OUT
	3213	; UNUSED
	3214	; I/O ERROR
	3215	; SELECTED
	3216	; OUT OF PAPER
	3217	; ACKNOWLEDGE
	3218	; NOT BUSY
	3219	;
	3220	; (OX) = PRINTER TO BE USED (0,1,2) CORRESPONDING TO ACTUAL
	3221	; VALUES IN PRINTER_BASE AREA
	3222	;
	3223	; DATA AREA PRINTER_BASE CONTAINS THE BASE ADDRESS OF THE PRINTER
	3224	; CARO(S) AVAILABLE (LOCATED AT BEGINNING OF DATA SEGMENT,
	3225	; 400H ABSOLUTE, 3 WORDS)
	3226	;
	3227	; DATA AREA PRINT_TIM_OUT (BTTE) MAY BE CHANGED TO CAUSE DIFFERENT
	3228	; TIME-OUT WAITS. DEFAULT=20
	3229	;
	3230	; REGISTERS AH IS MODIFIED
	3231	; ALL OTHERS UNCHANGED
	3232	-----
	3233	ASSUME CS:CODE,DS:DATA
EF02	3234	ORG 0EFO2H
EF02	3235	PRINTER_IO PROC FAR
EF02 FB	3236	STI ; INTERRUPTS BACK ON
EF03 1E	3237	PUSH DS ; SAVE SEGMENT
EF04 52	3238	PUSH DX
EF05 56	3239	PUSH SI
EF06 51	3240	PUSH CX
EF07 53	3241	PUSH BX
EF08 E8630F	3242	CALL DDS
EF0B 8BF2	3243	MOV SI,DX ; GET PRINTER PARM
EFDD 8A5C78	3244	MOV BL,PRINT_TIM_OUT[SI] ; LOAD TIME-OUT PARM
EFED D1E6	3245	SHL SI,1 ; WORD OFFSET INTO TABLE
EFE2 8B540B	3246	MOV OX,PRINTER_BASE[SI] ; GET BASE ADDRESS FOR PRINTER CARD
EFE5 0BD2	3247	OR DX,OX ; TEST OX FOR ZERO.
	3248	; INDICATING NO PRINTER
EFEE 740C	3249	JZ B1 ; RETURN
EFE9 0AE4	3250	OR AN,AN ; TEST FOR (AH)=0
EFE8 740E	3251	JZ B2 ; PRINT_AL
EFEF FECC	3252	DEC AN ; TEST FOR (AN)=1
EFEE 743F	3253	JZ B8 ; INIT_PRT

LOC OBJ	LINE	SOURCE	
EFF1 FECC	3254	DEC AH	; TEST FOR (AH)=2
EFF3 7428	3255	JZ B5	; PRINTER STATUS
EFF5	3256	B1:	; RETURN
EFF5 5B	3257	POP BX	
EFF6 59	3258	POP CX	
EFF7 5E	3259	POP SI	; RECOVER REGISTERS
EFF8 5A	3260	POP DX	; RECOVER REGISTERS
EFF9 1F	3261	POP DS	
EFFA CF	3262	IRET	
	3263		
	3264	;----- PRINT THE CHARACTER IN (AL)	
	3265		
EFFB	3266	B2:	
EFFB 50	3267	PUSH AX	; SAVE VALUE TO PRINT
EFFC EE	3268	OUT DX,AL	; OUTPUT CHAR TO PORT
EFFD 42	3269	INC DX	; POINT TO STATUS PORT
EFFE	3270	B3:	
EFFE 2BC9	3271	SUB CX,CX	; WAIT_BUSY
F000	3272	B3_1:	
F000 EC	3273	IN AL,DX	; GET STATUS
F001 8AE0	3274	MOV AH,AL	; STATUS TO AH ALSO
F003 A880	3275	TEST AL,80H	; IS THE PRINTER CURRENTLY BUSY
F005 750E	3276	JNZ B4	; OUT_STROBE
F007 E2F7	3277	LOOP B3_1	; TRY AGAIN
F009 FECB	3278	DEC BL	; DROP LOOP COUNT
F00B 75F1	3279	JNZ B3	; GO TILL TIMEOUT ENDS
F00D 80CC01	3280	OR AH,1	; SET ERROR FLAG
F010 80E4F9	3281	AND AH,0F9H	; TURN OFF THE OTHER BITS
F013 EB13	3282	JMP SHORT B7	; RETURN WITH ERROR FLAG SET
F015	3283	B4:	; OUT_STROBE
F015 B00D	3284	MOV AL,0DH	; SET THE STROBE HIGH
F017 42	3285	INC DX	; STROBE IS BIT 0 OF PORT C OF 8255
F01B EE	3286	OUT DX,AL	
F019 B00C	3287	MOV AL,0CH	; SET THE STROBE LOW
F01B EE	3288	OUT DX,AL	
F01C 58	3289	POP AX	; RECOVER THE OUTPUT CHAR
	3290		
	3291	;----- PRINTER STATUS	
	3292		
F01D	3293	B5:	
F01D 50	3294	PUSH AX	; SAVE AL REG
F01E	3295	B6:	
F01E 8B5408	3296	MOV DX,PRINTER_BASEIS1	
F021 42	3297	INC DX	
F022 EC	3298	IN AL,DX	; GET PRINTER STATUS
F023 8AE0	3299	MOV AH,AL	
F025 B0E4F8	3300	AND AH,0F8H	; TURN OFF UNUSED BITS
F026	3301	B7:	; STATUS_SET
F026 5A	3302	POP DX	; RECOVER AL REG
F029 8AC2	3303	MOV AL,DL	; GET CHARACTER INTO AL
F02B 80F44B	3304	XOR AH,4BH	; FLIP A COUPLE OF BITS
F02E EBC5	3305	JMP B1	; RETURN FROM ROUTINE
	3306		
	3307	;----- INITIALIZE THE PRINTER PORT	
	3308		
F030	3309	B8:	
F030 50	3310	PUSH AX	; SAVE AL
F031 42	3311	INC DX	; POINT TO OUTPUT PORT
F032 42	3312	INC DX	
F033 B008	3313	MOV AL,B	; SET INIT LINE LOW
F035 EE	3314	OUT DX,AL	
F036 B8E803	3315	MOV AX,1000	
F039	3316	B9:	; INIT_LOOP
F039 48	3317	DEC AX	; LOOP FOR RESET TO TAKE
F03A 75FD	3318	JNZ B9	; INIT_LOOP
F03C B00C	3319	MOV AL,0CH	; NO INTERRUPTS, NON AUTO LF,
	3320		; INIT HIGH
F03E EE	3321	OUT DX,AL	
F03F EBD0	3322	JMP B6	; PRT_STATUS_1
	3323	PRINTER_IO	ENDP
	3324		
F041 62E1	3325	C2 DW C24	; RETURN ADDRESS FOR DUMMY STACK
	3326		
	3327	;--- INT 10 -----	
	3328	; VIDEO_ID	
	3329	; THESE ROUTINES PROVIDE THE CRT INTERFACE	
	3330	; THE FOLLOWING FUNCTIONS ARE PROVIDED:	

LOC OBJ	LINE	SOURCE
	3331	(AH)=0 SET MODE (AL) CONTAINS MODE VALUE
	3332	(AL)=0 40X25 BM (POWER ON DEFAULT)
	3333	(AL)=1 40X25 COLOR
	3334	(AL)=2 80X25 BN
	3335	(AL)=3 80X25 COLOR
	3336	GRAPHICS MODES
	3337	(AL)=4 320X200 COLOR
	3338	(AL)=5 320X200 BM
	3339	(AL)=6 640X200 BN
	3340	CRT MODE=7 80X25 B&N CARO (USED INTERNAL TO VIDEO ONLY)
	3341	*** NOTE BN MODES OPERATE SAME AS COLOR MODES, BUT
	3342	COLOR BURST IS NOT ENABLED
	3343	(AH)=1 SET CURSOR TYPE
	3344	(CH) = BITS 4-0 = START LINE FOR CURSOR
	3345	*** HARDWARE WILL ALWAYS CAUSE BLN
	3346	*** SETTING BIT 5 OR 6 WILL CAUSE ERRATIC
	3347	BLINKING OR NO CURSOR AT ALL
	3348	(CL) = BITS 4-0 = END LINE FOR CURSOR
	3349	(AH)=2 SET CURSOR POSITION
	3350	(OH,OL) = ROW,COLUMN (0,0) IS UPPER LEFT
	3351	(BH) = PAGE NUMBER (MUST BE 0 FOR GRAPHICS MODES)
	3352	(AH)=3 READ CURSOR POSITION
	3353	(BH) = PAGE NUMBER (MUST BE 0 FOR GRAPHICS MODES)
	3354	ON EXIT (OH,OL) = ROW,COLUMN OF CURRENT CURSOR
	3355	(CN,CL) = CURSOR MODE CURRENTLY SET
	3356	(AH)=4 READ LIGHT PEN POSITION
	3357	ON EXIT:
	3358	(AH) = 0 -- LIGHT PEN SWITCH NOT DOWN/NOT TRIGGERED
	3359	(AH) = 1 -- VALID LIGHT PEN VALUE IN REGISTERS
	3360	(OH,OL) = ROW,COLUMN OF CHARACTER LP POSN
	3361	(CH) = RASTER LINE (0-199)
	3362	(BX) = PIXEL COLUMN (0-319,639)
	3363	(AH)=5 SELECT ACTIVE DISPLAY PAGE (VALID ONLY FOR ALPHA MODES)
	3364	(AL)=PEN PAGE VAL (0-7 FOR MODES 0&1, 0-3 FOR MODES 2&3)
	3365	(AH)=6 SCROLL ACTIVE PAGE UP
	3366	(AL) = NUMBER OF LINES, INPUT LINES BLANKED AT BOTTOM
	3367	OF WINDOW
	3368	AL = 0 MEANS BLANK ENTIRE WINDOW
	3369	(CH,CL) = ROW,COLUMN OF UPPER LEFT CORNER OF SCROLL
	3370	(OH,OL) = ROW,COLUMN OF LOWER RIGHT CORNER OF SCROLL
	3371	(BH) = ATTRIBUTE TO BE USED ON BLANK LINE
	3372	(AH)=7 SCROLL ACTIVE PAGE DOWN
	3373	(AL) = NUMBER OF LINES, INPUT LINES BLANKED AT TOP
	3374	OF WINDOW
	3375	AL = 0 MEANS BLANK ENTIRE WINDOW
	3376	(CN,CL) = ROW,COLUMN OF UPPER LEFT CORNER OF SCROLL
	3377	(OH,OL) = ROW,COLUMN OF LOWER RIGHT CORNER OF SCROLL
	3378	(BH) = ATTRIBUTE TO BE USED ON BLANK LINE
	3379	
	3380	CHARACTER HANDLING ROUTINES
	3381	
	3382	(AH) = 8 READ ATTRIBUTE/CHARACTER AT CURRENT CURSOR POSITION
	3383	(BN) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
	3384	ON EXIT:
	3385	(AL) = CHAR READ
	3386	(AH) = ATTRIBUTE OF CHARACTER READ (ALPHA MODES ONLY)
	3387	(AH) = 9 WRITE ATTRIBUTE/CHARACTER AT CURRENT CURSOR POSITION
	3388	(BN) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
	3389	(CX) = COUNT OF CHARACTERS TO WRITE
	3390	(AL) = CHAR TO WRITE
	3391	(BL) = ATTRIBUTE OF CHARACTER (ALPHA)/COLOR OF CHAR
	3392	(GRAPHICS)
	3393	SEE NOTE ON WRITE 007 FOR BIT 7 OF BL =).
	3394	(AH) = 10 WRITE CHARACTER ONLY AT CURRENT CURSOR POSITION
	3395	(BN) = DISPLAY PAGE (VALID FOR ALPHA MODES ONLY)
	3396	(CX) = COUNT OF CHARACTERS TO WRITE
	3397	(AL) = CHAR TO WRITE
	3398	FOR READ/WRITE CHARACTER INTERFACE WHILE IN GRAPHICS MODE, THE
	3399	CHARACTERS ARE FORMED FROM A CHARACTER GENERATOR IMAGE
	3400	MAINTAINED IN THE SYSTEM ROM. ONLY THE 1ST 128 CHARS
	3401	ARE CONTAINED THERE. TO READ/WRITE THE SECOND 128
	3402	CHARS, THE USER MUST INITIALIZE THE POINTER AT
	3403	INTERRUPT IFN (LOCATION 0007CH) TO POINT TO THE 1K BYTE
	3404	TABLE CONTAINING THE CODE POINTS FOR THE SECOND
	3405	128 CHARS (128-255).
	3406	FOR WRITE CHARACTER INTERFACE IN GRAPHICS MODE, THE REPLICATION
	3407	FACTOR CONTAINED IN (CX) ON ENTRY WILL PRODUCE VALID

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3408      ; RESULTS ONLY FOR CHARACTERS CONTAINED ON THE SAME ROW.      ;
3409      ; CONTINUATION TO SUCCEEDING LINES WILL NOT PRODUCE          ;
3410      ; CORRECTLY.                                                    ;
3411      ;                                                                ;
3412      ; GRAPHICS INTERFACE                                            ;
3413      ; (AH) = 11 SET COLOR PALETTE                                  ;
3414      ; (BH) = PALETTE COLOR ID BEING SET (0-127)                   ;
3415      ; (BL) = COLOR VALUE TO BE USED WITH THAT COLOR ID           ;
3416      ; NOTE: FOR THE CURRENT COLOR CARD, THIS ENTRY POINT          ;
3417      ; HAS MEANING ONLY FOR 320X200 GRAPHICS.                       ;
3418      ; COLOR ID = 0 SELECTS THE BACKGROUND COLOR (0-15);           ;
3419      ; COLOR ID = 1 SELECTS THE PALETTE TO BE USED:                 ;
3420      ; 0 = GREEN(1)/RED(2)/YELLOW(3)                                ;
3421      ; 1 = CYAN(1)/MAGENTA(2)/WHITE(3)                               ;
3422      ; IN 40X25 OR 80X25 ALPHA MODES, THE VALUE SET                 ;
3423      ; FOR PALETTE COLOR 0 INDICATES THE                             ;
3424      ; BORDER COLOR TO BE USED (VALUES 0-31,                          ;
3425      ; WHERE 16-31 SELECT THE HIGH INTENSITY                         ;
3426      ; BACKGROUND SET.                                              ;
3427      ; (AH) = 12 WRITE DOT                                           ;
3428      ; (DX) = ROW NUMBER                                             ;
3429      ; (CX) = COLUMN NUMBER                                          ;
3430      ; (AL) = COLOR VALUE                                           ;
3431      ; IF BIT 7 OF AL = 1, THEN THE COLOR VALUE IS                  ;
3432      ; EXCLUSIVE OR'D WITH THE CURRENT CONTENTS OF                   ;
3433      ; THE DOT                                                       ;
3434      ; (AH) = 13 READ DOT                                           ;
3435      ; (DX) = ROW NUMBER                                             ;
3436      ; (CX) = COLUMN NUMBER                                          ;
3437      ; (AL) RETURNS THE DOT READ                                     ;
3438      ;                                                                ;
3439      ; ASCII TELETYPE ROUTINE FOR OUTPUT                             ;
3440      ;                                                                ;
3441      ; (AH) = 14 WRITE TELETYPE TO ACTIVE PAGE                      ;
3442      ; (AL) = CHAR TO WRITE                                         ;
3443      ; (BL) = FOREGROUND COLOR IN GRAPHICS MODE                     ;
3444      ; NOTE -- SCREEN WIDTH IS CONTROLLED BY PREVIOUS MODE SET     ;
3445      ;                                                                ;
3446      ; (AH) = 15 CURRENT VIDEO STATE                                ;
3447      ; RETURNS THE CURRENT VIDEO STATE                               ;
3448      ; (AL) = MODE CURRENTLY SET ( SEE AH=0 FOR EXPLANATION)        ;
3449      ; (AH) = NUMBER OF CHARACTER COLUMNS ON SCREEN                ;
3450      ; (BH) = CURRENT ACTIVE DISPLAY PAGE                            ;
3451      ;                                                                ;
3452      ; CS,SS,DS,ES,BX,CX,DX PRESERVED DURING CALL                  ;
3453      ; ALL OTHERS DESTROYED                                          ;
3454      ; -----
3455      ASSUME CS:CODE,DS:DATA,ES:VIDEO_RAM
3456      ORG 0F04SH
3457      M1 LABEL WORD ; TABLE OF ROUTINES WITHIN VIDEO I/O
3458      DW OFFSET SET_MODE
3459      DW OFFSET SET_CTYPE
3460      DW OFFSET SET_CPOS
3461      DW OFFSET READ_CURSOR
3462      DW OFFSET READ_LPEN
3463      DW OFFSET ACT_DISP_PAGE
3464      DW OFFSET SCROLL_UP
3465      DW OFFSET SCROLL_DOWN
3466      DW OFFSET READ_AC_CURRENT
3467      DW OFFSET WRITE_AC_CURRENT
3468      DW OFFSET WRITE_C_CURRENT
3469      DW OFFSET SET_COLOR
3470      DW OFFSET WRITE_DOT
3471      DW OFFSET READ_DOT
3472      DW OFFSET WRITE_TTY
3473      DW OFFSET VIDEO_STATE
3474      M1L EQU $-M1
3475
3476      ORG 0F06SH
3477      VIDEO_IO PROC NEAR
3478      STI ; INTERRUPTS BACK ON
3479      CLD ; SET DIRECTION FORWARD
3480      PUSH ES
3481      PUSH DS ; SAVE SEGMENT REGISTERS
3482      PUSH DX
3483      PUSH CX
3484      PUSH BX

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LOC	OBJ	LINE	SOURCE
F06C	56	3485	PUSH SI
F06D	57	3486	PUSH DI
F06E	50	3487	PUSH AX ; SAVE AX VALUE
F06F	8AC4	3488	MOV AL,AH ; GET INTO LOW BYTE
F071	32E4	3489	XOR AH,AH ; ZERO TO HIGH BYTE
F073	01E0	3490	SAL AX,1 ; *2 FOR TABLE LOOKUP
F075	8BF0	3491	MOV SI,AX ; PUT INTO SI FOR BRANCH
F077	302000	3492	CMPL AX,H1L ; TEST FOR WITHIN RANGE
F07A	7204	3493	JB M2 ; BRANCH AROUND BRANCH
F07C	58	3494	POP AX ; THROW AWAY THE PARAMETER
F07D	E94501	3495	JMP VIDEO_RETURN ; DO NOTHING IF NOT IN RANGE
F080		3496	M2:
F080	E0B0E	3497	CALL DDS
F083	B000B8	3498	MOV AX,0B00B8 ; SEGMENT FOR COLOR CARD
F086	8B3E1000	3499	MOV DI,EQUIP_FLAG ; GET EQUIPMENT SETTING
F08A	81E73000	3500	AND DI,30H ; ISOLATE CRT SWITCHES
F08E	83FF30	3501	CMPL DI,30H ; IS SETTING FOR BW CARD?
F091	7502	3502	JNE M3
F093	B4B0	3503	MOV AH,0B0H ; SEGMENT FOR BW CARD
F095		3504	M3:
F095	8EC0	3505	MOV ES,AX ; SET UP TO POINT AT VIDEO RAM AREAS
F097	58	3506	POP AX ; RECOVER VALUE
F098	8A264900	3507	MOV AH,CRT_MODE ; GET CURRENT MODE INTO AH
F09C	2EFA445F0	3508	JMP WORD PTR CS:[SI+OFFSET M1]
		3509	VIDEO_IO ENDP
		3510	;
		3511	;
		3512	;
		3513	;
		3514	;
		3515	;
		3516	;
		3517	;
		3518	;
		3519	;
		3520	;
		3521	;
F0A4		3522	DRG OF0A4H
F0A4		3523	VIDEO_PARAMS LABEL BYTE
		3524	;
		3525	;
F0A4	38	3525	DB 38H,28H,2DH,0AH,1FH,6,19H ; SET UP FOR 40X25
F0A5	2B		
F0A6	2D		
F0A7	0A		
F0A8	1F		
F0A9	06		
F0AA	19		
F0AB	1C	3526	DB 1CH,2,7,6,7
F0AC	02		
F0AD	07		
F0AE	06		
F0AF	07		
F0B0	00	3527	DB 0,0,0,0
F0B1	00		
F0B2	00		
F0B3	00		
	0010	3528	M4 EQU \$-VIDEO_PARAMS
		3529	
F0B4	71	3530	DB 71H,50H,5AH,0AH,1FH,6,19H ; SET UP FOR 60X25
F0B5	50		
F0B6	5A		
F0B7	0A		
F0B8	1F		
F0B9	06		
F0BA	19		
F0BB	1C	3531	DB 1CH,2,7,6,7
F0BC	02		
F0BD	07		
F0BE	06		
F0BF	07		
F0C0	00	3532	DB 0,0,0,0
F0C1	00		
F0C2	00		
F0C3	00		
		3533	
F0C4	38	3534	DB 38H,2BH,2DH,0AH,7FH,6,64H ; SET UP FOR GRAPHICS
F0C5	28		

LOC OBJ	LINE	SOURCE
F0C6 2D		
F0C7 0A		
F0C8 7F		
F0C9 06		
F0CA 64		
F0CB 70	3535	DB 70H,2,1,6,7
F0CC 02		
F0CD 01		
F0CE 06		
F0CF 07		
F0D0 00	3536	DB 0,0,0,0
F0D1 00		
F0D2 00		
F0D3 00		
F0D4 61	3537	
F0D5 50	353B	DB 61H,5DH,52H,DFH,19H,6,19H ; SET UP FOR 80X25 B&W CARD
F0D6 52		
F0D7 0F		
F0D8 19		
F0D9 06		
F0DA 19		
F0DB 19	3539	DB 19H,2,0DH,DBH,DCH
F0DC 02		
F0DD 0D		
F0DE 0B		
F0DF 0C		
F0E0 00	3540	DB 0,0,0,0
F0E1 00		
F0E2 00		
F0E3 00		
F0E4	3541	
F0E4 000B	3542	M5 LABEL WORD ; TABLE OF REGEN LENGTHS
F0E6 0010	3543	DB 2048 ; 40X25
F0E8 0040	3544	DB 4096 ; 80X25
F0EA 0040	3545	DB 16384 ; GRAPHICS
	3546	DB 16384
	3547	
	3548	;----- COLUMNS
	3549	
F0EC	3550	M6 LABEL BYTE
F0EC 2B	3551	DB 40,40,80,80,40,40,80,80
F0ED 2B		
F0EE 50		
F0EF 50		
F0F0 2B		
F0F1 2B		
F0F2 50		
F0F3 50		
	3552	
	3553	;----- C_REG_TAB
	3554	
F0F4	3555	M7 LABEL BYTE ; TABLE OF MODE SETS
F0F4 2C	3556	DB 2CH,20H,2DH,29H,2AH,2EH,1EH,29H
F0F5 2B		
F0F6 2D		
F0F7 29		
F0F8 2A		
F0F9 2E		
F0FA 1E		
F0FB 29		
	3557	
F0FC	3558	SET_MODE PROC HEAR
F0FC BAD403	3559	MOV DX,0304H ; ADDRESS OF COLOR CARD
F0FF B300	3560	MOV BL,0 ; MODE SET FOR COLOR CARD
F101 83FF30	3561	CMP DI,30H ; IS BW CARD INSTALLED
F104 7506	3562	JNE M8 ; OK WITH COLOR
F106 B007	3563	MOV AL,7 ; INDICATE BW CARD MODE
F108 B2B4	3564	MOV DI,0B4H ; ADDRESS OF BW CARD (3B4)
F10A FEC3	3565	INC BL ; MODE SET FOR BW CARD
F10C	3566	
F10C 8AE0	3567	M8: MOV AH,AL ; SAVE MODE IN AH
F10E A24900	3568	MOV CRT_MODE,AL ; SAVE IN GLOBAL VARIABLE
F111 B9166300	3569	MOV ADDR_6B45,DX ; SAVE ADDRESS OF BASE
F115 1E	3570	PUSH DS ; SAVE POINTER TO DATA SEGMENT
F116 50	3571	PUSH AX ; SAVE MODE
F117 52	3572	PUSH DX ; SAVE OUTPUT PORT VALUE

LOC OBJ	LINE	SOURCE	
F118 83C204	3573	ADD DX,4	; POINT TO CONTROL REGISTER
F11B 8AC3	3574	MOV AL,BL	; GET MODE SET FOR CARD
F110 EE	3575	OUT DX,AL	; RESET VIDEO
F11E 5A	3576	POP OX	; BACK TO BASE REGISTER
F11F 2BC0	3577	SUB AX,AX	; SET UP FOR ABSD SEGMENT
F121 8ED8	3578	MOV DS,AX	; ESTABLISH VECTOR TABLE ADDRESSING
	3579	ASSUME DS:ABSD	
F123 C51E7400	3580	LDS BX,PARM_PTR	; GET POINTER TO VIDEO PARMS
F127 58	3581	POP AX	; RECOVER PARMS
	3582	ASSUME DS:CODE	
F128 B91000	3583	MOV CX,H4	; LENGTH OF EACH ROW OF TABLE
F12B 80FC02	3584	CMF AH,2	; DETERMINE WHICH ONE TO USE
F12E 7210	3585	JC H9	; MODE IS 0 OR 1
F130 03D9	3586	ADD BX,CX	; MOVE TO NEXT ROW OF IMIT TABLE
F132 80FC04	3587	CMF AH,4	
F135 7209	3588	JC H9	; MODE IS 2 OR 3
F137 03D9	3589	ADD BX,CX	; MOVE TO GRAPHICS ROW OF IMIT_TABLE
F139 80FC07	3590	CMF AH,7	
F13C 7202	3591	JC H9	; MODE IS 4,5, OR 6
F13E 03D9	3592	ADD BX,CX	; MOVE TO BM CARD ROW OF IMIT_TABLE
	3593		
	3594	;----- BX POINTS TO CORRECT ROW OF INITIALIZATION TABLE	
	3595		
F140	3596	M9:	; OUT_IMIT
F140 50	3597	PUSH AX	; SAVE MODE IN AH
F141 32E4	3598	XOR AH,AH	; AH WILL SERVE AS REGISTER
	3599		; NUMBER OURING LOOP
	3600		
	3601	;----- LOOP THROUGH TABLE, OUTPUTTING REG ADDRESS, THEN VALUE FROM TABLE	
	3602		
F143	3603	M10:	; IMIT LOOP
F143 8AC4	3604	MOV AL,AH	; GET 6945 REGISTER NUMBER
F145 EE	3605	OUT DX,AL	
F146 42	3606	INC DX	; POINT TO DATA PORT
F147 FEC4	3607	INC AH	; NEXT REGISTER VALUE
F149 8A07	3608	MOV AL,[BX]	; GET TABLE VALUE
F14B EE	3609	OUT DX,AL	; OUT TO CHIP
F14C 43	3610	INC BX	; NEXT IN TABLE
F14D 4A	3611	DEC DX	; BACK TO POINTER REGISTER
F14E E2F3	3612	LOOP M10	; DO THE WHOLE TABLE
F150 58	3613	POP AX	; GET MODE BACK
F151 1F	3614	POP DS	; RECOVER SEGMENT VALUE
	3615	ASSUME DS:DATA	
	3616		
	3617	;----- FILL REGEN AREA WITH BLANK	
	3618		
F152 33FF	3619	XOR DI,DI	; SET UP POINTER FOR REGEN
F154 B93E4E00	3620	MOV CRT_START,DI	; START ADDRESS SAVED IN GLOBAL
F158 C06620000	3621	MOV ACTIVE_PAGE,D	; SET PAGE VALUE
F15D B90020	3622	MOV CX,8192	; NUMBER OF WORDS IN COLOR CARD
F160 80FC04	3623	CMF AH,4	; TEST FOR GRAPHICS
F163 720B	3624	JC M12	; NO_GRAPHICS_INIT
F165 80FC07	3625	CMF AH,7	; TEST FOR BM CARD
F168 7404	3626	JE M11	; BM_CARD_INIT
F16A 33C0	3627	XOR AX,AX	; FILL FOR GRAPHICS MODE
F16C E005	3628	JMP SHORT M13	; CLEAR_BUFFER
F16E	3629	M11:	; BM_CARD_INIT
F16E B508	3630	MOV CN,08H	; BUFFER SIZE ON BM CARD
F170	3631	M12:	; NO_GRAPHICS_INIT
F170 B82007	3632	MOV AX,' '*7*256	; FILL CHAR FOR ALPHA
F173	3633	M13:	; CLEAR_BUFFER
F173 F3	3634	REP STOSW	; FILL THE REGEN BUFFER WITH BLANKS
F174 AB			
	3635		
	3636	;----- ENABLE VIDEO AND CORRECT PORT SETTING	
	3637		
F175 C70660000706	3638	MOV CURSDR_MODE,6D7H	; SET CURRENT CURSOR MODE
F17B A04900	3639	MOV AL,CRT_MODE	; GET THE MODE
F17E 32E4	3640	XOR AH,AH	; INTO AX REGISTER
F180 8BF0	3641	MOV SI,AX	; TABLE POINTER, INDEXED BY MODE
F182 8B166300	3642	MOV DX,ADDR_6845	; PREPARE TO OUTPUT TO
	3643		; VIDEO ENABLE PORT
F186 83C204	3644	ADD DX,4	
F189 2E8A84F4F0	3645	MOV AL,CS:[SI+OFFSET M71	
F18E EE	3646	OUT OX,AL	; SET VIDEO ENABLE PORT
F18F A26500	3647	MOV CRT_MODE_SET,AL	; SAVE THAT VALUE
	3648		

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LOC OBJ          LINE  SOURCE
3649      1----- DETERMINE NUMBER OF COLUMNS, BOTH FOR ENTIRE DISPLAY
3650      1----- AND THE NUMBER TO BE USED FOR TTY INTERFACE
3651
F192 2E8A84ECF0  3652      MOV     AL,CS:ISI + OFFSET N6J
F197 32E4        3653      XOR     AH,AH
F199 A34A00      3654      MOV     CRT_COLS,AX          ; NUMBER OF COLUMNS IN THIS SCREEN
3655
3656      1----- SET CURSOR POSITIONS
3657
F19C 01E60E00    3658      AND     SI,0EH          ; WORD OFFSET INTO CLEAR LENGTH TABLE
F1A0 2E8B0CE4F0  3659      MOV     CX,CS:ISI + OFFSET M5J ; LENGTH TO CLEAR
F1A5 090E4C00    3660      MOV     CRT_LEN,CX      ; SAVE LENGTH OF CRT -- NOT USED FOR BW
F1A9 090800      3661      MOV     CX,0           ; CLEAR ALL CURSOR POSITIONS
F1AC BF5000      3662      MOV     DI,OFFSET CURSOR_POSN
F1AF 1E          3663      PUSH    DS             ; ESTABLISH SEGMENT
F1B0 07          3664      POP     ES             ; ADDRESSING
F1B1 33C0        3665      XOR     AX,AX
F1B3 F3          3666      REP     STOSW          ; FILL WITH ZEROS
F1B4 AB
3667
3668      1----- SET UP OVERSCAN REGISTER
3669
F1B5 42          3670      INC     DX             ; SET OVERSCAN PORT TO A DEFAULT
F1B6 D030        3671      MOV     AL,30H        ; VALUE OF 30H FOR ALL NDDs
3672      ; EXCEPT 640X200
F1B8 803E490006  3673      CNP     CRT_NODE,6     ; SEE IF THE MODE IS 640X200 BW
F1B0 75D2        3674      JNZ     M14           ; IF IT ISNT 640X200, THEN GOTO REGULAR
F1BF D03F        3675      MOV     AL,3FH        ; IF IT IS 640X200, THEN PUT IN 3FH
F1C1            3676      N14:
F1C1 EE          3677      OUT     DX,AL          ; OUTPUT THE CORRECT VALUE TO 309 PORT
F1C2 A26600      3678      MOV     CRT_PALETTE,AL ; SAVE THE VALUE FOR FUTURE USE
3679
3680      1----- NORMAL RETURN FROM ALL VIDEO RETURNS
3681
F1C5            3682      VIDEO_RETURN:
F1C5 5F          3683      POP     DI
F1C6 5E          3684      POP     SI
F1C7 5B          3685      POP     BX
F1C8            3686      N15:
F1C8 59          3687      POP     CX             ; VIDEO_RETURN_C
F1C9 5A          3688      POP     DX
F1CA 1F          3689      POP     DS
F1CB 07          3690      POP     ES             ; RECOVER SEGMENTS
F1CC CF          3691      IRET                ; ALL DONE
3692      SET_NODE      ENDP
3693      1-----
3694      ; SET_CTYPE
3695      ; THIS ROUTINE SETS THE CURSOR VALUE
3696      ; INPUT
3697      ; (CX) HAS CURSOR VALUE CN-START LINE, CL-STOP LINE
3698      ; OUTPUT
3699      ; NONE
3700      1-----
F1CD            3701      SET_CTYPE      PROC    NEAR
F1CD B40A        3702      MOV     AH,10          ; 6845 REGISTER FOR CURSOR SET
F1CF 890E6000    3703      MOV     CURSOR_MODE,CX ; SAVE IN DATA AREA
F1D3 E80200      3704      CALL    N16           ; OUTPUT CX REG
F1D6 EBED        3705      JNP     VIDEO_RETURN
3706
3707      1----- THIS ROUTINE OUTPUTS THE CX REGISTER TO THE 6845 REGS NAMED IN AN
3708
F1D8            3709      N16:
F1D8 8B166300    3710      MOV     DX,ADDR_6845   ; ADDRESS REGISTER
F1DC 8AC4        3711      MOV     AL,AH          ; GET VALUE
F1DE EE          3712      OUT     DX,AL          ; REGISTER SET
F1DF 42          3713      INC     CX             ; DATA REGISTER
F1E0 8AC5        3714      MOV     AL,CH          ; DATA
F1E2 EE          3715      OUT     DX,AL
F1E3 4A          3716      DEC     DX
F1E4 8AC4        3717      MOV     AL,AH
F1E6 FEC0        3718      INC     AL             ; POINT TO OTHER DATA REGISTER
F1E8 EE          3719      OUT     DX,AL          ; SET FOR SECOND REGISTER
F1E9 42          3720      INC     CX
F1EA 8AC1        3721      MOV     AL,CL          ; SECOND DATA VALUE
F1EC EE          3722      OUT     DX,AL
F1ED C3          3723      RET
3724      SET_CTYPE      ENDP

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LOC	OBJ	LINE	SOURCE
		3725	-----
		3726	; SET_CPOS :
		3727	; THIS ROUTINE SETS THE CURRENT CURSOR :
		3728	; POSITION TO THE NEW X-Y VALUES PASSED :
		3729	; INPUT :
		3730	; DX - ROW,COLUMN OF NEW CURSOR :
		3731	; BH - DISPLAY PAGE OF CURSOR :
		3732	; OUTPUT :
		3733	; CURSOR IS SET AT 6B45 IF DISPLAY PAGE :
		3734	; IS CURRENT DISPLAY :
		3735	-----
F1EE		3736	SET_CPOS PROC NEAR
F1EE 8ACF		3737	MOV CL,BH
F1F0 32E0		3738	XOR CH,CH ; ESTABLISH LOOP COUNT
F1F2 D1E1		3739	SAL CX,1 ; WORD OFFSET
F1F4 8BF1		3740	MOV SI,CX ; USE INDEX REGISTER
F1F6 895450		3741	MOV [SI+OFFSET CURSOR_POSNI],DX ; SAVE THE POINTER
F1F9 383E6200		3742	CMP ACTIVE_PAGE,BH
F1FD 7505		3743	JNZ M17 ; SET_CPOS_RETURN
F1FF 8BC2		3744	MOV AX,DX ; GET ROW/COLUMN TO AX
F201 E80200		3745	CALL M18 ; CURSOR_SET
F204		3746	M17: ; SET_CPOS_RETURN
F204 EBBF		3747	JMP VIDEO_RETURN
		3748	SET_CPOS ENDP
		3749	
		3750	;----- SET CURSOR POSITION, AX HAS ROW/COLUMN FOR CURSOR
		3751	
F206		3752	M18 PROC NEAR
F206 E87C00		3753	CALL POSITION ; DETERMINE LOCATION IN REGEN BUFFER
F209 8BC8		3754	MOV CX,AX
F20B 030E4E00		3755	AOR CX,CRT_START ; ADD IN THE START ADDR FOR THIS PAGE
F20F 01F9		3756	SAR CX,1 ; DIVIDE BY 2 FOR CHAR ONLY COUNT
F211 B40E		3757	MOV AH,14 ; REGISTER NUMBER FOR CURSOR
F213 E8C2FF		3758	CALL M16 ; OUTPUT THE VALUE TO THE 6B45
F216 C3		3759	RET
		3760	M18 ENDP
		3761	-----
		3762	; ACT_OISP_PAGE :
		3763	; THIS ROUTINE SETS THE ACTIVE DISPLAY PAGE, ALLOWING THE :
		3764	; FULL USE OF THE RAM SET ASIDE FOR THE VIDEO ATTACHMENT :
		3765	; INPUT :
		3766	; AL HAS THE NEW ACTIVE DISPLAY PAGE :
		3767	; OUTPUT :
		3768	; THE 6B45 IS RESET TO DISPLAY THAT PAGE :
		3769	-----
F217		3770	ACT_OISP_PAGE PROC NEAR
F217 A26200		3771	MOV ACTIVE_PAGE,AL ; SAVE ACTIVE PAGE VALUE
F21A 8B0E4C00		3772	MOV CX,CRT_LEN ; GET SAVED LENGTH OF REGEN BUFFER
F21E 98		3773	CBW ; CONVERT AL TO WORD
F21F 50		3774	PUSH AX ; SAVE PAGE VALUE
F220 F7E1		3775	MUL CX ; DISPLAY PAGE TIMES REGEN LENGTH
F222 A34E00		3776	MOV CRT_START,AX ; SAVE START ADDRESS FOR
		3777	; LATER REQUIREMENTS
F225 8BC8		3778	MOV CX,AX ; START ADDRESS TO CX
F227 01F9		3779	SAR CX,1 ; DIVIDE BY 2 FOR 6B45 HANDLING
F229 B40C		3780	MOV AH,12 ; 6B45 REGISTER FOR START ADDRESS
F22B E8AAFF		3781	CALL M16
F22E 5B		3782	POP BX ; RECOVER PAGE VALUE
F22F 01E3		3783	SAL BX,1 ; *2 FOR WORD OFFSET
F231 8B4750		3784	MOV AX,[BX + OFFSET CURSOR_POSNI] ; GET CURSOR FOR THIS PAGE
F234 E8CFFF		3785	CALL M18 ; SET THE CURSOR POSITION
F237 E88C		3786	JMP SHORT VIDEO_RETURN
		3787	ACT_OISP_PAGE ENDP
		3788	-----
		3789	; READ_CURSOR :
		3790	; THIS ROUTINE READS THE CURRENT CURSOR VALUE FROM THE :
		3791	; 6B45, FORMATS IT, AND SENDS IT BACK TO THE CALLER :
		3792	; INPUT :
		3793	; BH - PAGE OF CURSOR :
		3794	; OUTPUT :
		3795	; DX - ROW, COLUMN OF THE CURRENT CURSOR POSITION :
		3796	; CX - CURRENT CURSOR MODE :
		3797	-----
F239		3798	READ_CURSOR PROC NEAR
F239 8A0F		3799	MOV BL,BH
F23B 32FF		3800	XOR BH,BH
F230 01E3		3801	SAL BX,1 ; WORD OFFSET

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LOC OBJ          LINE    SOURCE
F23F 005750      3002      MOV     DX,(BX+OFFSET CURSOR_POSN)
F242 00E6000     3003      MOV     CX,CURSOR_MODE
F246 5F          3004      POP     DI
F247 5E          3005      POP     SI
F248 5B          3006      POP     BX
F249 58          3007      POP     AX          ; DISCARD SAVED CX AND DX
F24A 58          3008      POP     AX
F24B 1F          3009      POP     DS
F24C 07          3010      POP     ES
F24D CF          3011      IRET
3012      REAO_CURSOR      ENDP
3013      ;-----
3014      ; SET COLOR
3015      ; THIS ROUTINE WILL ESTABLISH THE BACKGROUND COLOR, THE OVERSCAN :
3016      ; COLOR, AND THE FOREGROUND COLOR SET FOR MEDIUM RESOLUTION :
3017      ; GRAPHICS :
3018      ; INPUT :
3019      ; (BX) HAS COLOR ID :
3020      ; IF BH=0, THE BACKGROUND COLOR VALUE IS SET :
3021      ; FROM THE LOW BITS OF BL (0-31) :
3022      ; IF BH=1, THE PALETTE SELECTION IS MADE :
3023      ; BASED ON THE LOW BIT OF BL: :
3024      ; 0=GREEN, RED, YELLOW FOR COLORS 1,2,3 :
3025      ; 1=BLUE, CYAN, MAGENTA FOR COLORS 1,2,3 :
3026      ; (BL) HAS THE COLOR VALUE TO BE USED :
3027      ; OUTPUT :
3028      ; THE COLOR SELECTION IS UPDATED :
3029      ;-----
F24E          3030      SET_COLOR      PROC      NEAR
F24E 0B166300     3031      MOV     DX,ADDR_6845      ; I/O PORT FOR PALETTE
F252 83C205     3032      ADD     DX,5              ; OVERSCAN PORT
F255 A06400     3033      MOV     AL,CRT_PALETTE    ; GET THE CURRENT PALETTE VALUE
F258 0AFF       3034      OR      BH,BH             ; IS THIS COLOR 0?
F25A 750E       3035      JNZ     M20              ; OUTPUT COLOR 1
3036
3037      ;---- HANDLE COLOR 0 BY SETTING THE BACKGROUND COLOR
3038
F25C 24E0       3039      AND     AL,0E0H          ; TURN OFF LOW 5 BITS OF CURRENT
F25E 80E31F     3040      AND     BL,01FH          ; TURN OFF HIGH 3 BITS OF INPUT VALUE
F261 0AC3       3041      OR      AL,BL            ; PUT VALUE INTO REGISTER
F263          3042      M19:              ; OUTPUT THE PALETTE
F263 EE         3043      OUT     DX,AL            ; OUTPUT COLOR SELECTION TO 309 PORT
F264 A26600     3044      MOV     CRT_PALETTE,AL    ; SAVE THE COLOR VALUE
F267 E95BFF     3045      JMP     VIDEO_RETURN
3046
3047      ;---- HANDLE COLOR 1 BY SELECTING THE PALETTE TO BE USED
3048
F26A          3049      M20:
F26A 24DF       3050      AND     AL,0DFH          ; TURN OFF PALETTE SELECT BIT
F26C 00E0       3051      SHR     BL,1             ; TEST THE LOW ORDER BIT OF BL
F26E 73F3       3052      JNC     M19              ; ALREADY DONE
F270 0C20       3053      OR      AL,20H          ; TURN ON PALETTE SELECT BIT
F272 EBFF       3054      JMP     M19              ; GO ON IT
3055      SET_COLOR      ENDP
3056      ;-----
3057      ; VIDEO STATE :
3058      ; RETURNS THE CURRENT VIDEO STATE IN AX :
3059      ; AH = NUMBER OF COLUMNS ON THE SCREEN :
3060      ; AL = CURRENT VIDEO MODE :
3061      ; BH = CURRENT ACTIVE PAGE :
3062      ;-----
F274          3063      VIDEO_STATE      PROC      NEAR
F274 8A264A00     3064      MOV     AH,BYTE PTR CRT_COLS ; GET NUMBER OF COLUMNS
F278 A04900     3065      MOV     AL,CRT_MODE        ; CURRENT MODE
F27B 8A3E200    3066      MOV     BH,ACTIVE_PAGE     ; GET CURRENT ACTIVE PAGE
F27F 5F         3067      POP     DI                ; RECOVER REGISTERS
F280 5E         3068      POP     SI
F281 59         3069      POP     CX                ; DISCARD SAVED BX
F282 E943FF     3070      JMP     M15              ; RETURN TO CALLER
3071      VIDEO_STATE      ENDP
3072      ;-----
3073      ; POSITION :
3074      ; THIS SERVICE ROUTINE CALCULATES THE REGEN :
3075      ; BUFFER ADDRESS OF A CHARACTER IN THE ALPHA MODE :
3076      ; INPUT :
3077      ; AX = ROW, COLUMN POSITION :
3078      ; OUTPUT :

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LOC OBJ	LINE	SOURCE
	3879	; AX = OFFSET OF CHAR POSITION IN REGEN BUFFER ;
	3880	-----
F285	3881	POSITION PROC NEAR
F285 53	3882	PUSH BX ; SAVE REGISTER
F286 8BD8	3883	MOV BX,AX
F288 8AC4	3884	MOV AL,AH ; ROWS TO AL
F28A F6264A00	3885	MUL BYTE PTR CRT_COLS ; DETERMINE BYTES TO ROW
F28E 32FF	3886	XOR BH,BH
F290 03C3	3887	ADD AX,BX ; ADD IN COLUMN VALUE
F292 D1E0	3888	SAL AX,1 ; * 2 FOR ATTRIBUTE BYTES
F294 5B	3889	POP BX
F295 C3	3890	RET
	3891	POSITION ENDP
	3892	-----
	3893	; SCROLL UP ;
	3894	; THIS ROUTINE MOVES A BLOCK OF CHARACTERS UP ;
	3895	; ON THE SCREEN ;
	3896	; INPUT ;
	3897	; (AH) = CURRENT CRT MODE ;
	3898	; (AL) = NUMBER OF ROWS TO SCROLL ;
	3899	; (CX) = ROW/COLUMN OF UPPER LEFT CORNER ;
	3900	; (DX) = ROW/COLUMN OF LOWER RIGHT CORNER ;
	3901	; (BH) = ATTRIBUTE TO BE USED ON BLANKED LINE ;
	3902	; (DS) = DATA SEGMENT ;
	3903	; (ES) = REGEN BUFFER SEGMENT ;
	3904	; OUTPUT ;
	3905	; NONE -- THE REGEN BUFFER IS MODIFIED ;
	3906	-----
	3907	ASSUME CS:CODE,DS:DATA,ES:DATA
F296	3908	SCROLL_UP PROC NEAR
F296 8A08	3909	MOV BL,AL ; SAVE LINE COUNT IN BL
F298 80FC04	3910	CMP AH,4 ; TEST FOR GRAPHICS MODE
F29B 7208	3911	JC N1 ; HANDLE SEPARATELY
F29D 80FC07	3912	CMP AH,7 ; TEST FOR BW CARD
F2A0 7403	3913	JE N1
F2A2 E9F001	3914	JMP GRAPHICS_UP
F2A5	3915	N1: ; UP_CONTINUE
F2A5 53	3916	PUSH BX ; SAVE FILL ATTRIBUTE IN BH
F2A6 8BC1	3917	MOV AX,CX ; UPPER LEFT POSITION
F2A8 E83700	3918	CALL SCROLL_POSITION ; DO SETUP FOR SCROLL
F2AB 7431	3919	JZ N7 ; BLANK_FIELD
F2AD 03F0	3920	ADD SI,AX ; FROM ADDRESS
F2AF 8AE6	3921	MOV AH,DH ; # ROWS IN BLOCK
F2B1 2AE3	3922	SUB AH,BL ; # ROWS TO BE MOVED
F2B3	3923	N2: ; ROW_LOOP
F2B3 EB7200	3924	CALL N10 ; MOVE ONE ROW
F2B6 03F5	3925	ADD SI,BP
F2B8 03F0	3926	ADD DI,BP ; POINT TO NEXT LINE IN BLOCK
F2BA FECC	3927	DEC AH ; COUNT OF LINES TO MOVE
F2BC 75F5	3928	JNZ N2 ; ROW_LOOP
F2BE	3929	N3: ; CLEAR_ENTRY
F2BE 5B	3930	POP AX ; RECOVER ATTRIBUTE IN AH
F2BF B020	3931	MOV AL,' ' ; FILL WITH BLANKS
F2C1	3932	N4: ; CLEAR_LOOP
F2C1 E86000	3933	CALL N11 ; CLEAR THE ROW
F2C4 03FD	3934	ADD DI,BP ; POINT TO NEXT LINE
F2C6 FECB	3935	DEC BL ; COUNTER OF LINES TO SCROLL
F2CB 75F7	3936	JNZ N4 ; CLEAR_LOOP
F2CA	3937	N5: ; SCROLL_END
F2CA E8710C	3938	CALL 005
F2CD 803E490007	3939	CMP CRT_MODE,7 ; IS THIS THE BLACK AND WHITE CARD
F2D2 7407	3940	JE N6 ; IF SO, SKIP THE MODE RESET
F2D4 A06500	3941	MOV AL,CRT_MODE_SET ; GET THE VALUE OF THE MODE SET
F2D7 BAD803	3942	MOV DX,03D8H ; ALWAYS SET COLOR CARD PORT
F2DA EE	3943	OUT DX,AL
F2DB	3944	N6: ; VIDEO_RET_HERE
F2DB E9E7FE	3945	JMP VIDEO_RETURN
F2DE	3946	N7: ; BLANK_FIELD
F2DE 8ADE	3947	MOV BL,DH ; GET ROW COUNT
F2E0 EBDC	3948	JMP N3 ; GO CLEAR THAT AREA
	3949	SCROLL_UP ENDP
	3950	
	3951	;----- HANDLE COMMON SCROLL SET UP HERE
	3952	
F2E2	3953	SCROLL_POSITION PROC NEAR
F2E2 803E490002	3954	CMP CRT_MODE,2 ; TEST FOR SPECIAL CASE HERE
F2E7 7218	3955	JB N9 ; HAVE TO HANDLE BOX2S SEPARATELY

LOC OBJ	LINE	SOURCE	
F2E9 803E49003	3956	CNP	CRT_MODE,3
F2EE 7711	3957	JA	N9
	3958		
	3959	;----- 80X25 COLOR CARD SCROLL	
	3960		
F2F0 52	3961	PUSH	DX
F2F1 BADA03	3962	MOV	DX,3DAH ; GUARANTEED TO BE COLOR CARD HERE
F2F4 50	3963	PUSH	AX
F2F5	3964	N8:	; WAIT_DISP_ENABLE
F2F5 EC	3965	IN	AL,0X ; GET PORT
F2F6 A808	3966	TEST	AL,8 ; WAIT FOR VERTICAL RETRACE
F2F8 74FD	3967	JZ	N8 ; WAIT_DISP_ENABLE
F2FA B025	3968	MOV	AL,25H
F2FC B208	3969	MOV	OL,0D8H ; DX=308
F2FE EE	3970	OUT	DX,AL ; TURN OFF VIDEO
F2FF 58	3971	POP	AX ; DURING VERTICAL RETRACE
F300 5A	3972	POP	DX
F301	3973	N9:	
F301 E801FF	3974	CALL	POSITION ; CONVERT TO REGEN POINTER
F304 03064E00	3975	ADD	AX,CRT_START ; OFFSET OF ACTIVE PAGE
F308 88F8	3976	MOV	DI,AX ; TO ADDRESS FOR SCROLL
F30A 8BF0	3977	MOV	SI,AX ; FROM ADDRESS FOR SCROLL
F30C 2BD1	3978	SUB	DX,CX ; DX = #ROWS, #COLS IN BLOCK
F30E FEC6	3979	INC	DX
F310 FEC2	3980	INC	DL ; INCREMENT FOR 0 ORIGIN
F312 32ED	3981	XOR	CH,CH ; SET HIGH BYTE OF COUNT TO ZERO
F314 8B2E4A00	3982	MOV	BP,CRT_COLS ; GET NUMBER OF COLUMNS IN DISPLAY
F318 03ED	3983	ADD	BP,BP ; TIMES 2 FOR ATTRIBUTE BYTE
F31A 8AC3	3984	MOV	AL,BL ; GET LINE COUNT
F31C F6264A00	3985	MUL	BYTE PTR CRT_COLS ; DETERMINE OFFSET TO FROM ADDRESS
F320 03C0	3986	ADD	AX,AX ; *2 FOR ATTRIBUTE BYTE
F322 06	3987	PUSH	ES ; ESTABLISH ADDRESSING TO REGEN BUFFER
F323 1F	3988	POP	OS ; FOR BOTH POINTERS
F324 80FB00	3989	CMPL	BL,0 ; 0 SCROLL MEANS BLANK FIELD
F327 C3	3990	RET	; RETURN WITH FLAGS SET
	3991	SCROLL_POSITION ENDP	
	3992		
	3993	;----- MOVE_ROW	
	3994		
F328	3995	N10 PROC	NEAR
F328 8ACA	3996	MOV	CL,DL ; GET # OF COLS TO MOVE
F32A 56	3997	PUSH	SI
F32B 57	3998	PUSH	DI ; SAVE START ADDRESS
F32C F3	3999	REP	MOVSW ; MOVE THAT LINE ON SCREEN
F32D A5			
F32E 5F	4000	POP	DI
F32F 5E	4001	POP	SI ; RECOVER ADDRESSES
F330 C3	4002	RET	
	4003	N10	ENDP
	4004		
	4005	;----- CLEAR_ROW	
	4006		
F331	4007	N11 PROC	NEAR
F331 8ACA	4008	MOV	CL,OL ; GET # COLUMNS TO CLEAR
F333 57	4009	PUSH	DI
F334 F3	4010	REP	STOSW ; STORE THE FILL CHARACTER
F335 AB			
F336 5F	4011	POP	DI
F337 C3	4012	RET	
	4013	N11	ENDP
	4014	;-----	
	4015	; SCROLL_DOWN :	
	4016	; THIS ROUTINE MOVES THE CHARACTERS WITHIN A :	
	4017	; DEFINED BLOCK DOWN ON THE SCREEN, FILLING THE :	
	4018	; TOP LINES WITH A DEFINED CHARACTER :	
	4019	; INPUT :	
	4020	; (AN) = CURRENT CRT MODE :	
	4021	; (AL) = NUMBER OF LINES TO SCROLL :	
	4022	; (CX) = UPPER LEFT CORNER OF REGION :	
	4023	; (DX) = LOWER RIGHT CORNER OF REGION :	
	4024	; (BN) = FILL CHARACTER :	
	4025	; (DS) = DATA SEGMENT :	
	4026	; (ES) = REGEN SEGMENT :	
	4027	; OUTPUT :	
	4028	; NONE -- SCREEN IS SCROLLED :	
	4029	;-----	
F338	4030	SCROLL_DOWN	PROC NEAR

LOC OBJ	LINE	SOURCE	
F330 FD	4031	STD	; DIRECTION FOR SCROLL DOWN
F339 8AD0	4032	MOV BL,AL	; LINE COUNT TO BL
F33B 80FC04	4033	CMF AH,4	; TEST FOR GRAPHICS
F33E 7208	4034	JC N12	
F340 80FC07	4035	CMF AN,7	; TEST FOR BW CARD
F343 7403	4036	JE N12	
F345 E9A601	4037	JMP GRAPHICS_DOWN	
F348	4038	N12:	; CONTINUE DOWN
F348 53	4039	PUSH BX	; SAVE ATTRIBUTE IN BX
F349 8BC2	4040	MOV AX,BX	; LOWER RIGHT CORNER
F34B E894FF	4041	CALL SCROLL_POSITION	; GET REGEN LOCATION
F34E 7420	4042	JZ N16	
F350 2BF0	4043	SUB SI,AX	; SI IS FROM ADDRESS
F352 8AE6	4044	MOV AN,DH	; GET TOTAL # ROWS
F354 2AE3	4045	SUB AN,BL	; COUNT TO MOVE IN SCROLL
F356	4046	N13:	
F356 E8CFFF	4047	CALL N10	; MOVE ONE ROW
F359 28F5	4048	SUB SI,BP	
F35B 2BFD	4049	SUB DI,BP	
F35D FECC	4050	DEC AH	
F35F 75F5	4051	JNZ N13	
F361	4052	N14:	
F361 58	4053	POP AX	; RECOVER ATTRIBUTE IN AH
F362 B020	4054	MOV AL,' '	
F364	4055	N15:	
F364 E8CAFF	4056	CALL N11	; CLEAR ONE ROW
F367 2BFD	4057	SUB DI,BP	; GO TO NEXT ROW
F369 FECB	4058	DEC BL	
F36B 75F7	4059	JNZ N15	
F36D E9SAFF	4060	JMP N5	; SCROLL_END
F370	4061	N16:	
F370 8ADE	4062	MOV BL,DH	
F372 E8E0	4063	JMP N14	
	4064	SCROLL_DOWN ENDP	
	4065	;	
	4066	; READ_AC_CURRENT	;
	4067	; THIS ROUTINE READS THE ATTRIBUTE AND CHARACTER	;
	4068	; AT THE CURRENT CURSOR POSITION AND RETURNS THEM	;
	4069	; TO THE CALLER	;
	4070	;INPUT	;
	4071	; (AH) = CURRENT CRT MODE	;
	4072	; (BH) = DISPLAY PAGE (ALPHA MODES ONLY)	;
	4073	; (DS) = DATA SEGMENT	;
	4074	; (ES) = REGEN SEGMENT	;
	4075	;OUTPUT	;
	4076	; (AL) = CHAR READ	;
	4077	; (AH) = ATTRIBUTE READ	;
	4078	;	
	4079	ASSUME CS:CODE,DS:DATA,ES:DATA	
F374	4080	READ_AC_CURRENT PROC NEAR	
F374 80FC04	4081	CMF AH,4	; IS THIS GRAPHICS
F377 7208	4082	JC P1	
F379 80FC07	4083	CMF AN,7	; IS THIS BW CARD
F37C 7403	4084	JE P1	
F37E E9A802	4085	JMP GRAPHICS_READ	
F381	4086	P1:	; READ_AC_CONTINUE
F381 E81A00	4087	CALL FIND_POSITION	
F384 8BF3	4088	MOV SI,BX	; ESTABLISH ADDRESSING IN SI
	4089		
	4090	;----- WAIT FOR HORIZONTAL RETRACE	
	4091		
F386 8B166300	4092	MOV DX,ADDR_6845	; GET BASE ADDRESS
F38A 83C206	4093	ADD DX,6	; POINT AT STATUS PORT
F38D 06	4094	PUSH ES	
F38E 1F	4095	POP DS	; GET SEGMENT FOR QUICK ACCESS
F38F	4096	P2:	; WAIT FOR RETRACE LOW
F38F EC	4097	IN AL,DX	; GET STATUS
F390 A801	4098	TEST AL,1	; IS HORIZ RETRACE LOW
F392 75FB	4099	JNZ P2	; WAIT UNTIL IT IS
F394 FA	4100	CLI	; NO MORE INTERRUPTS
F395	4101	P3:	; WAIT FOR RETRACE HIGH
F395 EC	4102	IN AL,DX	; GET STATUS
F396 A801	4103	TEST AL,1	; IS IT HIGH
F398 74FB	4104	JZ P3	; WAIT UNTIL IT IS
F39A AD	4105	LDOSW	; GET THE CHAR/ATTR
F39B E927FE	4106	JMP VIDEO_RETURN	
	4107	READ_AC_CURRENT ENDP	


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LOC OBJ          LINE  SOURCE
4108
F39E             4109  FIND_POSITION  PROC   NEAR
F39E 8ACF        4110      MOV    CL,BH          ; DISPLAY PAGE TO CX
F3A0 32ED        4111      XOR     CH,CH
F3A2 8BF1        4112      MOV    SI,CX          ; MOVE TO SI FOR INDEX
F3A4 D1E6        4113      SAL     SI,1          ; * 2 FOR WORD OFFSET
F3A6 8B4450      4114      MOV    AX,[SI+ OFFSET CURSOR_POSH1 ; GET ROW/COLUMN OF THAT PAGE
F3A9 33D8        4115      XOR     BX,BX          ; SET START ADDRESS TO ZERO
F3AB E306        4116      JCXZ    PS          ; NO_PAGE
F3AD             4117  P4:          ; PAGE_LOOP
F3AD 031E4C00    4118      ADD     BX,CRT_LEN      ; LENGTH OF BUFFER
F3B1 E2FA        4119      LOOP   P4
F3B3             4120  PS:          ; NO_PAGE
F3B3 EBCFFE      4121      CALL   POSITION          ; DETERMINE LOCATION IN REGEN
F3B6 03D8        4122      ADD     BX,AX          ; ADD TO START OF REGEN
F3B8 C3          4123      RET
4124  FIND_POSITION  ENDP
4125  ;-----
4126  ; WRITE_AC_CURRENT :
4127  ; THIS ROUTINE WRITES THE ATTRIBUTE :
4128  ; AND CHARACTER AT THE CURRENT CURSOR :
4129  ; POSITION :
4130  ; INPUT :
4131  ; (AH) = CURRENT CRT MODE :
4132  ; (BH) = DISPLAY PAGE :
4133  ; (CX) = COUNT OF CHARACTERS TO WRITE :
4134  ; (AL) = CHAR TO WRITE :
4135  ; (BL) = ATTRIBUTE OF CHAR TO WRITE :
4136  ; (DS) = DATA SEGMENT :
4137  ; (ES) = REGEN SEGMENT :
4138  ; OUTPUT :
4139  ; NONE :
4140  ;-----
F3B9             4141  WRITE_AC_CURRENT  PROC   NEAR
F3B9 80FC04      4142      CMP     AH,4          ; IS THIS GRAPHICS
F3BC 7208        4143      JC      P6
F3BE 80FC07      4144      CMP     AH,7          ; IS THIS BW CARD
F3C1 7403        4145      JE      P6
F3C3 E9B201      4146      JMP     GRAPHICS_WRITE
F3C6             4147  P6:          ; WRITE_AC_CONTINUE
F3C6 8AE3        4148      MOV     AH,BL          ; GET ATTRIBUTE TO AH
F3C8 50          4149      PUSH    AX          ; SAVE ON STACK
F3C9 51          4150      PUSH    CX          ; SAVE WRITE COUNT
F3CA E801FF      4151      CALL    FIND_POSITION
F3CD 88FB        4152      MOV     DI,BX          ; ADDRESS TO DI REGISTER
F3CF 59          4153      POP     CX          ; WRITE COUNT
F3D0 5B          4154      POP     BX          ; CHARACTER IN BX REG
F3D1             4155  P7:          ; WRITE_LDDP
4156
4157  ;----- WAIT FOR HORIZONTAL RETRACE
4158
F3D1 8B166300    4159      MOV     DX,ADDR_6845    ; GET BASE ADDRESS
F3D5 83C206      4160      ADD     DX,6          ; POINT AT STATUS PORT
F3DB             4161  P8:
F3DB EC          4162      IN      AL,DX          ; GET STATUS
F3D9 A801        4163      TEST    AL,1          ; IS IT LOW
F3DB 75FB        4164      JNZ     P8          ; WAIT UNTIL IT IS
F3DD FA          4165      CLI          ; NO MORE INTERRUPTS
F3DE             4166  P9:
F3DE EC          4167      IN      AL,DX          ; GET STATUS
F3DF A801        4168      TEST    AL,1          ; IS IT HIGH
F3E1 74FB        4169      JZ      P9          ; WAIT UNTIL IT IS
F3E3 8BC3        4170      MOV     AX,BX          ; RECOVER THE CHAR/ATTR
F3E5 AB          4171      STOSW   ; PUT THE CHAR/ATTR
F3E6 FB          4172      STI          ; INTERRUPTS BACK ON
F3E7 E2E8        4173      LOOP    P7          ; AS MANY TIMES AS REQUESTED
F3E9 E9D9FD      4174      JMP     VIDEO_RETURN
4175  WRITE_AC_CURRENT  ENDP
4176  ;-----
4177  ; WRITE_C_CURRENT :
4178  ; THIS ROUTINE WRITES THE CHARACTER AT :
4179  ; THE CURRENT CURSOR POSITION, ATTRIBUTE :
4180  ; UNCHANGED :
4181  ; INPUT :
4182  ; (AH) = CURRENT CRT MODE :
4183  ; (BH) = DISPLAY PAGE :
4184  ; (CX) = COUNT OF CHARACTERS TO WRITE :

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LOC OBJ	LINE	SOURCE
	4185	; (AL) = CHAR TO WRITE ;
	4186	; (DS) = DATA SEGMENT ;
	4187	; (ES) = REGEN SEGMENT ;
	4188	; OUTPUT ;
	4189	; NONE ;
	4190	;
F3EC	4191	WRITE_C_CURRENT PROC NEAR
F3EC 80FC04	4192	CHP AH,4 ; IS THIS GRAPHICS
F3EF 7208	4193	JC P10
F3F1 80FC07	4194	CHP AH,7 ; IS THIS BN CARO
F3F4 7403	4195	JE P10
F3F6 E97F01	4196	JHP GRAPHICS_WRITE
F3F9	4197	P10:
F3F9 50	4198	PUSH AX ; SAVE ON STACK
F3FA 51	4199	PUSH CX ; SAVE WRITE COUNT
F3FB E8A0FF	4200	CALL FIND_POSITION
F3FE 88FB	4201	MOV DI,BX ; ADDRESS TO DI
F400 59	4202	POP CX ; WRITE COUNT
F401 5B	4203	POP BX ; BL HAS CHAR TO WRITE
F402	4204	P11: ; WRITE_LOOP
	4205	
	4206	;----- WAIT FOR HORIZONTAL RETRACE
	4207	
F402 8B166300	4208	MOV DX,ADDR_6845 ; GET BASE ADDRESS
F406 83C206	4209	ADD DX,6 ; POINT AT STATUS PORT
F409	4210	P12:
F409 EC	4211	IN AL,DX ; GET STATUS
F40A A801	4212	TEST AL,1 ; IS IT LOW
F40C 75FB	4213	JNZ P12 ; WAIT UNTIL IT IS
F40E FA	4214	CLI ; NO MORE INTERRUPTS
F40F	4215	P13:
F40F EC	4216	IN AL,DX ; GET STATUS
F410 A801	4217	TEST AL,1 ; IS IT HIGH
F412 74F8	4218	JZ P13 ; WAIT UNTIL IT IS
F414 BAC3	4219	MOV AL,BL ; RECOVER CHAR
F416 AA	4220	STOSB ; PUT THE CHAR/ATTR
F417 FB	4221	STI ; INTERRUPTS BACK ON
F418 47	4222	INC DI ; 80HP POINTER PAST ATTRIBUTE
F419 E2E7	4223	LOOP P11 ; AS MANY TIMES AS REQUESTED
F41B E9A7FD	4224	JMP VIDEO_RETURN
	4225	WRITE_C_CURRENT ENDP
	4226	;
	4227	; READ DOT -- WRITE DOT ;
	4228	; THESE ROUTINES WILL WRITE A DOT, OR READ THE DOT AT ;
	4229	; THE INDICATED LOCATION ;
	4230	; ENTRY -- ;
	4231	; DX = ROW (0-199) (THE ACTUAL VALUE DEPENDS ON THE MODE) ;
	4232	; CX = COLUMN (0-639) (THE VALUES ARE NOT RANGE CHECKED) ;
	4233	; AL = DOT VALUE TO WRITE (1,2 OR 4 BITS DEPENDING ON MODE, ;
	4234	; REQ'D FOR WRITE DOT ONLY, RIGHT JUSTIFIED) ;
	4235	; BIT 7 OF AL=1 INDICATES XOR THE VALUE INTO THE LOCATION ;
	4236	; DS = DATA SEGMENT ;
	4237	; ES = REGEN SEGMENT ;
	4238	; ;
	4239	; EXIT ;
	4240	; AL = DOT VALUE READ, RIGHT JUSTIFIED, READ ONLY ;
	4241	;
	4242	ASSUME CS:CODE,DS:DATA,ES:DATA
F41E	4243	READ_DOT PROC NEAR
F41E E83100	4244	CALL R3 ; DETERMINE BYTE POSITION OF DOT
F421 268A04	4245	MOV AL,ES:[SI] ; GET THE BYTE
F424 22C4	4246	AND AL,AH ; MASK OFF THE OTHER BITS IN THE BYTE
F426 D2E0	4247	SHL AL,CL ; LEFT JUSTIFY THE VALUE
F428 BACE	4248	MOV CL,DH ; GET NUMBER OF BITS IN RESULT
F42A D2C0	4249	ROL AL,CL ; RIGHT JUSTIFY THE RESULT
F42C E996FD	4250	JHP VIDEO_RETURN ; RETURN FROM VIDEO IO
	4251	READ_DOT ENDP
	4252	
F42F	4253	WRITE_DOT PROC NEAR
F42F 50	4254	PUSH AX ; SAVE DOT VALUE
F430 50	4255	PUSH AX ; TWICE
F431 E81E00	4256	CALL R3 ; DETERMINE BYTE POSITION OF THE DOT
F434 D2E8	4257	SHR AL,CL ; SHIFT TO SET UP THE BITS FOR OUTPUT
F436 22C4	4258	AND AL,AH ; STRIP OFF THE OTHER BITS
F438 268A0C	4259	MOV CL,ES:[SI] ; GET THE CURRENT BYTE
F43B 5B	4260	POP BX ; RECOVER XOR FLAG
F43C F6C380	4261	TEST BL,80H ; IS IT ON

LOC	OBJ	LINE	SOURCE
F43F	750D	4262	JNZ R2 ; YES, XOR THE DDT
F441	F6D4	4263	NOT AH ; SET THE MASK TO REMOVE THE
F443	22CC	4264	AND CL,AH ; INDICATED BITS
F445	0AC1	4265	DR AL,CL ; OR IN THE NEW VALUE OF THOSE BITS
F447		4266	R1: ; FINISH_DOT
F447	268D04	4267	MOV ES:[SI],AL ; RESTORE THE BYTE IN MEMORY
F44A	58	4268	PDP AX
F44B	E977FD	4269	JMP VIDEO_RETURN ; RETURN FROM VIDEO ID
F44E		4270	R2: ; XOR_DOT
F44E	32C1	4271	XOR AL,CL ; EXCLUSIVE OR THE DOTS
F450	E0F5	4272	JMP R1 ; FINISH UP THE WRITING
		4273	WRITE_DOT ENDP
		4274	;
		4275	; THIS SUBROUTINE DETERMINES THE REGEN BYTE LOCATION :
		4276	; OF THE INDICATED ROW COLUMN VALUE IN GRAPHICS MODE. :
		4277	; ENTRY -- :
		4278	; OX = ROW VALUE (0-1991) :
		4279	; CX = COLUMN VALUE (0-6391) :
		4280	; EXIT -- :
		4281	; SI = OFFSET INTO REGEN BUFFER FOR BYTE OF INTEREST :
		4282	; AH = MASK TO STRIP OFF THE BITS OF INTEREST :
		4283	; CL = BITS TO SHIFT TO RIGHT JUSTIFY THE MASK IN AH :
		4284	; DH = # BITS IN RESULT :
		4285	;
F452		4286	R3: PROC NEAR
F452	53	4287	PUSH BX ; SAVE BX DURING OPERATION
F453	50	4288	PUSH AX ; WILL SAVE AL DURING OPERATION
		4289	
		4290	;
		4291	;----- DETERMINE 1ST BYTE IN INDICATED ROW BY MULTIPLYING ROW VALUE BY 40
		4292	;----- (LOW BIT OF ROW DETERMINES EVEN/ODD, 80 BYTES/ROW
		4293	MOV AL,40
F454	B028	4294	PUSH OX ; SAVE ROW VALUE
F456	52	4295	AND OL,OFEM ; STRIP OFF ODD/EVEN BIT
F457	80E2FE	4296	MUL OL ; AX HAS ADDRESS OF 1ST BYTE
F45A	F6E2	4297	; OF INDICATED ROW
F45C	5A	4298	POP OX ; RECOVER IT
F45D	F6C201	4299	TEST OL,1 ; TEST FOR EVEN/ODD
F460	7403	4300	JZ R4 ; JUMP IF EVEN ROW
F462	050020	4301	ADO AX,2000H ; OFFSET TO LOCATION OF ODD ROWS
F465		4302	R4: ; EVEN_ROW
F465	8BF0	4303	MOV SI,AX ; MOVE POINTER TO SI
F467	58	4304	POP AX ; RECOVER AL VALUE
F468	8BD1	4305	MOV OX,CX ; COLUMN VALUE TO OX
		4306	
		4307	;
		4308	;----- DETERMINE GRAPHICS MODE CURRENTLY IN EFFECT
		4309	;
		4310	; SET UP THE REGISTERS ACCORDING TO THE MODE :
		4311	; CH = MASK FOR LOW OF COLUMN ADDRESS (7/3 FOR HIGH/ME0 RES) :
		4312	; CL = # OF ADDRESS BITS IN COLUMN VALUE (3/2 FOR H/M) :
		4313	; BL = MASK TO SELECT BITS FROM POINTED BYTE (80H/COH FOR H/M) :
		4314	; BH = NUMBER OF VALID BITS IN POINTED BYTE (1/2 FOR H/M) :
		4315	;
		4316	;
F46A	BBC002	4317	MOV BX,2C0H
F46D	B90203	4318	MOV CX,302H ; SET PARMS FOR ME0 RES
F470	803E490006	4319	CMF CRT_MODE,6
F475	7206	4320	JC R5 ; HANDLE IF ME0 RES
F477	BB8001	4321	MOV BX,180H
F47A	B90307	4322	MOV CX,703H ; SET PARMS FOR HIGH RES
		4323	
		4324	;
		4325	;
F47D		4326	R5:
F47D	22EA	4327	AND CH,OL ; ADDRESS OF PEL WITHIN BYTE TO CH
		4328	
		4329	;
		4330	;
F47F	03EA	4331	SHR OX,CL ; SHIFT BY CORRECT AMOUNT
F481	03F2	4332	ADO SI,OX ; INCREMENT THE POINTER
F483	8AF7	4333	MOV DH,BH ; GET THE # OF BITS IN RESULT TO DH
		4334	
		4335	;
		4336	;
F485	2AC9	4337	SUB CL,CL ; ZERO INTO STORAGE LOCATION
F487		4338	R6:

LOC OBJ	LINE	SOURCE
F487 D0C8	4339	ROR AL,1 ; LEFT JUSTIFY THE VALUE
	4340	; IN AL (FOR WRITE)
F489 02C0	4341	ADD CL,CN ; ADD IN THE BIT OFFSET VALUE
F48B FECF	4342	OEC BH ; LOOP CONTROL
F48D 75F8	4343	JNZ R6 ; ON EXIT, CL HAS SHIFT COUNT
	4344	; TO RESTORE BITS
F48F 8AE3	4345	MOV AN,BL ; GET MASK TO AH
F491 02EC	4346	SHR AH,CL ; MOVE THE MASK TO CORRECT LOCATION
F493 5B	4347	POP BX ; RECOVER REG
F494 C3	4348	RET ; RETURN WITH EVERYTHING SET UP
	4349	R3 ENDP
	4350	-----
	4351	; SCROLL UP
	4352	; THIS ROUTINE SCROLLS UP THE INFORMATION ON THE CRT
	4353	; ENTRY
	4354	; CH,CL = UPPER LEFT CORNER OF REGION TO SCROLL
	4355	; DN,DL = LOWER RIGHT CORNER OF REGION TO SCROLL
	4356	; BOTH OF THE ABOVE ARE IN CHARACTER POSITIONS
	4357	; BH = FILL VALUE FOR BLANKED LINES
	4358	; AL = # LINES TO SCROLL (AL=0 MEANS BLANK THE ENTIRE
	4359	; FIELD)
	4360	; OS = DATA SEGMENT
	4361	; ES = REGEN SEGMENT
	4362	; EXIT
	4363	; NOTHING, THE SCREEN IS SCROLLED
	4364	-----
F495	4365	GRAPHICS_UP PROC NEAR
F495 8AD8	4366	MOV BL,AL ; SAVE LINE COUNT IN BL
F497 8BC1	4367	MOV AX,CX ; GET UPPER LEFT POSITION INTO AX REG
	4368	
	4369	;----- USE CHARACTER SUBROUTINE FOR POSITIONING
	4370	;----- ADDRESS RETURNED IS MULTIPLIED BY 2 FROM CORRECT VALUE
	4371	
F499 EB6902	4372	CALL GRAPH_POSN
F49C 8BF8	4373	MOV DI,AX ; SAVE RESULT AS DESTINATION ADDRESS
	4374	
	4375	;----- DETERMINE SIZE OF WINDOW
	4376	
F49E 2B01	4377	SUB CX,CX
F4A0 81C20101	4378	ADD CX,101H ; ADJUST VALUES
F4A4 D0E6	4379	SAL DH,1 ; MULTIPLY # ROWS BY 4
	4380	; SINCE 8 VERT DOTS/CHAR
F4A6 D0E6	4381	SAL DN,1 ; AND EVEN/ODD ROWS
	4382	
	4383	;----- DETERMINE CRT MODE
	4384	
F4A8 803E490006	4385	CMP CRT_MODE,6 ; TEST FOR MEDIUM RES
F4AD 7304	4386	JNC R7 ; FIND_SOURCE
	4387	
	4388	;----- MEDIUM RES UP
	4389	
F4AF D0E2	4390	SAL DL,1 ; # COLUMNS * 2, SINCE 2 BYTES/CHAR
F4B1 D1E7	4391	SAL DI,1 ; OFFSET #2 SINCE 2 BYTES/CHAR
	4392	
	4393	;----- DETERMINE THE SOURCE ADDRESS IN THE BUFFER
	4394	
F4B3	4395	R7: ; FIND_SOURCE
F4B3 06	4396	PUSH ES ; GET SEGMENTS BOTH POINTING TO REGEN
F4B4 1F	4397	POP DS
F4B5 2AED	4398	SUB CN,CN ; ZERO TO HIGH OF COUNT REG
F4B7 D0E3	4399	SAL BL,1 ; MULTIPLY NUMBER OF LINES BY 4
F4B9 D0E3	4400	SAL BL,1
F4BB 742D	4401	JZ R11 ; IF ZERO, THEN BLANK ENTIRE FIELD
F4BD 8AC3	4402	MOV AL,BL ; GET NUMBER OF LINES IN AL
F4BF B450	4403	MOV AN,80 ; 80 BYTES/ROW
F4C1 F6E4	4404	MUL AH ; DETERMINE OFFSET TO SOURCE
F4C3 8BF7	4405	MOV SI,DI ; SET UP SOURCE
F4C5 03F0	4406	ADD SI,AX ; ADD IN OFFSET TO IT
F4C7 8AE6	4407	MOV AN,0H ; NUMBER OF ROWS IN FIELD
F4C9 2AE3	4408	SUB AN,BL ; DETERMINE NUMBER TO MOVE
	4409	
	4410	;----- LOOP THROUGH, MOVING ONE ROW AT A TIME, BOTH EVEN AND ODD FIELDS
	4411	
F4CB	4412	R8: ; ROW_LOOP
F4CB E88000	4413	CALL R17 ; MOVE ONE ROW
F4CE 81EEB01F	4414	SUB SI,2000H-80 ; MOVE TO NEXT ROW
F4D2 81EFB01F	4415	SUB SI,2000H-80

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LOC OBJ          LINE  SOURCE
F406 FECC        4416          DEC  AH          ; NUMBER OF ROWS TO MOVE
F408 75F1        4417          JNZ  RB          ; CONTINUE TILL ALL MOVED
4418
4419          ;----- FILL IN THE VACATED LINE(S)
4420
F40A             4421      R9:          ; CLEAR_ENTRY
F40A 8AC7        4422          MOV  AL,BH          ; ATTRIBUTE TO FILL WITH
F40C             4423      R10:         ;
F40C E8800       4424          CALL  R18          ; CLEAR THAT ROW
F40F 81EFB01F    4425          SUB  DI,2000H-BD      ; POINT TO NEXT LINE
F4E3 FECB        4426          DEC  BL          ; NUMBER OF LINES TO FILL
F4E5 75F5        4427          JNZ  R1D          ; CLEAR_LOOP
F4E7 E90BFC      4428          JMP   VIDEO_RETURN      ; EVERYTHING DONE
F4EA             4429      R11:         ; BLANK_FIELD
F4EA 8ADE        4430          MOV  BL,DH          ; SET BLANK COUNT TO
4431          ; EVERYTHING IN FIELD
F4EC EBEC        4432          JMP   R9          ; CLEAR THE FIELD
4433      GRAPHICS_UP  ENDP
4434
4435      ;-----
4435      ; SCROLL DOWN
4436      ; THIS ROUTINE SCROLLS DOWN THE INFORMATION ON THE CRT
4437      ; ENTRY
4438      ; CH,CL = UPPER LEFT CORNER OF REGION TO SCROLL
4439      ; OH,OL = LOWER RIGHT CORNER OF REGION TO SCROLL
4440      ; BOTH OF THE ABOVE ARE IN CHARACTER POSITIONS
4441      ; BH = FILL VALUE FOR BLANKED LINES
4442      ; AL = # LINES TO SCROLL (AL=D MEANS BLANK THE ENTIRE
4443      ; FIELD)
4444      ; DS = DATA SEGMENT
4445      ; ES = REGEN SEGMENT
4446      ; EXIT
4447      ; NOTHING, THE SCREEN IS SCROLLED
4448
4449      ;-----
4449      GRAPHICS_DOWN PROC  NEAR
4450          STD          ; SET DIRECTION
4451          MOV  BL,AL    ; SAVE LINE COUNT IN BL
4452          MOV  AX,DX    ; GET LOWER RIGHT POSITION INTO AX REG
4453
4454      ;----- USE CHARACTER SUBROUTINE FOR POSITIONING
4455      ;----- ADDRESS RETURNED IS MULTIPLIED BY 2 FROM CORRECT VALUE
4456
F4F3 EB0F02      4457          CALL  GRAPH_POSN
F4F6 8BF8        4458          MOV  DI,AX          ; SAVE RESULT AS DESTINATION ADDRESS
4459
4460      ;----- DETERMINE SIZE OF WINDOW
4461
F4F8 2B01        4462          SUB  DX,CX
F4FA 81C20101    4463          ADD  DX,DI*H          ; ADJUST VALUES
F4FE 00E6        4464          SAL  DH,1          ; MULTIPLY # ROWS BY 4
4465          ; SINCE 8 VERT DOTS/CHAR
F500 D0E6        4466          SAL  DH,1          ; AND EVEN/ODD ROWS
4467
4468      ;----- DETERMINE CRT MODE
4469
F502 803E490006  4470          CMP  CRT_MODE,6      ; TEST FOR MEDIUM RES
F507 7305        4471          JNC  R12          ; FIND_SOURCE_DOWN
4472
4473      ;----- MEDIUM RES DOWN
4474
F509 D0E2        4475          SAL  DL,1          ; # COLUMNS * 2, SINCE
4476          ; 2 BYTES/CHAR (OFFSET OK)
F50B 01E7        4477          SAL  DI,1          ; OFFSET #2 SINCE 2 BYTES/CHAR
F500 47          4478          INC  DI          ; POINT TO LAST BYTE
4479
4480      ;----- DETERMINE THE SOURCE ADDRESS IN THE BUFFER
4481
F50E             4482      R12:          ; FIND_SOURCE_DOWN
F50E 06          4483          PUSH  ES          ; BOTH SEGMENTS TO REGEN
F50F 1F          4484          POP   DS
F510 2AE0        4485          SUB  CH,CH          ; ZERO TO HIGH OF COUNT REG
F512 81C7F000    4486          ADD  DI,24D         ; POINT TO LAST ROW OF PIXELS
F516 D0E3        4487          SAL  BL,1          ; MULTIPLY NUMBER OF LINES BY 4
F518 D0E3        4488          SAL  BL,1
F51A 742E        4489          JZ   R16          ; IF ZERO, THEN BLANK ENTIRE FIELD
F51C 8AC3        4490          MOV  AL,BL          ; SET NUMBER OF LINES IN AL
F51E B450        4491          MOV  AN,BD          ; 8D BYTES/ROW
F520 F6E4        4492          MUL  AH          ; DETERMINE OFFSET TO SOURCE

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LOC OBJ	LINE	SOURCE
F522 0DF7	4493	MOV SI,01 ; SET UP SOURCE
F524 2BF0	4494	SUB SI,AX ; SUBTRACT THE OFFSET
F526 8AE6	4495	MOV AH,DN ; NUMBER OF ROWS IN FIELD
F528 2AE3	4496	SUB AH,BL ; DETERMINE NUMBER TO MOVE
	4497	
	4498	;----- LOOP THROUGH, MOVING ONE ROW AT A TIME, BOTH EVEN AND ODD FIELDS
	4499	
F52A	4500	R13: ; ROW_LOOP_DOWN
F52A E82100	4501	CALL R17 ; MOVE ONE ROW
F52D 81EE5020	4502	SUB SI,2000H+80 ; MOVE TO NEXT ROW
F531 81EF5020	4503	SUB SI,2000H+80
F535 FECC	4504	DEC AH ; NUMBER OF ROWS TO MOVE
F537 75F1	4505	JNZ R13 ; CONTINUE TILL ALL MOVED
	4506	
	4507	;----- FILL IN THE VACATED LINE(S)
	4508	
F539	4509	R14: ; CLEAR_ENTRY_DOWN
F539 8AC7	4510	MOV AL,BH ; ATTRIBUTE TO FILL WITH
F53B	4511	R15: ; CLEAR_LOOP_DOWN
F53B E82900	4512	CALL R18 ; CLEAR A ROW
F53E 81EF5020	4513	SUB DI,2000H+80 ; POINT TO NEXT LINE
F542 FECB	4514	DEC BL ; NUMBER OF LINES TO FILL
F544 75F5	4515	JNZ R15 ; CLEAR_LOOP_DOWN
F546 FC	4516	CLD ; RESET THE DIRECTION FLAG
F547 E97BFC	4517	JMP VIDEO_RETURN ; EVERYTHING DONE
F54A	4518	R16: ; BLANK_FIELD_DOWN
F54A 8ADE	4519	MOV BL,DN ; SET BLANK COUNT TO
	4520	; EVERYTHING IN FIELD
F54C EBEB	4521	JMP R14 ; CLEAR THE FIELD
	4522	GRAPHICS_DOWN ENDP
	4523	
	4524	;----- ROUTINE TO MOVE ONE ROW OF INFORMATION
	4525	
F54E	4526	R17 PROC NEAR
F54E 8ACA	4527	MOV CL,0L ; NUMBER OF BYTES IN THE ROW
F550 56	4528	PUSH SI
F551 57	4529	PUSH DI ; SAVE POINTERS
F552 F3	4530	REP MOVSB ; MOVE THE EVEN FIELD
F553 A4		
F554 5F	4531	POP DI
F555 5E	4532	POP SI
F556 81C60020	4533	ADD SI,2000H
F55A 81C70020	4534	ADD DI,2000H ; POINT TO THE ODD FIELD
F55E 56	4535	PUSH SI
F55F 57	4536	PUSH DI ; SAVE THE POINTERS
F560 8ACA	4537	MOV CL,0L ; COUNT BACK
F562 F3	4538	REP MOVSB ; MOVE THE ODD FIELD
F563 A4		
F564 5F	4539	POP DI
F565 5E	4540	POP SI ; POINTERS BACK
F566 C3	4541	RET ; RETURN TO CALLER
	4542	R17 ENDP
	4543	
	4544	;----- CLEAR A SINGLE ROW
	4545	
F567	4546	R18 PROC NEAR
F567 BACA	4547	MOV CL,DL ; NUMBER OF BYTES IN FIELD
F569 57	4548	PUSH DI ; SAVE POINTER
F56A F3	4549	REP STOSB ; STORE THE NEW VALUE
F56B AA		
F56C 5F	4550	POP DI ; POINTER BACK
F56D 81C70020	4551	ADD DI,2000H ; POINT TO ODD FIELD
F571 57	4552	PUSH DI
F572 8ACA	4553	MOV CL,DL
F574 F3	4554	REP STOSB ; FILL THE ODD FIELD
F575 AA		
F576 5F	4555	POP DI
F577 C3	4556	RET ; RETURN TO CALLER
	4557	R18 ENDP
	4558	
	4559	;----- GRAPHICS WRITE
	4560	; THIS ROUTINE WRITES THE ASCII CHARACTER TO THE
	4561	; CURRENT POSITION ON THE SCREEN.
	4562	; ENTRY
	4563	; AL = CHARACTER TO WRITE
	4564	; BL = COLOR ATTRIBUTE TO BE USED FOR FOREGROUND COLOR
	4565	; IF BIT 7 IS SET, THE CHAR IS XOR'D INTO THE REGEN

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4566 ;      BUFFER (0 IS USED FOR THE BACKGROUND COLOR)      ;
4567 ;      CX = NUMBER OF CHARS TO WRITE                      ;
4568 ;      DS = DATA SEGMENT                                ;
4569 ;      ES = REGEN SEGMENT                                ;
4570 ;      EXIT                                                ;
4571 ;      NOTHING IS RETURNED                                ;
4572 ;                                                         ;
4573 ;      GRAPHICS READ                                        ;
4574 ;      THIS ROUTINE READS THE ASCII CHARACTER AT THE CURRENT ;
4575 ;      CURSOR POSITION ON THE SCREEN BY MATCHING THE DOTS ON ;
4576 ;      THE SCREEN TO THE CHARACTER GENERATOR CODE POINTS ;
4577 ;      ENTRY                                                ;
4578 ;      NONE ( 0 IS ASSUMED AS THE BACKGROUND COLOR        ;
4579 ;      EXIT                                                ;
4580 ;      AL = CHARACTER READ AT THAT POSITION (0 RETURNED IF ;
4581 ;      NONE FOUND)                                         ;
4582 ;                                                         ;
4583 ;      FOR BOTH ROUTINES, THE IMAGES USED TO FORM CHARS ARE ;
4584 ;      CONTAINED IN ROM FOR THE 1ST 128 CHARS.  TO ACCESS CHARS ;
4585 ;      IN THE SECOND HALF, THE USER MUST INITIALIZE THE VECTOR AT ;
4586 ;      INTERRUPT 1FH (LOCATION 0007CH) TO POINT TO THE USER ;
4587 ;      SUPPLIED TABLE OF GRAPHIC IMAGES (8X8 BOXES). ;
4588 ;      FAILURE TO DO SO WILL CAUSE IH STRANGE RESULTS      ;
4589 ;-----
4590      ASSUME  CS:CODE,DS:DATA,ES:DATA
F576      GRAPHICS_WRITE  PROC  NEAR
F578 8400      NOV  AH,0      ; ZERO TO HIGH OF CODE POINT
F57A 50      PUSH  AX      ; SAVE CODE POINT VALUE
4594
4595 ;----- DETERMINE POSITION IN REGEN BUFFER TO PUT CODE POINTS
4596
F57B E88401    CALL  S26      ; FIND LOCATION IN REGEN BUFFER
F57E 88F8      MOV  DI,AX      ; REGEN POINTER IN DI
4599
4600 ;----- DETERMINE REGION TO GET CODE POINTS FROM
4601
F580 58      POP  AX      ; RECOVER CODE POINT
F581 3C80      CNP  AL,80H      ; IS IT IN SECOND HALF
F583 7306      JAE  SI      ; YES
4605
4606 ;----- IMAGE IS IN FIRST HALF, CONTAINED IN ROM
4607
F585 8E6EFA    MOV  SI,0FA6EH      ; CRT_CHAR_GEN (OFFSET OF IMAGES)
F588 0E      PUSH  CS      ; SAVE SEGMENT ON STACK
F589 E80F      JHP  SHORT S2      ; DETERMINE_MODE
4611
4612 ;----- IMAGE IS IN SECOND HALF, IN USER RAM
4613
F58B      S1:
F58B 2C80      SUB  AL,80H      ; EXTEND_CHAR
F58D 1E      PUSH  DS      ; ZERO ORIGIN FOR SECOND HALF
F58E 2BF6      SUB  SI,SI      ; SAVE DATA POINTER
F590 8EDE      MOV  DS,SI      ; ESTABLISH VECTOR ADDRESSING
4618      ASSUME  DS:ABS0
4619
F592 C5367C00  LOS  SI,EXT_PTR      ; GET THE OFFSET OF THE TABLE
F596 8CDA      MOV  DX,DS      ; GET THE SEGMENT OF THE TABLE
4622      ASSUME  DS:DATA
4623
F598 1F      POP  DS      ; RECOVER DATA SEGMENT
F599 52      PUSH  DX      ; SAVE TABLE SEGMENT ON STACK
4625
4626 ;----- DETERMINE GRAPHICS MODE IN OPERATION
4627
F59A      S2:
4628
F59A 01E0      SAL  AX,1      ; DETERMINE_MODE
F59C 01E0      SAL  AX,1      ; MULTIPLY CODE POINT
F59E 01E0      SAL  AX,1      ; VALUE BY 8
4632      ADD  SI,AX      ; SI HAS OFFSET OF DESIRED CODES
F5A0 03F0      CNP  CRT_MODE,6
F5A2 803E490006  CNP  CRT_MODE,6
4634
F5A7 1F      POP  DS      ; RECOVER TABLE POINTER SEGMENT
F5A8 722C      JC  S7      ; TEST FOR MEDIUM RESOLUTION MODE
4636
4637 ;----- HIGH RESOLUTION MODE
4638
F5AA      S3:
4639
F5AA 57      PUSH  DI      ; HIGH_CHAR
F5AB 56      PUSH  SI      ; SAVE REGEN POINTER
F5AC B604      MOV  DH,4      ; SAVE CODE POINTER
                        ; NUMBER OF TIMES THROUGH LOOP

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LOC OBJ	LINE	SOURCE	
F5AE	4643	S4:	
F5AE AC	4644	LODSB	; GET BYTE FROM CODE POINTS
F5AF F6C300	4645	TEST BL,80H	; SHOULD WE USE THE FUNCTION
F5B2 7516	4646	JNZ S6	; TO PUT CNAR IN
F5B4 AA	4647	STOSB	; STORE IN REGEN BUFFER
F5B5 AC	4648	LODSB	
F5B6	4649	S5:	
F5B6 268885FF1F	4650	MOV ES:[OI+2000H-1],AL	; STORE IN SECOND HALF
F5B8 83C74F	4651	ADD OI,79	; MOVE TO NEXT ROW IN REGEN
F5BE FECE	4652	DEC DN	; DONE WITH LOOP
F5C0 75EC	4653	JNZ S4	
F5C2 5E	4654	POP SI	
F5C3 5F	4655	POP DI	; RECOVER REGEN POINTER
F5C4 47	4656	INC OI	; POINT TO NEXT CNAR POSITION
F5C5 E2E3	4657	LOOP S3	; MORE CHARS TO WRITE
F5C7 E9FBFB	4658	JMP VIDEO_RETURN	
F5CA	4659	S6:	
F5CA 263205	4660	XOR AL,ES:[OI]	; EXCLUSIVE OR WITH CURRENT
F5CD AA	4661	STOSB	; STORE THE CODE POINT
F5CE AC	4662	LODSB	; AGAIN FOR ODD FIELD
F5CF 263285FF1F	4663	XOR AL,ES:[OI+2000H-1]	
F5D4 EBEO	4664	JMP S5	; BACK TO MAINSTREAM
	4665		
	4666	;----- MEDIUM RESOLUTION WRITE	
	4667		
F5D6	4668	S7:	; MED_RES_WRITE
F5D6 BAD3	4669	MOV OL,BL	; SAVE HIGH COLOR BIT
F5D8 D1E7	4670	SAL OI,1	; OFFSET*2 SINCE 2 BYTES/CNAR
F5DA E8D100	4671	CALL S19	; EXPAND BL TO FULL WORD OF COLOR
F5DD	4672	S8:	; MED_CHAR
F5DD 57	4673	PUSH DI	; SAVE REGEN POINTER
F5DE 56	4674	PUSH SI	; SAVE THE CODE POINTER
F5DF B604	4675	MOV DH,4	; NUMBER OF LOOPS
F5E1	4676	S9:	
F5E1 AC	4677	LODSB	; GET CODE POINT
F5E2 E8DE00	4678	CALL S21	; DOUBLE UP ALL THE BITS
F5E5 23C3	4679	AND AX,8X	; CONVERT THEM TO FOREGROUND
	4680		; COLOR (0 BACK)
F5E7 F6C280	4681	TEST DL,80H	; IS THIS XOR FUNCTION
F5EA 7407	4682	JZ S10	; NO, STORE IT IN AS IT IS
F5EC 263225	4683	XOR AH,ES:[OI]	; DO FUNCTION WITH HALF
F5EF 26324501	4684	XOR AL,ES:[OI+1]	; AND WITH OTHER HALF
F5F3	4685	S10:	
F5F3 268825	4686	MOV ES:[OI],AH	; STORE FIRST BYTE
F5F6 26884501	4687	MOV ES:[OI+1],AL	; STORE SECOND BYTE
F5FA AC	4688	LODSB	; GET CODE POINT
F5FB EDC500	4689	CALL S21	
F5FE 23C3	4690	AND AX,BX	; CONVERT TO COLOR
F600 F6C2B0	4691	TEST OL,80H	; AGAIN, IS THIS XOR FUNCTION
F603 740A	4692	JZ S11	; NO, JUST STORE THE VALUES
F605 2632A50020	4693	XOR AH,ES:[OI+2000H]	; FUNCTION WITH FIRST HALF
F60A 2632B50120	4694	XOR AL,ES:[OI+2001H]	; AND WITH SECOND HALF
F60F	4695	S11:	
F60F 2688A50020	4696	MOV ES:[OI+2000H],AH	
F614 2688850120	4697	MOV ES:[OI+2000H+1],AL	; STORE IN SECOND PORTION OF BUFFER
F619 83C750	4698	ADD OI,80	; POINT TO NEXT LOCATION
F61C FECE	4699	DEC DN	
F61E 75C1	4700	JNZ S9	; KEEP GOING
F620 5E	4701	POP SI	; RECOVER CODE POINTER
F621 5F	4702	POP DI	; RECOVER REGEN POINTER
F622 47	4703	INC OI	; POINT TO NEXT CNAR POSITION
F623 47	4704	INC DI	
F624 E2B7	4705	LOOP S8	; MORE TO WRITE
F626 E99CFB	4706	JMP VIDEO_RETURN	
	4707	GRAPHICS_WRITE ENDP	
	4708	;-----	
	4709	; GRAPHICS_READ :	
	4710	;-----	
F629	4711	GRAPHICS_READ PROC NEAR	
F629 E8D600	4712	CALL S26	; CONVERTED TO OFFSET IN REGEN
F62C 8BF0	4713	MOV SI,AX	; SAVE IN SI
F62E 83EC08	4714	SUB SP,8	; ALLOCATE SPACE TO SAVE THE
	4715		; READ CODE POINT
F631 8BEC	4716	MOV BP,SP	; POINTER TO SAVE AREA
	4717		
	4718	;----- DETERMINE GRAPHICS MODES	
	4719		

LOC OBJ	LINE	SOURCE	
F633 803E490006	4720	CMF CRT_MODE,6	
F638 06	4721	PUSH ES	
F639 1F	4722	POP DS	; POINT TO REGEN SEGMENT
F63A 721A	4723	JC S13	; MEDIUM RESOLUTION
	4724		
	4725	;----- HIGH RESOLUTION READ	
	4726		
	4727	;----- GET VALUES FROM REGEN BUFFER AND CONVERT TO CODE POINT	
	4728		
F63C B604	4729	MOV DH,4	; NUMBER OF PASSES
F63E	4730	S12:	
F63E 8A04	4731	MOV AL,[SI]	; GET FIRST BYTE
F640 B84600	4732	MOV [BP],AL	; SAVE IN STORAGE AREA
F643 45	4733	INC BP	; NEXT LOCATION
F644 8A840020	4734	MOV AL,[SI+2000H]	; GET LOWER REGION BYTE
F648 B84600	4735	MOV [BP],AL	; ADJUST AND STORE
F64B 45	4736	INC BP	
F64C B3C650	4737	ADD SI,B0	; POINTER INTO REGEN
F64F FECE	4738	DEC DH	; LOOP CONTROL
F651 75EB	4739	JNZ S12	; DO IT SOME MORE
F653 EB1790	4740	JMP S15	; GO MATCH THE SAVED CODE POINTS
	4741		
	4742	;----- MEDIUM RESOLUTION READ	
	4743		
F656	4744	S13:	; MED_RES_READ
F656 01E6	4745	SAL SI,1	; OFFSET*2 SINCE 2 BYTES/CHAR
F658 B604	4746	MOV DH,4	; NUMBER OF PASSES
F65A	4747	S14:	
F65A E88800	4748	CALL S23	; GET PAIR BYTES FROM REGEN
	4749		; INTO SINGLE SAVE
F65D 81C60020	4750	ADD SI,2000H	; GO TO LOWER REGION
F661 E88100	4751	CALL S23	; GET THIS PAIR INTO SAVE
F664 81EEB01F	4752	SUB SI,2000H-B0	; ADJUST POINTER BACK INTO UPPER
F668 FECE	4753	DEC DH	
F66A 75EE	4754	JNZ S14	; KEEP GOING UNTIL ALL B DONE
	4755		
	4756	;----- SAVE AREA HAS CHARACTER IN IT, MATCH IT	
	4757		
F66C	4758	S15:	; FIND_CHAR
F66C B6EFA90	4759	MOV DI,OFFSET CRT_CHAR_GEN	; ESTABLISH ADDRESSING
F670 0E	4760	PUSH CS	
F671 07	4761	POP ES	; CODE POINTS IN CS
F672 B3E008	4762	SUB BP,8	; ADJUST POINTER TO BEGINNING
	4763		; OF SAVE AREA
F675 8BFS	4764	MOV SI,BP	
F677 FC	4765	CLO	; ENSURE DIRECTION
F678 B000	4766	MOV AL,0	; CURRENT CODE POINT BEING MATCHED
F67A	4767	S16:	
F67A 16	4768	PUSH SS	; ESTABLISH ADDRESSING TO STACK
F67B 1F	4769	POP OS	; FOR THE STRING COMPARE
F67C BA8000	4770	MOV CX,128	; NUMBER TO TEST AGAINST
F67F	4771	S17:	
F67F 56	4772	PUSH SI	; SAVE SAVE AREA POINTER
F680 57	4773	PUSH DI	; SAVE CODE POINTER
F681 B90800	4774	MOV CX,8	; NUMBER OF BYTES TO MATCH
F684 F3	4775	REPE CMPSB	; COMPARE THE 8 BYTES
F685 A6			
F686 5F	4776	POP DI	; RECOVER THE POINTERS
F687 5E	4777	POP SI	
F688 741E	4778	JZ S18	; IF ZERO FLAG SET, THEN MATCH OCCURRED
F68A FECD	4779	INC AL	; NO MATCH, MOVE ON TO NEXT
F68C B3C708	4780	ADD DI,B	; NEXT CODE POINT
F68F 4A	4781	DEC DX	; LOOP CONTROL
F690 75ED	4782	JNZ S17	; DO ALL OF THEM
	4783		
	4784	;----- CHAR NOT MATCHED, MIGHT BE IN USER SUPPLIED SECOND HALF	
	4785		
F692 3C00	4786	CMF AL,0	; AL <> 0 IF ONLY 1ST HALF SCANNED
F694 7412	4787	JE S18	; IF = 0, THEN ALL HAS BEEN SCANNED
F696 2BC0	4788	SUB AX,AX	
F698 8ED8	4789	MOV DS,AX	; ESTABLISH ADDRESSING TO VECTOR
	4790	ASSUME DS:ABS0	
F69A C43E7C00	4791	LES DI,EXT_PTR	; GET POINTER
F69E 8CC0	4792	MOV AX,ES	; SEE IF THE POINTER REALLY EXISTS
F6A0 0BC7	4793	OR AX,DI	; IF ALL 0, THEN DOESN'T EXIST
F6A2 7404	4794	JZ S18	; NO SENSE LOOKING
F6A4 B080	4795	MOV AL,128	; ORIGIN FOR SECOND HALF

LOC OBJ	LINE	SOURCE
F6A6 E8D2	4796	JMP S16 ; GO BACK AND TRY FOR IT
	4797	ASSUME DS:DATA
	4798	
	4799	;----- CHARACTER IS FOUND (AL=0 IF NOT FOUND)
	4800	
F6A8	4801	S18:
F6A8 83C408	4802	ADD SP,8 ; READJUST THE STACK, THROW AWAY SAVE
F6AB E917FB	4803	JMP VIDEO_RETURN ; ALL DONE
	4804	GRAPHICS_READ ENDP
	4805	;-----
	4806	; EXPAND_MED_COLOR :
	4807	; THIS ROUTINE EXPANDS THE LOW 2 BITS IN BL TO :
	4808	; FILL THE ENTIRE BX REGISTER :
	4809	; ENTRY :
	4810	; BL = COLOR TO BE USED (LOW 2 BITS) :
	4811	; EXIT :
	4812	; BX = COLOR TO BE USED (8 REPLICATIONS OF THE :
	4813	; 2 COLOR BITS) :
	4814	;-----
F6AE	4815	S19: PROC NEAR
F6AE 80E303	4816	AND BL,3 ; ISOLATE THE COLOR BITS
F6B1 8AC3	4817	MOV AL,BL ; COPY TO AL
F6B3 51	4818	PUSH CX ; SAVE REGISTER
F6B4 890300	4819	MOV CX,3 ; NUMBER OF TIMES TO DO THIS
F6B7	4820	S20:
F6B7 D0E0	4821	SAL AL,1
F6B9 00E0	4822	SAL AL,1 ; LEFT SHIFT BY 2
F6BB 0A08	4823	OR BL,AL ; ANOTHER COLOR VERSION INTO BL
F6BD E2F8	4824	LOOP S20 ; FILL ALL OF BL
F6BF 8AFB	4825	MOV BH,BL ; FILL UPPER PORTION
F6C1 59	4826	POP CX ; REGISTER BACK
F6C2 C3	4827	RET ; ALL DONE
	4828	S19 ENDP
	4829	;-----
	4830	; EXPAND_BYTE :
	4831	; THIS ROUTINE TAKES THE BYTE IN AL AND DOUBLES :
	4832	; ALL OF THE BITS, TURNING THE 8 BITS INTO :
	4833	; 16 BITS. THE RESULT IS LEFT IN AX :
	4834	;-----
F6C3	4835	S21: PROC NEAR
F6C3 52	4836	PUSH OX ; SAVE REGISTERS
F6C4 51	4837	PUSH CX
F6C5 53	4838	PUSH BX
F6C6 2B02	4839	SUB DX,DX ; RESULT REGISTER
F6C8 890100	4840	MOV CX,1 ; MASK REGISTER
F6C8	4841	S22:
F6C8 6B06	4842	MOV BX,AX ; BASE INTO TEMP
F6C0 23D9	4843	AND SX,CX ; USE MASK TO EXTRACT A BIT
F6CF 0B03	4844	OR OX,BX ; PUT INTO RESULT REGISTER
F6D1 01E0	4845	SHL AX,1
F6D3 01E1	4846	SHL CX,1 ; SHIFT BASE AND MASK BY 1
F6D5 8B08	4847	MOV BX,AX ; BASE TO TEMP
F6D7 23D9	4848	AND SX,CX ; EXTRACT THE SAME BIT
F6D9 0B03	4849	OR OX,BX ; PUT INTO RESULT
F6DB 01E1	4850	SHL CX,1 ; SHIFT ONLY MASK NOW,
	4851	; MOVING TO NEXT BASE
F6DD 73EC	4852	JNC S22 ; USE MASK BIT COMING OUT TO TERMINATE
F6DF 8BC2	4853	MOV AX,DX ; RESULT TO PARAM REGISTER
F6E1 5B	4854	POP BX
F6E2 59	4855	POP CX ; RECOVER REGISTERS
F6E3 5A	4856	POP OX
F6E4 C3	4857	RET ; ALL DONE
	4858	S21 ENDP
	4859	;-----
	4860	; MED_READ_BYTE :
	4861	; THIS ROUTINE WILL TAKE 2 BYTES FROM THE REGEN :
	4862	; BUFFER, COMPARE AGAINST THE CURRENT FOREGROUND :
	4863	; COLOR, AND PLACE THE CORRESPONDING ON/OFF BIT :
	4864	; PATTERN INTO THE CURRENT POSITION IN THE SAVE :
	4865	; AREA :
	4866	; ENTRY :
	4867	; SI,DS = POINTER TO REGEN AREA OF INTEREST :
	4868	; BX = EXPANDED FOREGROUND COLOR :
	4869	; BP = POINTER TO SAVE AREA :
	4870	; EXIT :
	4871	; BP IS INCREMENT AFTER SAVE :
	4872	;-----

LOC	OBJ	LINE	SOURCE
F6E5		4873	S23 PROC NEAR
F6E5 8A24		4874	MOV AH,[SI]
F6E7 8A4401		4875	MOV AL,[SI+1]
F6EA B900C0		4876	MOV CX,DC00H
F6ED B200		4877	MOV DL,0
F6EF		4878	S24:
F6EF 85C1		4879	TEST AX,CX
F6F1 F8		4880	CUC
F6F2 7401		4881	JZ S25
F6F4 F9		4882	STC
F6F5 0002		4883	S25: RCL DL,1
F6F7 D1E9		4884	SHR CX,1
F6F9 D1E9		4885	SHR CX,1
F6FB 73F2		4886	JNC S24
F6FD 8B5600		4887	MOV [BP],DL
F700 45		4888	INC BP
F701 C3		4889	RET
		4890	S23 ENDP
		4891	;
		4892	; V4_POSITION :
		4893	; THIS ROUTINE TAKES THE CURSOR POSITION :
		4894	; CONTAINED IN THE MEMORY LOCATION, AND :
		4895	; CONVERTS IT INTO AN OFFSET INTO THE :
		4896	; REGEN BUFFER, ASSUMING ONE BYTE/CHAR. :
		4897	; FOR MEDIUM RESOLUTION GRAPHICS, :
		4898	; THE NUMBER MUST BE DOUBLED. :
		4899	; ENTRT :
		4900	; NO REGISTERS, MEMORY LOCATION :
		4901	; CURSOR_POSN IS USED :
		4902	; EXIT :
		4903	; AX CONTAINS OFFSET INTO REGEN BUFFER :
		4904	;
F702		4905	S26 PROC NEAR
F702 A15000		4906	MOV AX,CURSOR_POSN
F705		4907	GRAPH_POSN LABEL NEAR
F705 53		4908	PUSH BX
F706 8BD8		4909	MOV BX,AX
F708 8AC4		4910	MOV AL,AH
F70A F6264A00		4911	MUL BYTE PTR CRT_COLS
F70E 01E0		4912	SHL AX,1
F710 D1E0		4913	SHL AX,1
F712 2AFF		4914	SUB BH,BH
F714 03C3		4915	ADD AX,BX
F716 5B		4916	POP BX
F717 C3		4917	RET
		4918	S26 ENDP
		4919	;
		4920	; WRITE_TTY :
		4921	; THIS INTERFACE PROVIDES A TELETYPE LIKE INTERFACE TO THE VIDEO :
		4922	; CARO. THE INPUT CHARACTER IS WRITTEN TO THE CURRENT CURSOR :
		4923	; POSITION, AND THE CURSOR IS MOVED TO THE NEXT POSITION. IF THE :
		4924	; CURSOR LEAVES THE LAST COLUMN OF THE FIELD, THE COLUMN IS SET :
		4925	; TO ZERO, AND THE ROW VALUE IS INCREMENTED. IF THE ROW VALUE :
		4926	; LEAVES THE FIELD, THE CURSOR IS PLACED ON THE LAST ROW, FIRST :
		4927	; COLUMN, AND THE ENTIRE SCREEN IS SCROLLED UP ONE LINE. WHEN :
		4928	; THE SCREEN IS SCROLLED UP, THE ATTRIBUTE FOR FILLING THE NEWLY :
		4929	; BLANKED LINE IS READ FROM THE CURSOR POSITION ON THE PREVIOUS :
		4930	; LINE BEFORE THE SCROLL, IN CHARACTER MODE. IN GRAPHICS MODE, :
		4931	; THE 0 COLOR IS USED. :
		4932	; ENTRT :
		4933	; (AH) = CURRENT CRT MODE :
		4934	; (AL) = CHARACTER TO BE WRITTEN :
		4935	; NOTE THAT BACK SPACE, CAR RET, BELL AND LINE FEED ARE HANDLED :
		4936	; AS COMMANDS RATHER THAN AS DISPLAYABLE GRAPHICS :
		4937	; (BL) = FOREGROUND COLOR FOR CHAR WRITE IF CURRENTLY IN A :
		4938	; GRAPHICS MODE :
		4939	; EXIT :
		4940	; ALL REGISTERS SAVED :
		4941	;
		4942	ASSUME CS:CODE,DS:DATA
F718		4943	WRITE_TTY PROC NEAR
F718 50		4944	PUSH AX
F719 50		4945	PUSH AX
F71A B403		4946	MOV AH,3
F71C 8A3E6200		4947	MOV BH,ACTIVE_PAGE
F720 C010		4948	INT 10H
F722 5B		4949	POP AX

LOC OBJ	LINE	SOURCE
	4950	
	4951	;----- OX NOW HAS THE CURRENT CURSOR POSITION
	4952	
F723 3C08	4953	CHP AL,8 ; IS IT A BACKSPACE
F725 7452	4954	JE U8 ; BACK_SPACE
F727 3C00	4955	CHP AL,0DH ; IS IT CARRIAGE RETURN
F729 7457	4956	JE U9 ; CAR_RET
F72B 3C0A	4957	CHP AL,0AH ; IS IT A LINE FEED
F72D 7457	4958	JE U10 ; LINE_FEED
F72F 3C07	4959	CHP AL,07H ; IS IT A BELL
F731 745A	4960	JE U11 ; BELL
	4961	
	4962	;----- WRITE THE CHAR TO THE SCREEN
	4963	
	4964	
F733 B40A	4965	MOV AH,10 ; WRITE CHAR ONLY
F735 B90100	4966	MOV CX,1 ; ONLY ONE CHAR
F738 C010	4967	INT 10H ; WRITE THE CHAR
	4968	
	4969	;----- POSITION THE CURSOR FOR NEXT CHAR
	4970	
F73A FEC2	4971	INC DL
F73C 3A164A00	4972	CHP DL,BYTE PTR CRT_COLS ; TEST FOR COLUMN OVERFLOW
F740 7533	4973	JNZ U7 ; SET_CURSOR
F742 8200	4974	MOV DL,0 ; COLUMN FOR CURSOR
F744 80FE18	4975	CHP DH,24
F747 752A	4976	JNZ U6 ; SET_CURSOR_INC
	4977	
	4978	;----- SCROLL REQUIRED
	4979	
F749	4980	U1:
F749 8402	4981	MOV AH,2
F748 C010	4982	INT 10H ; SET THE CURSOR
	4983	
	4984	;----- DETERMINE VALUE TO FILL WITH DURING SCROLL
	4985	
F74D A04900	4986	MOV AL,CRT_MODE ; GET THE CURRENT MODE
F750 3C04	4987	CHP AL,4
F752 7206	4988	JC U2 ; READ-CURSOR
F754 3C07	4989	CHP AL,7
F756 8700	4990	MOV BH,0 ; FILL WITH BACKGROUND
F758 7506	4991	JNE U3 ; SCROLL-UP
F75A	4992	U2:
F75A 8408	4993	MOV AH,8 ; READ-CURSOR
F75C C010	4994	INT 10H ; READ CHAR/ATTR AT CURRENT CURSOR
F75E 8AFC	4995	MOV BH,AH ; STORE IN BH
F760	4996	U3:
F760 880106	4997	MOV AX,601H ; SCROLL-UP
F763 28C9	4998	SUB CX,CX ; SCROLL ONE LINE
F765 8618	4999	MOV DH,24 ; UPPER LEFT CORNER
F767 8A164A00	5000	MOV DL,BYTE PTR CRT_COLS ; LOWER RIGHT ROW
F768 FECA	5001	DEC DL ; LOWER RIGHT COLUMN
F76D	5002	U4:
F76D C010	5003	INT 10H ; VIDEO-CALL-RETURN
F76F	5004	U5:
F76F 58	5005	POP AX ; SCROLL UP THE SCREEN
F770 E952FA	5006	JMP VIDEO_RETURN ; TTY-RETURN
F773	5007	U6:
F773 FEC6	5008	INC DH ; RESTORE THE CHARACTER
F775	5009	U7:
F775 B402	5010	MOV AH,2 ; RETURN TO CALLER
F777 EBF4	5011	JMP U4 ; SET-CURSOR-INC
	5012	U7:
	5013	;----- BACK SPACE FOUND
	5014	
F779	5015	U8:
F779 80FA00	5016	CHP DL,0 ; ALREADY AT END OF LINE
F77C 74F7	5017	JE U7 ; SET_CURSOR
F77E FECA	5018	DEC DL ; NO -- JUST MOVE IT BACK
F780 EBF3	5019	JMP U7 ; SET_CURSOR
	5020	
	5021	;----- CARRIAGE RETURN FOUND
	5022	
F782	5023	U9:
F782 B200	5024	MOV DL,0 ; MOVE TO FIRST COLUMN
F784 EBEF	5025	JMP U7 ; SET_CURSOR
	5026	

LOC OBJ

LINE SOURCE

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5027 ;----- LINE FEED FOUND
5028
F786 5029 U10:
F786 80FE18 5030 CMP ON,24 ; BOTTOM OF SCREEN
F789 75E8 5031 JNE U6 ; YES, SCROLL THE SCREEN
F78B EBBC 5032 JMP U1 ; NO, JUST SET THE CURSOR
5033
5034 ;----- BELL FOUND
5035
F78D 5036 U11:
F78D 0302 5037 MOV BL,2 ; SET UP COUNT FOR BEEP
F78F E871EE 5038 CALL BEEP ; SOUND THE POD BELL
F792 E808 5039 JMP U5 ; TTY_RETURN
5040 WRITE_TTY ENDP
5041 ;-----
5042 ; LIGHT PEN :
5043 ; THIS ROUTINE TESTS THE LIGHT PEN SWITCH AND THE LIGHT :
5044 ; PEN TRIGGER. IF BOTH ARE SET, THE LOCATION OF THE LIGHT :
5045 ; PEN IS DETERMINED. OTHERWISE, A RETURN WITH NO :
5046 ; INFORMATION IS MADE. :
5047 ; ON EXIT :
5048 ; (AH) = 0 IF NO LIGHT PEN INFORMATION IS AVAILABLE :
5049 ; BX,CX,DX ARE DESTROYED :
5050 ; (AH) = 1 IF LIGHT PEN IS AVAILABLE :
5051 ; (DN,DL) = ROW,COLUMN OF CURRENT LIGHT PEN :
5052 ; POSITION :
5053 ; (CH) = RASTER POSITION :
5054 ; (BX) = BEST GUESS AT PIXEL HORIZONTAL POSITION :
5055 ;-----
5056 ASSUME CS:CODE,DS:DATA
5057 ;----- SUBTRACT_TABLE
F794 5058 V1 LABEL BYTE
F794 03 5059 DB 3,3,5,5,3,3,3,4 ;
F795 03
F796 05
F797 05
F798 03
F799 03
F79A 03
F79B 04
F79C

5060 READ_LPEN PROC NEAR
5061
5062 ;----- WAIT FOR LIGHT PEN TO BE DEPRESSED
5063
F79C B400 5064 MOV AH,0 ; SET NO LIGHT PEN RETURN CODE
F79E 0B166300 5065 MOV DX,ADDR_6845 ; GET BASE ADDRESS OF 6845
F7A2 03C206 5066 ADD DX,6 ; POINT TO STATUS REGISTER
F7A5 EC 5067 IN AL,DX ; GET STATUS REGISTER
F7A6 A804 5068 TEST AL,4 ; TEST LIGHT PEN SWITCH
F7A8 757E 5069 JNZ V6 ; NOT SET, RETURN
5070
5071 ;----- NOW TEST FOR LIGHT PEN TRIGGER
5072
F7AA A802 5073 TEST AL,2 ; TEST LIGHT PEN TRIGGER
F7AC 7503 5074 JNZ V7A ; RETURN WITHOUT RESETTING TRIGGER
F7AE E98100 5075 JMP V7
5076
5077 ;----- TRIGGER HAS BEEN SET, READ THE VALUE IN
5078
F7B1 5079 V7A:
F7B1 0410 5080 MOV AH,16 ; LIGHT PEN REGISTERS ON 6845
5081
5082 ;----- INPUT REGS POINTED TO BY AH, AND CONVERT TO ROW COLUMN IN DX
5083
F7B3 8B166300 5084 MOV DX,ADDR_6845 ; ADDRESS REGISTER FOR 6845
F7B7 8AC4 5085 MOV AL,AH ; REGISTER TO READ
F7B9 EE 5086 OUT DX,AL ; SET IT UP
F7BA 42 5087 INC DX ; DATA REGISTER
F7BB EC 5088 IN AL,DX ; GET THE VALUE
F7BC 8AE8 5089 MOV CH,AL ; SAVE IN CX
F7BE 4A 5090 DEC DX ; ADDRESS REGISTER
F7BF FEC4 5091 INC AH
F7C1 8AC4 5092 MOV AL,AH ; SECOND DATA REGISTER
F7C3 EE 5093 OUT DX,AL
F7C4 42 5094 INC DX ; POINT TO DATA REGISTER
F7C5 EC 5095 IN AL,DX ; GET SECOND DATA VALUE
F7C6 8AE5 5096 MOV AH,CH ; AX HAS INPUT VALUE

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LOC OBJ	LINE	SOURCE
	5097	
	5098	I----- AX HAS THE VALUE READ IN FROM THE 6845
	5099	
F7C8 8A1E4900	5100	MOV BL,CRT_MODE
F7CC 2AFF	5101	SUB BH,BH ; MODE VALUE TO BX
F7CE 2E8A9F94F7	5102	MOV BL,CS-VIIBX1 ; DETERMINE AMOUNT TO SUBTRACT
F7D3 2BC3	5103	SUB AX,BX ; TAKE IT AWAY
F7D5 8B1E4E00	5104	MOV BX,CRT_START
F7D9 01EB	5105	SHR BX,1
F7DB 28C3	5106	SUB AX,BX
F7DD 7902	5107	JNS V2 ; IF POSITIVE, DETERMINE MODE
F7DF 2BC0	5108	SUB AX,AX ; <0 PLAYS AS 0
	5109	
	5110	I----- DETERMINE MODE OF OPERATION
	5111	
F7E1	5112	V2: ; DETERMINE_MODE
F7E1 8103	5113	MOV CL,3 ; SET *8 SHIFT COUNT
F7E3 803E490004	5114	CMP CRT_MODE,4 ; DETERMINE IF GRAPHICS OR ALPHA
F7E8 722A	5115	JB V4 ; ALPHA_PEN
F7EA 803E490007	5116	CMP CRT_MODE,7
F7EF 7423	5117	JE V4 ; ALPHA_PEN
	5118	
	5119	I----- GRAPHICS MODE
	5120	
F7F1 8228	5121	MOV OL,40 ; DIVISOR FOR GRAPHICS
F7F3 F6F2	5122	DIV DL ; DETERMINE ROW(AL) AND COLUMN(AH)
	5123	; AL RANGE 0-99, AH RANGE 0-39
	5124	
	5125	I----- DETERMINE GRAPHIC ROW POSITION
	5126	
F7F5 8AE8	5127	MOV CH,AL ; SAVE ROW VALUE IN CH
F7F7 02ED	5128	ADD CH,CH ; *2 FOR EVEN/ODD FIELD
F7F9 8A0C	5129	MOV BL,AH ; COLUMN VALUE TO BX
F7FB 2AFF	5130	SUB BH,BH ; MULTIPLY BY 8 FOR MEDIUM RES
F7FD 803E490006	5131	CMP CRT_MODE,6 ; DETERMINE MEDIUM OR HIGH RES
F802 7504	5132	JNE V3 ; NOT_HIGH_RES
F804 B104	5133	MOV CL,4 ; SHIFT VALUE FOR HIGH RES
F806 00E4	5134	SAL AH,1 ; COLUMN VALUE TIMES 2 FOR HIGH RES
F808	5135	V3: ; NOT_HIGH_RES
F808 D3E3	5136	SHL BX,CL ; MULTIPLY *16 FOR HIGH RES
	5137	
	5138	I----- DETERMINE ALPHA CHAR POSITION
	5139	
F80A 8A04	5140	MOV OL,AH ; COLUMN VALUE FOR RETURN
F80C 8AF0	5141	MOV DH,AL ; ROW VALUE
F80E D0EE	5142	SHR DH,1 ; DIVIDE BY 4
F810 D0EE	5143	SHR DH,1 ; FOR VALUE IN 0-24 RANGE
F812 EB12	5144	JMP SHORT V5 ; LIGHT_PEN_RETURN_SET
	5145	
	5146	I----- ALPHA MODE ON LIGHT PEN
	5147	
FB14	5148	V4: ; ALPHA_PEN
FB14 F6364A00	5149	OIV BYTE PTR CRT_COLS ; DETERMINE ROW,COLUMN VALUE
FB18 8AF0	5150	MOV DH,AL ; ROWS TO DH
FB1A 8AD4	5151	MOV DL,AH ; COLS TO DL
FB1C 02E0	5152	SAL AL,CL ; MULTIPLY ROWS * 8
FB1E 8AE8	5153	MOV CH,AL ; GET RASTER VALUE TO RETURN REG
FB20 8A0C	5154	MOV BL,AH ; COLUMN VALUE
FB22 32FF	5155	XOR BH,BH ; TO BX
FB24 D3E3	5156	SAL BX,CL
FB26	5157	V5: ; LIGHT_PEN_RETURN_SET
FB26 B401	5158	MOV AH,1 ; INDICATE EVERYTHING SET
FB28	5159	V6: ; LIGHT_PEN_RETURN
FB28 52	5160	PUSH DX ; SAVE RETURN VALUE (IN CASE)
FB29 8B166300	5161	MOV OX,ADDR_6845 ; GET BASE ADDRESS
FB2D 83C207	5162	ADD OX,7 ; POINT TO RESET PARAM
FB30 EE	5163	OUT OX,AL ; ADDRESS, NOT DATA, IS IMPORTANT
FB31 5A	5164	POP OX ; RECOVER VALUE
FB32	5165	V7: ; RETURN_NO_RESET
FB32 5F	5166	POP OI
FB33 5E	5167	POP SI
FB34 1F	5168	POP OS ; DISCARD SAVED BX,CX,DX
FB35 1F	5169	POP OS
FB36 1F	5170	POP OS
	5171	
FB37 1F	5172	POP DS
FB38 07	5173	POP ES

F839 CF

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5174             IRET
5175 READ_LPEN      ENDP
5176
5177 ;--- INT 12 ---
5178 ; MEMORY_SIZE_DET
5179 ; THIS ROUTINE DETERMINES THE AMOUNT OF MEMORY IN THE SYSTEM
5180 ; AS REPRESENTED BY THE SWITCHES ON THE PLANAR. NOTE THAT THE
5181 ; SYSTEM MAY NOT BE ABLE TO USE I/O MEMORY UNLESS THERE IS A FULL
5182 ; COMPLEMENT OF 64K BYTES ON THE PLANAR.
5183 ; INPUT
5184 ; NO REGISTERS
5185 ; THE MEMORY_SIZE VARIABLE IS SET DURING POWER ON DIAGNOSTICS
5186 ; ACCORDING TO THE FOLLOWING HARDWARE ASSUMPTIONS:
5187 ; PORT 60 BITS 3,2 = 00 = 16K BASE RAM
5188 ;                   01 = 32K BASE RAM
5189 ;                   10 = 48K BASE RAM
5190 ;                   11 = 64K BASE RAM
5191 ; PORT 62 BITS 3-0 INDICATE AMOUNT OF I/O RAM IN 32K INCREMENTS
5192 ; E.G., 0000 = NO RAM IN I/O CHANNEL
5193 ;           0010 = 64K RAM IN I/O CHANNEL, ETC.
5194 ; OUTPUT
5195 ; (AX) = NUMBER OF CONTIGUOUS 1K BLOCKS OF MEMORY
5196 ;-----
5197 ASSUME CS:CODE,DS:DATA
5198 ORG 0F841H
5199 MEMORY_SIZE_DET PROC FAR
5200     STI                     ; INTERRUPTS BACK ON
5201     PUSH OS                 ; SAVE SEGMENT
5202     CALL ODS
5203     MOV AX,MEMORY_SIZE      ; GET VALUE
5204     POP DS                  ; RECOVER SEGMENT
5205     IRET                    ; RETURN TO CALLER
5206 MEMORY_SIZE_DET ENDP
5207

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F841

F841

F841 FB

F842 1E

F843 E8F806

F846 A11300

F849 1F

F84A CF

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5208 ;--- INT 11 ---
5209 ; EQUIPMENT DETERMINATION
5210 ; THIS ROUTINE ATTEMPTS TO DETERMINE WHAT OPTIONAL
5211 ; DEVICES ARE ATTACHED TO THE SYSTEM.
5212 ; INPUT
5213 ; NO REGISTERS
5214 ; THE EQUIP_FLAG VARIABLE IS SET DURING THE POWER ON
5215 ; DIAGNOSTICS USING THE FOLLOWING HARDWARE ASSUMPTIONS:
5216 ; PORT 60 = LOW ORDER BYTE OF EQUIPMENT
5217 ; PORT 3FA = INTERRUPT ID REGISTER OF 8250
5218 ; BITS 7-3 ARE ALWAYS 0
5219 ; PORT 378 = OUTPUT PORT OF PRINTER -- B255 PORT THAT
5220 ; CAN BE READ AS WELL AS WRITTEN
5221 ; OUTPUT
5222 ; (AX) IS SET, BIT SIGNIFICANT, TO INDICATE ATTACHED I/O
5223 ; BIT 15,14 = NUMBER OF PRINTERS ATTACHED
5224 ; BIT 13 NOT USED
5225 ; BIT 12 = GAME I/O ATTACHED
5226 ; BIT 11,10,9 = NUMBER OF RS232 CARDS ATTACHED
5227 ; BIT 8 UNUSED
5228 ; BIT 7,6 = NUMBER OF DISKETTE DRIVES
5229 ;           00=1, 01=2, 10=3, 11=4 ONLY IF BIT 0 = 1
5230 ; BIT 5,4 = INITIAL VIDEO MODE
5231 ;           00 = UNUSED
5232 ;           01 = 40X25 BH USING COLOR CARD
5233 ;           10 = 80X25 BH USING COLOR CARD
5234 ;           11 = 80X25 BH USING BH CARD
5235 ; BIT 3,2 = PLANAR RAM SIZE (00=16K,01=32K,10=48K,11=64K)
5236 ; BIT 1 NOT USED
5237 ; BIT 0 = IPL FROM DISKETTE -- THIS BIT INDICATES THAT
5238 ; THERE ARE DISKETTE DRIVES ON THE SYSTEM
5239 ;
5240 ; NO OTHER REGISTERS AFFECTED
5241 ;-----
5242 ASSUME CS:CODE,DS:DATA
5243 ORG 0FB40H
5244 EQUIPMENT PROC FAR
5245     STI                     ; INTERRUPTS BACK ON
5246     PUSH OS                 ; SAVE SEGMENT REGISTER
5247     CALL ODS
5248     MOV AX,EQUIP_FLAG      ; GET THE CURRENT SETTINGS
5249     POP OS                  ; RECOVER SEGMENT
5250     IRET                    ; RETURN TO CALLER

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F840

F840

F840 FB

F84E 1E

F84F E8EC06

F852 A11000

F855 1F

F856 CF

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5251 EQUIPMENT      ENDP
5252
5253 ;--- INT 15 -----
5254 ; CASSETTE I/O
5255 ; (AH) = 0  TURN CASSETTE MOTOR ON
5256 ; (AH) = 1  TURN CASSETTE MOTOR OFF
5257 ; (AH) = 2  READ 1 OR MORE 256 BYTE BLOCKS FROM CASSETTE
5258 ; (ES,BX) = POINTER TO DATA BUFFER
5259 ; (CX) = COUNT OF BYTES TO READ
5260 ; ON EXIT
5261 ; (ES,BX) = POINTER TO LAST BYTE READ + 1
5262 ; (CX) = COUNT OF BYTES ACTUALLY READ
5263 ; (CY) = 0 IF NO ERROR OCCURRED
5264 ;       = 1 IF ERROR OCCURRED
5265 ; (AH) = ERROR RETURN IF (CY)= 1
5266 ;       = 01 IF CRC ERROR WAS DETECTED
5267 ;       = 02 IF DATA TRANSITIONS ARE LOST
5268 ;       = 04 IF NO DATA WAS FOUND
5269 ; (AH) = 3  WRITE 1 OR MORE 256 BYTE BLOCKS TO CASSETTE
5270 ; (ES,BX) = POINTER TO DATA BUFFER
5271 ; (CX) = COUNT OF BYTES TO WRITE
5272 ; ON EXIT
5273 ; (EX,BX) = POINTER TO LAST BYTE WRITTEN + 1
5274 ; (CX) = 0
5275 ; (AH) = ANY OTHER THAN ABOVE VALUES CAUSES (CY)= 1
5276 ; AND (AH)= 80 TO BE RETURNED (INVALID COMMAND).
5277 ;-----
5278 ASSUME DS:DATA,ES:NOTHING,SS:NOTHING,CS:CODE
5279 ORG 0F859H
5280 CASSETTE_IO PROC FAR
5281 STI ; INTERRUPTS BACK DN
5282 PUSH DS ; ESTABLISH ADDRESSING TO DATA
5283 CALL DOS
5284 AND BIOS_BREAK, 7FH ; MAKE SURE BREAK FLAG IS OFF
5285 CALL W1 ; CASSETTE_IO_CONT
5286 POP DS
5287 RET 2 ; INTERRUPT RETURN
5288 CASSETTE_IO ENDP
5289 W1 PROC NEAR
5290 ;-----
5291 ; PURPOSE:
5292 ; TO CALL APPROPRIATE ROUTINE DEPENDING ON REG AH
5293 ;
5294 ; AH ROUTINE
5295 ;-----
5296 ; 0 MOTOR_ON
5297 ; 1 MOTOR_OFF
5298 ; 2 READ CASSETTE BLOCK
5299 ; 3 WRITE CASSETTE BLOCK
5300 ;-----
5301 OR AH,AH ; TURN ON MOTOR?
5302 JZ MOTOR_ON ; YES, DO IT
5303 DEC AH ; TURN OFF MOTOR?
5304 JZ MOTOR_OFF ; YES, DO IT
5305 DEC AH ; READ CASSETTE BLOCK?
5306 JZ READ_BLOCK ; YES, DO IT
5307 DEC AH ; WRITE CASSETTE BLOCK?
5308 JNZ W2 ; NOT_DEFINED
5309 JMP WRITE_BLOCK ; YES, DO IT
5310 W2: ; COMMAND NOT DEFINED
5311 MOV AH,080H ; ERROR, UNDEFINED OPERATION
5312 STC ; ERROR FLAG
5313 RET
5314 W1 ENDP
5315 MOTOR_ON PROC NEAR
5316 ;-----
5317 ; PURPOSE:
5318 ; TO TURN ON CASSETTE MOTOR
5319 ;-----
5320 IN AL,PORT_B ; READ CASSETTE OUTPUT
5321 AND AL,NOT_08H ; CLEAR BIT TO TURN ON MOTOR
5322 W3:
5323 OUT PORT_B,AL ; WRITE IT OUT
5324 SUB AN,AH ; CLEAR AH
5325 RET
5326 MOTOR_ON ENDP
5327 MOTOR_OFF PROC NEAR

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LOC OBJ

LINE SOURCE

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5328 ;-----
5329 ; PURPOSE:
5330 ; TO TURN CASSETTE MOTOR OFF
5331 ;-----
F88A E461 5332 IN AL,PORT_B ; READ CASSETTE OUTPUT
F88C 0C08 5333 OR AL,08H ; SET BIT TO TURN OFF
F88E EBF5 5334 JMP M3 ; WRITE IT, CLEAR ERROR, RETURN
5335 MOTOR_OFF ENDP
F890 5336 READ_BLOCK PROC NEAR
5337 ;-----
5338 ; PURPOSE:
5339 ; TO READ 1 OR MORE 256 BYTE BLOCKS FROM CASSETTE
5340 ;
5341 ; ON ENTRY:
5342 ; ES IS SEGMENT FOR MEMORY BUFFER (FOR COMPACT CODE)
5343 ; BX POINTS TO START OF MEMORY BUFFER
5344 ; CX CONTAINS NUMBER OF BYTES TO READ
5345 ; ON EXIT:
5346 ; BX POINTS 1 BYTE PAST LAST BYTE PUT IN MEM
5347 ; CX CONTAINS DECREMENTED BYTE COUNT
5348 ; DX CONTAINS NUMBER OF BYTES ACTUALLY READ
5349 ;
5350 ; CARRY FLAG IS CLEAR IF NO ERROR DETECTED
5351 ; CARRY FLAG IS SET IF CRC ERROR DETECTED
5352 ;-----
F890 53 5353 PUSH BX ; SAVE BX
F891 51 5354 PUSH CX ; SAVE CX
F892 56 5355 PUSH SI ; SAVE SI
F893 DE0700 5356 MOV SI, 7 ; SET UP RETRY COUNT FOR LEADER
F896 E8F01 5357 CALL BEGIN_OP ; BEGIN BY STARTING MOTOR
F899 5358 M4: ; SEARCH FOR LEADER
F899 E462 5359 IN AL,PORT_C ; GET INITIAL VALUE
F89B 2410 5360 AND AL,010H ; MASK OFF EXTRANEOUS BITS
F89D A26D00 5361 MOV LAST_VAL,AL ; SAVE IN LOC LAST_VAL
F8A0 8A7A3F 5362 MOV DX,16250 ; # OF TRANSITIONS TO LOOK FOR
F8A3 5363 M5: ; WAIT_FOR_EDGE
F8A3 F606710080 5364 TEST BIOS_BREAK, 80H ; CHECK FOR BREAK KEY
F8A8 7503 5365 JNZ M6A ; JUMP IF NO BREAK KEY
5366 ; JUMP IF BREAK KEY HIT
F8AA 5367 M6:
F8AA 4A 5368 DEC DX
F8AB 7503 5369 JNZ M7 ; JUMP IF BEGINNING OF LEADER
F8AD 5370 M6A:
F8AD E98400 5371 JMP M17 ; JUMP IF NO LEADER FOUND
F8B0 5372 M7:
F8B0 E0C600 5373 CALL READ_HALF_BIT ; IGNORE FIRST EDGE
F8B3 E3EE 5374 JCXZ M5 ; JUMP IF NO EDGE DETECTED
F8B5 BA7803 5375 MOV DX,0378H ; CHECK FOR HALF BITS
F8B8 B90002 5376 MOV CX,200H ; MUST HAVE AT LEAST THIS MANY ONE SIZE
5377 ; PULSES BEFORE CHECKING FOR SYNC BIT (0)
F8BB E421 5378 IN AL, 021H ; INTERRUPT MASK REGISTER
F8BD 0C01 5379 OR AL,1 ; DISABLE TIMER INTERRUPTS
F8BF E621 5380 OUT 021H, AL
F8C1 5381 M8: ; SEARCH-LDR
F8C1 F606710080 5382 TEST BIOS_BREAK, 80H ; CHECK FOR BREAK KEY
F8C6 756C 5383 JNZ M17 ; JUMP IF BREAK KEY HIT
F8C8 51 5384 PUSH CX ; SAVE REG CX
F8C9 E8AD00 5385 CALL READ_HALF_BIT ; GET PULSE WIDTH
F8CC 0BC9 5386 OR CX, CX ; CHECK FOR TRANSITION
F8CE 59 5387 POP CX ; RESTORE ONE BIT COUNTER
F8CF 74C8 5388 JZ M4 ; JUMP IF NO TRANSITION
F8D1 3B03 5389 CMP DX,BX ; CHECK PULSE WIDTH
F8D3 E304 5390 JCXZ M9 ; IF CX=0 THEN WE CAN LOOK
5391 ; FOR SYNC BIT (0)
F8D5 73C2 5392 JNC M4 ; JUMP IF ZERO BIT (NOT GOOD LEADER)
F8D7 E2E8 5393 LOOP M8 ; DEC CX AND READ ANOTHER HALF ONE BIT
F8D9 5394 M9: ; FIND-SYNC
F8D9 72E6 5395 JC M8 ; JUMP IF ONE BIT (STILL LEADER)
5396
5397 ;----- A SYNC BIT HAS BEEN FOUND. READ SYN CHARACTER:
5398
F8DB E89B00 5399 CALL READ_HALF_BIT ; SKIP OTHER HALF OF SYNC BIT (0)
F8DE E08A00 5400 CALL READ_BYTE ; READ SYN BYTE
F8E1 3C16 5401 CMP AL, 16H ; SYNCHRONIZATION CHARACTER
F8E3 7549 5402 JNE M16 ; JUMP IF BAD LEADER FOUND.
5403
5404 ;----- 6000 CRC SO READ DATA BLOCK(S)

```

LOC	OBJ	LINE	SOURCE	
		5405		
F8E5	5E	5406	POP SI	; RESTORE REGS
F8E6	59	5407	POP CX	
F8E7	5B	5408	POP BX	
		5409		
		5410	;-----	
		5410	; READ 1 OR MORE 256 BYTE BLOCKS FROM CASSETTE	
		5411	;	
		5412	; ON ENTRY:	
		5413	; ES IS SEGMENT FOR MEMORY BUFFER (FOR COMPACT CODE)	
		5414	; BX POINTS TO START OF MEMORY BUFFER	
		5415	; CX CONTAINS NUMBER OF BYTES TO READ	
		5416	; ON EXIT:	
		5417	; BX POINTS 1 BYTE PAST LAST BYTE PUT IN MEM	
		5418	; CX CONTAINS DECREMENTED BYTE COUNT	
		5419	; DX CONTAINS NUMBER OF BYTES ACTUALLY READ	
		5420	;-----	
F8E8	51	5421	PUSH CX	; SAVE BYTE COUNT
F8E9		5422	W10:	; COME HERE BEFORE EACH
		5423		; 256 BYTE BLOCK IS READ
F8E9	C7066900FFFF	5424	MOV	CRC_REG, 0FFFFH
F8EF	8A0001	5425	MOV	OX, 256
F8F2		5426	W11:	; INIT CRC REG
F8F2	F606710080	5427	TEST	BIOS_BREAK, 80H
F8F7	7523	5428	JNZ	W13
F8F9	E84F00	5429	CALL	READ_BYTE
F8FC	721E	5430	JC	W13
F8FE	E305	5431	JCXZ	W12
		5432		; CY SET INDICATES NO DATA TRANSITIONS
		5433		; IF WE'VE ALREADY REACHED
		5434		; END OF MEMORY BUFFER
F900	26BB07	5435	MOV	ES:[BX], AL
F903	43	5436	INC	BX
F904	49	5437	DEC	CX
F905		5438	W12:	; SKIP REST OF BLOCK
F905	4A	5439	DEC	OX
F906	7FEA	5440	JG	W11
F90B	E84000	5441	CALL	READ_BYTE
F90B	EB3000	5442	CALL	READ_BYTE
F90E	2AE4	5443	SUB	AH, AH
F910	813E69000F10	5444	CHP	CRC_REG, 1D0FH
F916	7506	5445	JNE	W14
F918	E306	5446	JCXZ	W15
		5447		; END OF MEMORY BUFFER
F91A	EB0C	5448	JMP	W10
F91C		5449	W13:	; STILL MORE, SO READ ANOTHER BLOCK
F91C	B401	5450	MOV	AN, 01H
		5451		; MISSING-OATA
F91E		5452	W14:	; NO DATA TRANSITIONS SO
F91E	FEC4	5453	INC	AH
		5454		; SET AN=02 TO INDICATE
F920		5455	W15:	; DATA TIMEOUT
F920	5A	5456	POP	DX
F921	2BD1	5457	SUB	OX, CX
		5458		; BAD-CRC
F923	50	5459	PUSH	AX
F924	F6C490	5460	TEST	AH, 90H
F927	7513	5461	JNZ	W18
F929	E81F00	5462	CALL	READ_BYTE
F92C	EB0E	5463	JMP	SHORT W18
F92E		5464	W16:	; CHECK FOR ERRORS
F92E	4E	5465	DEC	SI
F92F	7403	5466	JZ	W17
F931	E965FF	5467	JMP	W4
F934		5470	W17:	; JUMP IF TOO MANY RETRIES
		5471		; JUMP IF NOT TOO MANY RETRIES
		5472	;----- NO DATA FROM CASSETTE ERROR, I.E. TIMEOUT	
		5473		
F934	5E	5474	POP	SI
F935	59	5475	POP	CX
F936	5B	5476	POP	BX
F937	2BD2	5477	SUB	OX, OX
F939	B404	5478	MOV	AH, 04H
F93B	50	5479	PUSH	AX
F93C		5480	W18:	; MOT-OFF

LOC OBJ	LINE	SOURCE	
F93C E421	5481	IN AL, 021H	; RE_ENABLE INTERRUPTS
F93E 24FE	5482	AND AL, 0FFH- 1	
F940 E621	5483	OUT 021H, AL	
F942 E845FF	5484	CALL MOTOR_OFF	; TURN OFF MOTOR
F945 58	5485	POP AX	; RESTORE RETURN CODE
F946 80FC01	5486	CMF AH,01H	; SET CARRY IF ERROR (AH>0)
F949 F5	5487	CMC	
F94A C3	5488	RET	; FINISHED
	5489	READ_BLOCK ENDP	
	5490	-----	
	5491	; PURPOSE:	:
	5492	; TO READ A BYTE FROM CASSETTE	:
	5493	; ON EXIT	:
	5494	; REG AL CONTAINS READ DATA BYTE	:
	5495	-----	
F94B	5496	READ_BYTE PROC NEAR	
F94B 53	5497	PUSH BX	; SAVE REGS BX,CX
F94C 51	5498	PUSH CX	
F94D B108	5499	MOV CL,8H	; SET BIT COUNTER FOR 8 BITS
F94F	5500	W19:	; BYTE-ASH
F94F 51	5501	PUSH CX	; SAVE CX
	5502	-----	
	5503	; READ DATA BIT FROM CASSETTE	:
	5504	-----	
F950 E82600	5505	CALL READ_HALF_BIT	; READ ONE PULSE
F953 E320	5506	JCXZ W21	; IF CX=0 THEN TIMEOUT
	5507		; BECAUSE OF NO DATA TRANSITIONS
F955 53	5508	PUSH BX	; SAVE 1ST HALF BIT'S
	5509		; PULSE WIDTH (IN BX)
F956 E82000	5510	CALL READ_HALF_BIT	; READ COMPLEMENTARY PULSE
F959 58	5511	POP AX	; COMPUTE DATA BIT
F95A E319	5512	JCXZ W21	; IF CX=0 THEN TIMEOUT DUE TO
	5513		; NO DATA TRANSITIONS
F95C 0308	5514	ADD BX,AX	; PERIOD
F95E 01BDF006	5515	CMF BX, 06F0H	; CHECK FOR ZERO BIT
F962 F5	5516	CMC	; CARRY IS SET IF ONE BIT
F963 9F	5517	LAHF	; SAVE CARRY IN AH
F964 59	5518	POP CX	; RESTORE CX
	5519		; NOTE:
	5520		; MS BIT OF BYTE IS READ FIRST.
	5521		; REG CH IS SHIFTED LEFT WITH
	5522		; CARRY BEING INSERTED INTO LS
	5523		; BIT OF CH.
	5524		; AFTER ALL 8 BITS HAVE BEEN
	5525		; READ, THE MS BIT OF THE DATA BYTE
	5526		; WILL BE IN THE MS BIT OF REG CH
F965 0005	5527	RCL CH,1	; ROTATE REG CH LEFT WITH CARRY TO
	5528		; LS BIT OF REG CH
F967 9E	5529	SAHF	; RESTORE CARRY FOR CRC ROUTINE
F968 E80900	5530	CALL CRC_GEN	; GENERATE CRC FOR BIT
F96B FEC9	5531	OEC CL	; LOOP TILL ALL 8 BITS OF DATA
	5532		; ASSEMBLED IN REG CH
F96D 75E0	5533	JNZ W19	; BYTE_ASH
F96F 8AC5	5534	MOV AL,CH	; RETURN DATA BYTE IN REG AL
F971 F8	5535	CLC	
F972	5536	W20:	; RO-BYT-EX
F972 59	5537	POP CX	; RESTORE REGS CX,BX
F973 5B	5538	POP BX	
F974 C3	5539	RET	; FINISHED
F975	5540	W21:	; NO-OATA
F975 59	5541	POP CX	; RESTORE CX
F976 F9	5542	STC	; INDICATE ERROR
F977 EBF9	5543	JMP W20	; RO_BYT_EX
	5544	READ_BYTE ENDP	
	5545	-----	
	5546	; PURPOSE:	:
	5547	; TO COMPUTE TIME TILL NEXT DATA	:
	5548	; TRANSITION (EDGE)	:
	5549	; ON ENTRY:	:
	5550	; EDGE_CNT CONTAINS LAST EDGE COUNT	:
	5551	; ON EXIT:	:
	5552	; AX CONTAINS OLD LAST EDGE COUNT	:
	5553	; BX CONTAINS PULSE WIDTH (HALF BIT)	:
	5554	-----	
F979	5555	READ_HALF_BIT PROC NEAR	
F979 B96400	5556	MOV CX, 100	; SET TIME TO WAIT FOR BIT
F97C 8A266B00	5557	MOV AH, LAST_VAL	; GET PRESENT INPUT VALUE

LOC OBJ	LINE	SOURCE
F980	5558	W22: ; RD-H-BIT
F980 E462	5559	IN AL,PORT_C ; INPUT DATA BIT
F982 2410	5560	AND AL,010H ; MASK OFF EXTRANEIOUS BITS
F984 3AC4	5561	CMF AL,AH ; SAME AS BEFORE?
F986 E1F8	5562	LOOPE W22 ; LOOP TILL IT CHANGES
F988 A26B00	5563	MOV LAST_VAL,AL ; UPDATE LAST_VAL WITH NEW VALUE
F98B B080	5564	MOV AL,0 ; READ TIMER'S COUNTER COMMAND
F98D E643	5565	OUT TIM_CTL,AL ; LATCH COUNTER
F98F 8B1E6700	5566	MOV BX,EDGE_CNT ; BX GETS LAST EDGE COUNT
F993 E440	5567	IN AL,TIMER0 ; GET LS BYTE
F995 8AE0	5568	MOV AH,AL ; SAVE IN AH
F997 E440	5569	IN AL,TIMER0 ; GET MS BYTE
F999 86C4	5570	XCHG AL,AH ; XCHG MS,AL
F99B 2B08	5571	SUB BX,AX ; SET BX EQUAL TO HALF BIT PERIOD
F99D A36700	5572	MOV EDGE_CNT,AX ; UPDATE EDGE COUNT;
F9A0 C3	5573	RET
	5574	READ_HALF_BIT ENOP
	5575	;
	5576	; PURPOSE ;
	5577	; WRITE 1 OR MORE 256 BYTE BLOCKS TO CASSETTE. ;
	5578	; THE DATA IS PADDED TO FILL OUT THE LAST 256 BYTE BLOCK. ;
	5579	; ON ENTRY: ;
	5580	; BX POINTS TO MEMORY BUFFER ADDRESS ;
	5581	; CX CONTAINS NUMBER OF BYTES TO WRITE ;
	5582	; ON EXIT: ;
	5583	; BX POINTS 1 BYTE PAST LAST BYTE WRITTEN TO CASSETTE ;
	5584	; CX IS ZERO ;
	5585	;
F9A1	5586	WRITE_BLOCK PROC NEAR
F9A1 53	5587	PUSH BX
F9A2 51	5588	PUSH CX
F9A3 E461	5589	IN AL,PORT_B ; DISABLE SPEAKER
F9A5 24F0	5590	AND AL,NOT 02H
F9A7 0C01	5591	OR AL, 01H ; ENABLE TIMER
F9A9 E661	5592	OUT PORT_B,AL
F9AB B086	5593	MOV AL,086H ; SET UP TIMER -- MODE 3 SQUARE WAVE
F9AD E443	5594	OUT TIM_CTL,AL
F9AF 8BA600	5595	CALL BEGIN_OP ; START MOTOR AND DELAY
F9B2 B8A004	5596	MOV AX,1184 ; SET NORMAL BIT SIZE
F9B5 B88500	5597	CALL W31 ; SET_TIMER
F9B8 B90008	5598	MOV CX,0800H ; SET CX FOR LEADER BYTE COUNT
F9BB	5599	W23: ; WRITE LEADER
F9BB F9	5600	STC ; WRITE ONE BITS
F9BC E86800	5601	CALL WRITE_BIT
F9BF E2FA	5602	LOOP W23 ; LOOP 'TIL LEADER IS WRITTEN
F9C1 F8	5603	CLC ; WRITE SYNC BIT (0)
F9C2 E86200	5604	CALL WRITE_BIT
F9C5 59	5605	POP CX ; RESTORE REGS CX,BX
F9C6 5B	5606	POP BX
F9C7 B016	5607	MOV AL, 16H ; WRITE SYN CHARACTER
F9C9 E84400	5608	CALL WRITE_BYTE
	5609	;
	5610	; PURPOSE ;
	5611	; WRITE 1 OR MORE 256 BYTE BLOCKS TO CASSETTE ;
	5612	; ON ENTRY: ;
	5613	; BX POINTS TO MEMORY BUFFER ADDRESS ;
	5614	; CONTAINS NUMBER OF BYTES TO WRITE ;
	5615	; ON EXIT: ;
	5616	; BX POINTS 1 BYTE PAST LAST BYTE WRITTEN TO CASSETTE ;
	5617	; CX IS ZERO ;
	5618	;
F9CC	5619	WR_BLOCK:
F9CC C7066900FFFF	5620	MOV CRC_REG,0FFFFH ; INIT CRC
F9D2 BA0001	5621	MOV DX,256 ; FOR 256 BYTES
F9D5	5622	W24: ; WR-BLK
F9D5 268A07	5623	MOV AL,ES:[BX] ; READ BYTE FROM MEM
F9D8 E83500	5624	CALL WRITE_BYTE ; WRITE IT TO CASSETTE
F9DB E302	5625	JCXZ W25 ; UNLESS CX=0, ADVANCE PTRS & OEC COUNT
F9DD 43	5626	INC BX ; INC BUFFER POINTER
F9DE 49	5627	DEC CX ; DEC BYTE COUNTER
F9DF	5628	W25: ; SKIP-ADV
F9DF 4A	5629	OEC DX ; DEC BLOCK CNT
F9E0 7FF3	5630	JG W24 ; LOOP TILL 256 BYTE BLOCK
	5631	; IS WRITTEN TO TAPE
	5632	;
	5633	; WRITE CRC ;
	5634	; WRITE 1'S COMPLEMENT OF CRC REG TO CASSETTE ;

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5635 ; WHICH IS CHECKED FOR CORRECTNESS WHEN THE BLOCK IS READ :
5636 ; REG AX IS MODIFIED
5637 ;-----
F9E2 A16900 5638 MOV AX,CRC_REG ; WRITE THE ONE'S COMPLEMENT OF THE
5639 ; TWO BYTE CRC TO TAPE
F9E5 F7D0 5640 NOT AX ; FOR 1'S COMPLEMENT
F9E7 50 5641 PUSH AX ; SAVE IT
F9E8 86E0 5642 XCHG AH,AL ; WRITE MS BYTE FIRST
F9EA E82300 5643 CALL WRITE_BYTE ; WRITE IT
F9ED 58 5644 POP AX ; GET IT BACK
F9EE E81F00 5645 CALL WRITE_BYTE ; NOW WRITE LS BYTE
F9F1 0BC9 5646 OR CX,CX ; IS BYTE COUNT EXHAUSTED?
F9F3 7507 5647 JNZ WR_BLOCK ; JUMP IF NOT DONE YET
F9F5 51 5648 PUSH CX ; SAVE REG CX
F9F6 B92000 5649 MOV CX, 32 ; WRITE OUT TRAILER BITS
F9F9 W26: 5650 ; TRAIL-LOOP
F9F9 F9 5651 STC
F9FA E82A00 5652 CALL WRITE_BIT
F9FD E2FA 5653 LOOP W26 ; WRITE UNTIL TRAILER WRITTEN
F9FF 59 5654 POP CX ; RESTORE REG CX
FA00 B0B0 5655 MOV AL, 0B0H ; TURN TIMER2 OFF
FA02 E643 5656 OUT TIM_CTL, AL
FA04 D80100 5657 MOV AX, 1
FA07 E83300 5658 CALL W31 ; SET_TIMER
FA0A E87DFE 5659 CALL MOTOR_OFF ; TURN MOTOR OFF
FA0D 2BC0 5660 SUB AX,AX ; NO ERRORS REPORTED ON WRITE DP
FA0F C3 5661 RET ; FINISHED
5662 WRITE_BLOCK ENDP
5663 ;-----
5664 ; WRITE A BYTE TO CASSETTE.
5665 ; BYTE TO WRITE IS IN REG AL.
5666 ;-----
FA10 5667 WRITE_BYTE PROC NEAR
FA10 51 5668 PUSH CX ; SAVE REGS CX,AX
FA11 50 5669 PUSH AX
FA12 8AE8 5670 MOV CH,AL ; AL=BYTE TO WRITE.
5671 ; (MS BIT WRITTEN FIRST)
FA14 B108 5672 MOV CL,8 ; FOR 8 DATA BITS IN BYTE.
5673 ; NOTE: TWO EDGES PER BIT
FA16 5674 W27: ; DISASSEMBLE THE DATA BIT
FA16 00D5 5675 RCL CH,1 ; ROTATE MS BIT INTO CARRY
FA18 9C 5676 PUSHF ; SAVE FLAGS.
5677 ; NOTE: DATA BIT IS IN CARRY
FA19 E80B00 5678 CALL WRITE_BIT ; WRITE DATA BIT
FA1C 90 5679 POPF ; RESTORE CARRY FOR CRC CALC
FA1D E82400 5680 CALL CRC_GEN ; COMPUTE CRC ON DATA BIT
FA20 FEC9 5681 DEC CL ; LOOP TILL ALL 8 BITS DONE
FA22 75F2 5682 JNZ W27 ; JUMP IF NOT DONE YET
FA24 58 5683 POP AX ; RESTORE REGS AX,CX
FA25 59 5684 POP CX
FA26 C3 5685 RET ; WE ARE FINISHED
5686 WRITE_BYTE ENDP
5687 ;-----
5688 ; PURPOSE:
5689 ; TO WRITE A DATA BIT TO CASSETTE
5690 ; CARRY FLAG CONTAINS DATA BIT
5691 ; I.E. IF SET DATA BIT IS A ONE
5692 ; IF CLEAR DATA BIT IS A ZERO
5693 ;
5694 ; NOTE: TWO EDGES ARE WRITTEN PER BIT
5695 ; ONE BIT HAS 500 USEC BETWEEN EDGES
5696 ; FOR A 1000 USEC PERIOD (1 MILLISEC)
5697 ;
5698 ; ZERO BIT HAS 250 USEC BETWEEN EDGES
5699 ; FOR A 500 USEC PERIOD (.5 MILLISEC)
5700 ; CARRY FLAG IS DATA BIT
5701 ;-----
FA27 5702 WRITE_BIT PROC NEAR
5703 ; ASSUME IT'S A '1'
FA27 B8A004 5704 MOV AX,1184 ; SET AX TO NOMINAL ONE SIZE
FA2A 7203 5705 JC W28 ; JUMP IF ONE BIT
FA2C B85002 5706 MOV AX,592 ; NO, SET TO NOMINAL ZERO SIZE
FA2F 5707 W28: ; WRITE-BIT-AX
FA2F 50 5708 PUSH AX ; WRITE BIT WITH PERIOD EQ TO VALUE AX
FA30 5709 W29:
FA30 E642 5710 IN AL,PORT_C ; INPUT TIMER_0 OUTPUT
FA32 2420 5711 AND AL,020H

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LOC OBJ	LINE	SOURCE
FA34 74FA	5712	JZ W29 ; LOOP TILL HIGH
FA36	5713	W30:
FA36 E462	5714	IH AL,PORT_C ; NOW WAIT TILL TIMER'S OUTPUT IS LOW
FA38 2420	5715	AND AL,020H
FA3A 75FA	5716	JNZ W30
	5717	
	5718	; RELOAD TIMER WITH PERIOD
FA3C 58	5719	POP AX ; FOR NEXT DATA BIT
FA3D	5720	W31: ; RESTORE PERIOD COUNT
FA3D E642	5721	OUT 042H, AL ; SET TIMER
FA3F 0AC4	5722	MOV AL, AH ; SET LOW BYTE OF TIMER 2
FA41 E642	5723	OUT 042H, AL ; SET HIGH BYTE OF TIMER 2
FA43 C3	5724	RET
	5725	WRITE_BIT ENDP
	5726	-----
	5727	; UPDATE CRC REGISTER WITH NEXT DATA BIT ;
	5728	; CRC IS USED TO DETECT READ ERRORS ;
	5729	; ASSUMES DATA BIT IS IN CARRY ;
	5730	; ;
	5731	; REG AX IS MODIFIED ;
	5732	; FLAGS ARE MODIFIED ;
	5733	-----
FA44	5734	CRC_GEN PROC HEAR
FA44 A16900	5735	MOV AX,CRC_REG
	5736	
	5737	; THE FOLLOWING INSTRUCTIONS
	5738	; WILL SET THE OVERFLOW FLAG
	5739	; IF CARRY AND MS BIT OF CRC
	5740	; ARE UNEQUAL
FA47 D108	5741	RCL AX,1
FA49 D1D0	5742	RCL AX,1
FA4B F8	5743	CLC ; CLEAR CARRY
FA4C 7104	5744	JNO W32 ; SKIP IF NO OVERFLOW
	5745	; IF DATA BIT XORED WITH
	5746	; CRC REG BIT 15 IS ONE
FA4E 351008	5747	XOR AX,0B10H ; THEN XOR CRC REG WITH 0B01H
FA51 F9	5748	STC ; SET CARRY
FA52	5749	W32:
FA52 D1D0	5750	RCL AX,1 ; ROTATE CARRY (DATA BIT)
	5751	; INTO CRC REG
FA54 A36900	5752	MOV CRC_REG,AX ; UPDATE CRC_REG
FA57 C3	5753	RET ; FINISHED
	5754	CRC_GEN ENDP
FA58	5755	BEGIN_OP PROC HEAR
FA58 E826FE	5756	CALL MOTOR_ON ; TURN ON MOTOR
FA5B B342	5757	MOV BL,42H ; DELAY FOR TAPE DRIVE
	5758	; TO GET UP TO SPEED (1/2 SEC)
FA5D	5759	W33:
FA5D B90007	5760	MOV CX,700H ; INNER LOOP= APPROX. 10 MILLISEC
FA60 E2FE	5761	W34: LOOP W34
FA62 FECB	5762	DEC BL
FA64 75F7	5763	JNZ W33
FA66 C3	5764	RET
	5765	BEGIN_OP ENDP
	5766	
FA67 20323031	5767	E1 DB ' 201',13,10
FA6B 00		
FA6C 0A		
	5768	
	5769	-----
	5770	; CHARACTER GENERATOR GRAPHICS FOR 320X200 AND 640X200 GRAPHICS
	5771	-----
FA6E	5772	ORG 0FA6EH
FA6E	5773	CRT_CHAR_GEN LABEL BYTE
FA6E 0000000000000000	5774	DB 000H,000H,000H,000H,000H,000H,000H,000H ; 0_00
FA76 7E81A581B099817E	5775	DB 07EH,081H,0A5H,081H,0B0H,099H,081H,07EH ; D_01
FA7E 7EFDDBFFC3E7FF7E	5776	DB 07EH,0FFH,00BH,0FFH,0C3H,0E7H,0FFH,07EH ; 0_02
FA86 6CFEFEFE7C381000	5777	DB 06CH,0FEH,0FEH,0FEH,07CH,03BH,010H,000H ; 0_03
FA8E 10387CFE7C381000	5778	DB 010H,03BH,07CH,0FEH,07CH,03BH,010H,000H ; 0_04
FA96 387C38FE7C387C	5779	DB 03BH,07CH,03BH,0FEH,0FEH,07CH,03BH,07CH ; 0_05
FA9E 1010387CFE7C387C	5780	DB 010H,010H,03BH,07CH,0FEH,07CH,03BH,07CH ; 0_06
FAA6 0000183C3C180000	5781	DB 000H,000H,018H,03CH,03CH,018H,000H,000H ; 0_07
FAAE FFFFE7C3C3E7FF7E	5782	DB 0FFH,0FFH,0E7H,0C3H,0C3H,0E7H,0FFH,0FFH ; 0_08
FAAB 003C664292663C00	5783	DB 000H,03CH,066H,042H,042H,066H,03CH,000H ; 0_09
FA8E FFC399B0BD99C3FF	5784	DB 0FFH,0C3H,099H,0BDH,0BDH,0C3H,0FFH,0FFH ; 0_0A
FA6C 0F070F7DCCCCC78	5785	DB 00FH,007H,00FH,07DH,0CCH,0CCH,0CCH,07BH ; 0_0B
FACE 3C6666663C187E18	5786	DB 03CH,066H,066H,066H,03CH,018H,07EH,018H ; 0_0C

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FAD6 3F333F303070F0E0 5787 0B 03FH,033H,03FH,030H,030H,070H,0F0H,0E0H ; D_00
FADE 7F637F636367E6C0 5788 0B 07FH,063H,07FH,063H,063H,067H,0E6H,0C0H ; D_0E
FAE6 995A3CE7E73C5A99 5789 0B 099H,05AH,03CH,0E7H,0E7H,03CH,05AH,099H ; D_0F
FAEE 8E0EF0F8F8E08000 5790 0B 080H,0E0H,0F8H,0FEH,0F8H,0E0H,080H,000H ; D_10
FAF6 020E3EFE3E0E0200 5791 0B 002H,00EH,03EH,0FEH,03EH,0CEH,002H,000H ; D_11
FAFE 183C7E187E3C18FF 5792 0B 018H,03CH,07EH,018H,018H,07EH,03CH,018H ; D_12
FB06 6666666666066000 5793 0B 066H,066H,066H,066H,066H,000H,066H,000H ; D_13
FB0E 7F0D0B7B181B1800 5794 0B 07FH,00BH,00BH,07EH,01BH,01BH,01BH,000H ; D_14
FB16 3E63366C6C38C778 5795 0B 03EH,063H,03EH,06CH,06CH,03BH,0CCH,07EH ; D_15
FB1E 000000007E7E7E00 5796 0B 000H,000H,000H,000H,07EH,07EH,07EH,000H ; D_16
FB26 183C7E187E3C18FF 5797 0B 018H,03CH,07EH,018H,07EH,03CH,018H,0FFH ; D_17
FB2E 183C7E1818181800 5798 0B 018H,03CH,07EH,018H,018H,018H,018H,000H ; D_18
FB36 181818187E3C1800 5799 0B 018H,018H,018H,018H,07EH,03CH,018H,000H ; D_19
FB3E 00180CFE0C180000 5800 0B 000H,018H,00CH,0FEH,00CH,018H,000H,000H ; D_1A
FB46 003060FE0C030000 5801 0B 000H,030H,060H,0FEH,060H,030H,000H,000H ; D_1B
FB4E 0000C0C0CF0E0000 5802 0B 000H,000H,0C0H,0C0H,0C0H,0FEH,000H,000H ; D_1C
FB56 002460FF66240000 5803 0B 000H,024H,066H,0FFH,066H,024H,000H,000H ; D_1D
FB5E 00183C7EFFFF0000 5804 0B 000H,018H,03CH,07EH,0FFH,0FFH,000H,000H ; D_1E
FB66 00FFFF7F3C180000 5805 0B 000H,0FFH,0FFH,07EH,03CH,018H,000H,000H ; D_1F
FB6E 0000000000000000 5806 0B 000H,000H,000H,000H,000H,000H,000H,000H ; SP_D_20
FB76 3078783030003000 5807 0B 030H,078H,078H,030H,030H,000H,030H,000H ; D_21
FB7E 6C6C6C0000000000 5808 0B 06CH,06CH,06CH,000H,000H,000H,000H,000H ; D_22
FB86 6C6CFE6CFE6C6C00 5809 0B 06CH,06CH,0FEH,06CH,0FEH,06CH,06CH,000H ; D_23
FB8E 307CC0780CF80000 5810 0B 030H,07CH,0C0H,07EH,0C0H,0F8H,03CH,000H ; D_24
FB96 00C6C183066C6000 5811 0B 000H,0C6H,0CCH,018H,030H,066H,0C6H,000H ; PER_CENT_D_25
FB9E 386C38760CC77600 5812 0B 038H,06CH,038H,07EH,0CCH,0CCH,07EH,000H ; A_26
FBA6 606C000000000000 5813 0B 060H,060H,0C0H,000H,000H,0C0H,000H,000H ; D_27
FBAE 1830606060301800 5814 0B 018H,030H,060H,060H,060H,030H,018H,000H ; D_28
FBB6 6030181818306000 5815 0B 060H,030H,018H,018H,018H,030H,060H,000H ; D_29
FBBE 00663CF3C6600000 5816 0B 000H,066H,03CH,0FFH,03CH,066H,000H,000H ; D_2A
FBC6 003030FC03000000 5817 0B 000H,030H,030H,0FCH,030H,030H,000H,000H ; D_2B
FBCF 0000000000003060 5818 0B 000H,000H,000H,000H,000H,030H,030H,060H ; D_2C
FBD6 0000000FC0000000 5819 0B 000H,000H,000H,0FCH,000H,000H,000H,000H ; D_2D
FBD7 0000000000000000 5820 0B 000H,000H,000H,000H,000H,030H,030H,000H ; D_2E
FBE6 060C183060C08000 5821 0B 060H,00CH,018H,030H,060H,0CCH,060H,000H ; D_2F
FBE7 7CC4CE0F6E647C00 5822 0B 07CH,0C6H,0CEH,0DEH,0F6H,06EH,07CH,000H ; D_30
FBF6 307030303030FC00 5823 0B 030H,070H,030H,030H,030H,030H,0FCH,000H ; D_31
FBF7 78CC0C3866CCFC00 5824 0B 078H,0CCH,00CH,038H,060H,0CCH,0FCH,000H ; D_32
FC06 78CC0C3800CC7C00 5825 0B 078H,0CCH,00CH,038H,00CH,0CCH,078H,000H ; D_33
FC0E 1C3C6CCCFC0C1E00 5826 0B 01CH,06CH,06CH,0CCH,0FEH,00CH,01EH,000H ; A_34
FC16 FCC0F80C0CC78000 5827 0B 0FCH,0C0H,0F8H,00CH,00CH,0CCH,078H,000H ; D_35
FC1E 386C0CF8CC0CC780 5828 0B 038H,060H,0CCH,0F8H,0CCH,0CCH,078H,000H ; D_36
FC26 FCC0C01830303000 5829 0B 0FCH,0CCH,00CH,018H,030H,030H,030H,000H ; D_37
FC2E 78CCCC780CC78000 5830 0B 078H,0CCH,0CCH,078H,0CCH,0CCH,078H,000H ; D_38
FC36 78CCCC7C0C187000 5831 0B 078H,0CCH,0CCH,07CH,0CCH,018H,070H,000H ; D_39
FC3E 0030300000003000 5832 0B 000H,030H,030H,000H,000H,030H,030H,000H ; D_3A
FC46 0030300000303060 5833 0B 000H,030H,030H,000H,000H,030H,030H,060H ; D_3B
FC4E 183060C060301800 5834 0B 018H,030H,060H,0C0H,060H,030H,018H,000H ; D_3C
FC56 0000FC0000FC0000 5835 0B 000H,000H,0FCH,000H,000H,0FCH,000H,000H ; D_3D
FC5E 6030180C18306000 5836 0B 060H,030H,018H,0CCH,018H,030H,060H,000H ; D_3E
FC66 78CC0C1830003000 5837 0B 078H,0CCH,00CH,018H,030H,000H,030H,000H ; D_3F
FC6E 7CC60E0E0EC78000 5838 0B 07CH,0C6H,0DEH,00EH,0DEH,0CCH,078H,000H ; D_40
FC76 3078CCCCFC0CC000 5839 0B 030H,078H,0CCH,0CCH,0FCH,0CCH,0CCH,000H ; A_41
FC7E FC66667C6666FC00 5840 0B 0FCH,066H,066H,07CH,066H,066H,0FCH,000H ; B_42
FC86 3C666C0C0C066C00 5841 0B 03CH,066H,0C0H,0C0H,0C0H,066H,03CH,000H ; C_43
FC8E F86C6666666CF800 5842 0B 0F8H,06CH,066H,066H,066H,06CH,0F8H,000H ; D_44
FC96 FE6268786862FE00 5843 0B 0FEH,062H,068H,078H,068H,062H,0FEH,000H ; E_45
FC9E FE6268786862FE00 5844 0B 0FEH,062H,068H,078H,068H,060H,0F0H,000H ; F_46
FCA6 3C66C0C0CE663E00 5845 0B 03CH,066H,0C0H,0C0H,0CEH,066H,03EH,000H ; D_47
FCAE CCCCCCF0CCCC0000 5846 0B 0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,000H ; H_48
FCBE 7830303030307800 5847 0B 078H,030H,030H,030H,030H,030H,078H,000H ; I_49
FCBE 1E0C0C0C0C0C7800 5848 0B 01EH,0CCH,00CH,00CH,0CCH,0CCH,078H,000H ; J_D_4A
FCE6 F6666C786C66E600 5849 0B 0E6H,066H,06CH,078H,06CH,066H,0E6H,000H ; K_D_4B
FCEE F06060606266FE00 5850 0B 0F0H,060H,060H,060H,062H,066H,0FEH,000H ; L_D_4C
FCD6 C6EEFFED6C6C6000 5851 0B 0C6H,0EEH,0FEH,0FEH,0D6H,0C6H,0C6H,000H ; M_D_4D
FCE6 C6F6F6DEFC6C6000 5852 0B 0C6H,0E6H,0F6H,0DEH,0CEH,0C6H,0C6H,000H ; N_D_4E
FCE6 386C6C6C6C6C3800 5853 0B 038H,06CH,0C6H,0C6H,0C6H,06CH,038H,000H ; O_D_4F
FCEE FC66667C6060F000 5854 0B 0FCH,066H,066H,07CH,060H,060H,0F0H,000H ; P_D_50
FCF6 78CCCCC0C781C000 5855 0B 078H,0CCH,0CCH,0CCH,0CCH,078H,01CH,000H ; Q_D_51
FCFE FC66667C6666E600 5856 0B 0FCH,066H,066H,07CH,06CH,066H,0E6H,00CH ; R_D_52
FD06 78CCE0701CC77800 5857 0B 078H,0CCH,0E0H,070H,01CH,0CCH,078H,000H ; S_D_53
FD0E FC84303030307800 5858 0B 0FCH,0B4H,030H,030H,030H,030H,078H,000H ; T_D_54
FD16 CCCCCCCCCC0C7800 5859 0B 0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,0CCH,000H ; U_D_55
FD1E CCCCCCCCCC783000 5860 0B 0CCH,0CCH,0CCH,0CCH,0CCH,078H,030H,000H ; V_D_56
FD26 C6C6C6D6FEEEC600 5861 0B 0C6H,0C6H,06CH,0D6H,0FEH,0EEH,0C6H,000H ; W_D_57
FD2E C6C6C638386C6000 5862 0B 0C6H,0C6H,06CH,038H,038H,06CH,0C6H,000H ; X_D_58
FD36 CCCCCC7830307800 5863 0B 0CCH,0CCH,0CCH,078H,030H,030H,078H,000H ; Y_D_59

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FD3E FEC68C18326FE00 5864 DB 0FEH,0C6H,08CH,018H,032H,066H,0FEH,000H ; Z D_5A
FD4E 7860606060607800 5865 DB 07BH,060H,060H,060H,060H,060H,07BH,000H ; I D_5B
FD4E C06030180C060200 5866 DB 0C0H,060H,030H,01BH,00CH,066H,002H,000H ; BACKSLASH D_5C
FD5E 7818181818187800 5867 DB 07BH,01BH,018H,018H,018H,018H,01BH,07BH,000H ; I D_5D
FD5E 10386C6000000000 5868 DB 010H,038H,06CH,DC6H,000H,000H,000H,000H ; CIRCUMFLEX D_5E
FD6E 00000000000000FF 5869 DB 000H,000H,000H,000H,000H,000H,000H,0FFH ; _ D_5F
FD6E 3030180000000000 5870 DB 030H,030H,018H,000H,000H,000H,000H,000H ; ' D_60
FD7E 0000780C7CC7600 5871 DB 000H,000H,078H,00CH,07CH,0CCH,076H,000H ; LOWER CASE A D_61
FD7E E060607C66660C00 5872 DB 0E0H,060H,060H,07CH,066H,066H,0DCH,000H ; L.C. B D_62
FD8E 000078CC0CCT7800 5873 DB D00H,D00H,078H,0CCH,DC0H,0CCH,078H,000H ; L.C. C D_63
FD8E 1C0C0C7CCCC7600 5874 DB 01CH,00CH,00CH,07CH,0CCH,0CCH,076H,000H ; L.C. D D_64
FD9E 000078CCFCC07800 5875 DB 000H,060H,078H,0CCH,0FCH,0C0H,078H,000H ; L.C. E D_65
FD9E 386C60F0660F000 5876 DB 038H,06CH,060H,0F0H,060H,060H,0F0H,000H ; L.C. F D_66
FDAE E9606C76666C000 5878 DB 000H,000H,076H,0CCH,0CCH,07CH,00CH,0F8H ; L.C. G D_67
FDAE E9606C76666C000 5878 DB 0E0H,060H,06CH,076H,066H,066H,0E6H,000H ; L.C. H D_68
FDB6 3000703030307800 5879 DB 030H,000H,070H,030H,030H,030H,078H,000H ; L.C. I D_69
FDBE 0C000C0C0C0C0C78 5880 DB 00CH,000H,00CH,00CH,0CCH,0CCH,0CCH,078H ; L.C. J D_6A
FDC6 E06066C786CE600 5881 DB 0E0H,060H,066H,06CH,078H,06CH,0E6H,000H ; L.C. K D_6B
FDC6 7030303030307800 5882 DB 070H,030H,030H,030H,030H,030H,078H,000H ; L.C. L D_6C
FDD6 0000CFFEFED6C600 5883 DB 000H,000H,0CCH,0FEH,0FEH,0D6H,0C6H,000H ; L.C. M D_6D
FDEE 0000FACCC0CC0000 5884 DB 000H,000H,0F8H,0CCH,0CCH,0CCH,0CCH,000H ; L.C. N D_6E
FDEE 000078CCCCC7800 5885 DB 000H,000H,078H,0CCH,0CCH,0CCH,078H,000H ; L.C. O D_6F
FDEE 0000DC66667C60F0 5886 DB 000H,000H,0DCH,066H,066H,07CH,060H,0F0H ; L.C. P D_70
FDFE 00007C00780CF800 5887 DB 000H,000H,076H,0CCH,0CCH,07CH,00CH,01EH ; L.C. Q D_71
FDFE 0000DC766660F000 5888 DB 000H,000H,00CH,076H,066H,060H,0F0H,000H ; L.C. R D_72
FE06 00007C00780CF800 5889 DB 000H,000H,07CH,0C0H,078H,00CH,0F8H,000H ; L.C. S D_73
FE0E 10307C30303A1800 5890 DB 010H,030H,07CH,030H,030H,034H,018H,000H ; L.C. T D_74
FE16 0000CCCCCCT7600 5891 DB 000H,000H,0CCH,0CCH,0CCH,0CCH,076H,000H ; L.C. U D_75
FE1E 0000CCCCC783000 5892 DB 000H,000H,0CCH,0CCH,0CCH,078H,030H,000H ; L.C. V D_76
FE26 0000C6D6FEFE6C00 5893 DB 000H,000H,0C6H,0D6H,0FEH,0FEH,06CH,000H ; L.C. W D_77
FE2E 0000C66C386CC600 5894 DB 000H,000H,0C6H,06CH,038H,06CH,06CH,000H ; L.C. X D_78
FE3E 0000CCCCC7C0CF80 5895 DB 000H,000H,0CCH,0CCH,0CCH,07CH,00CH,0F8H ; L.C. Y D_79
FE3E 0000F983064FC00 5896 DB 000H,000H,0FCH,098H,030H,064H,0FCH,000H ; L.C. Z D_7A
FE4E 1C3030E030301C00 5897 DB 01CH,030H,030H,0E0H,030H,030H,01CH,000H ; _ 0_7B
FE4E 1818180018181800 5898 DB 018H,018H,018H,000H,018H,018H,018H,000H ; _ 0_7C
FE5E E030301C3030E000 5899 DB 0E0H,030H,030H,01CH,030H,030H,0E0H,000H ; _ 0_7D
FE5E 76DC000000000000 5900 DB 076H,0DCH,000H,000H,000H,000H,000H,000H ; TILDE D_7E
FE6E 0010386CC6C6FE00 5901 DB 000H,010H,038H,06CH,0C6H,0C6H,0FEH,000H ; DELTA D_7F

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5902
5903 ;--- INT 1A -----
5904 ; TIME_OF_DAY
5905 ; THIS ROUTINE ALLDWS THE CLOCK TO BE SET/READ
5906 ;
5907 ; INPUT
5908 ; (AH) = 0 READ THE CURRENT CLOCK SETTING
5909 ; RETURNS CX = HIGH PORTION OF COUNT
5910 ;          DX = LOW PORTION OF COUNT
5911 ;          AL = 0 IF TIMER HAS NOT PASSED
5912 ;          24 HOURS SINCE LAST READ
5913 ;          <0 IF ON ANOTHER DAY
5914 ; (AH) = 1 SET THE CURRENT CLOCK
5915 ;          CX = HIGH PORTION OF COUNT
5916 ;          DX = LOW PORTION OF COUNT
5917 ; NOTE: COUNTS OCCUR AT THE RATE OF
5918 ;       1193180/65536 COUNTS/SEC
5919 ;       (OR ABOUT 18.2 PER SECONDD -- SEE EQUATES BELOW)
5920 ;-----

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FE6E          ASSUME CS:CODE,DS:DATA
FE6E          ORG 0FE6EH
FE6E          TIME_DF_DAY  PRDC  FAR
FE6E FB          STI          ; INTERRUPTS BACK ON
FE6F 1E          PUSH DS      ; SAVE SEGMENT
FE70 EACB00      CALL D0S
FE73 0AE4        DR AH,AH      ; AH=0
FE75 7407        JZ T2         ; READ_TIME
FE77 FECC        DEC AH        ; AH=1
FE79 7416        JZ T3         ; SET_TIME
FE7B            T1:           ; TOD_RETURN
FE7B FB          STI          ; INTERRUPTS BACK ON
FE7C 1F          POP DS       ; RECOVER SEGMENT
FE7D CF          IRET         ; RETURN TO CALLER
FE7E            T2:           ; READ_TIME
FE7E FA          CLI          ; NO TIMER INTERRUPTS WHILE READING
FE7F A07000      MOV AL,TIMER_DFL
FE82 C06700000   MOV TIMER_DFL,0 ; GET OVERFLOW, AND RESET THE FLAG
FE87 8B0E6E00    MOV CX,TIMER_HIGH
FE88 8B16C000    MOV DX,TIMER_LOW

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LOC OBJ	LINE	SOURCE
FE0F EBFA	5941	JMP T1 ; TOD_RETURN
FE91	5942	T3: SET_TIME
FE91 FA	5943	CLI ; NO INTERRUPTS WHILE WRITING
FE92 8916C00	5944	MOV TIMER_LOW,0X
FE96 8906E00	5945	MOV TIMER_HIGH,CX ; SET THE TIME
FE9A C606700000	5946	MOV TIMER_OFL,0 ; RESET OVERFLOW
FE9F EBDA	5947	JMP T1 ; TOD_RETURN
	5948	TIME_OF_OAY ENDP
	5949	
	5950	;
	5951	; THIS ROUTINE HANDLES THE TIMER INTERRUPT FROM ;
	5952	; CHANNEL 0 OF THE 8253 TIMER. INPUT FREQUENCY ;
	5953	; IS 1.19318 MHZ AND THE DIVISOR IS 65536, RESULTING ;
	5954	; IN APPROX. 18.2 INTERRUPTS EVERY SECOND. ;
	5955	;
	5956	; THE INTERRUPT HANDLER MAINTAINS A COUNT OF INTERRUPTS ;
	5957	; SINCE POWER ON TIME, WHICH MAY BE USED TO ESTABLISH ;
	5958	; TIME OF DAY. ;
	5959	; THE INTERRUPT HANDLER ALSO DECREMENTS THE MOTOR ;
	5960	; CONTROL COUNT OF THE DISKETTE, AND WHEN IT EXPIRES, ;
	5961	; WILL TURN OFF THE DISKETTE MOTOR, AND RESET THE ;
	5962	; MOTOR RUNNING FLAGS. ;
	5963	; THE INTERRUPT HANDLER WILL ALSO INVOKE A USER ROUTINE ;
	5964	; THROUGH INTERRUPT ICH AT EVERY TIME TICK. THE USER ;
	5965	; MUST CODE A ROUTINE AND PLACE THE CORRECT ADDRESS IN ;
	5966	; THE VECTOR TABLE. ;
	5967	;
FEA5	5968	ORG OFEA5H
FEA5	5969	TIMER_INT PROC FAR
FEA5 FB	5970	STI ; INTERRUPTS BACK ON
FEA6 1E	5971	PUSH OS
FEA7 50	5972	PUSH AX
FEA8 52	5973	PUSH DX ; SAVE MACHINE STATE
FEA9 E89200	5974	CALL DDS
FEAC FF066C00	5975	INC TIMER_LOW ; INCREMENT TIME
FEBO 7504	5976	JNZ T4 ; TEST_DAY
FEB2 FF066E00	5977	INC TIMER_HIGH ; INCREMENT HIGH WORD OF TIME
FEB6	5978	T4: ; TEST_DAY
FEBA 833E6E0018	5979	CHP TIMER_HIGH,018H ; TEST FOR COUNT EQUALING 24 HOURS
FEBB 7515	5980	JHZ T5 ; DISKETTE_CTL
FEBD 813E6C00B000	5981	CHP TIMER_LOW,0B0H
FEC3 750D	5982	JHZ T5 ; DISKETTE_CTL
	5983	
	5984	;
	5985	;----- TIMER HAS GONE 24 HOURS
FEC5 2BC0	5986	SUB AX,AX
FEC7 A36E00	5987	MOV TIMER_HIGH,AX
FECA A36C00	5988	MOV TIMER_LOW,AX
FEC0 C606700001	5989	MOV TIMER_OFL,1
	5990	
	5991	;
	5992	;----- TEST FOR DISKETTE TIME OUT
FED2	5993	T3: ; DISKETTE_CTL
FED2 FE0E4000	5994	DEC MOTOR_COUNT
FED6 750B	5995	JNZ T6 ; RETURN IF COUNT NOT OUT
FED8 80263F00F0	5996	AND MOTOR_STATUS,0F0H ; TURN OFF MOTOR RUNNING BITS
FEDD 800C	5997	MOV AL,0CH
FEDF BAF203	5998	MOV DX,03F2H ; FDC CTL PORT
FE22 EE	5999	OUT DX,AL ; TURN OFF THE MOTOR
FE23	6000	T6: ; TIMER_RET;
FE23 CD1C	6001	INT ICH ; TRANSFER CONTROL TO A USER ROUTINE
FE25 B020	6002	MOV AL,EDI
FE27 E620	6003	OUT 020H,AL ; END OF INTERRUPT TO 8259
FE29 5A	6004	POP CX
FE2A 5B	6005	POP AX
FE2B 1F	6006	POP OS ; RESET MACHINE STATE
FE2C CF	6007	IRET ; RETURN FROM INTERRUPT
	6008	TIMER_INT ENDP
	6009	
FEED 31363031	6010	F3B 0B '1801',13,10
FEF1 00		
FEF2 0A		
	6011	
	6012	;
	6013	; THESE ARE THE VECTORS WHICH ARE MOVED INTO ;
	6014	; THE 6086 INTERRUPT AREA DURING POWER ON. ;
	6015	; ONLY THE OFFSETS ARE DISPLAYED HERE. CODE SEGMENT ;

```

6016 ; WILL BE ADDED FOR ALL OF THEM, EXCEPT WHERE NOTED ;
6017 ;-----
6018 ASSUME CS:CODE
6019 ORG 0FEF3N
FEF3 VECTOR_TABLE LABEL WORD ; VECTOR TABLE FOR MOVE TO INTERRUPTS
FEF3 A5FE 6021 DW OFFSET TIMER_INT ; INTERRUPT 8
FEF5 87E9 6022 DW OFFSET KB_INT ; INTERRUPT 9
FEF7 0DE6 6023 DW OFFSET 0_EOI ; INTERRUPT A
FEF9 0DE6 6024 DW OFFSET 0_EOI ; INTERRUPT B
FEFB 0DE6 6025 DW OFFSET 0_EOI ; INTERRUPT C
FEFD 0DE6 6026 DW OFFSET 0_EOI ; INTERRUPT D
FEFF 57EF 6027 DW OFFSET DISK_INT ; INTERRUPT E
FF01 0DE6 6028 DW OFFSET 0_EOI ; INTERRUPT F
FF03 65F0 6029 DW OFFSET VIDEO_IO ; INTERRUPT 10H
FF05 40F8 6030 DW OFFSET EQUIPMENT ; INTERRUPT 11H
FF07 41F8 6031 DW OFFSET MEMORY_SIZE_OET ; INTERRUPT 12H
FF09 59EC 6032 DW OFFSET DISKETTE_IO ; INTERRUPT 13H
FF0B 39E7 6033 DW OFFSET RS232_IO ; INTERRUPT 14H
FF0D 59F8 6034 DW OFFSET CASSETTE_IO ; INTERRUPT 15H
FF0F 2EE8 6035 DW OFFSET KEYBOARD_IO ; INTERRUPT 16N
FF11 D2EF 6036 DW OFFSET PRINTER_IO ; INTERRUPT 17H
6037
FF13 0000 6038 DW 00000N ; INTERRUPT 18H
6039 ; DW 0F600H ; MUST BE INSERTED INTO TABLE LATER
6040
FF15 F2E6 6041 DW OFFSET BOOT_STRAP ; INTERRUPT 19H
FF17 6EFE 6042 DW TIME_OF_DAY ; INTERRUPT 1AH -- TIME OF DAY
FF19 53FF 6043 DW DUMMY_RETURN ; INTERRUPT 1BH -- KEYBOARD BREAK ADDR
FF1B 53FF 6044 DW DUMMY_RETURN ; INTERRUPT 1C -- TIMER BREAK ADDR
FF1D A4F0 6045 DW VIDEO_PARMS ; INTERRUPT 1D -- VIDEO PARAMETERS
FF1F C7EF 6046 DW OFFSET DISK_BASE ; INTERRUPT 1E -- DISK PARMS
FF21 0000 6047 DW 0 ; INTERRUPT 1F -- POINTER TO VIDEO EXT
6048
FF23 50415249545920 6049 D2 DB 'PARITY CHECK 1',13,10
43484543482031
FF31 0D
FF32 0A
FF33 20333031 6050 F1 DB '301',13,10
FF37 0D
FF38 0A
FF39 313331 6051 F2 DB '131',13,10
FF3C 0D
FF3D 0A
6052
FF3E 6053 DDS PROC NEAR
FF3E 50 6054 PUSH AX ; SAVE AX
FF3F B84000 6055 MOV AX,DATA ; SET DATA SEGMENT
FF42 8EDB 6056 MOV DS,AX ; RESTORE AX
FF44 58 6057 POP AX
FF45 C3 6058 RET
6059 DDS ENDP
6060
6061 ;-----
6062 ; TEMPORARY INTERRUPT SERVICE ROUTINE ;
6063 ;-----
FF47 6064 ORG 0FF47H
FF47 6065 D11 PROC NEAR
FF47 B401 6066 MOV AH,1
FF49 50 6067 PUSH AX ; SAVE REG AX CONTENTS
FF4A B0FF 6068 MOV AL,0FFH ; MASK ALL INTERRUPTS OFF
FF4C E621 6069 DUT INTA01,AL
FF4E B020 6070 MOV AL,EOI
FF50 E620 6071 OUT INTA00,AL
FF52 58 6072 POP AX ; RESTORE REG AX CONTENTS
FF53 6073 DUMMY_RETURN: ; NEED IRET FOR VECTOR TABLE
FF53 CF 6074 IRET
6075 D11 ENDP
6076
6077 ;-- INT 5 -----
6078 ; THIS LOGIC WILL BE INVOKED BY INTERRUPT 05N TO PRINT THE ;
6079 ; SCREEN. THE CURSOR POSITION AT THE TIME THIS ROUTINE IS INVOKED ;
6080 ; WILL BE SAVED AND RESTORED UPON COMPLETION. THE ROUTINE IS ;
6081 ; INTENDED TO RUN WITH INTERRUPTS ENABLED. IF A SUBSEQUENT ;
6082 ; 'PRINT SCREEN' KEY IS DEPRESSED DURING THE TIME THIS ROUTINE ;
6083 ; IS PRINTING IT WILL BE IGNORED. ;
6084 ; ADDRESS 50:0 CONTAINS THE STATUS OF THE PRINT SCREEN: ;
6085 ; ;

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6086 ; 50:0 =D EITHER PRINT SCREEN HAS NOT BEEN CALLED ;
6087 ; OR UPON RETURN FROM A CALL THIS INDICATES ;
6088 ; A SUCCESSFUL OPERATION. ;
6089 ; =I PRINT SCREEN IS IN PROGRESS ;
6090 ; =255 ERROR ENCOUNTERED DURING PRINTING ;
6091 ; -----
6092 ASSUME CS:CODE,DS:X00DATA
FF54 6093 ORG OFF54H
FF54 6094 PRINT_SCREEN PROC FAR
FF54 FB 6095 STI ; MUST RUN WITH INTERRUPTS ENABLED
FF55 1E 6096 PUSH DS ; MUST USE 50:0 FOR DATA AREA STORAGE
FF56 50 6097 PUSH AX
FF57 53 6098 PUSH BX
FF58 51 6099 PUSH CX ; WILL USE THIS LATER FOR CURSOR LIMITS
FF59 52 6100 PUSH DX ; WILL HOLD CURRENT CURSOR POSITION
FF5A 885000 6101 MOV AX,X00DATA ; HEX 50
FF5D 8ED8 6102 MOV DS,AX
FF5F 803E000001 6103 CMP STATUS_BYTE,1 ; SEE IF PRINT ALREADY IN PROGRESS
FF64 745F 6104 JZ EXIT ; JUMP IF PRINT ALREADY IN PROGRESS
FF66 C06000001 6105 MOV STATUS_BYTE,1 ; INDICATE PRINT NOW IN PROGRESS
FF68 840F 6106 MOV AH,15 ; WILL REQUEST THE CURRENT SCREEN MODE
FF6D C010 6107 INT 10H ; [AL]=MODE
6108 ; [AH]=NUMBER COLUMNS/LINE
6109 ; [BH]=VISUAL PAGE
6110 ; -----
6111 ; AT THIS POINT WE KNOW THE COLUMNS/LINE ARE IN ;
6112 ; [AX] AND THE PAGE IF APPLICABLE IS IN [BH]. THE STACK ;
6113 ; HAS DS,AX,BX,CX,DX PUSHED. [AL] HAS VIDEO MODE ;
6114 ; -----
FF6F 8ACC 6115 MOV CL,AH ; WILL MAKE USE OF [CX] REGISTER TO
FF71 B519 6116 MOV CH,25 ; CONTROL ROW & COLUMNS
FF73 E85500 6117 CALL CRLF ; CARRIAGE RETURN LINE FEED ROUTINE
FF76 51 6118 PUSH CX ; SAVE SCREEN BOUNDS
FF77 B403 6119 MOV AH,3 ; WILL NOW READ THE CURSOR.
FF79 C010 6120 INT 10H ; AND PRESERVE THE POSITION
FF7B 59 6121 POP CX ; RECALL SCREEN BOUNDS
FF7C 52 6122 PUSH DX ; RECALL [BH]=VISUAL PAGE
FF7D 3302 6123 XOR CX,CX ; WILL SET CURSOR POSITION TO [0,0]
6124 ; -----
6125 ; THE LOOP FROM PRI10 TO THE INSTRUCTION PRIOR TO PRI20 ;
6126 ; IS THE LOOP TO READ EACH CURSOR POSITION FROM THE ;
6127 ; SCREEN AND PRINT. ;
6128 ; -----
FF7F 6129 PRI10:
FF7F B402 6130 MOV AH,2 ; TO INDICATE CURSOR SET REQUEST
FF81 C010 6131 INT 10H ; NEW CURSOR POSITION ESTABLISHED
FF83 B408 6132 MOV AH,8 ; TO INDICATE READ CHARACTER
FF85 C010 6133 INT 10H ; CHARACTER NOW IN [AL]
FF87 0AC0 6134 OR AL,AL ; SEE IF VALID CHAR
FF89 7502 6135 JNZ PRI15 ; JUMP IF VALID CHAR
FF8B B020 6136 MOV AL,' ' ; MAKE A BLANK
FF8D 6137 PRI15:
FF8D 52 6138 PUSH DX ; SAVE CURSOR POSITION
FF8E 3302 6139 XOR DX,DX ; INDICATE PRINTER 1
FF90 32E4 6140 XOR AH,AH ; TO INDICATE PRINT CHAR IN [AL]
FF92 C017 6141 INT 17H ; PRINT THE CHARACTER
FF94 5A 6142 POP DX ; RECALL CURSOR POSITION
FF95 F6C425 6143 TEST AN,25H ; TEST FOR PRINTER ERROR
FF98 7521 6144 JNZ ERR1D ; JUMP IF ERROR DETECTED
FF9A FEC2 6145 INC DL ; ADVANCE TO NEXT COLUMN
FF9C 3ACA 6146 CMP CL,DL ; SEE IF AT END OF LINE
FF9E 75DF 6147 JNZ PRI1D ; IF NOT PROCEED
FFA0 3202 6148 XOR DL,DL ; BACK TO COLUMN 0
FFA2 8AE2 6149 MOV AH,0L ; [AH]=0
FFA4 52 6150 PUSH DX ; SAVE NEW CURSOR POSITION
FFA5 E82300 6151 CALL CRLF ; LINE FEED CARRIAGE RETURN
FFA8 5A 6152 POP DX ; RECALL CURSOR POSITION
FFA9 FEC6 6153 INC DH ; ADVANCE TO NEXT LINE
FFAB 3AEE 6154 CMP CH,DH ; FINISHED?
FFAD 7500 6155 JNZ PRI2D ; IF NOT CONTINUE
FFAF 6156 PRI20:
FFAF 5A 6157 POP DX ; RECALL CURSOR POSITION
FFB0 B402 6158 MOV AH,2 ; TO INDICATE CURSOR SET REQUEST
FFB2 C010 6159 INT 10H ; CURSOR POSITION RESTORED
FFB4 C060000000 6160 MOV SYSTATUS_BYTE,0 ; INDICATE FINISHED
FFB9 E80A 6161 JMP SHORLY_EXIT ; EXIT THE ROUTINE
FFBB 6162 ERR1D:

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LOC OBJ	LINE	SOURCE	
FFBB SA	6163	POP	DX ; GET CURSOR POSITION
FFBC B402	6164	MOV	AX,2 ; TO REQUEST CURSOR SET
FFBE CD10	6165	INT	10H ; CURSOR POSITION RESTORED
FFC0	6166	ERR20:	
FFC0 C6060000FF	6167	MOV	STATUS_BYTE,0FFH ; INDICATE ERROR
FFC5	6168	EXIT:	
FFC5 SA	6169	POP	DX ; RESTORE ALL THE REGISTERS USED
FFC6 59	6170	PDP	CX
FFC7 5B	6171	PDP	BX
FFC8 58	6172	PDP	AX
FFC9 1F	6173	PDP	DS
FFCA CF	6174	IRET	
	6175	PRINT_SCREEN	ENDP
	6176		
	6177	;----- CARRIAGE RETURN, LINE FEED SUBROUTINE	
	6178		
FFCB	6179	CRLF	PROC NEAR
FFCB 3302	6180	XOR	DX,DX ; PRINTER 0
FFCD 32E4	6181	XOR	AX,AX ; WILL NOW SEND INITIAL LF,CR
	6182		; TO PRINTER
FFCF B00A	6183	MOV	AL,12Q ; LF
FFD1 CD17	6184	INT	17H ; SEND THE LINE FEED
FFD3 32E4	6185	XOR	AX,AX ; NOW FOR THE CR
FFD5 B00D	6186	MOV	AL,15Q ; CR
FFD7 CD17	6187	INT	17H ; SEND THE CARRIAGE RETURN
FFD9 C3	6188	RET	
	6189	CRLF	ENDP
	6190		
FFDA 50415249545920 43484543482032	6191	D1	DB 'PARITY CHECK 2',13,10
FFE8 0D			
FFE9 0A			
FFEA 363031	6192	F3	DB '601',13,10
FFED 0D			
FFEE 0A			
	6193		
----	6194	CODE	ENDS
	6195		
	6196		;-----
	6197		; POWER ON RESET VECTOR ;
	6198		;-----
----	6199	VECTOR	SEGMENT AT 0FFFFH
	6200		
	6201		;----- POWER ON RESET
	6202		
0000 EABE000F0	6203	JMP	RESET
	6204		
0005 31302F32372F38 32	6205	DB	'10/27/82' ; RELEASE MARKER
----	6206	VECTOR	ENDS
	6207		END

```

1  $TITLE(FIXED DISK BIOS FOR IBM DISK CONTROLLER)
2
3  |-- INT 13 -----
4  |
5  | FIXED DISK I/O INTERFACE
6  |
7  | THIS INTERFACE PROVIDES ACCESS TO 5 1/4" FIXED DISKS
8  | THROUGH THE IBM FIXED DISK CONTROLLER.
9  |
10 |-----
11
12 |-----
13 | THE BIOS ROUTINES ARE MEANT TO BE ACCESSED THROUGH
14 | SOFTWARE INTERRUPTS ONLY. ANY ADDRESSES PRESENT IN
15 | THE LISTINGS ARE INCLUDED ONLY FOR COMPLETENESS,
16 | NOT FOR REFERENCE. APPLICATIONS WHICH REFERENCE
17 | ABSOLUTE ADDRESSES WITHIN THE CODE SEGMENT
18 | VIOLATE THE STRUCTURE AND DESIGN OF BIOS.
19 |-----
20 |
21 | INPUT (AH = HEX VALUE)
22 |
23 | (AH)=00 RESET DISK (OL = 80H,81H) / DISKETTE
24 | (AH)=01 READ THE STATUS OF THE LAST DISK OPERATION INTO (AL)
25 | NOTE: OL < 80H = DISKETTE
26 | OL > 80H = DISK
27 | (AH)=02 READ THE DESIRED SECTORS INTO MEMORY
28 | (AH)=03 WRITE THE DESIRED SECTORS FROM MEMORY
29 | (AH)=04 VERIFY THE DESIRED SECTORS
30 | (AH)=05 FORMAT THE DESIRED TRACK
31 | (AH)=06 FORMAT THE DESIRED TRACK AND SET BAD SECTOR FLAGS
32 | (AH)=07 FORMAT THE DRIVE STARTING AT THE DESIRED TRACK
33 | (AH)=08 RETURN THE CURRENT DRIVE PARAMETERS
34 |
35 | (AH)=09 INITIALIZE DRIVE PAIR CHARACTERISTICS
36 | INTERRUPT 41 POINTS TO DATA BLOCK
37 | (AH)=0A READ LONG
38 | (AH)=0B WRITE LONG
39 | NOTE: READ AND WRITE LONG ENCOMPASS 512 + 4 BYTES ECC
40 | (AH)=0C SEEK
41 | (AH)=0D ALTERNATE DISK RESET (SEE OL)
42 | (AH)=0E READ SECTOR BUFFER
43 | (AH)=0F WRITE SECTOR BUFFER,
44 | (RECOMMENDED PRACTICE BEFORE FORMATTING)
45 | (AH)=10 TEST DRIVE READY
46 | (AH)=11 RECALIBRATE
47 | (AH)=12 CONTROLLER RAM DIAGNOSTIC
48 | (AH)=13 DRIVE DIAGNOSTIC
49 | (AH)=14 CONTROLLER INTERNAL DIAGNOSTIC
50 |
51 | REGISTERS USED FOR FIXED DISK OPERATIONS
52 |
53 | (DL) - DRIVE NUMBER (80H-87H FOR DISK, VALUE CHECKED)
54 | (DH) - HEAD NUMBER (0-7 ALLOWED, NOT VALUE CHECKED)
55 | (CH) - CYLINDER NUMBER (0-1023, NOT VALUE CHECKED)(SEE CL)
56 | (CL) - SECTOR NUMBER (1-17, NOT VALUE CHECKED)
57 |
58 | NOTE: HIGH 2 BITS OF CYLINDER NUMBER ARE PLACED
59 | IN THE HIGH 2 BITS OF THE CL REGISTER
60 | (10 BITS TOTAL)
61 | (AL) - NUMBER OF SECTORS (MAXIMUM POSSIBLE RANGE 1-80H,
62 | FOR READ/WRITE LONG 1-7FH)
63 | (INTERLEAVE VALUE FOR FORMAT 1-16H)
64 | (ES:BX) - ADDRESS OF BUFFER FOR READS AND WRITES,
65 | (NOT REQUIRED FOR VERIFY)
66 |
67 | OUTPUT
68 | AN = STATUS OF CURRENT OPERATION
69 | STATUS BITS ARE DEFINED IN THE EQUATES BELOW
70 | CY = 0 SUCCESSFUL OPERATION (AN=0 ON RETURN)
71 | CY = 1 FAILED OPERATION (AH HAS ERROR REASON)
72 |
73 | NOTE: ERROR 11H INDICATES THAT THE DATA READ HAD A RECOVERABLE
74 | ERROR WHICH WAS CORRECTED BY THE ECC ALGORITHM. THE DATA
75 | IS PROBABLY GOOD, HOWEVER THE BIOS ROUTINE INDICATES AN
76 | ERROR TO ALLOW THE CONTROLLING PROGRAM A CHANCE TO DECIDE
77 | FOR ITSELF. THE ERROR MAY NOT RECUR IF THE DATA IS

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78 | REWRITTEN. (AL) CONTAINS THE BURST LENGTH.
79 |
80 | IF DRIVE PARAMETERS WERE REQUESTED.
81 |
82 | DL = NUMBER OF CONSECUTIVE ACKNOWLEDGING DRIVES ATTACHED (0-21
83 | (CONTROLLER CARD ZERO TALLY ONLY)
84 | DH = MAXIMUM USEABLE VALUE FOR HEAD NUMBER
85 | CH = MAXIMUM USEABLE VALUE FOR CYLINDER NUMBER
86 | CL = MAXIMUM USEABLE VALUE FOR SECTOR NUMBER
87 | AND CYLINDER NUMBER HIGH BITS
88 |
89 | REGISTERS WILL BE PRESERVED EXCEPT WHEN THEY ARE USED TO RETURN
90 | INFORMATION.
91 |
92 | NOTE: IF AN ERROR IS REPORTED BY THE DISK CODE, THE APPROPRIATE
93 | ACTION IS TO RESEY THE DISK, THEN RETRY THE OPERATION.
94 |
95 |-----
96 |
00FF 97 SENSE_FAIL EQU 0FFH ; SENSE OPERATION FAILED
00B8 98 UNDEF_ERR EQU 0BDH ; UNDEFINED ERROR OCCURRED
0080 99 TIME_OUT EQU 80H ; ATTACHMENT FAILED TO RESPOND
0040 100 BAD_SEEK EQU 40H ; SEEK OPERATION FAILED
0020 101 BAD_CHTLR EQU 20H ; CONTROLLER HAS FAILED
0011 102 DATA_CORRECTED EQU 11H ; ECC CORRECTED DATA ERROR
0010 103 BAD_ECC EQU 10H ; BAD ECC ON DISK READ
0008 104 BAD_TRACK EQU 08H ; BAD TRACK FLAG DETECTED
0009 105 DMA_BOUNDARY EQU 09H ; ATTEMPT TO DMA ACROSS 64K BOUNDARY
0007 106 INIT_FAIL EQU 07H ; DRIVE PARAMETER ACTIVITY FAILED
0005 107 BAD_RESEY EQU 05H ; RESEY FAILED
0004 108 RECORD_NOT_FND EQU 04H ; REQUESTED SECTOR NOT FOUND
0002 109 BAD_ADDR_MARK EQU 02H ; ADDRESS MARK NOT FOUND
0001 110 BAD_CMD EQU 01H ; BAD COMMAND PASSED TO DISK I/O
111
112 |-----
113 | INTERRUPT AND STATUS AREAS :
114 |-----
115
---- 116 DUMMY SEGMENT AT 0
0034 117 ORG 00H*4 ; FIXED DISK INTERRUPT VECTOR
0034 118 HDISK_INT LABEL DWORD
004C 119 ORG 13H*4 ; DISK INTERRUPT VECTOR
004C 120 ORG_VECTOR LABEL DWORD
0064 121 ORG 19H*4 ; BOOTSTRAP INTERRUPT VECTOR
0064 122 BOOT_VEC LABEL DWORD
0078 123 ORG 1EH*4 ; DISKETTE PARAMETERS
0078 124 DISKETTE_PARM LABEL DWORD
0100 125 ORG 040H*4 ; NEW DISKETTE INTERRUPT VECTOR
0100 126 DISK_VECTOR LABEL DWORD
0104 127 ORG 041H*4 ; FIXED DISK PARAMETER VECTOR
0104 128 HF_TBL_VEC LABEL DWORD
7C00 129 ORG 7C00H ; BOOTSTRAP LOADER VECTOR
7C00 130 BOOT_LOCH LABEL FAR
---- 131 DUMMY ENDS
132
---- 133 DATA SEGMENT AT 40H
0042 134 ORG 42H
0042 135 CMD_BLOCK LABEL BYTE
0042 (7 ??) 136 HD_ERROR DB 7 DUP(?) ; OVERLAYS DISKETTE STATUS
006C 137 ORG 06CH
006C ??? 138 TIMER_LOW DW ? ; TIMER LOW WORD
0072 139 ORG 72H
0072 ??? 140 RESET_FLAG DW ? ; 1234H IF KEYBOARD RESET UNDERWAY
0074 141 ORG 74H
0074 ?? 142 DISK_STATUS DB ? ; FIXED DISK STATUS BYTE
0075 ?? 143 HF_NUM DB ? ; COUNT OF FIXED DISK DRIVES
0076 ?? 144 CONTROL_BYTE DB ? ; CONTROL BYTE DRIVE OPTIONS
0077 ?? 145 PORT_OFF DB ? ; PORT OFFSET
---- 146 DATA ENDS
147
---- 148 CODE SEGMENT
149
150 |-----
151 | HARDWARE SPECIFIC VALUES :
152 | :
153 | - CONTROLLER I/O PORT :
154 | > WHEN READ FROM: :

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```

155 | HF_PORT+0 - READ DATA (FROM CONTROLLER TO CPU) :
156 | HF_PORT+1 - READ CONTROLLER HARDWARE STATUS :
157 | (CONTROLLER TO CPU) :
158 | HF_PORT+2 - READ CONFIGURATION SWITCHES :
159 | HF_PORT+3 - NOT USED :
160 | > WHEN WRITTEN TO: :
161 | HF_PORT+0 - WRITE DATA (FROM CPU TO CONTROLLER) :
162 | HF_PORT+1 - CONTROLLER RESET :
163 | HF_PORT+2 - GENERATE CONTROLLER SELECT PULSE :
164 | HF_PORT+3 - WRITE PATTERN TO DMA AND INTERRUPT :
165 | MASK REGISTER :
166 | :
167 | -----
168
0320 169 HF_PORT EQU 0320H ; DISK PORT
0008 170 RI_BUSY EQU 00001000B ; DISK PORT 1 BUSY BIT
0004 171 RI_BUSY EQU 00000100B ; COMMAND/DATA BIT
0002 172 RI_IOMODE EQU 00000010B ; MODE BIT
0001 173 RI_REQ EQU 00000001B ; REQUEST BIT
174
0047 175 DMA_READ EQU 01000111B ; CHANNEL 3 (047H)
0048 176 DMA_WRITE EQU 01001011B ; CHANNEL 3 (04BH)
0000 177 DMA EQU 0 ; DMA ADDRESS
0082 178 DMA_HIGH EQU 082H ; PORT FOR HIGH 4 BITS OF DMA
179
0000 180 TST_ROY_CMD EQU 00000000B ; CNTLR READY (00H)
0001 181 RECAL_CMD EQU 00000001B ; RECAL (01H)
0003 182 SENSE_CMD EQU 00000011B ; SENSE (03H)
0004 183 FMTDRV_CMD EQU 00000100B ; DRIVE (04H)
0005 184 CHK_TRK_CMD EQU 00000101B ; T CHK (05H)
0006 185 FMTTRK_CMD EQU 00000110B ; TRACK (06H)
0007 186 FMTBAQ_CMD EQU 00000111B ; BAD (07H)
0008 187 READ_CMD EQU 00001000B ; READ (08H)
000A 188 WRITE_CMD EQU 00001010B ; WRITE (0AH)
000B 189 SEEK_CMD EQU 00001011B ; SEEK (0BH)
000C 190 INIT_ORV_CMD EQU 00001100B ; INIT (0CH)
000D 191 RD_ECC_CMD EQU 00001101B ; BURST (0DH)
000E 192 RD_BUFF_CMD EQU 00001110B ; BUFFER (0EH)
000F 193 WR_BUFF_CMD EQU 00001111B ; BUFFER (0FH)
00E0 194 RAM_DIAG_CMD EQU 11100000B ; RAM (E0H)
00E3 195 CHK_ORV_CMD EQU 11100011B ; DRV (E3H)
00E4 196 CNTLR_DIAG_CMD EQU 11100100B ; CNTLR (E4H)
00E5 197 RD_LONG_CMD EQU 11100101B ; RLONG (E5H)
00E6 198 WR_LONG_CMD EQU 11100110B ; WLONG (E6H)
199
0020 200 INT_CTL_PORT EQU 20H ; 8259 CONTROL PORT
0020 201 EOI EQU 20H ; END OF INTERRUPT COMMAND
202
0006 203 MAX_FILE EQU 8
0002 204 S_MAX_FILE EQU 2
205
206 ASSUME CS:CODE
207 ORG 0H
0000 55 208 DB 055H ; GENERIC BIOS HEADER
0001 AA 209 DB 0AAH
0002 10 210 DB 16D
211
212 ;-----
213 ; FIXED DISK I/O SETUP :
214 | :
215 | - ESTABLISH TRANSFER VECTORS FOR THE FIXED DISK :
216 | - PERFORM POWER ON DIAGNOSTICS :
217 | SHOULD AN ERROR OCCUR A "1701" MESSAGE IS DISPLAYED :
218 | :
219 | -----
220
0003 221 DISK_SETUP PROC FAR
0003 EB1E 222 JMP SHORT L3
0005 35303030303539 223 DB '5000059 (C)COPYRIGHT IBM 1982' ; COPYRIGHT NOTICE
20284329434F50
59524947485420
2049424D203139
3832
0023 224 L3:
225 ASSUME 05:DUPPLY
226 SUB AX,AX ; ZERO
0023 2B00 227 MOV 05,AX
0025 6E06

```

LOC	OBJ	LINE	SOURCE
0027	FA	228	CLI
0028	A14C00	229	MOV AX,H0R0 PTR ORG_VECTOR ; GET DISKETTE VECTOR
002B	A30001	230	MOV H0R0 PTR DISK_VECTOR,AX ; INTO INT 40H
002E	A14E00	231	MOV AX,H0R0 PTR ORG_VECTOR+2
0031	A30201	232	MOV WORD PTR DISK_VECTOR+2,AX
0034	C7064C005602	233	MOV WORD PTR ORG_VECTOR, OFFSET DISK_IO ; HDISK HANDLER
003A	8C0E4E00	234	MOV WORD PTR ORG_VECTOR+2,CS
003E	B86007	235	MOV AX, OFFSET H0_INT ; HDISK INTERRUPT
0041	A33400	236	MOV WORD PTR HDISK_INT,AX
0044	8C0E3E00	237	MOV WORD PTR HDISK_INT+2,CS
0048	C70664008601	238	MOV WORD PTR BOOT_VEC,OFFSET BOOT_STRAP ; BOOTSTRAP
004E	8C0E6E00	239	MOV WORD PTR BOOT_VEC+2,CS
0052	C7060401E703	240	MOV WORD PTR HF_TBL_VEC,OFFSET FO_TBL ; PARAMETER TBL
0058	8C0E0E01	241	MOV WORD PTR HF_TBL_VEC+2,CS
005C	FB	242	STI
		243	
		244	ASSUME DS:DATA
005D	B84000	245	MOV AX,DATA ; ESTABLISH SEGMENT
0060	8E08	246	MOV DS,AX
0062	C606740000	247	MOV DISK_STATUS,0 ; RESET THE STATUS INDICATOR
0067	C606750000	248	MOV HF_NUM,0 ; ZERO COUNT OF DRIVES
006C	C606430000	249	MOV CHD_BLOCK+1,0 ; DRIVE ZERO, SET VALUE IN BLOCK
0071	C606770000	250	MOV PORT_OFF,0 ; ZERO CARO OFFSET
		251	
0076	B92500	252	MOV CX,25H ; RETRY COUNT
0079		253	
0079	E8F200	254	L4: CALL H0_RESET_I ; RESET CONTROLLER
007C	7305	255	JNC L7
007E	E2F9	256	LOOP L4 ; TRY RESET AGAIN
0080	E9BF00	257	JMP ERROR_EX
00B3		258	
00B3	890100	259	L7: MOV CX,1
00B6	BAB000	260	MOV DX,B0H
		261	
00B9	B80012	262	MOV AX,1200H ; CONTROLLER DIAGNOSTICS
00BC	CD13	263	INT 13H
00BE	7303	264	JNC P7
0090	E9AF00	265	JMP ERROR_EX
0093		266	
0093	B80014	267	P7: MOV AX,1400H ; CONTROLLER DIAGNOSTICS
0096	CD13	268	INT 13H
009B	7303	269	JNC P9
009A	E9AS00	270	JMP ERROR_EX
009D		271	
009D	C7066C000000	272	P9: MOV TIMER_LOW,0 ; ZERO TIMER
00A3	A17800	273	MOV AX,RESET_FLAG
00A6	303412	274	CMPI AX,1234H ; KEYDDAR0 RESET
00A9	7506	275	JNLE P8
00AB	C7066C009A01	276	MOV TIMER_LOW,4100 ; SKIP WAIT ON RESET
00B1		277	
00B1	E421	278	P8: IN AL,021H ; TIMER
00B3	24FE	279	AND AL,0FEH ; ENABLE TIMER
00B5	E621	280	OUT 021H,AL ; START TIMER
00B7		281	
00B7	E8B400	282	P4: CALL H0_RESET_I ; RESET CONTROLLER
00BA	7207	283	JC P10
00BC	B80010	284	MOV AX,1000H ; READY
00BF	CD13	285	INT 13H
00C1	730B	286	JNC P2
00C3		287	
00C3	A16C00	288	P10: MOV AX,TIMER_LOW
00C6	30BE01	289	CMPI AX,4460 ; 25 SECONDS
00C9	72EC	290	JB P4
00CB	EB7590	291	JMP ERROR_EX
00CE		292	
00CE	B90100	293	P2: MOV CX,1
00D1	BAB000	294	MOV DX,B0H
		295	
00D4	B80011	296	MOV AX,1100H ; RECALIBRATE
00D7	CD13	297	INT 13H
00D9	7267	298	JC ERROR_EX
		299	
00DB	B80009	300	MOV AX,0900H ; SET DRIVE PARAMETERS
00DE	CD13	301	INT 13H
00E0	7260	302	JC ERROR_EX
		303	
00E2	B800C8	304	MOV AX,0CB00H ; ONA TO BUFFER

LOC OBJ	LINE	SOURCE
00E5 BEC0	305	MOV ES,AX ; SET SEGMENT
00E7 2B0B	306	SUB BX,BX
00E9 B8000F	307	MOV AX,DF 00H ; WRITE SECTOR BUFFER
00EC CD13	308	INT 13H
00EE 7252	309	JC ERROR_EX
	310	
00F0 FE067500	311	INC HF_MRM ; ORIVE ZERO RESPONDED
	312	
00F4 8A1302	313	MOV DX,213H ; EXPANSION BOX
00F7 B000	314	MOV AL,D
00F9 EE	315	OUT DX,AL ; TURN BOX OFF
00FA BA2103	316	MOV DX,321H ; TEST IF CONTROLLER
00FD EC	317	IN AL,DX ; ... IS IN THE SYSTEM UNIT
00FE 240F	318	AND AL,0FH
0100 3C0F	319	CMP AL,0FH
0102 7406	320	JE BOX_ON
0104 C706C00A401	321	MOV TIMER_LOW,420D ; CONTROLLER IS IN SYSTEM UNIT
010A	322	BOX_ON:
010A BA1302	323	MOV DX,213H ; EXPANSION BOX
010D B0FF	324	MOV AL,0FFH
010F EE	325	OUT DX,AL ; TURN BOX ON
	326	
0110 B90100	327	MOV CX,1 ; ATTEMPT NEXT DRIVES
0113 BA0100	328	MOV DX,D01H
0116	329	P3:
0116 2B00	330	SUB AX,AX ; RESET
0118 CD13	331	INT 13H
011A 7240	332	JC POD_DONE
011C B80011	333	MOV AX,01100H ; RECAL
011F CD13	334	INT 13H
0121 730B	335	JNC P5
0123 A16C00	336	MOV AX,TIMER_LOW
0126 3DBE01	337	CMP AX,446D ; 25 SECONDS
0129 72EB	338	JB P3
012B EB2F90	339	JMP POD_DONE
012E	340	P5:
012E B80009	341	MOV AX,0900H ; INITIALIZE CHARACTERISTICS
0131 CD13	342	INT 13H
0133 7227	343	JC POD_DONE
0135 FE067500	344	INC HF_MRM ; TALLY ANOTHER DRIVE
0139 81FA8100	345	CMP DX,(80H + S_MAX_FILE - 1)
013D 7310	346	JAE POD_DONE
013F 42	347	INC DX
0140 EDD4	348	JMP P3
	349	
	350	;----- POD ERROR
	351	
0142	352	ERROR_EX:
0142 B00F00	353	MOV BP,DFH ; POD ERROR FLAG
0145 2BC0	354	SUB AX,AX
0147 8BF0	355	MOV SI,AX
0149 B9060090	356	MOV CX,F17L ; MESSAGE CHARACTER COUNT
014D B700	357	MOV BH,D ; PAGE ZERO
014F	358	OUT_CH:
014F 2E0A046B01	359	MOV AL,CS:F171SI1 ; GET BYTE
0154 B40E	360	MOV AH,14D ; VIDEO OUT
0156 C010	361	INT 10H ; DISPLAY CHARACTER
0158 46	362	INC SI ; NEXT CHAR
0159 E2F4	363	LOOP OUT_CH ; DO MORE
015B F9	364	STC
015C	365	POD_DONE:
015C FA	366	CLI
015D E421	367	IN AL,021H ; BE SURE TIMER IS DISABLED
015F 0C01	368	OR AL,01H
0161 E621	369	OUT 021H,AL
0163 FB	370	STI
0164 E8A500	371	CALL OSBL
0167 CB	372	RET
	373	
0168 31373031	374	F17 DD '17D1',00H,DAH

LOC	OBJ	LINE	SOURCE
016C	00		
016D	0A		
0006		375	F17L EQU \$-F17
		376	
016E		377	HD_RESET_I PROC NEAR
016E 51		378	PUSH CX ; SAVE REGISTER
016F S2		379	PUSH DX
0170 FB		380	CLC ; CLEAR CARRY
0171 B90001		381	MOV CX,0100H ; RETRY COUNT
0174		382	L6:
0174 E0706		383	CALL PORT_1
0177 EE		384	OUT 0X,AL ; RESET CARD
0178 E00306		385	CALL PORT_1
017B EC		386	IN AL,0X ; CHECK STATUS
017C 2402		387	AND AL,2 ; ERROR BIT
017E 7403		388	JZ R3
0180 E2F2		389	LDDP L6
0182 F9		390	STC
0183		391	R3:
0183 5A		392	POP OX ; RESTORE REGISTER
0184 S9		393	POP CX
0185 C3		394	RET
		395	HD_RESET_I ENDP
		396	
		397	DISK_SETUP ENDP
		398	
		399	----- INT 19 -----
		400	;
		401	; INTERRUPT 19 BDDT STRAP LOADER
		402	;
		403	; - THE FIXED DISK BIDS REPLACES THE INTERRUPT 19
		404	; BOOT STRAP VECTOR WITH A POINTER TO THIS BOOT ROUTINE
		405	; - RESET THE DEFAULT DISK AND DISKETTE PARAMETER VECTORS
		406	; - THE BDDT BLOCK TO BE READ IN WILL BE ATTEMPTED FROM
		407	; CYLINDER 0 SECTOR 1 OF THE DEVICE.
		408	; - THE BOOTSTRAP SEQUENCE IS:
		409	;
		410	;> ATTEMPT TO LOAD FROM THE DISKETTE INTO THE BOOT
		411	;> LOCATION (0000:7C00) AND TRANSFER CONTROL THERE
		412	;> IF THE DISKETTE FAILS THE FIXED DISK IS TRIED FOR A
		413	VALID BOOTSTRAP BLOCK. A VALID BDDT BLOCK ON THE
		414	FIXED DISK CONSISTS OF THE BYTES 05SH 0A00 AS THE
		415	LAST TWO BYTES OF THE BLOCK
		416	;> IF THE ABOVE FAILS CONTROL IS PASSED TO RESIDENT BASIC
		417	;
		418	-----
01B6		419	BOOT_STRAP:
		420	ASSUME DS:DUMMY,ES:DUMMY
01B6 EBC0		421	SUB AX,AX
01B6 EEDB		422	MOV DS,AX ; ESTABLISH SEGMENT
		423	
		424	;----- RESET PARAMETER VECTORS
		425	
01BA FA		426	CLI
01BB C7060401E703		427	MOV WORD PTR HF_TBL_VEC, OFFSET FD_TBL
0191 8C0E0601		428	MOV WORD PTR HF_TBL_VEC+2, CS
0195 C70678000102		429	MOV WORD PTR DISKETTE_PARM, OFFSET DISKETTE_TBL
019B 8C0E7A00		430	MOV WORD PTR DISKETTE_PARM+2, CS
019F FB		431	STI
		432	
		433	;----- ATTEMPT BOOTSTRAP FROM DISKETTE
		434	
01A0 B90300		435	MOV CX,3 ; SET RETRY COUNT
01A3		436	H1: ; IPL_SYSTEM
01A3 S1		437	PUSH CX ; SAVE RETRY COUNT
01A4 2B02		438	SUB DX,DX ; ORIVE ZERO
01A6 2BC0		439	SUB AX,AX ; RESET THE DISKETTE
01AB CD13		440	INT 13H ; FILE ID CALL
01AA 720F		441	JC H2 ; IF ERROR, TRY AGAIN
01AC B00102		442	MOV AX,0201H ; READ IN THE SINGLE SECTOR
		443	
01AF 2B02		444	SUB OX,OX
01B1 8EC2		445	MOV ES,OX ; ESTABLISH SEGMENT
01B3 BB007C		446	MOV BX,OFFSET BOOT_LOCN
		447	
01B6 B90100		448	MOV CX,1 ; SECTOR 1, TRACK 0
01B9 CD13		449	INT 13H ; FILE ID CALL

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LOC OBJ          LINE SOURCE
0100 59          450 H2: PDP CX ; RECOVER RETRY COUNT
010C 730A        451 JNC H4 ; CF SET BY UNSUCCESSFUL READ
010E 80FC80      452 CHP AH,80H ; IF TIME OUT, NO RETRY
01C1 740A        453 JZ M5 ; TRY FIXED DISK
01C3 E2DE        454 LOOP M1 ; DO IT FOR RETRY TIMES
01C5 EB0690      455 JMP M5 ; UNABLE TO IPL FROM THE DISKETTE
01C8             456 M4: ; IPL WAS SUCCESSFUL
01C8 EA007C0000  457 JMP BOOT_LOCN
                                458
                                459 ;----- ATTEMPT BOOTSTRAP FROM FIXED DISK
                                460
01C0             461 H5:
01C0 2BC0        462 SUB AX,AX ; RESET DISKETTE
01CF 2B02        463 SUB DX,DX
01D1 CD13        464 INT 13H
01D3 B90300      465 MOV CX,3 ; SET RETRY COUNT
01D6             466 H6: ; IPL_SYSTEM
01D6 51          467 PUSH CX ; SAVE RETRY COUNT
01D7 BA8000      468 MOV DX,0080H ; FIXED DISK ZERO
01DA 2BC0        469 SUB AX,AX ; RESET THE FIXED DISK
01DC CD13        470 INT 13H ; FILE IO CALL
01DE 7212        471 JC M7 ; IF ERROR, TRY AGAIN
01E0 B80102      472 MOV AX,0201H ; READ IN THE SINGLE SECTOR
01E3 2B0B        473 SUB BX,BX
01E5 8EC3        474 MOV ES,BX
01E7 B0007C      475 MOV BX,OFFSET BOOT_LOCN ; TO THE BOOT LOCATION
01EA BA8000      476 MOV DX,80H ; DRIVE NUMBER
01EO B90100      477 MOV CX,1 ; SECTOR 1, TRACK 0
01F0 CD13        478 INT 13H ; FILE IO CALL
01F2 59          479 H7: PDP CX ; RECOVER RETRY COUNT
01F3 7208        480 JC M8
01F5 A1FE70      481 MOV AX,WORD PTR BOOT_LOCN+5100
01F8 3055AA      482 CHP AX,0AA55H ; TEST FOR GENERIC BOOT BLOCK
01FB 74CB        483 JZ H4
01FD             484 H8:
01F0 E207        485 LOOP H6 ; DO IT FOR RETRY TIMES
                                486
                                487 ;----- UNABLE TO IPL FROM THE DISKETTE OR FIXED DISK
                                488
01FF C01B        489 INT 18H ; RESIDENT BASIC
                                490
0201             491 DISKETTE_TBL:
                                492
0201 CF          493 DB 11001111B ; SRT=C, NO UNLOAD-OF - 1ST SPEC BYTE
0202 02          494 DB 2 ; NO LOAD=1, MODE=DMA - 2ND SPEC BYTE
0203 25          495 DB 25H ; WAIT AFTER OPN TIL MOTOR OFF
0204 02          496 DB 2 ; S12 BYTES PER SECTOR
0205 0B          497 DB 8 ; EOT (LAST SECTOR ON TRACK)
0206 2A          498 DB 02AH ; GAP LENGTH
0207 FF          499 DB 0FFH ; DTL
0208 50          500 DB 050H ; GAP LENGTH FOR FORMAT
0209 F6          501 DB 0F6H ; FILL BYTE FOR FORMAT
020A 19          502 DB 25 ; HEAD SETTLE TIME (MILLISECONDS)
020B 04          503 DB 4 ; MOTOR START TIME (1/8 SECOND)
                                504
                                505 ;----- MAKE SURE THAT ALL HOUSEKEEPING IS DONE BEFORE EXIT
                                506
020C             507 DSBL PROC NEAR
                                508 ASSUME DS:DATA
020C 1E          509 PUSH D5 ; SAVE SEGMENT
020D B84000      510 MOV AX,DATA
0210 8EDB        511 MOV D5,AX
                                512
0212 8A267700    513 MOV AH,PORT_OFF
0216 50          514 PUSH AX ; SAVE OFFSET
                                515
0217 C606770000  516 MOV PORT_OFF,0H
021C EB6905      517 CALL PORT_3
021F 2AC0        518 SUB AL,AL
0221 EE          519 DUT DX,AL ; RESET INT/DMA MASK
0222 C606770004  520 MOV PORT_OFF,4H
0227 E05E05      521 CALL PORT_3
022A 2AC0        522 SUB AL,AL
022C EE          523 OUT DX,AL ; RESET INT/DMA MASK
022D C606770005  524 MOV PORT_OFF,0H
0232 F85305      525 CALL PORT_3
0235 2AC0        526 SUB AL,AL

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LOC OBJ	LINE	SOURCE	
0237 EE	527	OUT	DX,AL ; RESET INT/DMA MASK
0238 C60677000C	528	MOV	PORT_OFF,0CH
023D E84805	529	CALL	PORT_3
0240 2AC0	530	SUB	AL,AL
0242 EE	531	OUT	DX,AL ; RESET INT/DMA MASK
0243 B007	532	MOV	AL,07H
0245 E60A	533	OUT	DMA+10,AL ; SET DMA MODE TO DISABLE
0247 FA	534	CLI	; DISABLE INTERRUPTS
0248 E421	535	IN	AL,021H
024A 0C20	536	OR	AL,020H
024C E621	537	OUT	021H,AL ; DISABLE INTERRUPT 5
024E FB	538	STI	; ENABLE INTERRUPTS
024F 58	539	POP	AX ; RESTORE OFFSET
0250 88267700	540	MOV	PORT_OFF,AH
0254 1F	541	POP	DS ; RESTORE SEGMENT
0255 C3	542	RET	
	543	OSBL	ENDP
	544		
	545		-----
	546		FIXED DISK BIOS ENTRY POINT
	547		-----
	548		
0256	549	DISK_IO PROC	FAR
	550	ASSUME	DS:NOTHING,ES:NOTHING
0256 80FA80	551	CHP	DL,80H ; TEST FOR FIXED DISK DRIVE
0259 7305	552	JAE	HARD_DISK ; YES, HANDLE NERE
025B CD40	553	INT	40H ; DISKETTE HANDLER
025D	554	RET_2:	
025D CA0200	555	RET	2 ; BACK TO CALLER
0260	556	HARD_DISK:	
	557	ASSUME	DS:DATA
0260 FB	558	STI	; ENABLE INTERRUPTS
0261 0AE4	559	DR	AH,AH
0263 7509	560	JNZ	A3
0265 CD40	561	INT	40H ; RESET NEC WHEN AH=0
0267 2AE4	562	SUB	AH,AH
0269 80FA81	563	CHP	DL,(80H + S_MAX_FILE - 1)
026C 77EF	564	JA	RET_2
026E	565	A3:	
026E 80FC08	566	CHP	AH,08 ; GET PARAMETERS IS A SPECIAL CASE
0271 7503	567	JNZ	A2
0273 E91A01	568	JMP	GET_PARH_N
0276	569	A2:	
0276 53	570	PUSH	8X ; SAVE REGISTERS DURING OPERATION
0277 51	571	PUSH	CX
0278 52	572	PUSH	DX
0279 1E	573	PUSH	DS
027A 06	574	PUSH	ES
027B 56	575	PUSH	SI
027C 57	576	PUSH	DI
	577		
027D E86A00	578	CALL	DISK_ID_CONT ; PERFORM THE OPERATION
	579		
0280 50	580	PUSH	AX
0281 EB88FF	581	CALL	D5BL ; BE SURE DISABLES OCCURRED
0284 884000	582	MOV	AX,DATA
0287 8ED8	583	MOV	DS,AX
0289 58	584	POP	AX ; ESTABLISH SEGMENT
028A 8A267400	585	MOV	AH,DISK_STATUS
028E 80FC01	586	CHP	AH,1
0291 F5	587	CMC	
0292 5F	588	POP	DI ; SET THE CARRY FLAG TO INDICATE
0293 5E	589	POP	SI ; SUCCESS OR FAILURE
0294 07	590	POP	ES ; RESTORE REGISTERS
0295 1F	591	POP	DS
0296 5A	592	POP	DX
0297 59	593	POP	CX
0298 5B	594	POP	BX
0299 CA0200	595	RET	2 ; THROW AWAY SAVED FLAGS
	596	DISK_IO ENDP	
	597		
029C	598	M1	LABEL WORD ; FUNCTION TRANSFER TABLE
029C 3883	599	OW	DISK_RESET ; 000H
029E 4003	600	OW	RETURNH_STATUS ; 001H
02A0 5603	601	OW	DISK_READ ; 002H
02A2 6003	602	OW	DISK_WRITE ; 003H
02A4 6A03	603	OW	DISK_VERIFY ; 004H

LOC	OBJ	LINE	SOURCE	
02A6	7203	604	OW	FMT_TRK
02A8	7903	605	OW	FMT_BAD
02AA	8003	606	OW	FMT_ORV
02AC	3003	607	OW	BAD_COMMAND
02AE	2704	608	OW	INIT_ORV
02B0	CF04	609	OW	RD_LONG
02B2	BD04	610	OW	WR_LONG
02B4	F204	611	OW	DISK_SEEK
02B6	3003	612	OW	DISK_RESET
02B8	F904	613	OW	RD_BUFF
02BA	0705	614	OW	WR_BUFF
02BC	1505	615	OW	TST_RDY
02BE	1C05	616	OW	HDISK_RECAL
02C0	2305	617	OW	RAH_DIAG
02C2	2A05	618	OW	CHK_ORV
02C4	3105	619	OW	CHTLR_DIAG
002A		620	MIL	EQU
		621		4-M1
02C6		622	SETUP_A	PROC HEAR
		623		
02C6	C606740000	624	MOV	DISK_STATUS,0
02C8	S1	625	PUSH	CX
		626		
		627	1-----	CALCULATE THE PORT OFFSET
		628		
02CC	6AEA	629	MOV	CH,DL
02CE	80CA01	630	DR	DL,1
0201	FECA	631	DEC	DL
0203	00E2	632	SHL	DL,1
0205	88167700	633	MOV	PORT_OFF,DL
0209	8AD5	634	MOV	DL,CH
020B	80E201	635	AND	DL,1
		636		
02DE	D105	637	MOV	CL,S
02E0	D2E2	638	SHL	DL,CL
02E2	0AD6	639	OR	DL,0H
02E4	88164300	640	MOV	CHD_BLOCK+1,DL
02E8	59	641	POP	CX
02E9	C3	642	RET	
		643	SETUP_A	ENDP
		644		
02EA		645	DISK_ID_CNT	PROC HEAR
02EA	50	646	PUSH	AX
02EB	884000	647	MOV	AX,DATA
02EE	8ED8	648	MOV	DS,AX
02F0	58	649	POP	AX
02F1	80FC01	650	CHP	AH,01H
02F4	7503	651	JHZ	A4
02F6	EB9590	652	JMP	RETURNH_STATUS
02F9		653	A4:	
02F9	80EA80	654	SUB	DL,80H
02FC	80FA08	655	CHP	DL,MAX_FILE
02FF	732F	656	JAE	BAD_COMMAND
		657		
0301	E8C2FF	658	CALL	SETUP_A
		659		
		660	1-----	SET UP COMMAND BLOCK
		661		
0304	FEC9	662	DEC	CL
0306	C606420000	663	MOV	CHD_BLOCK+0,0
030B	880E4400	664	MOV	CHD_BLOCK+2,CL
030F	882E4500	665	MOV	CHD_BLOCK+3,CH
0313	A24600	666	MOV	CHD_BLOCK+4,AL
0316	A07600	667	MOV	AL,CONTROL_BYTE
0319	A24700	668	MOV	CHD_BLOCK+5,AL
031C	50	669	PUSH	AX
0310	8AC4	670	MOV	AL,AH
031F	32E4	671	XOR	AH,AH
0321	D1E0	672	SAL	AX,1
0323	8BF0	673	MOV	SI,AX
0325	302A00	674	CHP	AX,MIL
0328	58	675	POP	AX
0329	7305	676	JNB	BAD_COMMAND
032B	2EFA49C02	677	JMP	WORD PTR CS:[SI + OFFSET M1]
0330		678	BAD_COMMAND:	
0330	C606740001	679	MOV	DISK_STATUS,BAD_CMD
0335	B000	680	MOV	AL,0

LOC OBJ	LINE	SOURCE
0337 C3	681	RET
	682	DISK_IO_CONT ENDP
	683	
	684	-----
	685	RESET THE DISK SYSTEM (AH = 000H) :
	686	-----
	687	
0338	688	DISK_RESET PROC NEAR
0338 E04304	689	CALL PORT_1 ; RESET PORT
0338 EE	690	OUT DX,AL ; ISSUE RESET
033C E03F04	691	CALL PORT_1 ; CONTROLLER HARDWARE STATUS
033F EC	692	IN AL,DX ; GET STATUS
0340 2402	693	AND AL,2 ; ERROR BIT
0342 7406	694	JZ DR1
0344 C606740005	695	MOV DISK_STATUS,BAD_RESET
0349 C3	696	RET
034A	697	DR1:
034A E9DA00	698	JMP INIT_ORV ; SET THE ORIVE PARAMETERS
	699	DISK_RESET ENDP
	700	
	701	-----
	702	DISK STATUS ROUTINE (AH = 001H) :
	703	-----
	704	
0340	705	RETURN_STATUS PROC NEAR
0340 A07400	706	MOV AL,DISK_STATUS ; OBTAIN PREVIOUS STATUS
0350 C606740000	707	MOV DISK_STATUS,0 ; RESET STATUS
0355 C3	708	RET
	709	RETURN_STATUS ENDP
	710	
	711	-----
	712	DISK READ ROUTINE (AH = 002H) :
	713	-----
	714	
0356	715	DISK_READ PROC NEAR
0356 B047	716	MOV AL,DMA_READ ; MODE BYTE FOR DMA READ
0358 C60642000B	717	MOV CHD_BLOCK+0,READ_CMD
035D E9E501	718	JMP DMA_OPN
	719	DISK_READ ENDP
	720	
	721	-----
	722	DISK WRITE ROUTINE (AH = 003H) :
	723	-----
	724	
0360	725	DISK_WRITE PROC NEAR
0360 B04B	726	MOV AL,DMA_WRITE ; MODE BYTE FOR DMA WRITE
0362 C60642000A	727	MOV CHD_BLOCK+0,WRITE_CMD
0367 E9DB01	728	JMP DMA_OPN
	729	DISK_WRITE ENDP
	730	
	731	-----
	732	DISK VERIFY (AH = 004H) :
	733	-----
	734	
036A	735	DISK_VERF PROC NEAR
036A C606420005	736	MOV CHD_BLOCK+0,CNK_TRK_CMD
036F E9C401	737	JMP NDIA_OPN
	738	DISK_VERF ENDP
	739	
	740	-----
	741	FORMATTING (AH = 005H 006H 007H) :
	742	-----
	743	
0372	744	FMT_TRK PROC NEAR ; FORMAT TRACK (AH = 005H)
0372 C606420006	745	MOV CHD_BLOCK,FMTTRK_CMD
0377 EB0C	746	JMP SHORT FMT_CONT
	747	FMT_TRK ENDP
	748	
0379	749	FMT_BAD PROC NEAR ; FORMAT BAD TRACK (AH = 006H)
0379 C61A20007	750	MOV CHD_BLOCK,FMTBAD_CMD
037E EB05	751	JMP SHORT FMT_CONT
	752	FMT_BAD ENDP
	753	
0380	754	FMT_DRV PROC NEAR ; FORMAT DRIVE (AH = 007H)
0380 C606420004	755	MOV CHD_BLOCK,FMTDRV_CMD
	756	FMT_DRV ENDP
	757	

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LOC OBJ          LINE  SOURCE
0305             758  FMT_CONT:
0305 A04400       759      MOV     AL,CHD_BLOCK*2      ; ZERO OUT SECTOR FIELD
0306 24C0         760      AND     AL,110000000B
030A A24400       761      MOV     CHD_BLOCK*2,AL
030D E9A601       762      JMP     HDMA_DPM
0305             763
0305             764  ;-----
0305             765  ;   GET PARAMETERS   (AH = 8)   ;
0305             766  ;-----
0305             767
0390             768  GET_PARM_N   LABEL   NEAR
0390             769  GET_PARM   PROC     FAR      ; GET DRIVE PARAMETERS
0390 1E           770      PUSH    DS      ; SAVE REGISTERS
0391 06           771      PUSH    ES
0392 53           772      PUSH    BX
0392             773
0392             774      ASSUME   DS:DUPMY
0393 2BC0         775      SUB     AX,AX      ; ESTABLISH ADDRESSING
0395 8E08         776      MOV     DS,AX
0397 C41E0401     777      LES     BX,HF_TBL_VEC
0398 B04000       778      ASSUME   DS:DATA
0398 B04000       779      MOV     AX,DATA
039E 8E08         780      MOV     DS,AX      ; ESTABLISH SEGMENT
039E             781
03A0 80EA80       782      SUB     DL,80H
03A3 80FA08       783      CMP     DL,HAX_FILE      ; TEST WITHIN RANGE
03A6 732F         784      JAE     G4
03A6             785
03A8 E81BFF       786      CALL    SETUP_A
03A8             787
03AB E80F03       788      CALL    SH2_OFFS
03AE 7227         789      JC      G4
03B0 0308         790      ADD     BX,AX
03B0             791
03B2 268B07       792      MOV     AX,ES:[BX]      ; MAX NUMBER OF CYLINDERS
03B5 200200       793      SUB     AX,2      ; ADJUST FOR 0-N
03B5             794      ; AND RESERVE LAST TRACK
03B8 8AE8         795      MOV     CH,AL
03BA 250003       796      AND     AX,0300H      ; HIGH TWO BITS OF CYL
03BD 01E8         797      SHR     AX,1
03BF 01E8         798      SHR     AX,1
03C1 0C11         799      OR      AL,011H      ; SECTORS
03C3 8AC8         800      MOV     CL,AL
03C3             801
03C5 268A7702     802      MOV     DH,ES:[BX][2]      ; HEADS
03C9 FECE         803      DEC     DH      ; 0-N RANGE
03CB 8A167500     804      MOV     DL,HF_NUM      ; DRIVE COUNT
03CF 28C0         805      SUB     AX,AX
03D1             806
03D1 5B           807      POP     BX      ; RESTORE REGISTERS
03D2 07           808      POP     ES
03D3 1F           809      POP     DS
03D4 CA0200       810      RET     2
03D7             811
03D7 C606740007   812      MOV     DISK_STATUS,INIT_FAIL ; OPERATION FAILED
03DC 8407         813      MOV     AH,INIT_FAIL
03DE 2AC0         814      SUB     AL,AL
03E0 2B02         815      SUB     DX,DX
03E2 2BC9         816      SUB     CX,CX
03E4 F9           817      STC      ; SET ERROR FLAG
03E5 E8EA         818      JMP     G5
03E5             819  GET_PARM   ENDP
03E5             820
03E5             821  ;-----
03E5             822  ; INITIALIZE DRIVE CHARACTERISTICS ;
03E5             823  ; ;
03E5             824  ; FIXED DISK PARAMETER TABLE ;
03E5             825  ; ;
03E5             826  ; - THE TABLE IS COMPOSED OF A BLOCK DEFINED AS: ;
03E5             827  ; ;
03E5             828  ;   (1 WORD) - MAXIMUM NUMBER OF CYLINDERS ;
03E5             829  ;   (1 BYTE) - MAXIMUM NUMBER OF HEADS ;
03E5             830  ;   (1 WORD) - STARTING REDUCED WRITE CURRENT CYL ;
03E5             831  ;   (1 WORD) - STARTING WRITE PRECOMPENSATION CYL ;
03E5             832  ;   (1 BYTE) - MAXIMUM ECC DATA BURST LENGTH ;
03E5             833  ;   (1 BYTE) - CONTROL BYTE (DRIVE STEP OPTION) ;
03E5             834  ;   BIT   7  DISABLE DISK-ACCESS RETRIES ;
03E5             835  ;   BIT   6  DISABLE ECC RETRIES ;

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836 |          BITS 5-3 ZERO |
837 |          BITS 2-0 DRIVE OPTION |
838 |          (1 BYTE) - STANDARD TIME OUT VALUE (SEE BELOW) |
839 |          (1 BYTE) - TIME OUT VALUE FOR FORMAT DRIVE |
840 |          (1 BYTE) - TIME OUT VALUE FOR CHECK DRIVE |
841 |          (4 BYTES) |
842 |          - RESERVED FOR FUTURE USE |
843 | |
844 |          - TO DYNAMICALLY DEFINE A SET OF PARAMETERS |
845 |          BUILD A TABLE OF VALUES AND PLACE THE |
846 |          CORRESPONDING VECTOR INTO INTERRUPT 41. |
847 | |
848 |          NOTE: |
849 |          THE DEFAULT TABLE IS VECTORED IN FOR |
850 |          AN INTERRUPT 19H (BOOTSTRAP) |
851 | |
852 | |
853 | ON THE CARD SWITCH SETTINGS |
854 | |
855 |          DRIVE 0   DRIVE 1 |
856 |          ----- |
857 |          ON : / : |
858 |          : -1- -2- / -3- -4- : |
859 |          OFF : / : |
860 |          ----- |
861 | |
862 | |
863 |          TRANSLATION TABLE |
864 | |
865 |          1/3 : 2/4 : TABLE ENTRY |
866 |          ----- |
867 |          ON : ON : 0 |
868 |          ON : DFF : 1 |
869 |          OFF : ON : 2 |
870 |          OFF : DFF : 3 |
871 | |
872 | ----- |
873 | |
03E7 |          FD_TBL: |
874 | |
875 |          |
876 |          |
877 |          |
878 |          DW 0306D |
879 |          DB 02D |
880 |          DW 0306D |
881 |          DW 0000D |
882 |          DB 0BH |
883 |          DB 00H |
884 |          DB 0CH |
885 |          DB 0B4H |
886 |          DB 028H |
887 |          DB 0,0,0,0 |
888 | |
889 |          |
890 |          |
891 |          DW 0375D |
892 |          DB 08D |
893 |          DW 0375D |
894 |          DW 0000D |
895 |          DB 0BH |
896 |          DB 05H |
897 |          DB 0CN |
898 |          DB 0B4H |
899 |          DB 028H |
900 |          DB 0,0,0,0 |
901 | |
902 |          |
903 |          |
904 |          DW 0306D |
905 |          DB 06D |
906 |          DW 0128D |
907 |          DW 0256D |
908 |          DB 0BH |
909 |          DB 05H |
910 |          DB 0CN |
911 |          DB 0B4H |

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| STANDARD
| FORMAT DRIVE
| CHECK DRIVE

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| STANDARD
| FORMAT DRIVE
| CHECK DRIVE

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| STANDARD
| FORMAT DRIVE

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LOC	OBJ	LINE	SOURCE
0412	28	912	DB 028H ; CHECK DRIVE
0413	00000000	913	DB 0,0,0,0
		914	
		915	I----- DRIVE TYPE 03
		916	
0417	3201	917	DW 0306D
0419	04	918	DB 040
041A	3201	919	DW 0306D
041C	0000	920	DW 0000D
041E	0B	921	DB 0BH
041F	05	922	DB 05H
0420	0C	923	DB 0CH ; STANDARD
0421	B4	924	DB DBAH ; FORMAT DRIVE
0422	28	925	DB 028H ; CHECK DRIVE
0423	00000000	926	DB 0,0,0,0
		927	
0427		928	INIT_DRV PROC NEAR
		929	
		930	I----- DO DRIVE ZERO
		931	
0427	C0642000C	932	MOV CHD_BLOCK+0,INIT_DRV_CMD
042C	C06430000	933	MOV CHD_BLOCK+1,0
0431	E81000	934	CALL INIT_DRV_R
0434	720D	935	JC INIT_DRV_OUT
		936	
		937	I----- DD DRIVE ONE
		938	
0436	C0642000C	939	MOV CHD_BLOCK+0,INIT_DRV_CMD
043B	C06430020	940	MOV CHD_BLOCK+1,0D100000B
0440	E80100	941	CALL INIT_DRV_R
0443		942	INIT_DRV_OUT:
0443	C3	943	RET
		944	INIT_DRV ENDP
		945	
0444		946	INIT_DRV_R PROC NEAR
		947	ASSUME ES:CODE
0444	2AC0	948	SUB AL,AL
0446	E81901	949	CALL COMMAND ; ISSUE THE COMMAND
0449	7301	950	JNC B1
044B	C3	951	RET
044C		952	B1:
044C	1E	953	PUSH DS ; SAVE SEGMENT
		954	ASSUME DS:DUPDIY
044D	2BC0	955	SUB AX,AX
044F	8ED8	956	MOV DS,AX ; ESTABLISH SEGMENT
0451	C41E0401	957	LES BX,HF_TBL_VEC
0455	1F	958	POP DS ; RESTORE SEGMENT
		959	ASSUME DS:DATA
0456	E83403	960	CALL SH2_OFFS
0459	7257	961	JC B3
045B	D3D8	962	ADD BX,AX
		963	
		964	I----- SEND DRIVE PARAMETERS MOST SIGNIFICANT BYTE FIRST
		965	
045D	BF0100	966	MOV DI,1
0460	E85F00	967	CALL INIT_DRV_S
0463	724D	968	JC B3
		969	
0465	BF0000	970	MOV DI,0
0468	E85700	971	CALL INIT_DRV_S
046B	7245	972	JC B3
		973	
046D	BF0200	974	MOV DI,2
0470	E84F00	975	CALL INIT_DRV_S
0473	723D	976	JC B3
		977	
0475	BF0400	978	MOV DI,4
0478	E84700	979	CALL INIT_DRV_S
047B	7235	980	JC B3
		981	
047D	BF0300	982	MOV DI,3
0480	E83F00	983	CALL INIT_DRV_S
0483	722D	984	JC B3
		985	
0485	BF0600	986	MOV DI,6
0488	E83700	987	CALL INIT_DRV_S
048B	7225	988	JC B3

LOC OBJ	LINE	SOURCE
	989	
0480 BF0500	990	MOV OI,5
0490 E82F00	991	CALL INIT_DRV_S
0493 7210	992	JC B3
	993	
0495 BF0700	994	MOV DI,7
0498 E82700	995	CALL INIT_DRV_S
049B 7215	996	JC B3
	997	
049D BF0800	998	MOV DI,8 ; DRIVE STEP OPTION
04A0 268A01	999	MOV AL,ES:[BX + DI]
04A3 A27600	1000	MOV CONTROL_BYTE,AL
	1001	
04A6 2BC9	1002	SUB CX,CX
04A8	1003	B5:
04A8 E8D302	1004	CALL PORT_1
04AB EC	1005	IN AL,DX
04AC A802	1006	TEST AL,RI_IOMODE ; STATUS INPUT MODE
04AE 7509	1007	JNZ B6
04B0 E2F6	1008	LOOP B5
04B2	1009	B3:
04B2 C606740007	1010	MOV DISK_STATUS,INIT_FAIL ; OPERATION FAILED
04B7 F9	1011	STC
04B8 C3	1012	RET
	1013	
04B9	1014	B6:
04B9 E8B502	1015	CALL PORT_0
04BC EC	1016	IN AL,DX
04BD 2402	1017	AND AL,2 ; MASK ERROR BIT
04BF 75F1	1018	JNZ B3
04C1 C3	1019	RET
	1020	ASSUME ES:NOTHING
	1021	INIT_DRV_R ENDP
	1022	
	1023	;----- SEND THE BYTE OUT TO THE CONTROLLER
	1024	
04C2	1025	INIT_DRV_S PROC NEAR
04C2 E8C501	1026	CALL HD_WAIT_REQ
04C5 7207	1027	JC D1
04C7 E8A702	1028	CALL PORT_0
04CA 268A01	1029	MOV AL,ES:[BX + DI]
04CD EE	1030	OUT DX,AL
04CE	1031	D1:
04CE C3	1032	RET
	1033	INIT_DRV_S ENDP
	1034	
	1035	;------
	1036	; READ LONG (AH = 0AH) ;
	1037	;------
	1038	
04CF	1039	RD_LONG PROC NEAR
04CF E81900	1040	CALL CHK_LONG
04D2 726B	1041	JC B6
04D4 C6064200E5	1042	MOV CMD_BLOCK+0,RD_LONG_CMD
04D9 B047	1043	MOV AL,0AH_READ
04DB EB68	1044	JMP SHORT 0AH_DPN
	1045	RD_LONG ENDP
	1046	
	1047	;------
	1048	; WRITE LONG (AH = 0BH) ;
	1049	;------
	1050	
04D0	1051	WR_LONG PROC NEAR
04D0 E80B00	1052	CALL CHK_LONG
04E0 725D	1053	JC B6
04E2 C6064200E6	1054	MOV CMD_BLOCK+0,WR_LONG_CMD
04E7 B04B	1055	MOV AL,0AH_WRITE
04E9 EB5A	1056	JMP SHORT 0AH_OPN
	1057	WR_LONG ENDP
	1058	
04EB	1059	CHK_LONG PROC NEAR
04EB A06400	1060	MOV AL,CMD_BLOCK+4
04EE 3CB0	1061	CMF AL,080H
04F0 F5	1062	CMC
04F1 C3	1063	RET
	1064	CHK_LONG ENDP
	1065	

LOC	OBJ	LINE	SOURCE
		1066	-----
		1067	SEEK (AH = 0CH)
		1068	-----
		1069	
04F2		1070	DISK_SEEK PROC NEAR
04F2 C60642000B		1071	MOV CMD_BLOCK,SEEK_CMD
04F7 EB3D		1072	JMP SHORT NDMA_OPN
		1073	DISK_SEEK ENDP
		1074	
		1075	-----
		1076	READ SECTOR BUFFER (AH = 0EH)
		1077	-----
		1078	
04F9		1079	RD_BUFF PROC NEAR
04F9 C60642000E		1080	MOV CMD_BLOCK+0,RD_BUFF_CMD
04FE C606460001		1081	MOV CMD_BLOCK+4,1 ; ONLY ONE BLOCK
0503 B047		1082	MOV AL,NDMA_READ
0505 EB3E		1083	JMP SHORT NDMA_OPN
		1084	RD_BUFF ENDP
		1085	
		1086	-----
		1087	WRITE SECTOR BUFFER (AH = 0FH)
		1088	-----
		1089	
0507		1090	WR_BUFF PROC NEAR
0507 C60642000F		1091	MOV CMD_BLOCK+0,WR_BUFF_CMD
050C C606460001		1092	MOV CMD_BLOCK+4,1 ; ONLY ONE BLOCK
0511 B04B		1093	MOV AL,NDMA_WRITE
0513 EB3D		1094	JMP SHORT NDMA_OPN
		1095	WR_BUFF ENDP
		1096	
		1097	-----
		1098	TEST DISK READY (AH = 010H)
		1099	-----
		1100	
0515		1101	TST_ROY PROC NEAR
0515 C606420000		1102	MOV CMD_BLOCK+0,TST_ROY_CMD
051A EB1A		1103	JMP SHORT NDMA_OPN
		1104	TST_ROY ENDP
		1105	
		1106	-----
		1107	RECALIBRATE (AH = 011H)
		1108	-----
		1109	
051C		1110	HOISK_RECAL PROC NEAR
051C C606420001		1111	MOV CMD_BLOCK,RECAL_CMD
0521 EB13		1112	JMP SHORT NDMA_OPN
		1113	HOISK_RECAL ENDP
		1114	
		1115	-----
		1116	CONTROLLER RAM DIAGNOSTICS (AH = 012H)
		1117	-----
		1118	
0523		1119	RAM_OIAG PROC NEAR
0523 C606420000		1120	MOV CMD_BLOCK+0,RAM_OIAG_CMD
0528 EB0C		1121	JMP SHORT NDMA_OPN
		1122	RAM_OIAG ENDP
		1123	
		1124	-----
		1125	DRIVE DIAGNOSTICS (AH = 013H)
		1126	-----
		1127	
052A		1128	CHK_DRV PROC NEAR
052A C6064200E3		1129	MOV CMD_BLOCK+0,CHK_DRV_CMD
052F EB05		1130	JMP SHORT NDMA_OPN
		1131	CHK_DRV ENDP
		1132	
		1133	-----
		1134	CONTROLLER INTERNAL DIAGNOSTICS (AH = 014H)
		1135	-----
		1136	
0531		1137	CNTLR_DIAG PROC NEAR
0531 C6064200E4		1138	MOV CMD_BLOCK+0,CNTLR_DIAG_CMD
		1139	CNTLR_DIAG ENDP
		1140	

LOC OBJ	LINE	SOURCE
	1141	-----
	1142	; SUPPORT ROUTINES ;
	1143	-----
	1144	
0536	1145	NDMA_OPN:
0536 B002	1146	MOV AL,02H
0538 E82700	1147	CALL COMMAND ; ISSUE THE COMMAND
0538 7221	1148	JC 611
053D EB16	1149	JMP SHORT 63
053F	1150	G6:
053F C606740009	1151	MOV DISK_STATUS,DMA_BOUNDARY
0544 C3	1152	RET
0545	1153	DMA_OPN:
0545 E85701	1154	CALL DMA_SETUP ; SET UP FOR DMA OPERATION
0548 72F5	1155	JC 68
054A 8C03	1156	MOV AL,03H
054C E81300	1157	CALL COMMAND ; ISSUE THE COMMAND
054F 720D	1158	JC 611
0551 B003	1159	MOV AL,03H
0553 E60A	1160	OUT DMA+10,AL ; INITIALIZE THE DISK CHANNEL
0555	1161	G3:
0555 E421	1162	IN AL,021H
0557 24DF	1163	AND AL,0DFH
0559 E621	1164	OUT 021H,AL
055B E8AA01	1165	CALL WAIT_INT
055E	1166	G11:
055E E83B00	1167	CALL ERROR_CHK
0561 C3	1168	RET
	1169	
	1170	-----
	1171	; COMMAND ;
	1172	; THIS ROUTINE OUTPUTS THE COMMAND BLOCK ;
	1173	; INPUT ;
	1174	; AL = CONTROLLER DMA/INTERRUPT REGISTER MASK ;
	1175	-----
	1176	
	1177	
0562	1178	COMMAND PROC NEAR
0562 BE4200	1179	MOV SI,OFFSET CMD_BLOCK
0565 E81B02	1180	CALL PORT_2
0568 EE	1181	OUT DX,AL ; CONTROLLER SELECT PULSE
0569 E81C02	1182	CALL PORT_3
056C EE	1183	OUT DX,AL
056D 2E19	1184	SUB CX,CX ; WAIT COUNT
056F E89C02	1185	CALL PORT_1
0572	1186	WAIT_BUSY:
0572 EC	1187	IN AL,0X ; GET STATUS
0573 240F	1188	AND AL,0FH
0575 3C0D	1189	CHP AL,R1_BUSY OR R1_BUS OR R1_REQ
0577 7409	1190	JE C1
0579 E2F7	1191	LOOP WAIT_BUSY
057B C606740080	1192	MOV DISK_STATUS,TIME_OUT
0580 F9	1193	STC
0581 C3	1194	RET ; ERROR RETURN
0582	1195	C1:
0582 FC	1196	CLO
0583 B90600	1197	MOV CX,6 ; BYTE COUNT
0586	1198	CH3:
0586 E8E801	1199	CALL PORT_0
0589 AC	1200	LODSB
058A EE	1201	OUT DX,AL ; GET THE NEXT COMMAND BYTE
058B E2F9	1202	LOOP CH3 ; OUT IT GOES
	1203	; DO MORE
058D E8EE01	1204	CALL PORT_1 ; STATUS
0590 EC	1205	IN AL,0X
0591 A801	1206	TEST AL,R1_REQ
0593 7406	1207	JZ CH7
0595 C606740020	1208	MOV DISK_STATUS,BAD_CNTRL
059A F9	1209	STC
059B	1210	CH7:
059B C3	1211	RET
	1212	COMMAND ENDP
	1213	
	1214	-----
	1215	; SENSE STATUS BYTES ;
	1216	; ;
	1217	; BYTE 0 ;

LOC OBJ	LINE	SOURCE
	1218	BIT 7 ADDRESS VALID, WHEN SET
	1219	BIT 6 SPARE, SET TO ZERO
	1220	BITS 5-4 ERROR TYPE
	1221	BITS 3-0 ERROR CODE
	1222	
	1223	BYTE 1
	1224	BITS 7-6 ZERO
	1225	BIT 5 DRIVE (0-1)
	1226	BITS 4-0 HEAD NUMBER
	1227	
	1228	BYTE 2
	1229	BITS 7-5 CYLINDER HIGH
	1230	BITS 4-0 SECTOR NUMBER
	1231	
	1232	BYTE 3
	1233	BITS 7-0 CYLINDER LOW
	1234	
	1235	-----
	1236	
059C	1237	ERROR_CHK PROC NEAR
	1238	ASSUME ES:DATA
059C A07400	1239	MOV AL,DISK_STATUS ; CHECK IF THERE WAS AN ERROR
059F 0AC0	1240	OR AL,AL
05A1 7501	1241	JNZ G21
05A3 C3	1242	RET
	1243	
	1244	----- PERFORM SENSE STATUS
	1245	
05A4	1246	G21:
05A4 B94000	1247	MOV AX,DATA
05A7 8EC0	1248	MOV ES,AX ; ESTABLISH SEGMENT
05A9 2BC0	1249	SUB AX,AX
05AB 8BF8	1250	MOV DI,AX
05AD C06420003	1251	MOV CTR,BLOCK+0,SENSE_CHK
05B2 2AC0	1252	SUB AL,AL
05B4 E0ABFF	1253	CALL COMMAND ; ISSUE SENSE STATUS COMMAND
05B7 7223	1254	JC SENSE_ABORT ; CANNOT RECOVER
05B9 B90400	1255	MOV CX,4
05BC	1256	G22:
05BC E0CB00	1257	CALL HD_WAIT_REQ
05BF 7220	1258	JC G24
05C1 E8AD01	1259	CALL PORT_0
05C4 EC	1260	IN AL,DX
05C5 26884542	1261	MOV ES:HD_ERROR(DI),AL ; STORE AWAY SENSE BYTES
05C9 47	1262	INC DI
05CA E0B101	1263	CALL PORT_1
05CD E2ED	1264	LOOP G22
05CF E0B800	1265	CALL HD_WAIT_REQ
05D2 7200	1266	JC G24
05D4 E89A01	1267	CALL PORT_0
05D7 EC	1268	IN AL,DX
05DB AB02	1269	TEST AL,2
05DA 740F	1270	JZ STAT_ERR
05DC	1271	SENSE_ABORT:
05DC C064740FF	1272	MOV DISK_STATUS,SENSE_FAIL
05E1	1273	G24:
05E1 F9	1274	STC
05E2 C3	1275	RET
	1276	ERROR_CHK ENDP
	1277	
05E3 1A06	1278	T_0 DW TYPE_0
05E5 2706	1279	T_1 DW TYPE_1
05E7 6A06	1280	T_2 DW TYPE_2
05E9 7706	1281	T_3 DW TYPE_3
	1282	
05EB	1283	STAT_ERR:
05EB 268A1E4200	1284	MOV BL,ES:HD_ERROR ; GET ERROR BYTE
05F0 6AC3	1285	MOV AL,BL
05F2 240F	1286	AND AL,0FH
05F4 80E330	1287	AND BL,0D10000B ; ISOLATE TYPE
05F7 2AFF	1288	SUB BH,BH
05F9 B103	1289	MOV CL,3
05FB D3EB	1290	SHR BX,CL ; ADJUST
05FD 2EFA7E305	1291	JMP WORD PTR CS:[BX + OFFSET T_0]
	1292	ASSUME ES:NOTHING
	1293	
06D2	1294	TYPED_TABLE LABEL BYTE

LOC OBJ	LINE	SOURCE
0602 00204020800020	1295	DB 0,BAD_CNTLRL,BAD_SEEK,BAD_CNTLRL,TIME_OUT,0,BAD_CNTLRL
0609 0040	1296	DB 0,BAD_SEEK
0009	1297	TYPE0_LEN EQU \$-TYPE0_TABLE
0608	1298	TYPE1_TABLE LABEL BYTE
0608 1010020004	1299	DB BAD_ECC,BAD_ECC,BAD_ADDR_MARK,0,RECORD_NOT_FND
0610 400000110B	1300	DB BAD_SEEK,0,0,DATA_CORRECTED,BAD_TRACK
000A	1301	TYPE1_LEN EQU \$-TYPE1_TABLE
0615	1302	TYPE2_TABLE LABEL BTTE
0615 0102	1303	DB BAD_CHD,BAD_ADOR_MARK
0002	1304	TYPE2_LEN EQU \$-TYPE2_TABLE
0617	1305	TYPE3_TABLE LABEL BTTE
0617 202010	1306	DB BAD_CNTLRL,BAD_CNTLRL,BAD_ECC
0003	1307	TYPE3_LEN EQU \$-TYPE3_TABLE
	1308	
	1309	I----- TYPE 0 ERROR
	1310	
061A	1311	TYPE_0:
061A BB0206	1312	MOV BX,OFFSET TYPE0_TABLE
061D 3C09	1313	CHP AL,TYPE0_LEN ; CHECK IF ERROR IS DEFINED
061F 7363	1314	JAE UNDEF_ERR_L
0621 2ED7	1315	XLAT CS:TYPE0_TABLE ; TABLE LOOKUP
0623 A27400	1316	MOV DISK_STATUS,AL ; SET ERROR CODE
0626 C3	1317	RET
	1318	
	1319	I----- TYPE 1 ERROR
	1320	
0627	1321	TYPE_1:
0627 BB0B06	1322	MOV BX,OFFSET TYPE1_TABLE
062A 8BCB	1323	MOV CX,AX
062C 3C0A	1324	CHP AL,TYPE1_LEN ; CHECK IF ERROR IS DEFINED
062E 7354	1325	JAE UNDEF_ERR_L
0630 2ED7	1326	XLAT CS:TYPE1_TABLE ; TABLE LOOKUP
0632 A27400	1327	MOV DISK_STATUS,AL ; SET ERROR CODE
0635 80E108	1328	AND CL,DSH ; CORRECTED ECC
0638 80F908	1329	CHP CL,DSH
063B 752A	1330	JNZ G30
	1331	
	1332	I----- OBTAIN ECC ERROR BURST LENGTH
	1333	
0630 C606420000	1334	MOV CMD_BLOCK+0,RO_ECC_CMD
0642 2AC0	1335	SUB AL,AL
0644 E81BFF	1336	CALL COMMAND
0647 721E	1337	JC G30
0649 E83E00	1338	CALL HD_WAIT_REQ
064C 7219	1339	JC G30
064E E82001	1340	CALL PORT_0
0651 EC	1341	IN AL,DX
0652 8AC8	1342	MOV CL,AL
0654 E83300	1343	CALL HD_WAIT_REQ
0657 720E	1344	JC G30
0659 E81501	1345	CALL PORT_0
065C EC	1346	IN AL,DX
065D A801	1347	TEST AL,D1H
065F 7406	1348	JZ G30
0661 C606740020	1349	MOV DISK_STATUS,BAD_CNTLRL
0666 F9	1350	STC
0667	1351	G30: MOV AL,CL
0667 8AC1	1352	
0669 C3	1353	RET
	1354	
	1355	I----- TYPE 2 ERROR
	1356	
066A	1357	TYPE_2:
066A BB1506	1358	MOV BX,OFFSET TYPE2_TABLE
066D 3C02	1359	CHP AL,TYPE2_LEN ; CHECK IF ERROR IS DEFINED
066F 7313	1360	JAE UNDEF_ERR_L
0671 2ED7	1361	XLAT CS:TYPE2_TABLE ; TABLE LOOKUP
0673 A27400	1362	MOV DISK_STATUS,AL ; SET ERROR CODE
0676 C3	1363	RET
	1364	
	1365	I----- TYPE 3 ERROR
	1366	
0677	1367	TYPE_3:
0677 BB1706	1368	MOV BX,OFFSET TYPE3_TABLE
067A 3C03	1369	CHP AL,TYPE3_LEN
067C 7306	1370	JAE UNDEF_ERR_L
067E 2ED7	1371	XLAT CS:TYPE3_TABLE

LOC OBJ	LINE	SOURCE
0680 A27400	1372	HDV DISK_STATUS,AL
0683 C3	1373	RET
	1374	
0684	1375	UNDEF_ERR_L:
0684 C6867400BB	1376	MOV DISK_STATUS,UNDEF_ERR
0689 C3	1377	RET
	1378	
068A	1379	HD_WAIT_REQ PROC NEAR
068A 51	1380	PUSH CX
068B 28C9	1381	SUB CX,CX
068D E8EE00	1382	CALL PORT_1
0690	1383	L1:
0690 EC	1384	JH AL,BX
0691 A801	1385	TEST AL,RI_REQ
0693 7508	1386	JNZ L2
0695 E2F9	1387	LOOP L1
0697 C6867400BB	1388	HDV DISK_STATUS,TIME_OUT
069C F9	1389	STC
069D	1390	L2:
069D 59	1391	PDP CX
069E C3	1392	RET
	1393	NO_WAIT_REQ ENDP
	1394	
	1395	-----
	1396	; DMA_SETUP ;
	1397	; THIS ROUTINE SETS UP FOR DMA OPERATIONS. ;
	1398	; INPUT ;
	1399	; [AL] = MODE BYTE FOR THE DMA ;
	1400	; [ES:BX] = ADDRESS TO READ/WRITE THE DATA ;
	1401	; OUTPUT ;
	1402	; [AX] DESTROYED ;
	1403	-----
069F	1404	DMA_SETUP PROC NEAR
069F 50	1405	PUSH AX
06A0 A04600	1406	MOV AL,CMD_BLOCK+4
06A3 3CB1	1407	CMP AL,01H ; BLOCK COUNT OUT OF RANGE
06A5 58	1408	POP AX
06A6 7202	1409	JB J1
06A8 F9	1410	STC
06A9 C3	1411	RET
06AA	1412	J1:
06AA 51	1413	PUSH CX ; SAVE THE REGISTER
06AB FA	1414	CLI ; NO MORE INTERRUPTS
06AC E60C	1415	DUT DMA+12,AL ; SET THE FIRST/LAST F/F
06AE 50	1416	PUSH AX
06AF 58	1417	POP AX
06B0 E60B	1418	OUT DMA+11,AL ; OUTPUT THE MODE BYTE
06B2 8CC0	1419	MOV AX,ES ; GET THE ES VALUE
06B4 B104	1420	MOV CL,4 ; SHIFT COUNT
06B6 03C0	1421	RDL AX,CL ; ROTATE LEFT
06B8 8AE8	1422	MOV CH,AL ; GET HIGHEST BYTE OF ES TO CH
06BA 24F0	1423	AND AL,0F0H ; ZERO THE LOW BYTE FROM SEGMENT
06BC 03C3	1424	ADO AX,BX ; TEST FOR CARRY FROM ADDITION
06BE 7302	1425	JNC J33
06C0 FEC5	1426	INC CH ; CARRY MEANS HIGH 4 BITS MUST BE INC
06C2	1427	J33:
06C2 50	1428	PUSH AX ; SAVE START ADDRESS
06C3 E606	1429	DUT DMA+6,AL ; OUTPUT LOW ADDRESS
06C5 8AC4	1430	MOV AL,AH
06C7 E606	1431	DUT DMA+6,AL ; OUTPUT HIGH ADDRESS
06C9 8AC5	1432	MOV AL,CH ; GET HIGH 4 BITS
06CB 240F	1433	AND AL,0FH
06CD E682	1434	OUT DMA_HIGH,AL ; OUTPUT THE HIGH 4 BITS TO PAGE REG
	1435	
	1436	----- DETERMINE COUNT
	1437	
06CF A04600	1438	MOV AL,CMD_BLOCK+4 ; RECOVER BLOCK COUNT
06D2 D0E0	1439	SHL AL,1 ; MULTIPLY BY 512 BYTES PER SECTOR
06D4 FEC0	1440	DEC AL ; AND DECREMENT VALUE BY ONE
06D6 8AE0	1441	MOV AH,AL
06D8 B0FF	1442	MOV AL,0FFH
	1443	
	1444	----- HANDLE READ AND WRITE LONG (5160 BYTE BLOCKS)
	1445	
06DA 50	1446	PUSH AX ; SAVE REGISTER
06DB A04200	1447	MOV AL,CMD_BLOCK+0 ; GET COMMAND
06DE 3CE5	1448	CHP AL,RD_LONG_CMD

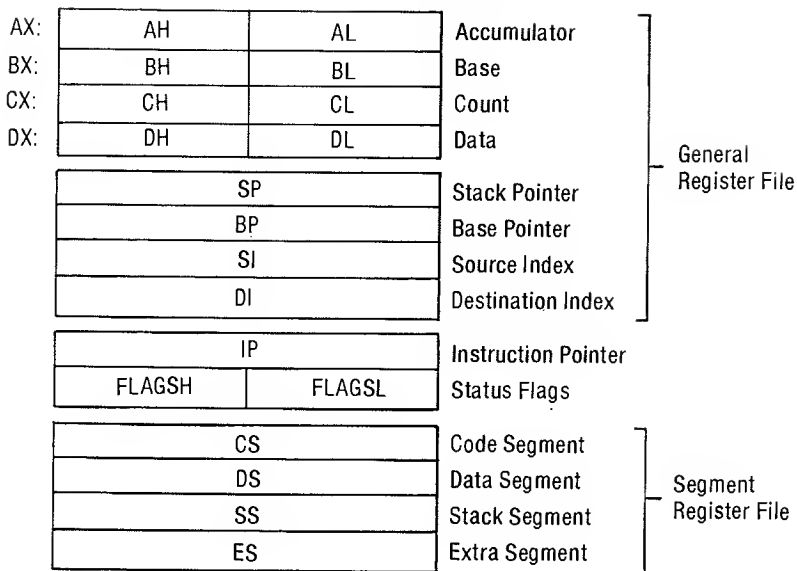
LOC OBJ	LINE	SOURCE
06E0 7407	1449	JE ADD4
06E2 3CE6	1450	CHP AL,HR_LONG_CHD
06E4 7403	1451	JE ADD4
06E6 58	1452	POP AX ; RESTORE REGISTER
06E7 EB11	1453	JMP SHORT J20
06E9	1454	ADD4:
06E9 58	1455	POP AX ; RESTORE REGISTER
06EA B80402	1456	MOV AX,5160 ; ONE BLOCK (512) PLUS 4 BYTES ECC
06ED 53	1457	PUSH BX
06EE 2AFF	1458	SUB BH,BH
06F0 8A1E4600	1459	MOV BL,CHD_BLOCK+4
06F4 52	1460	PUSH DX
06F5 F7E3	1461	MUL BX ; BLOCK COUNT TIMES 516
06F7 5A	1462	POP DX
06F8 5B	1463	POP BX
06F9 48	1464	DEC AX ; ADJUST
06FA	1465	J20:
	1466	
06FA 50	1467	PUSH AX ; SAVE COUNT VALUE
06FB E607	1468	OUT DMA+7,AL ; LOW BYTE OF COUNT
06FD 8AC4	1469	MOV AL,AH
06FF E607	1470	OUT DMA+7,AL ; HIGH BYTE OF COUNT
0701 FB	1471	STI ; INTERRUPTS BACK ON
0702 59	1472	POP CX ; RECOVER COUNT VALUE
0703 58	1473	POP AX ; RECOVER ADDRESS VALUE
0704 03C1	1474	ADD AX,CX ; ADD, TEST FOR 64K OVERFLOW
0706 59	1475	POP CX ; RECOVER REGISTER
0707 C3	1476	RET ; RETURN TO CALLER, CFL SET BY ABOVE IF ERROR
	1477	OHA_SETUP ENDP
	1478	
	1479	-----
	1480	WAIT_INT :
	1481	; THIS ROUTINE WAITS FOR THE FIXED DISK :
	1482	; CONTROLLER TO SIGNAL THAT AN INTERRUPT :
	1483	; HAS OCCURRED. :
	1484	-----
0708	1485	WAIT_INT PROC NEAR
0708 F8	1486	STI ; TURN ON INTERRUPTS
0709 53	1487	PUSH BX ; PRESERVE REGISTERS
070A 51	1488	PUSH CX
070B 06	1489	PUSH ES
070C 56	1490	PUSH SI
070D 1E	1491	PUSH DS
	1492	ASSUME DS:OUPHY
070E 2BC0	1493	SUB AX,AX
0710 8ED6	1494	MOV OS,AX ; ESTABLISH SEGMENT
0712 C4360601	1495	LES SI,HF_TBL_VEC
	1496	ASSUME OS:DATA
0716 1F	1497	POP DS
	1498	
	1499	----- SET TIMEOUT VALUES
	1500	
0717 2AFF	1501	SUB BH,BH
0719 268A5C09	1502	MOV BL,BYTE PTR ES:[SI+9] ; STANDARD TIME OUT
071D 8A264200	1503	MOV ...
0721 80FC04	1504	CHP AH,FHDRV_CHD
0724 7506	1505	JNZ W5
0726 268A5C0A	1506	MOV BL,BYTE PTR ES:[SI+0AH] ; FORMAT DRIVE
072A EB09	1507	JMP SHORT W4
072C 80FCE3	1508	W5: CHP AH,CHK_ORV_CHD
072F 7504	1509	JNZ W4
0731 268A5C0B	1510	MOV BL,BYTE PTR ES:[SI+0BH] ; CHECK DRIVE
0735	1511	W4:
0735 2BC9	1512	SUB CX,CX
	1513	
	1514	----- WAIT FOR INTERRUPT
	1515	
0737	1516	W1:
0737 E84400	1517	CALL PORT_1
073A EC	1518	IN AL,0X
073B 2420	1519	AND AL,020H
073D 3C20	1520	CHP AL,020H ; I/O INTERRUPT OCCUR
073F 740A	1521	JZ W2
0741 E2F4	1522	LOOP W1 ; INNER LOOP
0743 4B	1523	DEC BX
0744 75F1	1524	JNZ W1 ; OUTER LOOP
0746 C606740080	1525	MOV OISK_STATUS,TIME_OUT
074B	1526	W2:

LOC OBJ	LINE	SOURCE	
0740 E82300	1527	CALL	PORT_0
074E EC	1528	IN	AL,0X
074F 2402	1529	AND	AL,2
0751 08067400	1530	OR	OISK_STATUS,AL
0755 E83000	1531	CALL	PORT_3
0758 32C0	1532	XOR	AL,AL
075A EE	1533	OUT	0X,AL
075B 5E	1534	POP	SI
075C 07	1535	POP	ES
075D 59	1536	POP	CX
075E 5B	1537	POP	DX
075F C3	1538	RET	
	1539	WAIT_INT	ENDP
	1540		
0760	1541	HO_INT PROC	NEAR
0760 50	1542	PUSH	AX
0761 B020	1543	MOV	AL,EOI
0763 E620	1544	OUT	INT_CTL_PORT,AL
0765 B007	1545	MOV	AL,07H
0767 E60A	1546	OUT	0MA+10,AL
0769 E421	1547	IN	AL,021H
076B 0C20	1548	OR	AL,020H
076D E621	1549	OUT	021H,AL
076F 58	1550	POP	AX
0770 CF	1551	IRET	
	1552	NO_INT ENDP	
	1553		
	1554		-----
	1555	PORTS	:
	1556	GENERATE PROPER PORT VALUE	:
	1557	BASED ON THE PORT OFFSET	:
	1558		-----
	1559		
0771	1560	PORT_0 PROC	NEAR
0771 BA2003	1561	MOV	0X,HF_PORT
0774 50	1562	PUSH	AX
0775 2AE4	1563	SUB	AH,AH
0777 A07700	1564	MOV	AL,PORT_OFF
077A 0300	1565	ADD	0X,AX
077C 58	1566	POP	AX
077D C3	1567	RET	
	1568	PORT_0 ENDP	
	1569		
077E	1570	PORT_1 PROC	NEAR
077E E8F0FF	1571	CALL	PORT_0
0781 42	1572	INC	0X
0782 C3	1573	RET	
	1574	PORT_1 ENDP	
	1575		
0783	1576	PORT_2 PROC	NEAR
0783 E8F8FF	1577	CALL	PORT_1
0786 42	1578	INC	0X
0787 C3	1579	RET	
	1580	PORT_2 ENDP	
	1581		
0788	1582	PORT_3 PROC	NEAR
0788 E8F8FF	1583	CALL	PORT_2
078B 42	1584	INC	0X
078C C3	1585	RET	
	1586	PORT_3 ENDP	
	1587		
	1588		-----
	1589	SM2_OFFS	:
	1590	DETERMINE PARAMETER TABLE OFFSET	:
	1591	USING CONTROLLER PORT TWO AND	:
	1592	ORIVE NUMBER SPECIFIER (0-1)	:
	1593		-----
	1594		
078D	1595	SM2_OFFS	PROC NEAR
078D E8F3FF	1596	CALL	PORT_2
0790 EC	1597	IN	AL,0X
0791 50	1598	PUSH	AX
0792 E8E9FF	1599	CALL	PORT_1
0795 EC	1600	IN	AL,0X
0796 2402	1601	AND	AL,2
0798 58	1602	POP	AX
0799 7516	1603	JNZ	SM2_OFFS_ERR
079B 8A264300	1604	MOV	AH,CMD_BLOCK+1

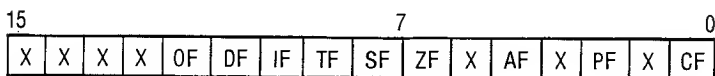
LOC OBJ	LINE	SOURCE	
079F 00E420	1605	AND AH,00100000B	; DRIVE 0 OR 1
07A2 7504	1606	JNZ SW2_AND	
07A4 D0E0	1607	SHR AL,1	; ADJUST
07A6 D0E0	1608	SHR AL,1	
07A8	1609	SW2_AND:	
07AB 2403	1610	AND AL,011B	; ISOLATE
07AA B104	1611	MOV CL,4	
07AC D2E0	1612	SHL AL,CL	; ADJUST
07AE 2AE4	1613	SUB AH,AH	
07B0 C3	1614	RET	
07B1	1615	SW2_DFFS_ERR:	
07B1 F9	1616	STC	
07B2 C3	1617	RET	
	1618	SW2_OFFS	ENDP
	1619		
07B3 30302F31362F3032	1620	DB '08/16/82'	; RELEASE MARKER
	1621		
07BB	1622	END_ADDRESS	LABEL BYTE
----	1623	CODE ENDS	
	1624	END	

APPENDIX B: 8088 ASSEMBLY INSTRUCTION SET REFERENCE

8088 Register Model



Instructions which reference the flag register file as a 16-bit object use the symbol **FLAGS** to represent the file:



x = Don't Care

AF: Auxiliary Carry - BCD	<div style="font-size: 4em;">}</div> 8080 Flags
CF: Carry Flag	
PF: Parity Flag	
SF: Sign Flag	
ZF: Zero Flag	

DF: Direction Flag (Strings)	<div style="font-size: 4em;">}</div> 8088 Flags
IF: Interrupt Enable Flag	
OF: Overflow Flag ($CF \oplus SF$)	
TF: Trap - Single Step Flag	

Operand Summary

"reg field Bit Assignments:

16-Bit (w=1)	8-Bit (w=0)	Segment
000 AX	000 AL	00 ES
001 CX	001 CL	01 CS
010 DX	010 DL	10 SS
011 BX	011 BL	11 DS
100 SP	100 AH	
101 BP	101 CH	
110 SI	110 DH	
111 DI	111 BH	

Second Instruction Byte Summary

mod	xxx	r/m
-----	-----	-----

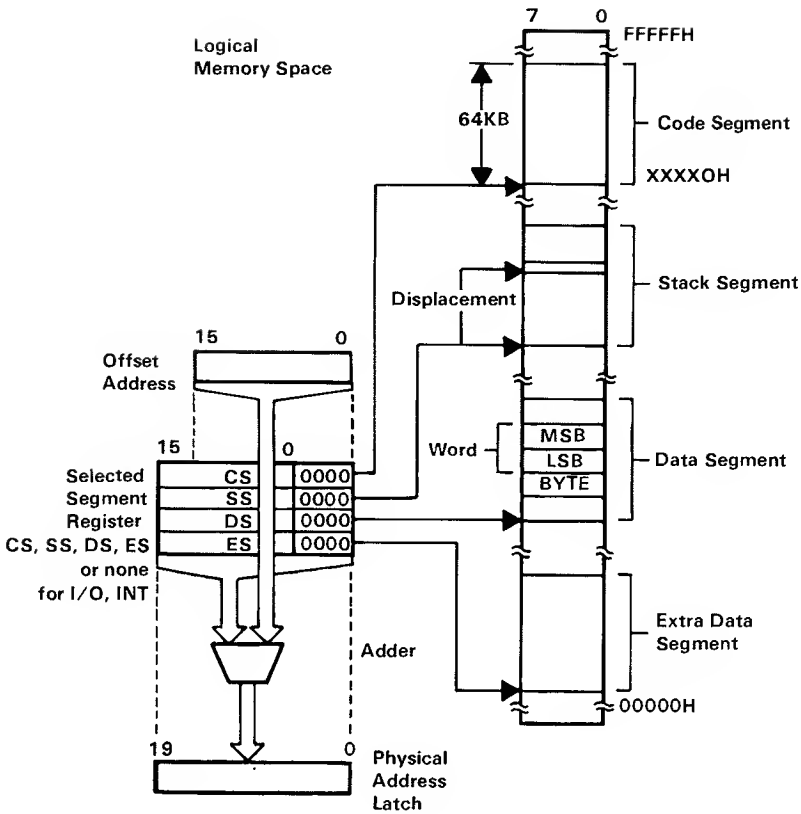
mod	Displacement
00	DISP=0*, disp-low and disp-high are absent
01	DISP=disp-low sign-extended to 16-bits, disp-high is absent
10	DISP=disp-high: disp-low
11	r/m is treated as a "reg" field

r/m	Operand Address
000	(BX) + (SI) + DISP
001	(BX) + (DI) + DISP
010	(BP) + (SI) + DISP
011	(BP) + (DI) + DISP
100	(SI) + DISP
101	(DI) + DISP
110	(BP) + DISP*
111	(BX) + DISP

DISP follows 2nd byte of instruction (before data if required).

*except if mod = 00 and r/m = 110 then EA = disp-high: disp-low.

Memory Segmentation Model



Segment Override Prefix

0 0 1 reg 1 1 0

Use of Segment Override

Operand Register	Default	With Override Prefix
IP (Code Address)	CS	Never
SP (Stack Address)	SS	Never
BP (Stack Address or Stack Marker)	SS	BP + DS or ES, or CS
SI or DI (not including strings)	DS	ES, SS, or CS
SI (Implicit Source Address for Strings)	DS	ES, SS, or CS
DI (Implicit Destination Address for Strings)	ES	Never

Data Transfer

MOV = Move

Register/memory to/from register

1	0	0	0	1	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	1	0	0	0	1	1	w	mod	0	0	0	r/m	data	data if w=1
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	-------------

Immediate to register

1	0	1	1	w	reg	data	data if w=1
---	---	---	---	---	-----	------	-------------

Memory to accumulator

1	0	1	0	0	0	0	w	addr-low	addr-high
---	---	---	---	---	---	---	---	----------	-----------

Accumulator to memory

1	0	1	0	0	0	1	w	addr-low	addr-high
---	---	---	---	---	---	---	---	----------	-----------

Register/memory to segment register

1	0	0	0	1	1	1	0	mod	0	reg	r/m
---	---	---	---	---	---	---	---	-----	---	-----	-----

Segment register to register/memory

1	0	0	0	1	1	0	0	mod	0	reg	r/m
---	---	---	---	---	---	---	---	-----	---	-----	-----

PUSH = Push

Register/memory

1	1	1	1	1	1	1	1	mod	1	1	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Register

0	1	0	1	0	reg
---	---	---	---	---	-----

Segment register

0	0	0	reg	1	1	0
---	---	---	-----	---	---	---

POP = Pop

Register/memory

1	0	0	0	1	1	1	1	mod	0	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Register

0	1	0	1	1	reg
---	---	---	---	---	-----

Segment register

0	0	0	reg	1	1	1
---	---	---	-----	---	---	---

XCHG = Exchange

Register/memory with register

1	0	0	0	0	1	1	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Register with accumulator

1	0	0	1	0	reg
---	---	---	---	---	-----

IN = Input to AL/AX from

Fixed port

1	1	1	0	0	1	0	w	port
---	---	---	---	---	---	---	---	------

Variable port (DX)

1	1	1	0	1	1	0	w
---	---	---	---	---	---	---	---

OUT = Output from AL/AX to

Fixed port

1	1	1	0	0	1	1	w	port
---	---	---	---	---	---	---	---	------

Variable port (DX)

1	1	1	0	1	1	0	w
---	---	---	---	---	---	---	---

XLAT = Translate byte to AL

1	1	0	1	0	1	1	1
---	---	---	---	---	---	---	---

LEA = Load EA to register

1	0	0	0	1	1	0	1	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

LDS = Load pointer to DS

1	1	0	0	0	1	0	1	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

LES = Load pointer to ES

1	1	0	0	0	1	0	0	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

LAHF = Load AH with flags

1	0	0	1	1	1	1	1
---	---	---	---	---	---	---	---

SAHF = Store AH into flags

1	0	0	1	1	1	1	0
---	---	---	---	---	---	---	---

PUSHF = Push flags

1	0	0	1	1	1	0	0
---	---	---	---	---	---	---	---

POPF = Pop flags

1	0	0	1	1	1	0	1
---	---	---	---	---	---	---	---

Arithmetic

ADD = Add

Register/memory with register to either

0	0	0	0	0	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	0	0	0	0	0	s	w	mod	0	0	0	r/m	data	data if s:w=01
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	----------------

Immediate to accumulator

0	0	0	0	0	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

ADC = Add with carry

Register/memory with register to either

0	0	0	1	0	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	0	0	0	0	0	s	w	mod	0	1	0	r/m	data	data if s:w=01
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	----------------

Immediate to accumulator

0	0	0	1	0	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

INC = Increment

Register/memory

1	1	1	1	1	1	1	w	mod	0	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Register

0	1	0	0	0	reg
---	---	---	---	---	-----

AAA = ASCII adjust for add

0	0	1	1	0	1	1	1
---	---	---	---	---	---	---	---

DAA = Decimal adjust for add

0	0	1	0	0	1	1	1
---	---	---	---	---	---	---	---

SUB = Subtract

Register/memory and register to either

0	0	1	0	1	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate from register/memory

1	0	0	0	0	0	s	w	mod	1	0	1	r/m	data	data if s:w=01
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	----------------

Immediate from accumulator

0	0	1	0	1	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

SBB = Subtract with borrow

Register/memory and register to either

0	0	0	1	1	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate from register/memory

1	0	0	0	0	0	s	w	mod	0	1	1	r/m	data	data if s:w=01
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	----------------

Immediate from accumulator

0	0	0	1	1	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

DEC = Decrement

Register/memory

1	1	1	1	1	1	1	w	mod	0	0	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Register

0	1	0	0	1	reg
---	---	---	---	---	-----

NEG = Change sign

1	1	1	1	0	1	1	w	mod	0	1	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

CMP = Compare

Register/memory and register

0	0	1	1	1	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate with register/memory

1	0	0	0	0	0	s	w	mod	1	1	1	r/m	data	data if s:w=01
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	----------------

Immediate with accumulator

0	0	1	1	1	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

AAS = ASCII adjust for subtract

0	0	1	1	1	1	1	1
---	---	---	---	---	---	---	---

DAS = Decimal adjust for subtract

0	0	1	0	1	1	1	1
---	---	---	---	---	---	---	---

MUL = Multiply (unsigned)

1	1	1	1	0	1	1	w	mod	1	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

IMUL = Integer multiply (signed)

1	1	1	1	0	1	1	w	mod	1	0	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

AAM = ASCII adjust for multiply

1	1	0	1	0	1	0	0	0	0	0	1	0	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

DIV = Divide (unsigned)

1	1	1	1	0	1	1	w	mod	1	1	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

IDIV = Integer divide (signed)

1	1	1	1	0	1	1	w	mod	1	1	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

AAD = ASCII adjust for divide

1	1	0	1	0	1	0	1	0	0	0	0	1	0	1	0
---	---	---	---	---	---	---	---	---	---	---	---	---	---	---	---

CBW = Convert byte to word

1	0	0	1	1	0	0	0
---	---	---	---	---	---	---	---

CWD = Convert word to double word

1	0	0	1	1	0	0	1
---	---	---	---	---	---	---	---

Logic

NDT = Invert

1	1	1	1	0	1	1	w	mod	0	1	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

SHL/SAL = Shift logical/arithmetic left

1	1	0	1	0	0	v	w	mod	1	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

SHR = Shift logical right

1	1	0	1	0	0	v	w	mod	1	0	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

SAR = Shift arithmetic right

1	1	0	1	0	0	v	w	mod	1	1	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

ROL = Rotate left

1	1	0	1	0	0	v	w	mod	0	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

RDR = Rotate right

1	1	0	1	0	0	v	w	mod	0	0	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

RCL = Rotate through carry left

1	1	0	1	0	0	v	w	mod	0	1	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

RCR = Rotate through carry right

1	1	0	1	0	0	v	w	mod	0	1	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

AND = And

Register/memory and register to either

0	0	1	0	0	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	0	0	0	0	0	0	w	mod	1	0	0	r/m	data	data if w=1
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	-------------

Immediate to accumulator

0	0	1	0	0	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

TEST = And function to flags, no result
Register/memory and register

1	0	0	0	0	1	0	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate data and register/memory

1	1	1	1	0	1	1	w	mod	0	0	0	r/m	data	data if w=1
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	-------------

Immediate data and accumulator

1	0	1	0	1	0	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

OR = OR

Register/memory and register to either

0	0	0	0	1	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	0	0	0	0	0	0	w	mod	0	0	1	r/m	data	data if w=1
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	-------------

Immediate to accumulator

0	0	0	0	1	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

XOR = Exclusive or

Register/memory and register to either

0	0	1	1	0	0	d	w	mod	reg	r/m
---	---	---	---	---	---	---	---	-----	-----	-----

Immediate to register/memory

1	0	0	0	0	0	0	w	mod	1	1	0	r/m	data	data if w=1
---	---	---	---	---	---	---	---	-----	---	---	---	-----	------	-------------

Immediate to accumulator

0	0	1	1	0	1	0	w	data	data if w=1
---	---	---	---	---	---	---	---	------	-------------

String Manipulation

REP = Repeat

1	1	1	1	0	0	1	z
---	---	---	---	---	---	---	---

MOVS = Move String

1	0	1	0	0	1	0	w
---	---	---	---	---	---	---	---

CMPS = Compare String

1	0	1	0	0	1	1	w
---	---	---	---	---	---	---	---

SCAS = Scan String

1	0	1	0	1	1	1	w
---	---	---	---	---	---	---	---

LODS = Load String

1	0	1	0	1	1	0	w
---	---	---	---	---	---	---	---

STOS = Store String

1	0	1	0	1	0	1	w
---	---	---	---	---	---	---	---

Control Transfer

CALL = Call

Direct within segment

1	1	1	0	1	0	0	0	disp-low	disp-high
---	---	---	---	---	---	---	---	----------	-----------

Indirect within segment

1	1	1	1	1	1	1	1	mod	0	1	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Direct intersegment

1	0	0	1	1	0	1	0	offset-low	offset-high
---	---	---	---	---	---	---	---	------------	-------------

seg-low	seg-high
---------	----------

Indirect intersegment

1	1	1	1	1	1	1	1	mod	0	1	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

JMP = Unconditional Jump

Direct within segment

1	1	1	0	1	0	0	1	disp-low	disp-high
---	---	---	---	---	---	---	---	----------	-----------

Direct within segment-short

1	1	1	0	1	0	1	1	disp
---	---	---	---	---	---	---	---	------

Indirect within segment

1	1	1	1	1	1	1	1	mod	1	0	0	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Direct intersegment

1	1	1	0	1	0	1	0	offset-low	offset-high
---	---	---	---	---	---	---	---	------------	-------------

seg-low	seg-high
---------	----------

Indirect intersegment

1	1	1	1	1	1	1	1	mod	1	0	1	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

RET = Return from CALL

Within segment

1	1	0	0	0	0	1	1
---	---	---	---	---	---	---	---

Within segment adding immediate to SP

1	1	0	0	0	0	1	0
data-low				data-high			

Intersegment

1	1	0	0	1	0	1	1
---	---	---	---	---	---	---	---

Intersegment, adding immediate to SP

1	1	0	0	0	0	1	0
data-low				data-high			

JE/JZ = Jump on equal/zero

0	1	1	1	0	1	0	0
disp							

JL/JNGE = Jump on less/not greater or equal

0	1	1	1	1	1	0	0
disp							

JLE/JNG = Jump on less or equal/not greater

0	1	1	1	1	1	1	0
disp							

JB/JNAE = Jump on below/not above or equal

0	1	1	1	0	0	1	0
disp							

JBE/JNA = Jump on below or equal/not above

0	1	1	1	0	1	1	0
disp							

JP/JPE = Jump on parity/parity even

0	1	1	1	1	0	1	0
disp							

JO = Jump on overflow

0	1	1	1	0	0	0	0
disp							

JS = Jump on sign

0	1	1	1	1	0	0	0
disp							

JNE/JNZ = Jump on not equal/not zero

0	1	1	1	0	1	0	1
disp							

JNL/JGE = Jump on not less/greater or equal

0	1	1	1	1	1	0	1
disp							

JNLE/JG = Jump on not less or equal/greater

0 1 1 1 1 1 1 1	disp
-----------------	------

JNB/JAE = Jump on not below/above or equal

0 1 1 1 0 0 1 1	disp
-----------------	------

JNBE/JA = Jump on not below or equal/above

0 1 1 1 0 1 1 1	disp
-----------------	------

JNP/JPO = Jump on not parity/parity odd

0 1 1 1 1 0 1 1	disp
-----------------	------

JNO = Jump on not overflow

0 1 1 1 0 0 0 1	disp
-----------------	------

JNS = Jump on not sign

0 1 1 1 1 0 0 1	disp
-----------------	------

LOOP = Loop CX times

1 1 1 0 0 0 1 0	disp
-----------------	------

LOOPZ/LOOPE = Loop while zero/equal

1 1 1 0 0 0 0 1	disp
-----------------	------

LOOPNZ/LOOPNE = Loop while not zero/not equal

1 1 1 0 0 0 0 0	disp
-----------------	------

JCXZ = Jump on CX zero

1 1 1 0 0 0 1 1	disp
-----------------	------

8088 Conditional Transfer Operations

Instruction	Condition	Interpretation
JE or JZ	ZF = 1	"equal" or "zero"
JL or JNGE	(SF xor OF) = 1	"less" or "not greater or equal"
JLE or JNG	((SF xor OF) or ZF) = 1	"less or equal" or "not greater"
JB or JNAE or JC	CF = 1	"below" or "not above or equal"
JBE or JNA	(CF or ZF) = 1	"below or equal" or "not above"
JP or JPE	PF = 1	"parity" or "parity even"
JO	OF = 1	"overflow"
JS	SF = 1	"sign"
JNE or JNZ	ZF = 0	"not equal" or "not zero"
JNL or JGE	(SF xor OF) = 0	"not less" or "greater or equal"
JNLE or JG	((SF xor OF) or ZF) = 0	"not less or equal" or "greater"
JNB or JAE or JNC	CF = 0	"not below" or "above or equal"
JNBE or JA	(CF or ZF) = 0	"not below or equal" or "above"
JNP or JPO	PF = 0	"not parity" or "parity odd"
JNO	OF = 0	"not overflow"
JNS	SF = 0	"not sign"

*"Above" and "below" refer to the relation between two unsigned values, while "greater" and "less" refer to the relation between two signed values.

INT = Interrupt
Type specified

1	1	0	0	1	1	0	1	type
---	---	---	---	---	---	---	---	------

Type 3

1	1	0	0	1	1	0	0
---	---	---	---	---	---	---	---

INT0 = Interrupt on overflow

1	1	0	0	1	1	1	0
---	---	---	---	---	---	---	---

IRET = Interrupt return

1	1	0	0	1	1	1	1
---	---	---	---	---	---	---	---

Processor Control

CLC = Clear carry

1	1	1	1	1	0	0	0
---	---	---	---	---	---	---	---

STC = Set carry

1	1	1	1	1	0	0	1
---	---	---	---	---	---	---	---

CMC = Complement carry

1	1	1	1	0	1	0	1
---	---	---	---	---	---	---	---

NOP = No operation

1	0	0	1	0	0	0	0
---	---	---	---	---	---	---	---

CLD = Clear direction

1	1	1	1	1	1	0	0
---	---	---	---	---	---	---	---

STD = Set direction

1	1	1	1	1	1	0	1
---	---	---	---	---	---	---	---

CLI = Clear interrupt

1	1	1	1	1	0	1	0
---	---	---	---	---	---	---	---

STI = Set interrupt

1	1	1	1	1	0	1	1
---	---	---	---	---	---	---	---

HLT = Halt

1	1	1	1	0	1	0	0
---	---	---	---	---	---	---	---

WAIT = Wait

1	0	0	1	1	0	1	1
---	---	---	---	---	---	---	---

LOCK = Bus lock prefix

1	1	1	1	0	0	0	0
---	---	---	---	---	---	---	---

ESC = Escape (to external device)

1	1	0	1	1	x	x	x	mod	x	x	x	r/m
---	---	---	---	---	---	---	---	-----	---	---	---	-----

Footnotes:

if d = 1 then "to"; if d = 0 then "from"

if w = 1 then word instruction; if w = 0 then byte instruction

if s:w = 01 then 16 bits of immediate data from the operand

if s:w = 11 then an immediate data byte is sign extended to form the 16-bit operand

if v = 0 then "count" = 1; if v = 1 then "count" in (CL)

x = don't care

z is used for some string primitives to compare with ZF FLAG

AL = 8-bit accumulator

AX = 16-bit accumulator

CX = Count register

DS = Data segment

DX = Variable port register

ES = Extra segment

Above/below refers to unsigned value

Greater = more positive;

Less = less positive (more negative) signed values

8088 Instruction Set Matrix

LO HI	0 1 2 3 4 5 6 7							
	0	1	2	3	4	5	6	7
0	ADD b,f,r/m	ADD w,f,r/m	ADD b,t,r/m	ADD w,t,r/m	ADD b,ia	ADD w,ia	PUSH ES	POP ES
1	ADC b,f,r/m	ADC w,f,r/m	ADC b,t,r/m	ADC w,t,r/m	ADC b,i	ADC w,i	PUSH SS	POP SS
2	AND b,f,r/m	AND w,f,r/m	AND b,t,r/m	AND w,t,r/m	AND b,i	AND w,i	SEG =ES	DAA
3	XOR b,f,r/m	XOR w,f,r/m	XOR b,t,r/m	XOR w,t,r/m	XOR b,i	XOR w,i	SEG =SS	AAA
4	INC AX	INC CX	INC DX	INC BX	INC SP	INC BP	INC SI	INC DI
5	PUSH AX	PUSH CX	PUSH DX	PUSH BX	PUSH SP	PUSH BP	PUSH SI	PUSH DI
6								
7	JO	JNO	JB/ JNAE	JNB/ JAE	JE/ JZ	JNE/ JNZ	JBE/ JNA	JNBE/ JA
8	Immed b,r/m	Immed w,r/m	Immed b,r/m	Immed is,r/m	TEST b,r/m	TEST w,r/m	XCHG b,r/m	XCHG w,r/m
9	NOP	XCHG CX	XCHG DX	XCHG BX	XCHG SP	XCHG BP	XCHG SI	XCHG DI
A	MOV m AL	MOV m AL	MOV AL m	MOV AL m	MOVS b	MOVS w	CMPS b	CMPS w
B	MOV i AL	MOV i CL	MOV i DL	MOV i BL	MOV i AH	MOV i CH	MOV i DH	MOV i BH
C			RET (i+SP)	RET	LES	LDS	MOV b,i,r/m	MOV w,i,r/m
D	Shift b	Shift w	Shift b,v	Shift w,v	AAM	AAD		XLAT
E	LOOPNZ/ LOOPNE	LOOPZ/ LOOPE	LOOP	JCXZ	IN b	IN w	OUT b	OUT w
F	LOCK		REP	REP z	HLT	CMC	Grp 1 b,r/m	Grp 1 w,r/m

b = byte operation

d = direct

f = from CPU reg

i = immediate

ia = immed. to accum.

id = indirect

is = immed. byte, sign ext.

l = long ie. intersegment

m = memory

r/m = EA is second byte

si = short intrasegment

sr = segment register

t = to CPU reg

v = variable

w = word operation

z = zero

8088 Instruction Set Matrix

HI \ LO	8	9	A	B	C	D	E	F
	0	1	2	3	4	5	6	7
0	OR b,f,r/m	w,f,r/m	OR b,t,r/m	OR w,t,r/m	OR b,i	OR w,i	PUSH CS	
1	SBB b,f,r/m	SBB w,f,r/m	SBB b,t,r/m	SBB w,t,r/m	SBB b,i	SBB w,i	PUSH DS	POP DS
2	SUB b,f,r/m	SUB w,f,r/m	SUB b,t,r/m	SUB w,t,r/m	SUB b,i	SUB w,i	SEG= CS	DAS
3	CMP b,f,r/m	CMP w,f,r/m	CMP b,t,r/m	CMP w,t,r/m	CMP b,i	CMP w,i	SEG= CS	AAS
4	DEC AX	DEC CX	DEC DX	DEC BX	DEC SP	DEC BP	DEC SI	DEC DI
5	POP AX	POP CX	POP DX	POP BX	POP SP	POP BP	POP SI	POP DI
6								
7	JS	JNS	JP/ JPE	JNP/ JPO	JL/ JNGE	JNL/ JGE	JLE/ JNG	JNLE/ JG
8	MOV b,f,r/m	MOV w,f,r/m	MOV b,t,r/m	MOV w,t,r/m	MOV sr,t,r/m	LEA	MOV sr,f,r/m	POP r/m
9	CBW	CWD	CALL l,d	WAIT	PUSHF	POPF	SAHF	LAHF
A	TEST b,i	TEST w,i	STOS b	STOS w	LODS b	LODS w	SCAS b	SCAS w
B	MOV i AX	MOV i CX	MOV i DX	MOV i BX	MOV i SP	MOV i BP	MOV i SI	MOV i DI
C			RET l,(i+SP)	RET l	INT Type 3	INT (Any)	INT0	IRET
D	ESC 0	ESC 1	ESC 2	ESC 3	ESC 4	ESC 5	ESC 6	ESC 7
E	CALL d	JMP d	JMP l,d	JMP si,d	IN v,b	IN v,w	OUT v,b	OUT v,w
F	CLC	STC	CLI	STI	CLD	STD	Grp 2 b,r/m	Grp 2 w,r/m

where:

mod \square r/m	000	001	010	011	100	101	110	111
Immed	ADD	OR	ADC	SBB	AND	SUB	XOR	CMP
Shift	ROL	ROR	RCL	RCR	SHL/SAL	SHR	—	SAR
Grp 1	TEST	—	NOT	NEG	MUL	IMUL	DIV	IDIV
Grp 2	INC	DEC	CALL id	CALL l,id	JMP id	JMP l,id	PUSH	—

Instruction Set Index

Mnemonic	Page	Mnemonic	Page	Mnemonic	Page
AAA	B-7	JG	B-13	MOV	B-5
AAD	B-9	JGE	B-12	MOVS	B-10
AAM	B-8	JL	B-12	MUL	B-8
AAS	B-8	JLE	B-12	NEG	B-8
ADC	B-7	JMP	B-11	NOP	B-15
ADD	B-7	JNA	B-12	NOT	B-9
AND	B-9	JNAE	B-12	OR	B-10
CALL	B-11	JNB	B-13	OUT	B-6
CBW	B-9	JNBE	B-13	POP	B-5
CLC	B-15	JNE	B-12	POPF	B-6
CLD	B-15	JNG	B-12	PUSH	B-5
CLI	B-15	JNGE	B-12	PUSHF	B-6
CMC	B-15	JNL	B-12	RCL	B-9
CMP	B-8	JNLE	B-13	RCR	B-9
CMPS	B-10	JNO	B-13	REP	B-10
CWD	B-9	JNP	B-13	RET	B-12
DAA	B-7	JNS	B-13	ROL	B-9
DAS	B-8	JNZ	B-12	ROR	B-9
DEC	B-8	JO	B-12	SAHF	B-6
DIV	B-8	JP	B-12	SAL	B-9
ESC	B-15	JPE	B-12	SAR	B-9
HLT	B-15	JPO	B-13	SBB	B-8
IDIV	B-9	JS	B-12	SCAS	B-10
IMUL	B-8	JZ	B-12	SHL	B-9
IN	B-6	LAHF	B-6	SHR	B-9
INC	B-7	LDS	B-6	STC	B-15
INT	B-14	LEA	B-6	STD	B-15
INTO	B-14	LES	B-6	STI	B-15
IRET	B-14	LOCK	B-15	STOS	B-11
JA	B-13	LODS	B-11	SUB	B-7
JAE	B-13	LOOP	B-13	TEST	B-10
JB	B-12	LOOPE	B-13	WAIT	B-15
JBE	B-12	LOOPNE	B-13	XCHG	B-6
JCXZ	B-13	LOOPNZ	B-13	XLAT	B-6
JE	B-12	LOOPZ	B-13	XOR	B-10

APPENDIX C: OF CHARACTERS, KEYSTROKES, AND COLOR

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
00	0	Blank (Null)	Ctrl 2		Black	Black	Non-Display
01	1	☺	Ctrl A		Black	Blue	Underline
02	2	☹	Ctrl B		Black	Green	Normal
03	3	♥	Ctrl C		Black	Cyan	Normal
04	4	♦	Ctrl D		Black	Red	Normal
05	5	♣	Ctrl E		Black	Magenta	Normal
06	6	♠	Ctrl F		Black	Brown	Normal
07	7	•	Ctrl G		Black	Light Grey	Normal
08	8	•	Ctrl H, Backspace, Shift Backspace		Black	Dark Grey	Non-Display
09	9	○	Ctrl I		Black	Light Blue	High Intensity Underline
0A	10	○	Ctrl J, Ctrl ↵		Black	Light Green	High Intensity
0B	11	♂	Ctrl K		Black	Light Green	High Intensity
0C	12	♀	Ctrl L		Black	Light Red	High Intensity
0D	13	♪	Ctrl M, ↵, Shift ↵		Black	Light Magenta	High Intensity
0E	14	♪	Ctrl N		Black	Yellow	High Intensity
0F	15	☀	Ctrl O		Black	White	High Intensity
10	16	▶	Ctrl P		Blue	Black	Normal
11	17	◀	Ctrl Q		Blue	Blue	Underline
12	18	↕	Ctrl R		Blue	Green	Normal
13	19	!!	Ctrl S		Blue	Cyan	Normal
14	20	¶	Ctrl T		Blue	Red	Normal
15	21	§	Ctrl U			Magenta	Normal
16	22	■	Ctrl V		Blue	Brown	Normal
17	23	↑	Ctrl W		Blue	Light Grey	Normal

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
18	24	↑	Ctrl X		Blue	Dark Grey	High Intensity
19	25	↓	Ctrl Y		Blue	Light Blue	High Intensity Underline
1A	26	→	Ctrl Z		Blue	Light Green	High Intensity
1B	27	←	Ctrl [, Esc, Shift Esc, Ctrl Esc		Blue	Light Cyan	High Intensity
1C	28	↖	Ctrl \		Blue	Light Red	High Intensity
1D	29	↔	Ctrl]		Blue	Light Magenta	High Intensity
1E	30	▲	Ctrl 6		Blue	Yellow	High Intensity
1F	31	▼	Ctrl _		Blue	White	High Intensity
20	32	Blank Space	Space Bar, Shift, Space, Ctrl Space, Alt Space		Green	Black	Normal
21	33	!	!	Shift	Green	Blue	Underline
22	34	"	"	Shift	Green	Green	Normal
23	35	#	#	Shift	Green	Cyan	Normal
24	36	\$	\$	Shift	Green	Red	Normal
25	37	%	%	Shift	Green	Magenta	Normal
26	38	&	&	Shift	Green	Brown	Normal
27	39	'	'		Green	Light Grey	Normal
28	40	((Shift	Green	Dark Grey	High Intensity
29	41))	Shift	Green	Light Blue	High Intensity Underline
2A	42	*	*	Note 1	Green	Light Green	High Intensity
28	43	+	+	Shift	Green	Light Cyan	High Intensity
2C	44	·	·		Green	Light Red	High Intensity
2D	45	—	—		Green	Light Magenta	High Intensity
2E	46	.	.	Note 2	Green	Yellow	High Intensity

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
2F	47	/	/		Green	White	High Intensity
30	48	0	0	Note 3	Cyan	Black	Normal
31	49	1	1	Note 3	Cyan	Blue	Underline
32	50	2	2	Note 3	Cyan	Green	Normal
33	51	3	3	Note 3	Cyan	Cyan	Normal
34	52	4	4	Note 3	Cyan	Red	Normal
35	53	5	5	Note 3	Cyan	Magenta	Normal
36	54	6	6	Note 3	Cyan	Brown	Normal
37	55	7	7	Note 3	Cyan	Light Grey	Normal
38	56	8	8	Note 3	Cyan	Dark Grey	High Intensity
39	57	9	9	Note 3	Cyan	Light Blue	High Intensity Underline
3A	58	:	:	Shift	Cyan	Light Green	High Intensity
3B	59	;	;		Cyan	Light Cyan	High Intensity
3C	60	<	<	Shift	Cyan	Light Red	High Intensity
3D	61	=	=		Cyan	Light Magenta	High Intensity
3E	62	>	>	Shift	Cyan	Yellow	High Intensity
3F	63	?	?	Shift	Cyan	White	High Intensity
40	64	@	@	Shift	Red	Black	Normal
41	65	A	A	Note 4	Red	Blue	Underline
42	66	B	B	Note 4	Red	Green	Normal
43	67	C	C	Note 4	Red	Cyan	Normal
44	68	D	D	Note 4	Red	Red	Normal
45	69	E	E	Note 4	Red	Magenta	Normal
46	70	F	F	Note 4	Red	Brown	Normal
47	71	G	G	Note 4	Red	Light Grey	Normal
48	72	H	H	Note 4	Red	Dark Grey	High Intensity
49	73	I	I	Note 4	Red	Light Blue	High Intensity Underline
4A	74	J	J	Note 4	Red	Light Green	High Intensity

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
4B	75	K	K	Note 4	Red	Light Cyan	High Intensity
4C	76	L	L	Note 4	Red	Light Red	High Intensity
4D	77	M	M	Note 4	Red	Light Magenta	High Intensity
4E	78	N	N	Note 4	Red	Yellow	High Intensity
4F	79	O	O	Note 4	Red	White	High Intensity
50	80	P	P	Note 4	Magenta	Black	Normal
51	81	Q	Q	Note 4	Magenta	Blue	Underline
52	82	R	R	Note 4	Magenta	Green	Normal
53	83	S	S	Note 4	Magenta	Cyan	Normal
54	84	T	T	Note 4	Magenta	Red	Normal
55	85	U	U	Note 4	Magenta	Magenta	Normal
56	86	V	V	Note 4	Magenta	Brown	Normal
57	87	W	W	Note 4	Magenta	Light Grey	Normal
58	88	X	X	Note 4	Magenta	Dark Grey	High Intensity
59	89	Y	Y	Note 4	Magenta	Light Blue	High Intensity Underline
5A	90	Z	Z	Note 4	Magenta	Light Green	High Intensity
5B	91	[[Magenta	Light Cyan	High Intensity
5C	92	\	\		Magenta	Light Red	High Intensity
5D	93]]		Magenta	Light Magenta	High Intensity
5E	94	^	^	Shift	Magenta	Yellow	High Intensity
5F	95	—	—	Shift	Magenta	White	High Intensity
60	96	'	'		Yellow	Black	Normal
61	97	a	a	Note 5	Yellow	Blue	Underline
62	98	b	b	Note 5	Yellow	Green	Normal
63	99	c	c	Note 5	Yellow	Cyan	Normal
64	100	d	d	Note 5	Yellow	Red	Normal
65	101	e	e	Note 5	Yellow	Magenta	Normal
66	102	f	f	Note 5	Yellow	Brown	Normal



























C-4 Of Characters, Keystrokes, and Colors
















Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
67	103	g	g	Note 5	Yellow	Light Grey	Normal
68	104	h	h	Note 5	Yellow	Dark Grey	High Intensity
69	105	i	i	Note 5	Yellow	Light Blue	High Intensity Underline
6A	106	j	j	Note 5	Yellow	Light Green	High Intensity
6B	107	k	k	Note 5	Yellow	Light Cyan	High Intensity
6C	108	l	l	Note 5	Yellow	Light Red	High Intensity
6D	109	m	m	Note 5	Yellow	Light Magenta	High Intensity
6E	110	n	n	Note 5	Yellow	Yellow	High Intensity
6F	111	o	o	Note 5	Yellow	White	High Intensity
70	112	p	p	Note 5	White	Black	Reverse Video
71	113	q	q	Note 5	White	Blue	Underline
72	114	r	r	Note 5	White	Green	Normal
73	115	s	s	Note 5	White	Cyan	Normal
74	116	f	f	Note 5	White	Red	Normal
75	117	u	u	Note 5	White	Magenta	Normal
76	118	v	v	Note 5	White	Brown	Normal
77	119	w	w	Note 5	White	Light Grey	Normal
78	120	x	x	Note 5	White	Dark Grey	Reverse Video
79	121	y	y	Note 5	White	Light Blue	High Intensity Underline
7A	122	z	z	Note 5	White	Light Green	High Intensity
7B	123	{	{	Shift	White	Light Cyan	High Intensity
7C	124			Shift	White	Light Red	High Intensity
7D	125	}	}	Shift	White	Light Magenta	High Intensity
7E	126	~	~	Shift	White	Yellow	High Intensity
7F	127	Δ	Ctrl ←		White	White	High Intensity

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
* * * * B0 to FF Hex are Flashing in both Color & IBM Monochrome * * * *							
80	128	Ç	Alt 128	Note 6	Black	Black	Non-Display
81	129	ü	Alt 129	Note 6	Black	Blue	Underline
82	130	é	Alt 130	Note 6	Black	Green	Normal
83	131	â	Alt 131	Note 6	Black	Cyan	Normal
84	132	ä	Alt 132	Note 6	Black	Red	Normal
85	133	à	Alt 133	Note 6	Black	Magenta	Normal
86	134	ã	Alt 134	Note 6	Black	Brown	Normal
87	135	ç	Alt 135	Note 6	Black	Light Grey	Normal
88	136	ê	Alt 136	Note 6	Black	Dark Grey	Non-Display
89	137	ë	Alt 137	Note 6	Black	Light Blue	High Intensity Underline
8A	138	è	Alt 138	Note 6	Black	Light Green	High Intensity
8B	139	ĩ	Alt 139	Note 6	Black	Light Cyan	High Intensity
8C	140	î	Alt 140	Note 6	Black	Light Red	High Intensity
8D	141	ì	Alt 141	Note 6	Black	Light Magenta	High Intensity
8E	142	Ä	Alt 142	Note 6	Black	Yellow	High Intensity
8F	143	Å	Alt 143	Note 6	Black	White	High Intensity
90	144	É	Alt 144	Note 6	Blue	Black	Normal
91	145	æ	Alt 145	Note 6	Blue	Blue	Underline
92	146	Æ	Alt 146	Note 6	Blue	Green	Normal
93	147	ô	Alt 147	Note 6	Blue	Cyan	Normal
94	148	ö	Alt 148	Note 6	Blue	Red	Normal
95	149	ò	Alt 149	Note 6	Blue	Magenta	Normal
96	150	û	Alt 150	Note 6	Blue	Brown	Normal
97	151	ù	Alt 151	Note 6	Blue	Light Grey	Normal
98	152	ÿ	Alt 152	Note 6	Blue	Dark Grey	High Intensity
99	153	ö	Alt 153	Note 6	Blue	Light Blue	High Intensity Underline
9A	154	ü	Alt 154	Note 6	Blue	Light Green	High Intensity





C-6 Of Characters, Keystrokes, and Colors

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
9B	155	¢	Alt 155	Note 6	Blue	Light Cyan	High Intensity
9C	156	£	Alt 156	Note 6	Blue	Light Red	High Intensity
9D	157	¥	Alt 157	Note 6	Blue	Light Magenta	High Intensity
9E	158	Pt	Alt 158	Note 6	Blue	Yellow	High Intensity
9F	159	∫	Alt 159	Note 6	Blue	White	High Intensity
A0	160	á	Alt 160	Note 6	Green	Black	Normal
A1	161	í	Alt 161	Note 6	Green	Blue	Underline
A2	162	ó	Alt 162	Note 6	Green	Green	Normal
A3	163	ú	Alt 163	Note 6	Green	Cyan	Normal
A4	164	ñ	Alt 164	Note 6	Green	Red	Normal
A5	165	Ñ	Alt 165	Note 6	Green	Magenta	Normal
A6	166	<u>a</u>	Alt 166	Note 6	Green	Brown	Normal
A7	167	<u>o</u>	Alt 167	Note 6	Green	Light Grey	Normal
A8	168	¿	Alt 168	Note 6	Green	Dark Grey	High Intensity
A9	169	┐	Alt 169	Note 6	Green	Light Blue	High Intensity Underline
AA	170	┐	Alt 170	Note 6	Green	Light Green	High Intensity
AB	171	½	Alt 171	Note 6	Green	Light Cyan	High Intensity
AC	172	¼	Alt 172	Note 6	Green	Light Red	High Intensity
AD	173	i	Alt 173	Note 6	Green	Light Magenta	High Intensity
AE	174	<<	Alt 174	Note 6	Green	Yellow	High Intensity
AF	175	>>	Alt 175	Note 6	Green	White	High Intensity
B0	176	⋮	Alt 176	Note 6	Cyan	Black	Normal
B1	177	⋈	Alt 177	Note 6	Cyan	Blue	Underline
B2	178	⋈	Alt 178	Note 6	Cyan	Green	Normal
B3	179		Alt 179	Note 6	Cyan	Cyan	Normal
B4	180		Alt 180	Note 6	Cyan	Red	Normal
B5	181		Alt 181	Note 6	Cyan	Magenta	Normal
B6	182		Alt 182	Note 6	Cyan	Brown	Normal

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
B7	183		Alt 183	Note 6	Cyan	Light Grey	Normal
B8	184		Alt 184	Note 6	Cyan	Dark Grey	High Intensity
B9	185		Alt 185	Note 6	Cyan	Light Blue	High Intensity Underline
BA	186		Alt 186	Note 6	Cyan	Light Green	High Intensity
BB	187		Alt 187	Note 6	Cyan	Light Cyan	High Intensity
BC	188		Alt 188	Note 6	Cyan	Light Red	High Intensity
BD	189		Alt 189	Note 6	Cyan	Light Magenta	High Intensity
BE	190		Alt 190	Note 6	Cyan	Yellow	High Intensity
BF	191		Alt 191	Note 6	Cyan	White	High Intensity
C0	192		Alt 192	Note 6	Red	Black	Normal
C1	193		Alt 193	Note 6	Red	Blue	Underline
C2	194		Alt 194	Note 6	Red	Green	Normal
C3	195		Alt 195	Note 6	Red	Cyan	Normal
C4	196		Alt 196	Note 6	Red	Red	Normal
C5	197		Alt 197	Note 6	Red	Magenta	Normal
C6	198		Alt 198	Note 6	Red	Brown	Normal
C7	199		Alt 199	Note 6	Red	Light Grey	Normal
C8	200		Alt 200	Note 6	Red	Dark Grey	High Intensity
C9	201		Alt 201	Note 6	Red	Light Blue	High Intensity Underline
CA	202		Alt 202	Note 6	Red	Light Green	High Intensity
CB	203		Alt 203	Note 6	Red	Light Cyan	High Intensity
CC	204		Alt 204	Note 6	Red	Light Red	High Intensity
CD	205		Alt 205	Note 6	Red	Light Magenta	High Intensity
CE	206		Alt 206	Note 6	Red	Yellow	High Intensity
CF	207		Alt 207	Note 6	Red	White	High Intensity
DO	208		Alt 208	Note 6	Magenta	Black	Normal

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
D1	209		Alt 209	Note 6	Magenta	Blue	Underline
D2	210		Alt 210	Note 6	Magenta	Green	Normal
D3	211		Alt 211	Note 6	Magenta	Cyan	Normal
D4	212		Alt 212	Note 6	Magenta	Red	Normal
D5	213		Alt 213	Note 6	Magenta	Magenta	Normal
D6	214		Alt 214	Note 6	Magenta	Brown	Normal
D7	215		Alt 215	Note 6	Magenta	Light Grey	Normal
D8	216		Alt 216	Note 6	Magenta	Dark Grey	High Intensity
D9	217		Alt 217	Note 6	Magenta	Light Blue	High Intensity Underline
DA	218		Alt 218	Note 6	Magenta	Light Green	High Intensity
DB	219		Alt 219	Note 6	Magenta	Light Cyan	High Intensity
DC	220		Alt 220	Note 6	Magenta	Light Red	High Intensity
DD	221		Alt 221	Note 6	Magenta	Light Magenta	High Intensity
DE	222		Alt 222	Note 6	Magenta	Yellow	High Intensity
DF	223		Alt 223	Note 6	Magenta	White	High Intensity
E0	224	α	Alt 224	Note 6	Yellow	Black	Normal
E1	225	β	Alt 225	Note 6	Yellow	Blue	Underline
E2	226	Γ	Alt 226	Note 6	Yellow	Green	Normal
E3	227	π	Alt 227	Note 6	Yellow	Cyan	Normal
E4	228	Σ	Alt 228	Note 6	Yellow	Red	Normal
E5	229	σ	Alt 229	Note 6	Yellow	Magenta	Normal
E6	230	μ	Alt 230	Note 6	Yellow	Brown	Normal
E7	231	τ	Alt 231	Note 6	Yellow	Light Grey	Normal
E8	232	Φ	Alt 232	Note 6	Yellow	Dark Grey	High Intensity
E9	233	θ	Alt 233	Note 6	Yellow	Light Blue	High Intensity Underline
EA	234	Ω	Alt 234	Note 6	Yellow	Light Green	High Intensity
EB	235	δ	Alt 235	Note 6	Yellow	Light Cyan	High Intensity

Value		As Characters			As Text Attributes		
					Color/Graphics Monitor Adapter		IBM Monochrome Display Adapter
Hex	Dec	Symbol	Keystrokes	Modes	Background	Foreground	
EC	236	∞	Alt 236	Note 6	Yellow	Light Red	High Intensity
ED	237	φ	Alt 237	Note 6	Yellow	Light Magenta	High Intensity
EE	238	€	Alt 238	Note 6	Yellow	Yellow	High Intensity
EF	239	∩	Alt 239	Note 6	Yellow	White	High Intensity
F0	240	≡	Alt 240	Note 6	White	Black	Reverse Video
F1	241	±	Alt 241	Note 6	White	Blue	Underline
F2	242	≧	Alt 242	Note 6	White	Green	Normal
F3	243	≦	Alt 243	Note 6	White	Cyan	Normal
F4	244	↵	Alt 244	Note 6	White	Red	Normal
F5	245	↵	Alt 245	Note 6	White	Magenta	Normal
F6	246	+	Alt 246	Note 6	White	Brown	Normal
F7	247	ℓ	Alt 247	Note 6	White	Light Grey	Normal
F8	248	○	Alt 248	Note 6	White	Dark Grey	Reverse Video
F9	249	●	Alt 249	Note 6	White	Light Blue	High Intensity Underline
FA	250	•	Alt 250	Note 6	White	Light Green	High Intensity
FB	251	√	Alt 251	Note 6	White	Light Cyan	High Intensity
FC	252	η	Alt 252	Note 6	White	Light Red	High Intensity
FD	253	2	Alt 253	Note 6	White	Light Magenta	High Intensity
FE	254	■	Alt 254	Note 6	White	Yellow	High Intensity
FF	255	BLANK	Alt 255	Note 6	White	White	High Intensity

- NOTE 1 Asterisk (*) can easily be keyed using two methods:
1) hit the  key or 2) in shift mode hit the  key.
- NOTE 2 Period (.) can easily be keyed using two methods:
1) hit the  key or 2) in shift or Num Lock mode hit the  key.
- NOTE 3 Numeric characters (0—9) can easily be keyed using two methods: 1) hit the numeric keys on the top row of the typewriter portion of the keyboard or 2) in shift or Num Lock mode hit the numeric keys in the 10—key pad portion of the keyboard.
- NOTE 4 Upper case alphabetic characters (A—Z) can easily be keyed in two modes: 1) in shift mode the appropriate alphabetic key or 2) in Caps Lock mode hit the appropriate alphabetic key.
- NOTE 5 Lower case alphabetic characters (a—z) can easily be keyed in two modes: 1) in "normal" mode hit the appropriate key or 2) in Caps Lock combined with shift mode hit the appropriate alphabetic key.
- NOTE 6 The 3 digits after the Alt key must be typed from the numeric key pad (keys 71—73, 75—77, 79—82). Character codes 000 through 255 can be entered in this fashion. (With Caps Lock activated, Character codes 97 through 122 will display upper case rather than lower case alphabetic characters.)

Character Set (00-7F) Quick Reference

DECIMAL VALUE	➡	0	16	32	48	64	80	96	112
⬇	HEXA- DECIMAL VALUE	0	1	2	3	4	5	6	7
0	0	BLANK (NULL)	▶	BLANK (SPACE)	0	@	P	‘	p
1	1	😊	◀	!	1	A	Q	a	q
2	2	😬	↕	"	2	B	R	b	r
3	3	♥	!!	#	3	C	S	c	s
4	4	♦	¶	\$	4	D	T	d	t
5	5	♣	§	%	5	E	U	e	u
6	6	♠	■	&	6	F	V	f	v
7	7	•	↕	'	7	G	W	g	w
8	8	●	↑	(8	H	X	h	x
9	9	○	↓)	9	I	Y	i	y
10	A	◯	→	*	:	J	Z	j	z
11	B	♂	←	+	;	K	I	k	{
12	C	♀	└	,	<	L	\	l	
13	D	🎵	↔	—	=	M	I	m	}
14	E	🎵	▲	.	>	N	^	n	~
15	F	☀	▼	/	?	O	—	o	△

Character Set (80-FF) Quick Reference

DECIMAL VALUE	➡	128	144	160	176	192	208	224	240
⬇	HEXA- DECIMAL VALUE	8	9	A	B	C	D	E	F
0	0	Ç	É	á	▤	▥	▦	∞	≡
1	1	ü	æ	í	▧	▨	▩	β	±
2	2	é	Æ	ó	▪	▫	▬	Γ	≥
3	3	â	ô	ú	▭	▮	▯	π	≤
4	4	ä	ö	ñ	▰	▱	▲	Σ	∫
5	5	à	ò	Ñ	▴	▵	▶	σ	
6	6	å	û	ä	▷	▸	▹	μ	÷
7	7	ç	ù	ó	▹	►	▻	τ	≈
8	8	ê	ÿ	ı	▻	▼	▽	ϕ	◦
9	9	ë	Ö	┐	▾	▿	▾	θ	•
10	A	è	Ü	┐	▿	▾	▾	Ω	•
11	B	ï	ç	½	▿	▾	▾	δ	√
12	C	î	£	¼	▿	▾	▾	∞	n
13	D	ì	¥	ì	▿	▾	▾	φ	2
14	E	Ä	℞	«	▿	▾	▾	€	■
15	F	Å	ƒ	»	▿	▾	▾	∩	BLANK 'FF'

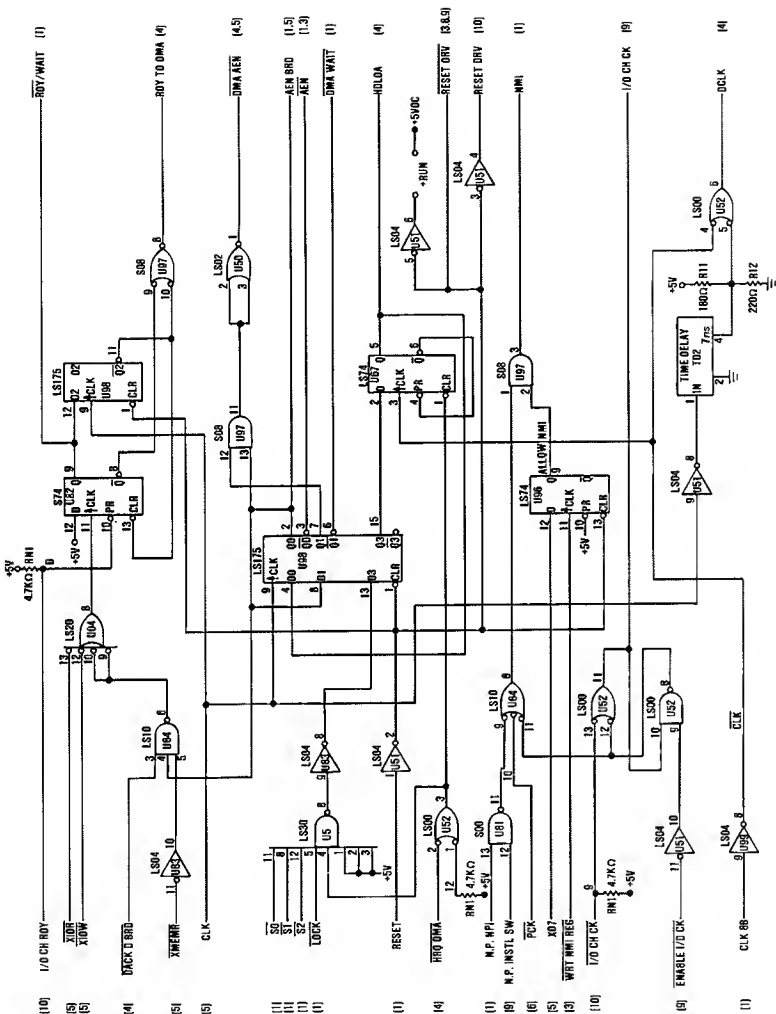
Appendix C

Notes:

APPENDIX D: LOGIC DIAGRAMS

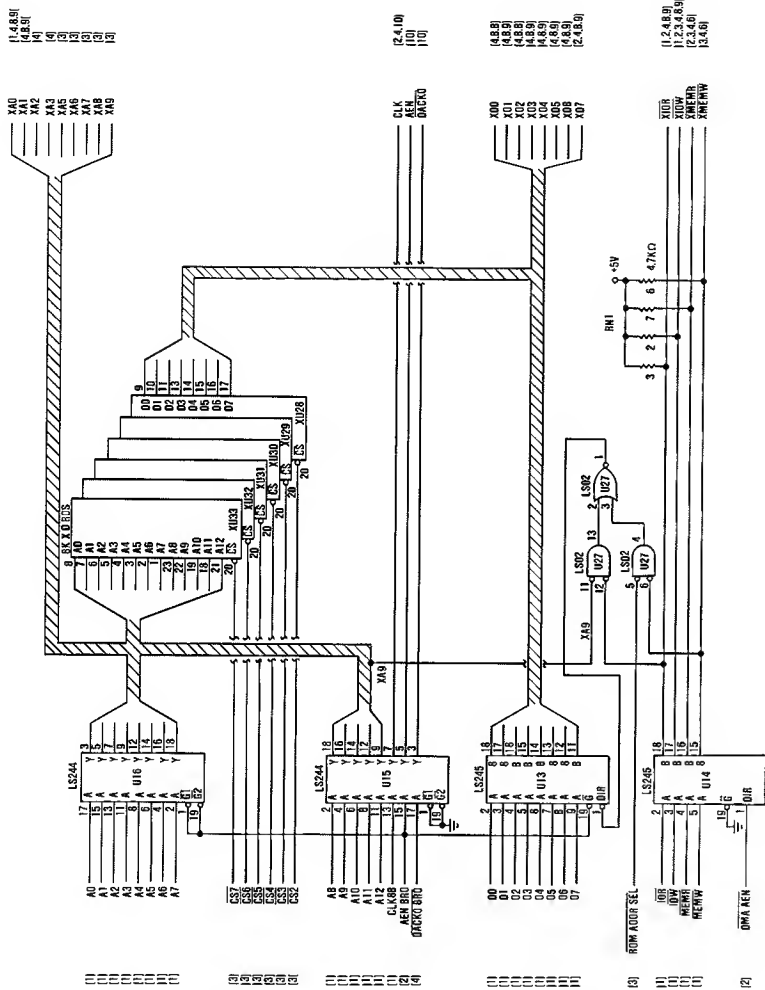
System Board (16/64K)	D-2
System Board (64/256K)	D-12
Keyboard – Type 1	D-22
Keyboard – Type 2	D-24
Expansion Board	D-25
Extender Card	D-26
Receiver Card	D-29
Printer	D-32
Printer Adapter	D-35
Monochrome Display Adapter	D-36
Color/Graphics Monitor Adapter	D-46
Color Display	D-52
Monochrome Display	D-54
5–1/4 Inch Diskette Drive Adapter	D-55
5–1/4 Inch Diskette Drive – Type 1	D-59
5–1/4 Inch Diskette Drive – Type 2	D-62
Fixed Disk Drive Adapter	D-64
Fixed Disk Drive – Type 1	D-70
Fixed Disk Drive – Type 2	D-73
32K Memory Expansion Option	D-76
64K Memory Expansion Option	D-79
64/256K Memory Expansion Option	D-82
Game Control Adapter	D-86
Prototype Card	D-87
Asynchronous Communications Adapter	D-88
Binary Synchronous Communications Adapter	D-89
SDLC Communications Adapter	D-91



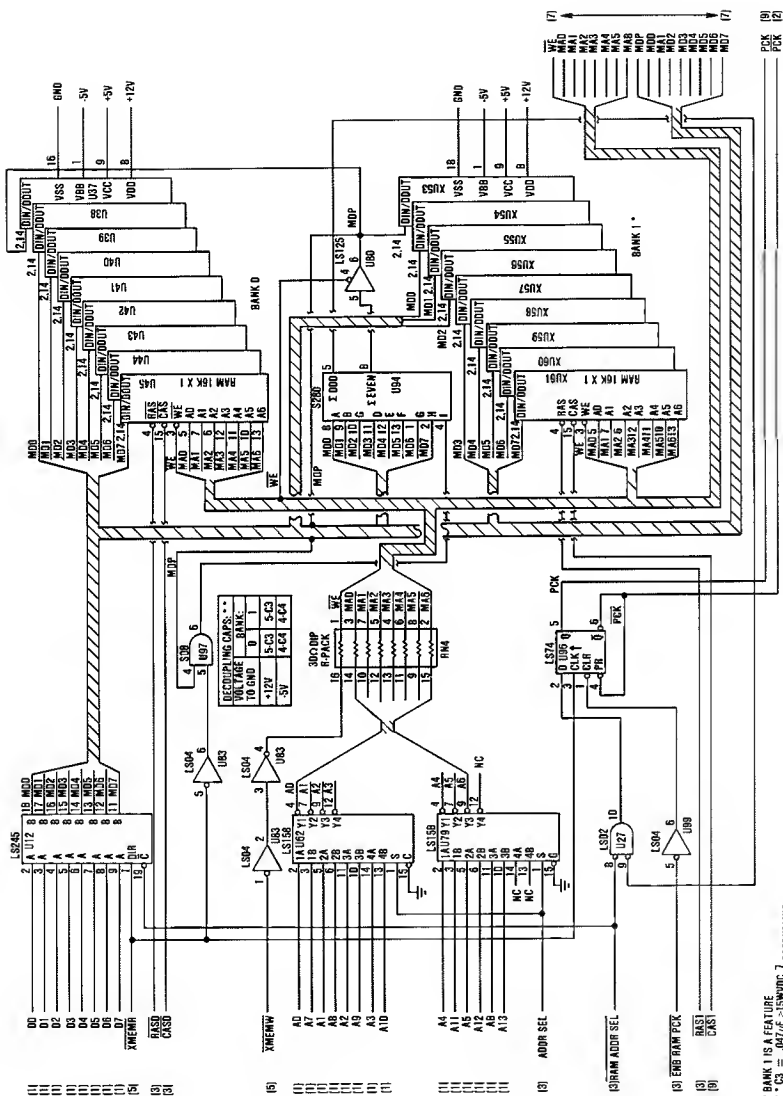


16/64K System Board (Sheet 2 of 10)

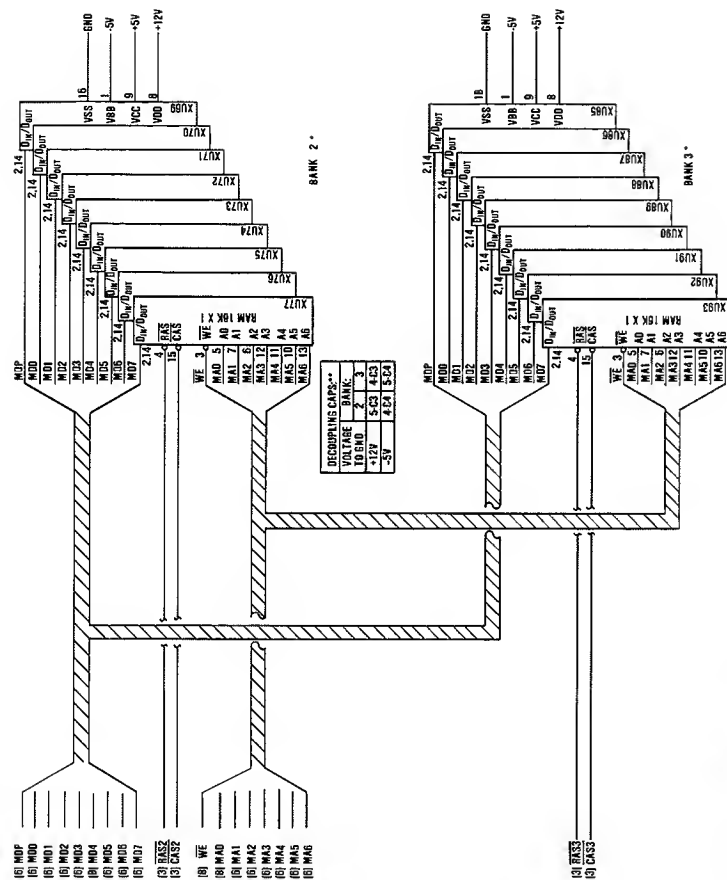
[illegible]



16/64K System Board (Sheet 5 of 10)

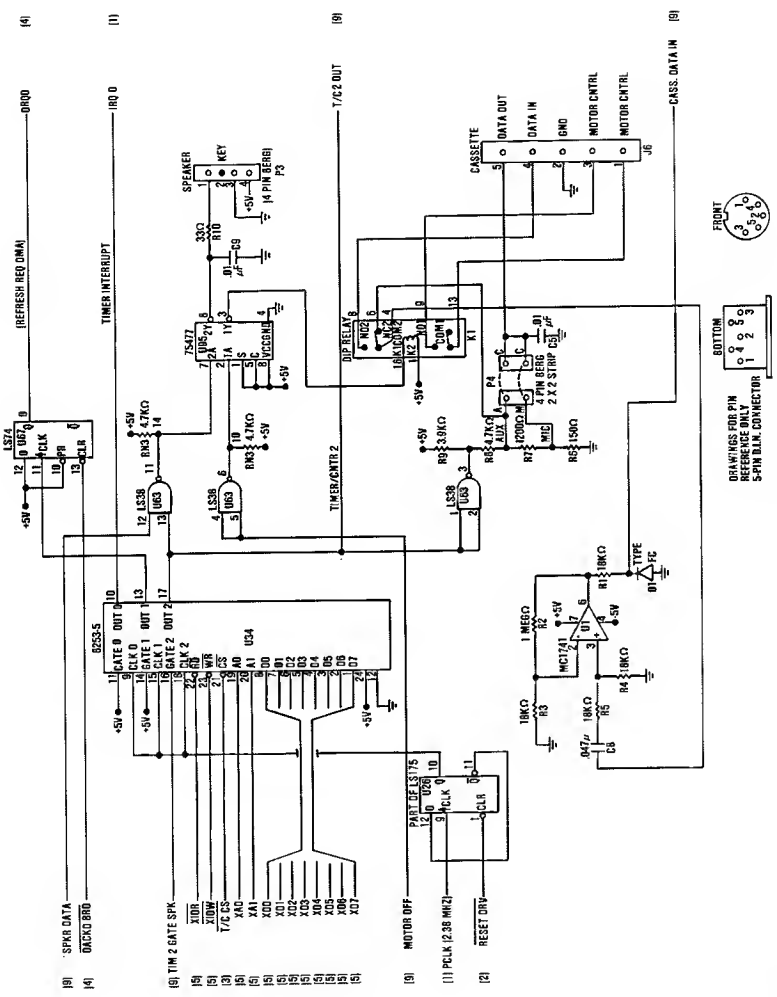


* BANK 1 IS A FEATURE
 ** C3 = .001UF .5WVDC
 C4 = .001UF .5WVDC

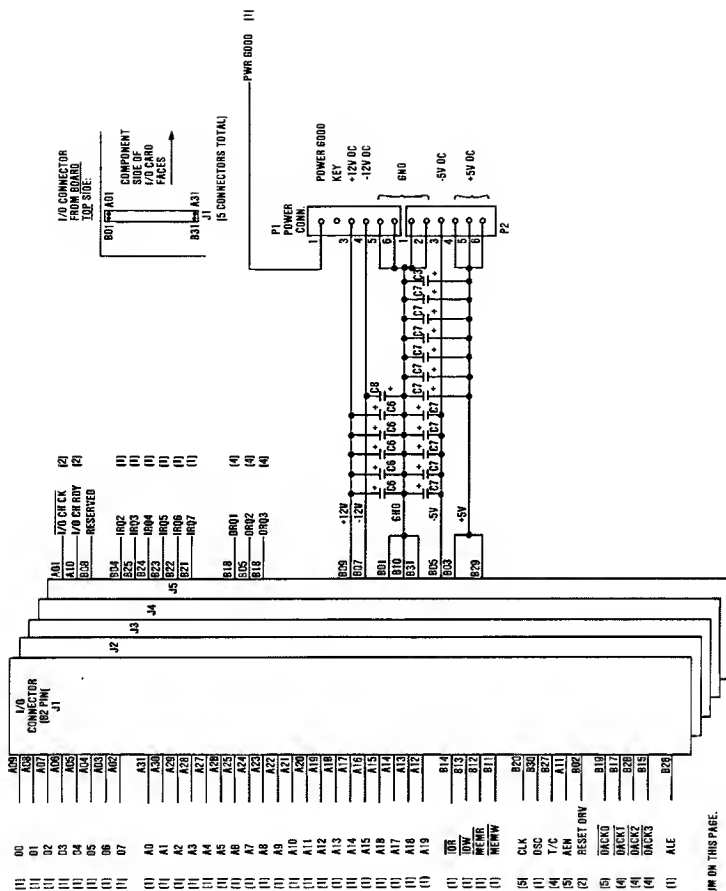


*BANKS 2 & 3 ARE FEATURES.
 **CS = 0.01µF ±5%WDC
 C4 = 0.01µF ±5%WDC } DECOUPLING

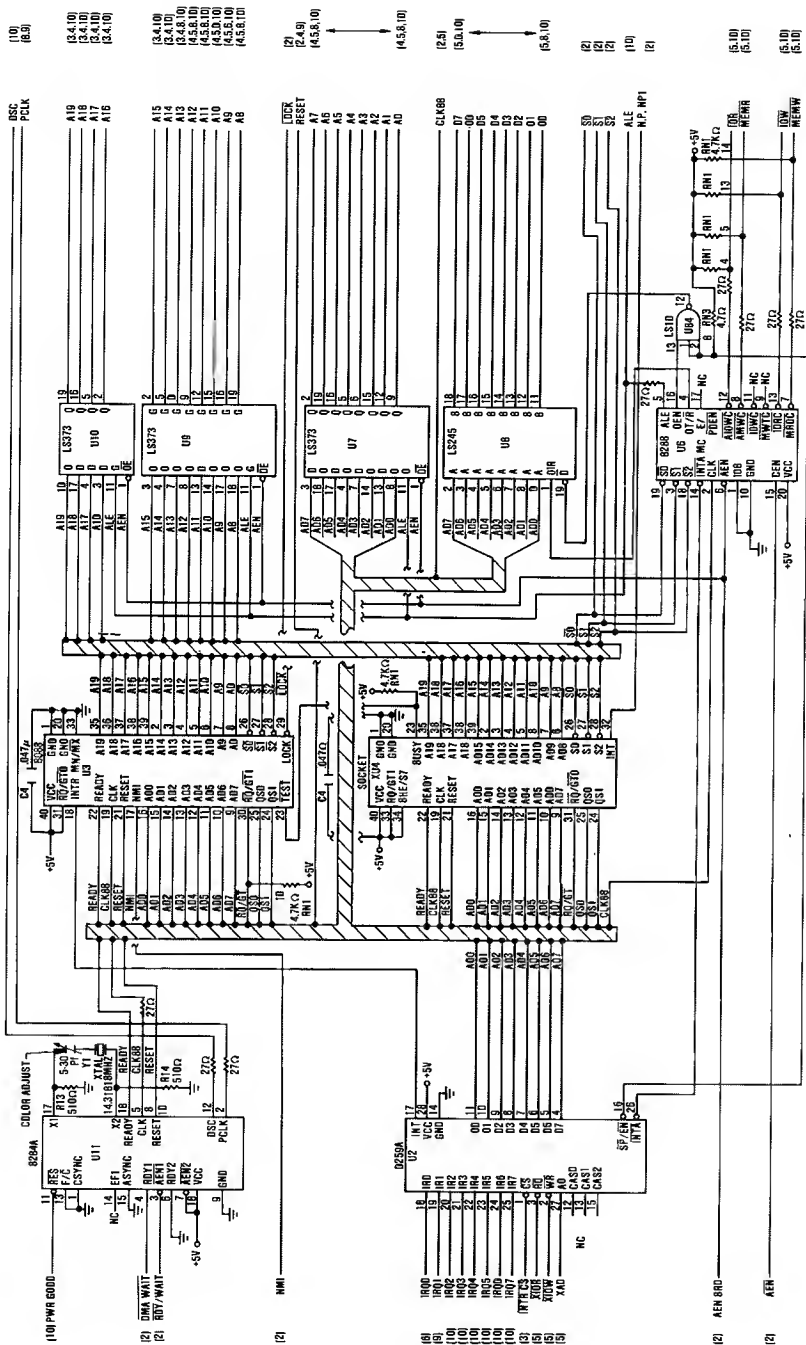
16/64K System Board (Sheet 7 of 10)



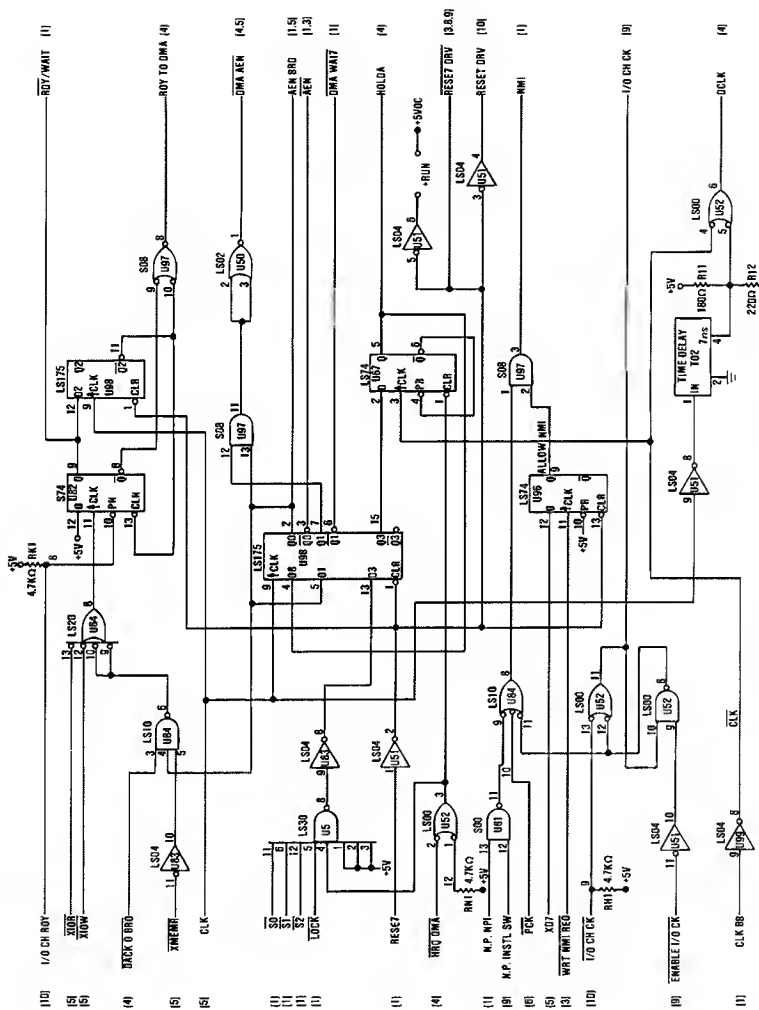
NOTE:
1. ALL CAPS ARE 8.24F TANTALUM ON THIS PAGE.

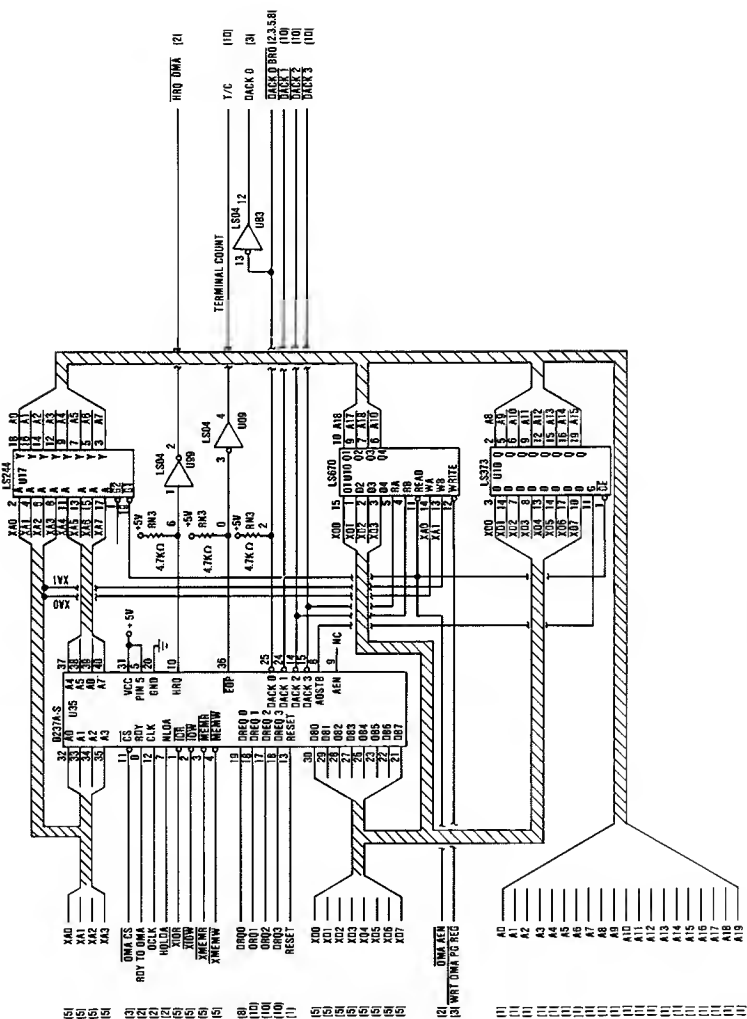


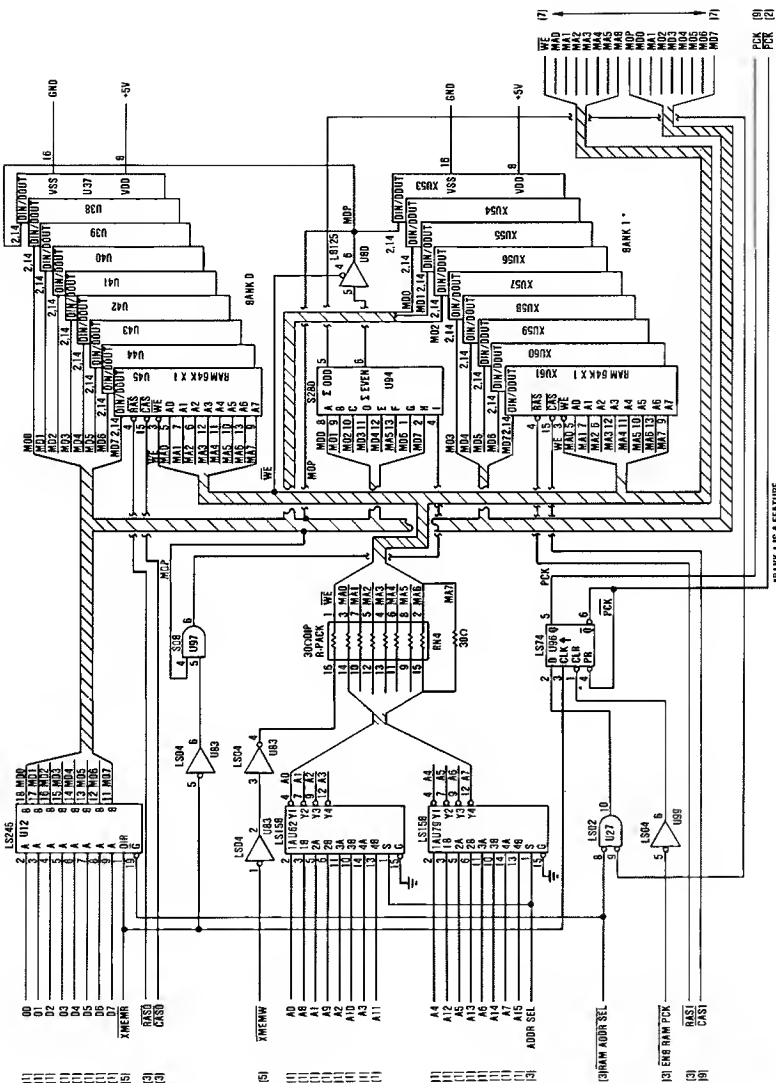
D-12 Logic Diagrams



64/256K System Board (Sheet 1 of 10)





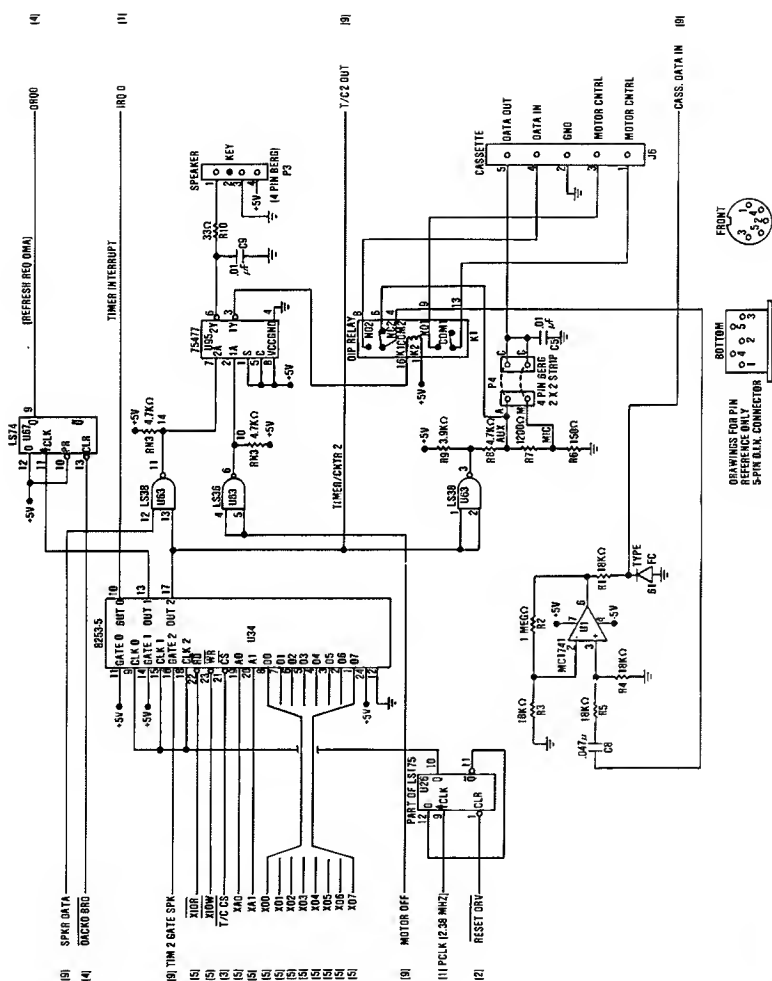


"BANK 1 IS A FEATURE"

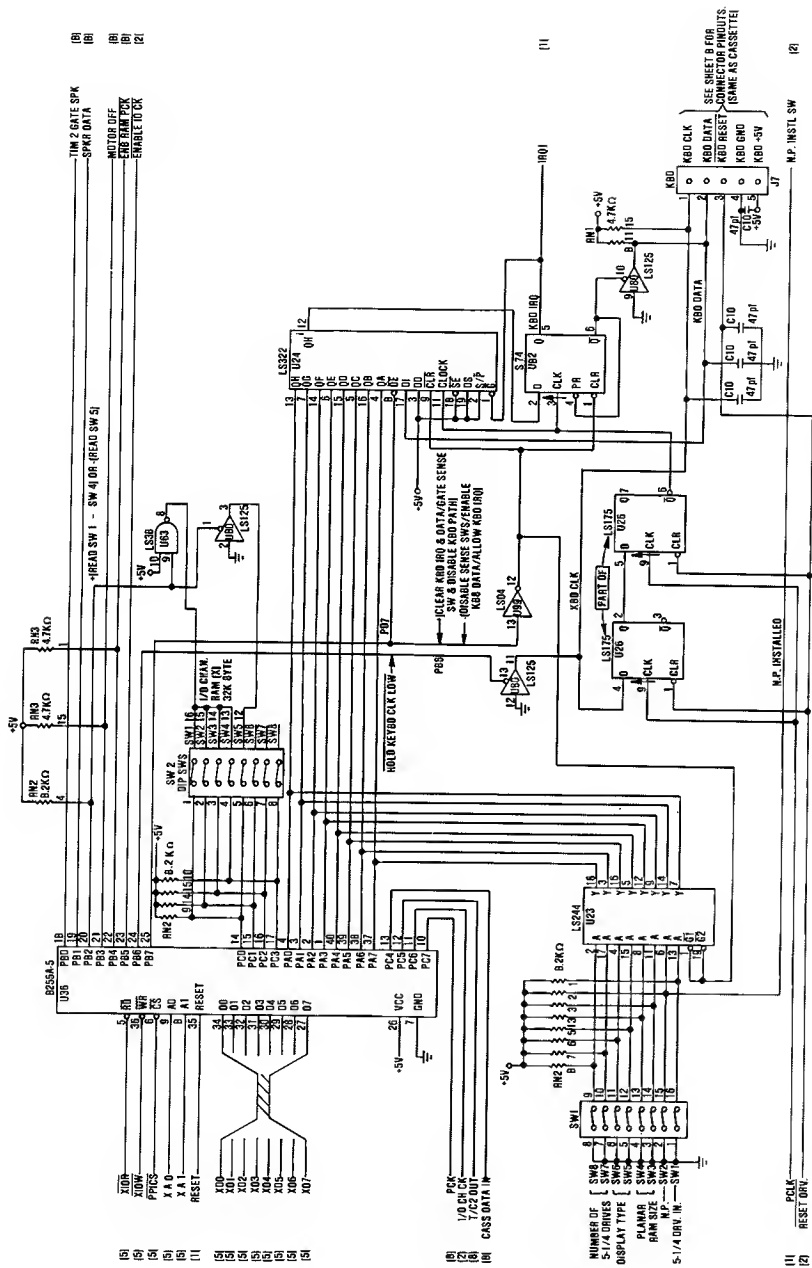
64/256K System Board (Sheet 6 of 10)

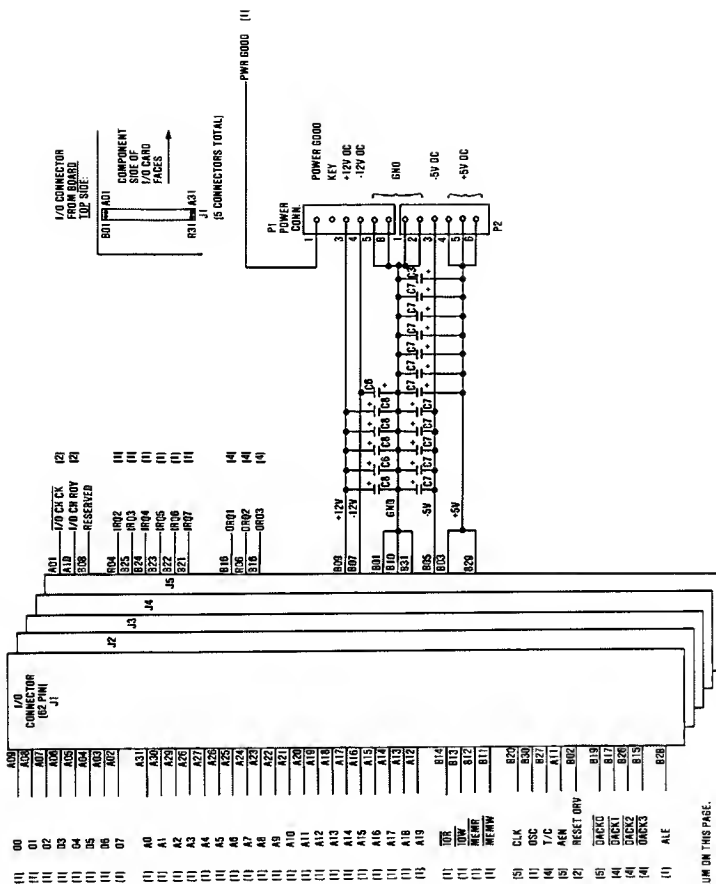


64/256K System Board (Sheet 7 of 10)

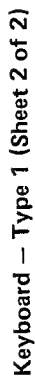


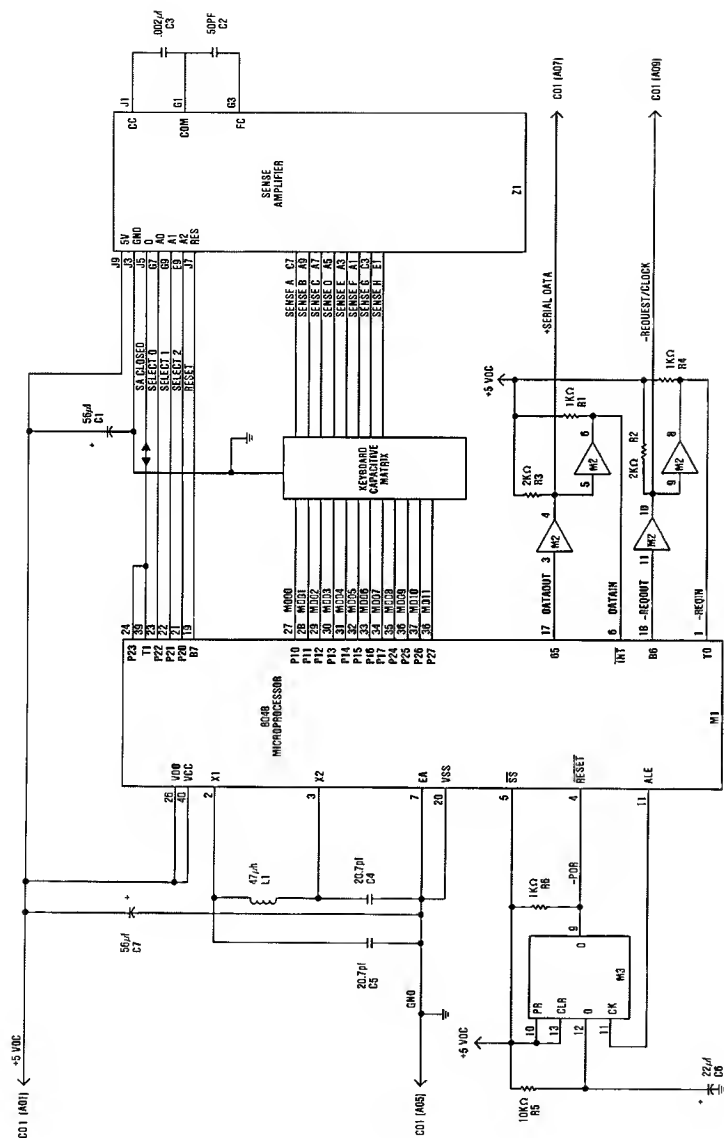
64/256K System Board (Sheet 8 of 10)



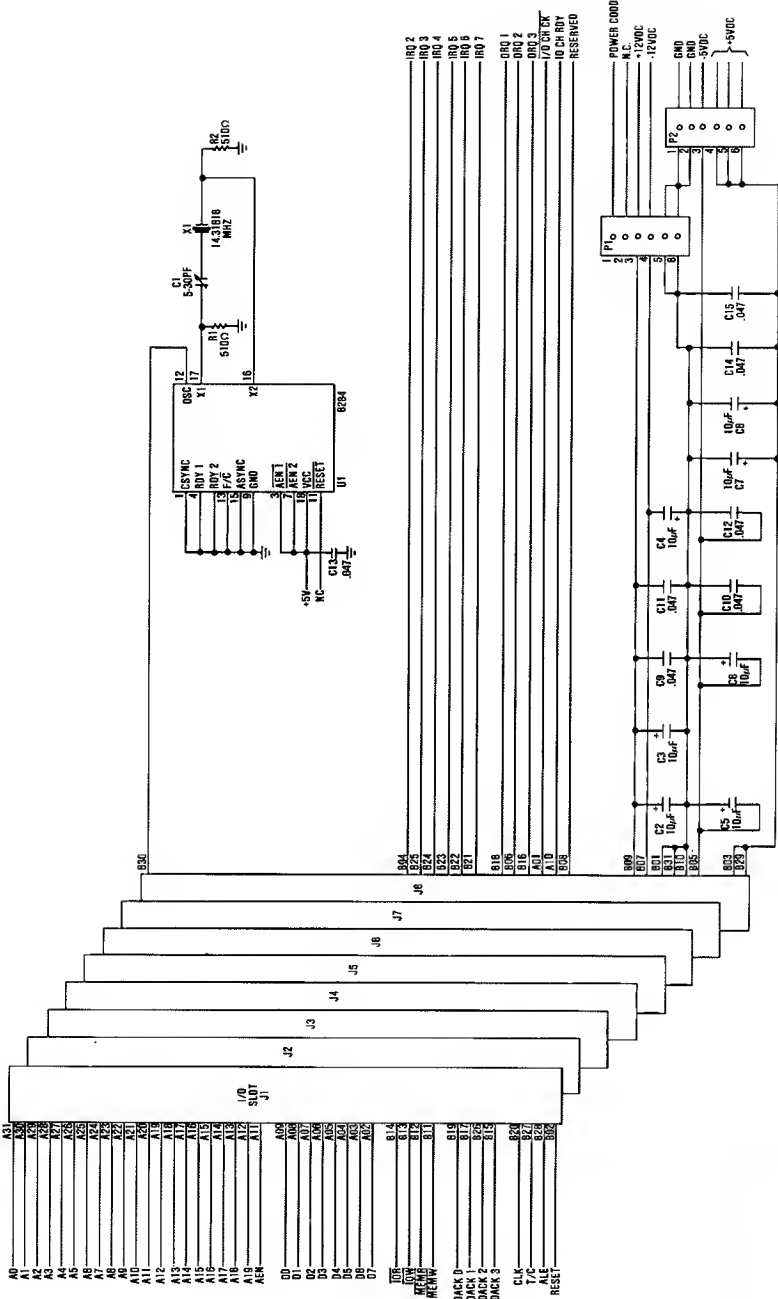


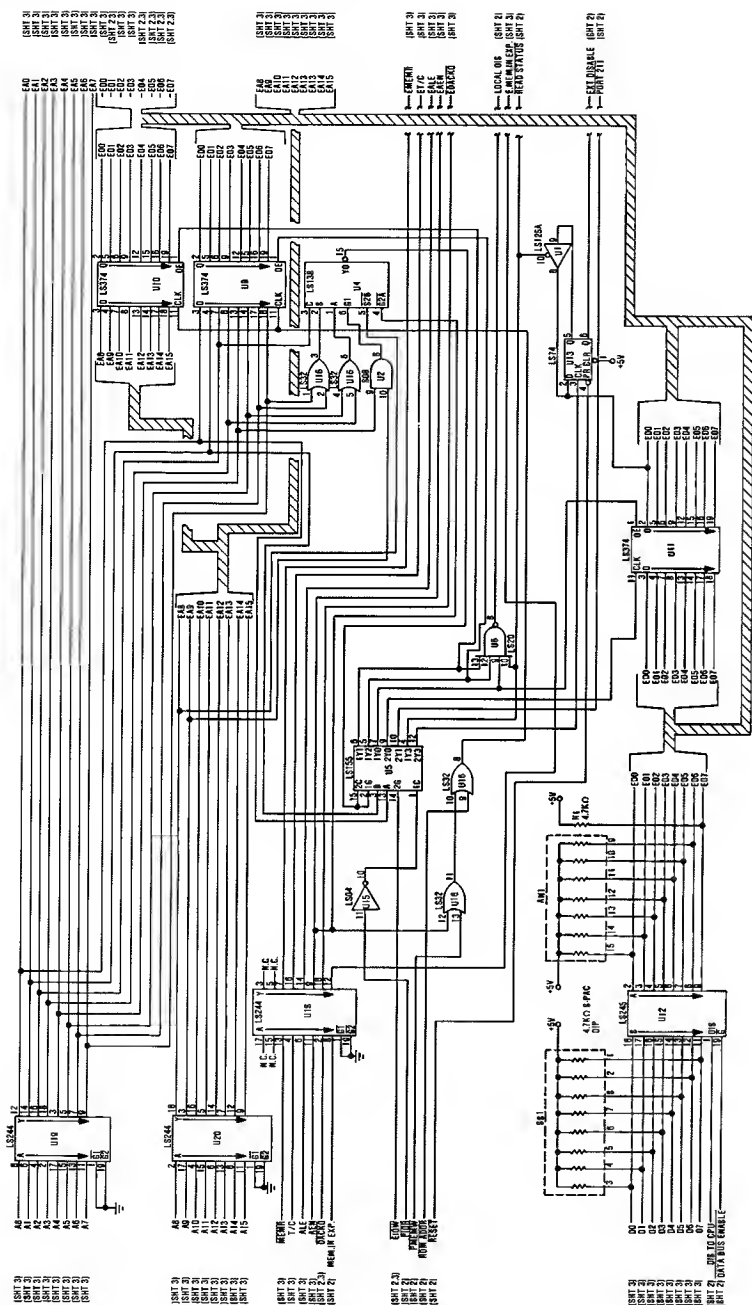
64/256K System Board (Sheet 10 of 10)

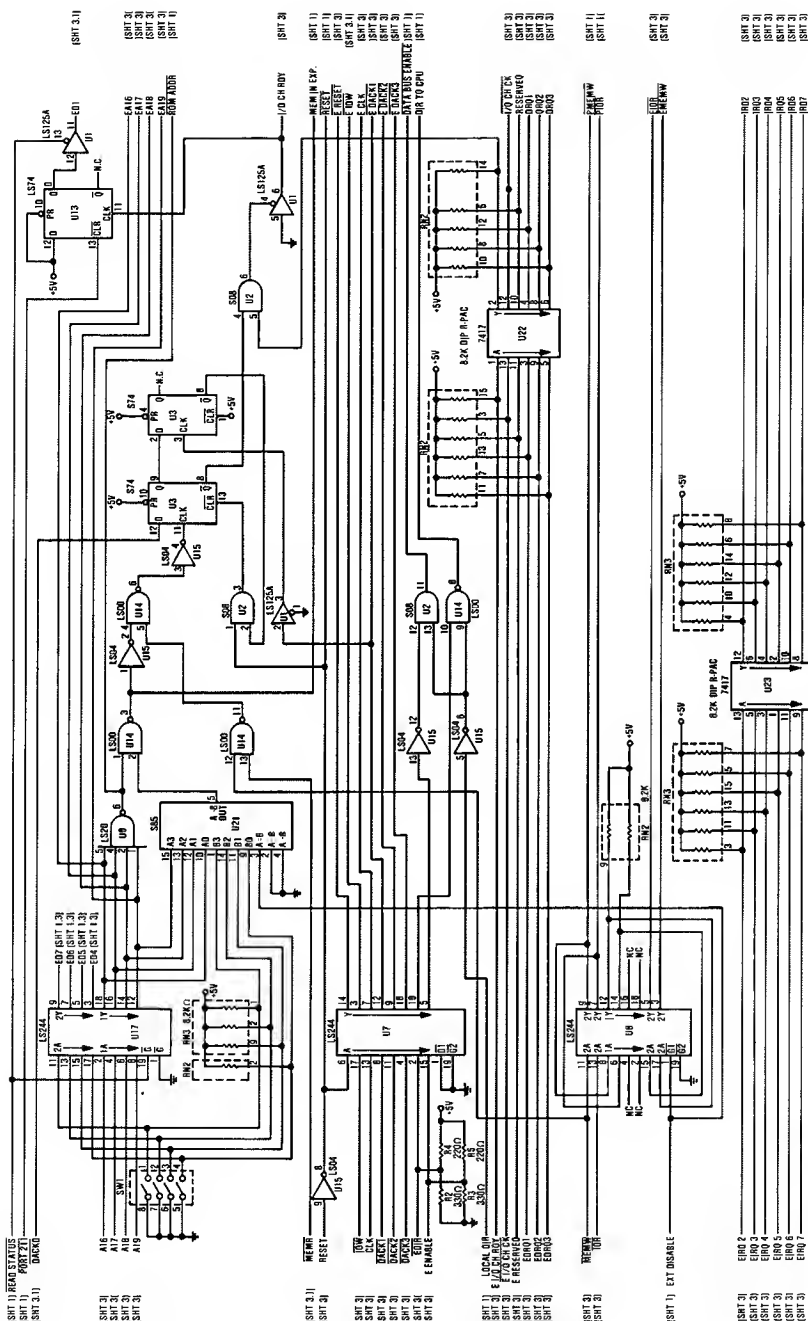




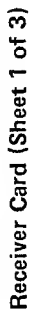
Keyboard — Type 2 (Sheet 1 of 1)

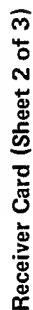


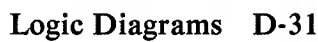


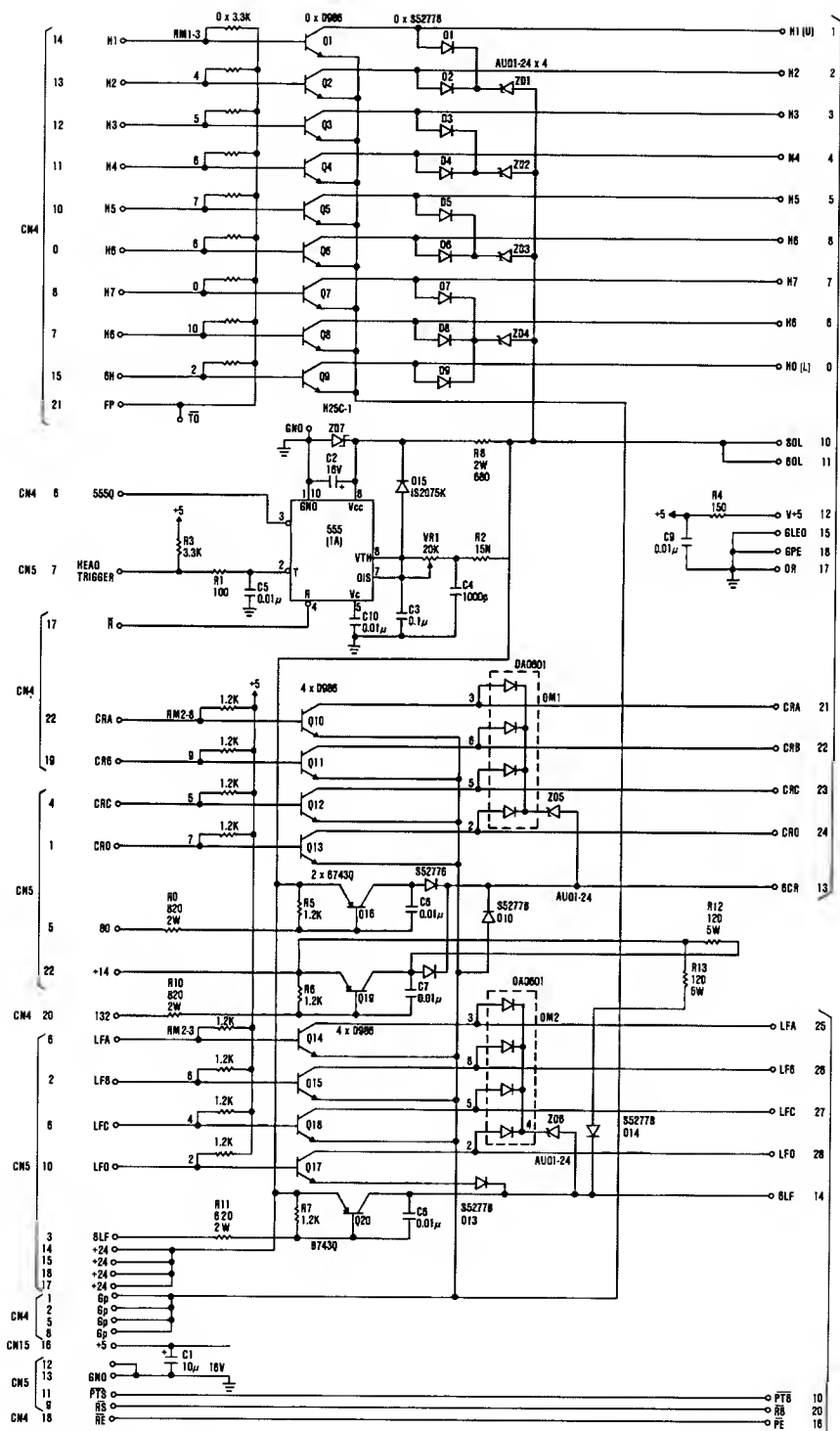


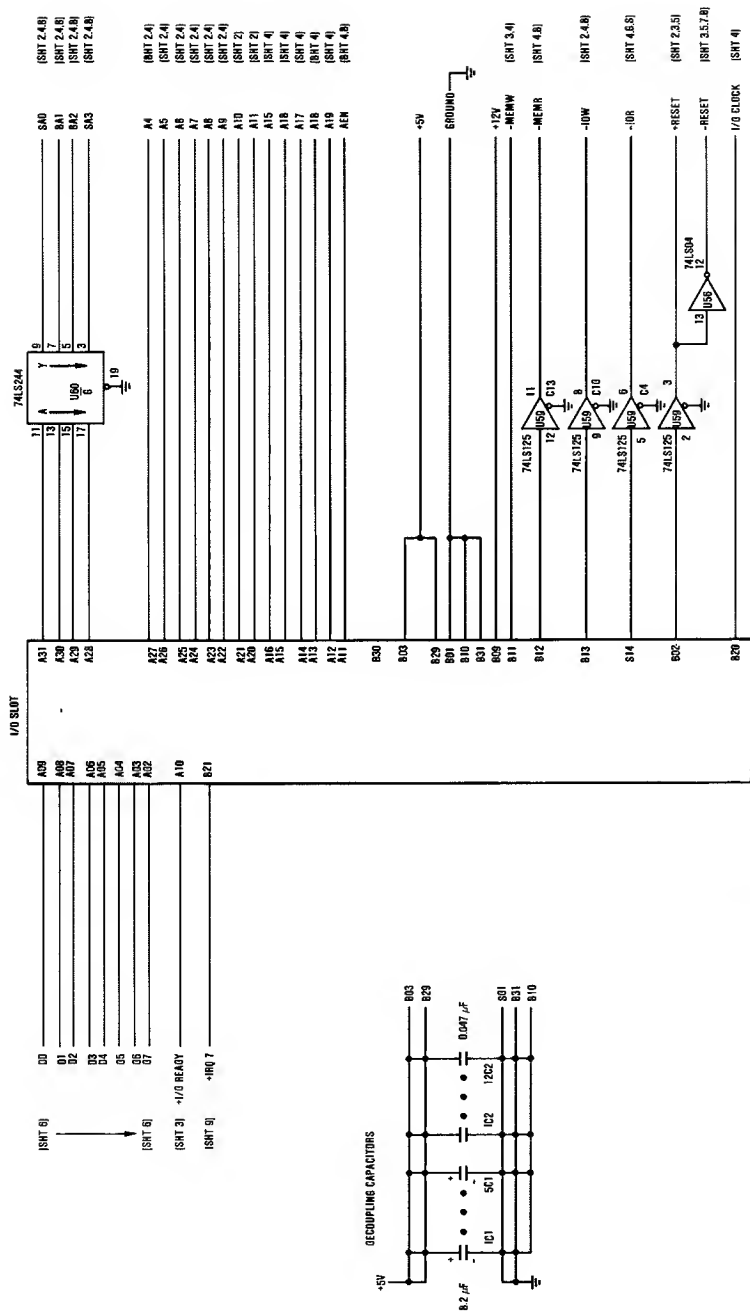
Extender Card (Sheet 2 of 3)





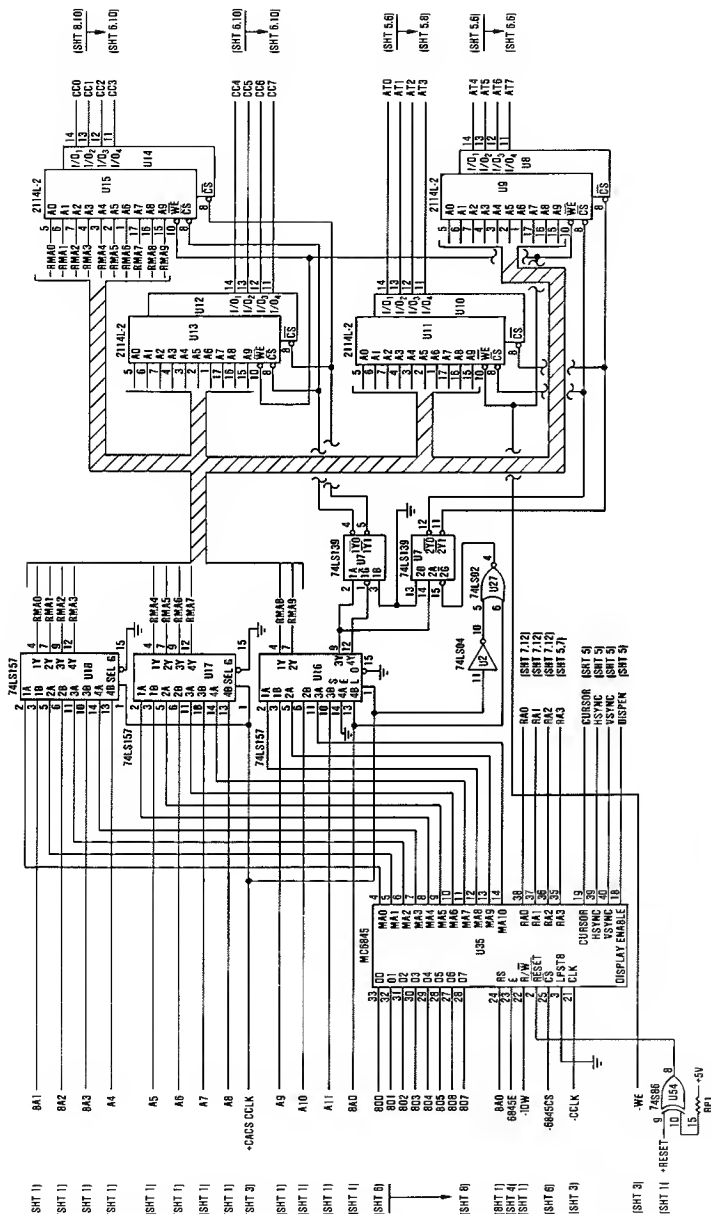


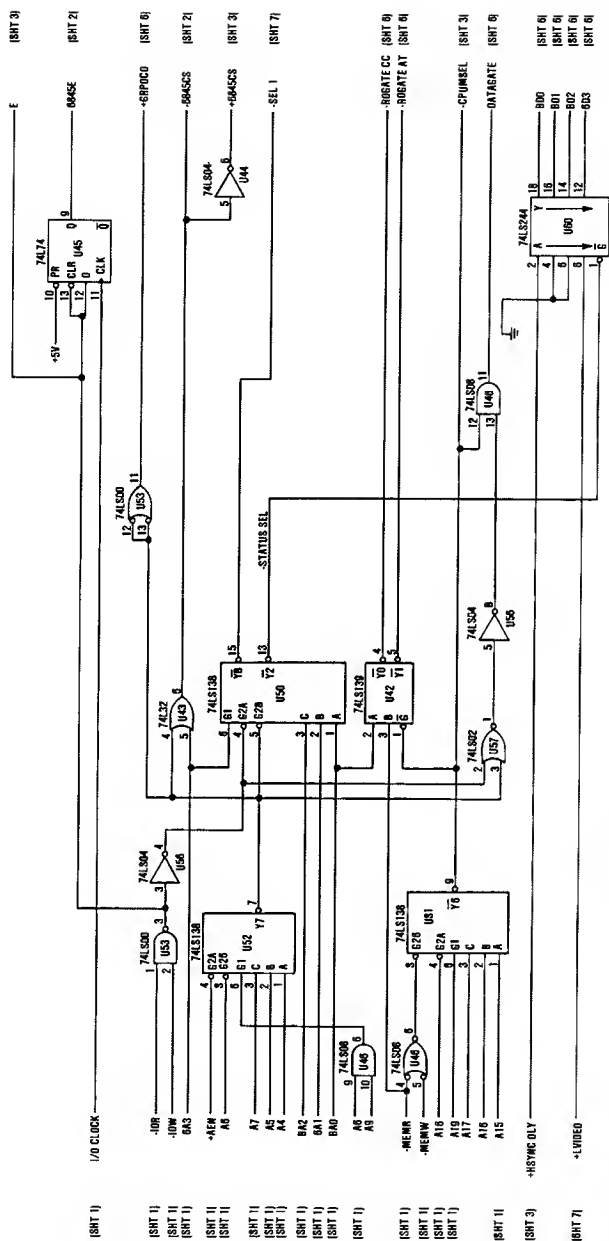




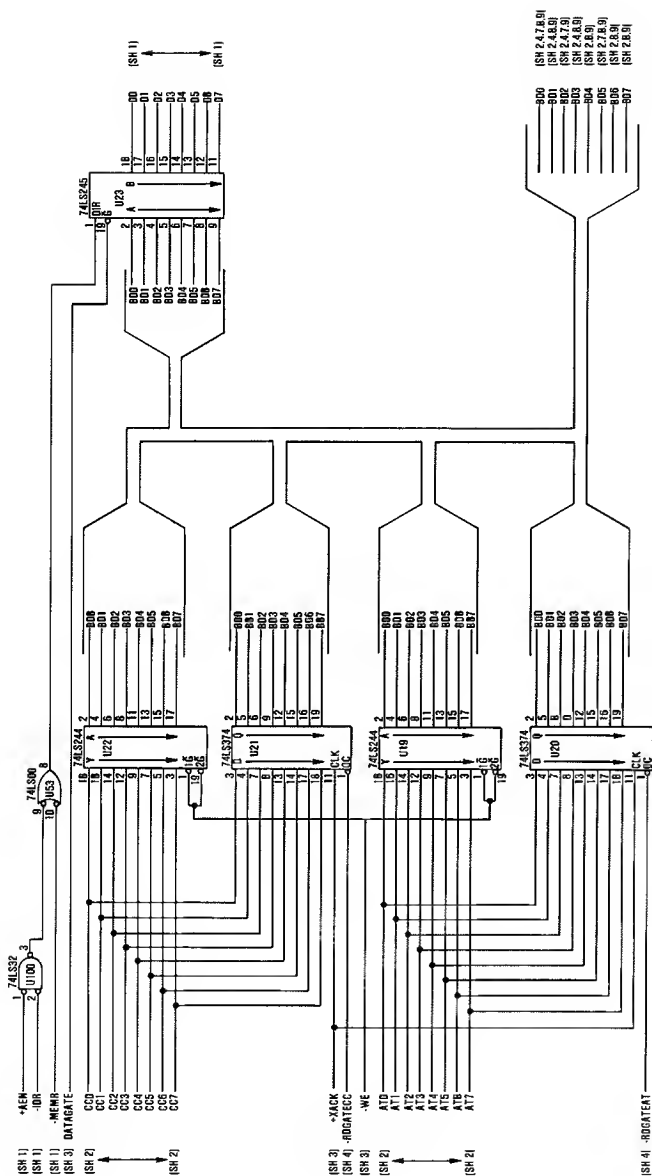
Monochrome Display Adapter (Sheet 1 of 10)

Monochrome Display Adapter (Sheet 2 of 10)



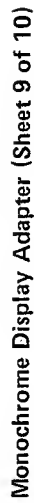


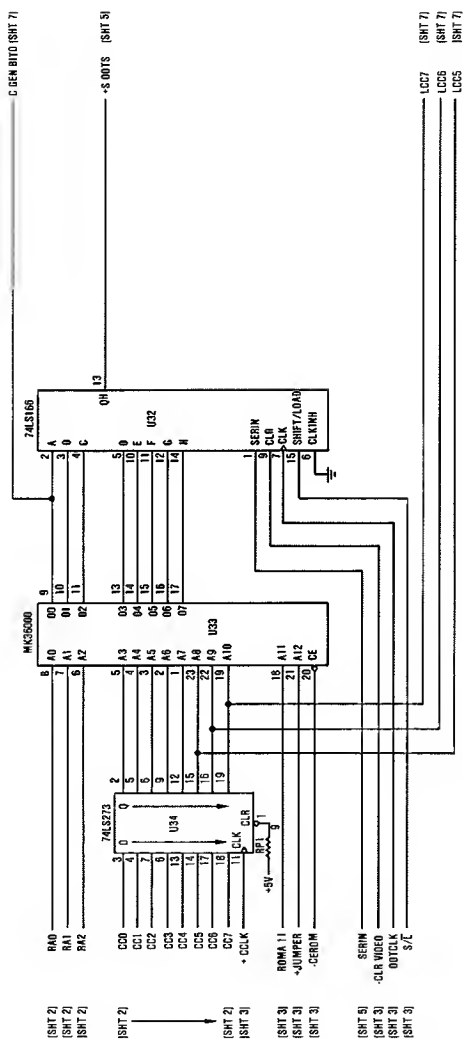


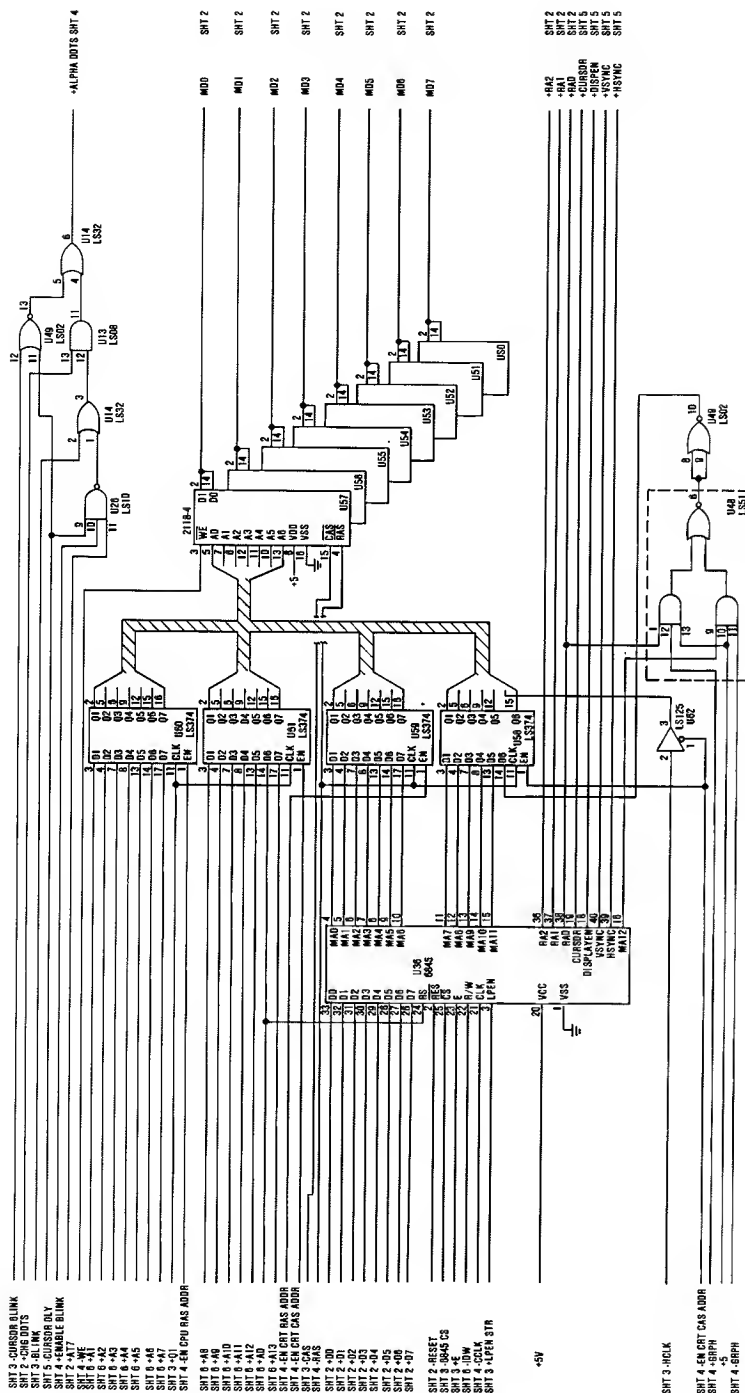


Monochrome Display Adapter (Sheet 6 of 10)

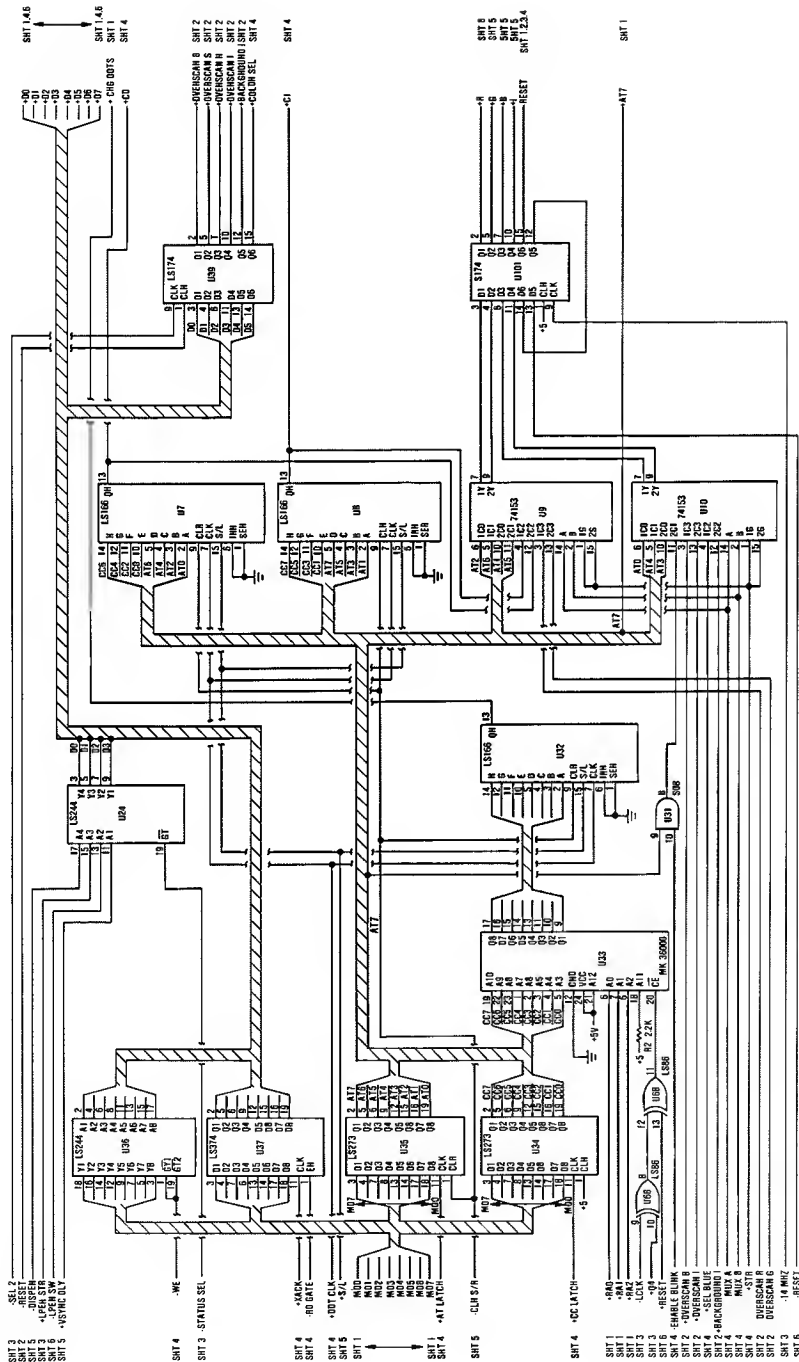
[illegible]



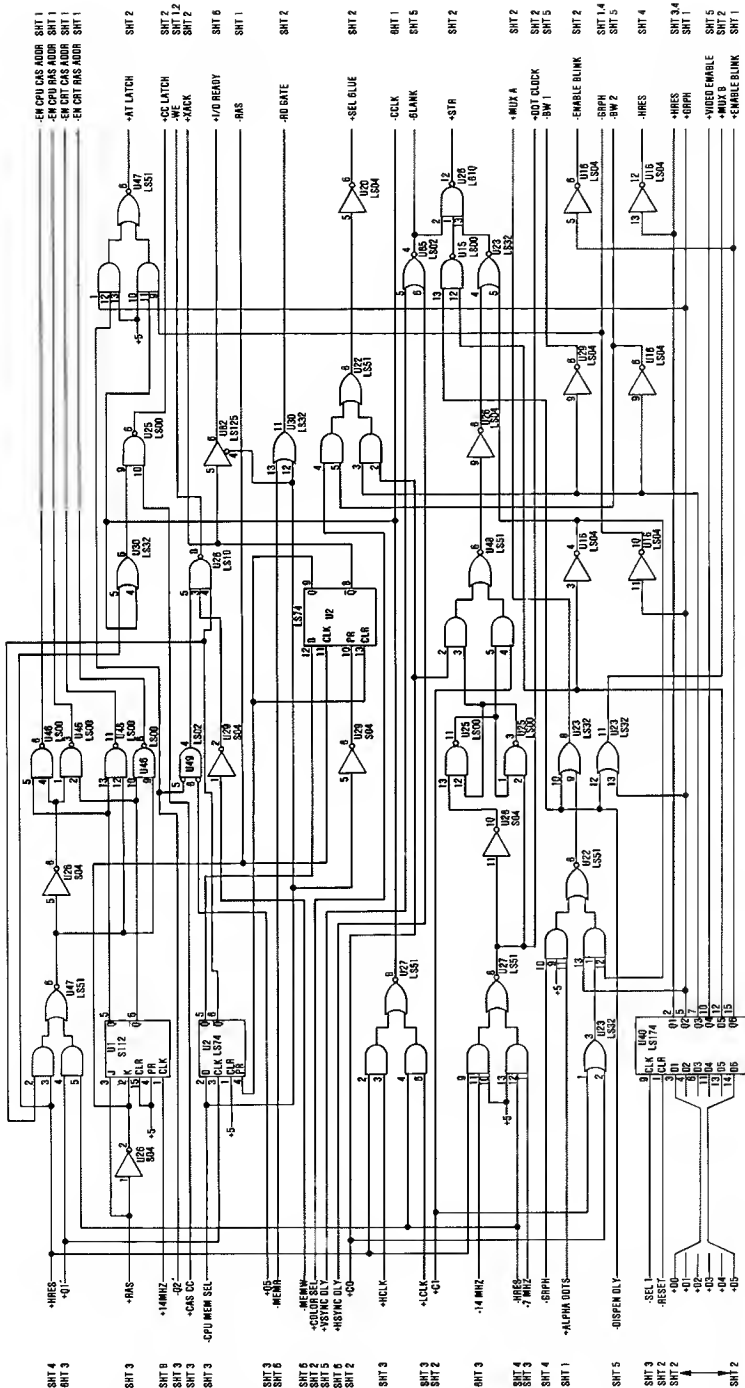


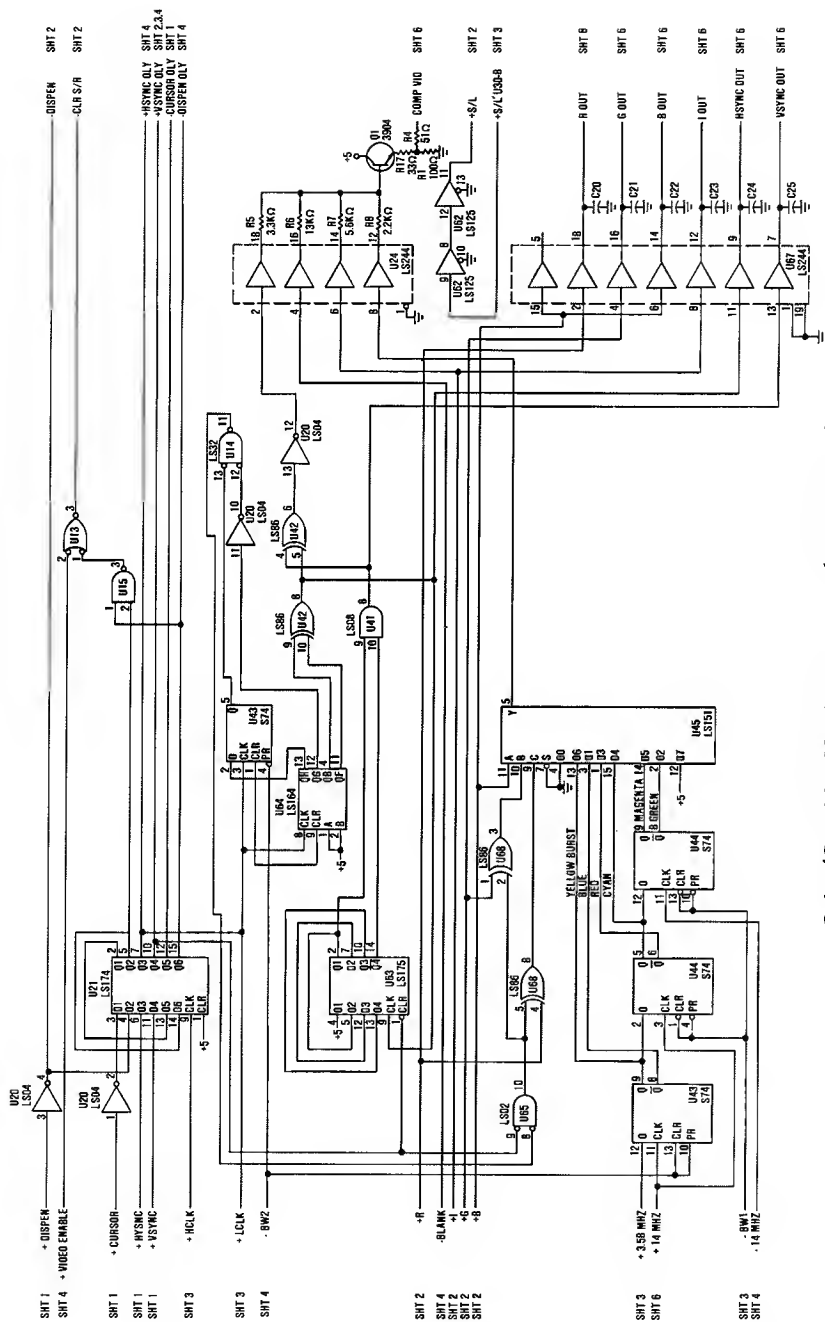


Color/Graphics Monitor Adapter (Sheet 1 of 6)



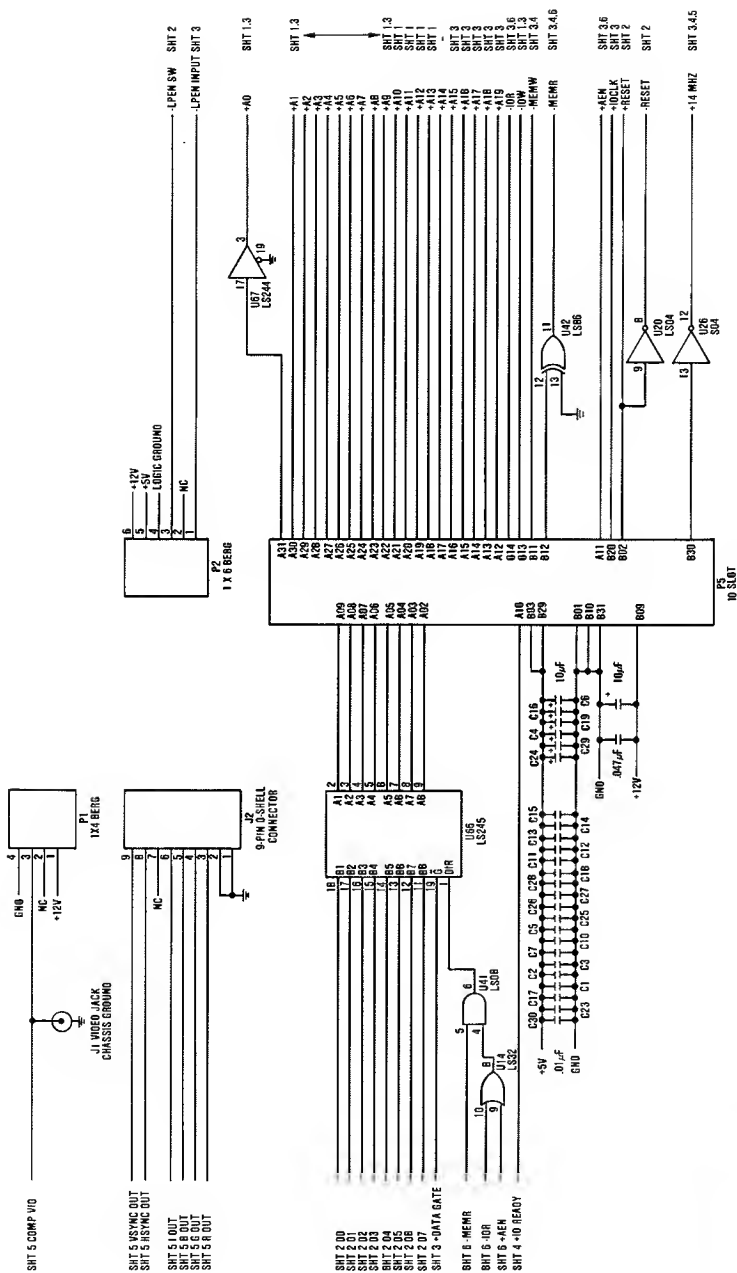
Color/Graphics Monitor Adapter (Sheet 2 of 6)



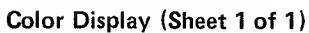


Color/Graphics Monitor Adapter (Sheet 5 of 6)

INTERFACE PAGE

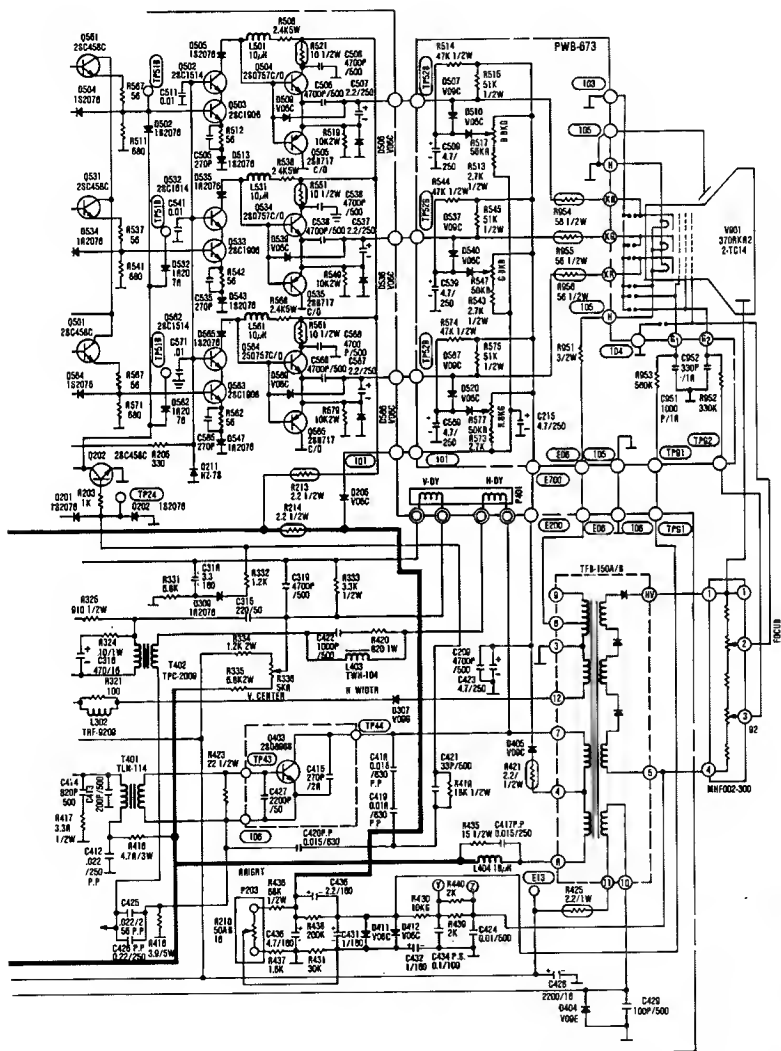


**HAZARDOUS VOLTAGES
UP TO 450 VOLTS EXIST
ON THE PRINTED
CIRCUIT BOARDS**



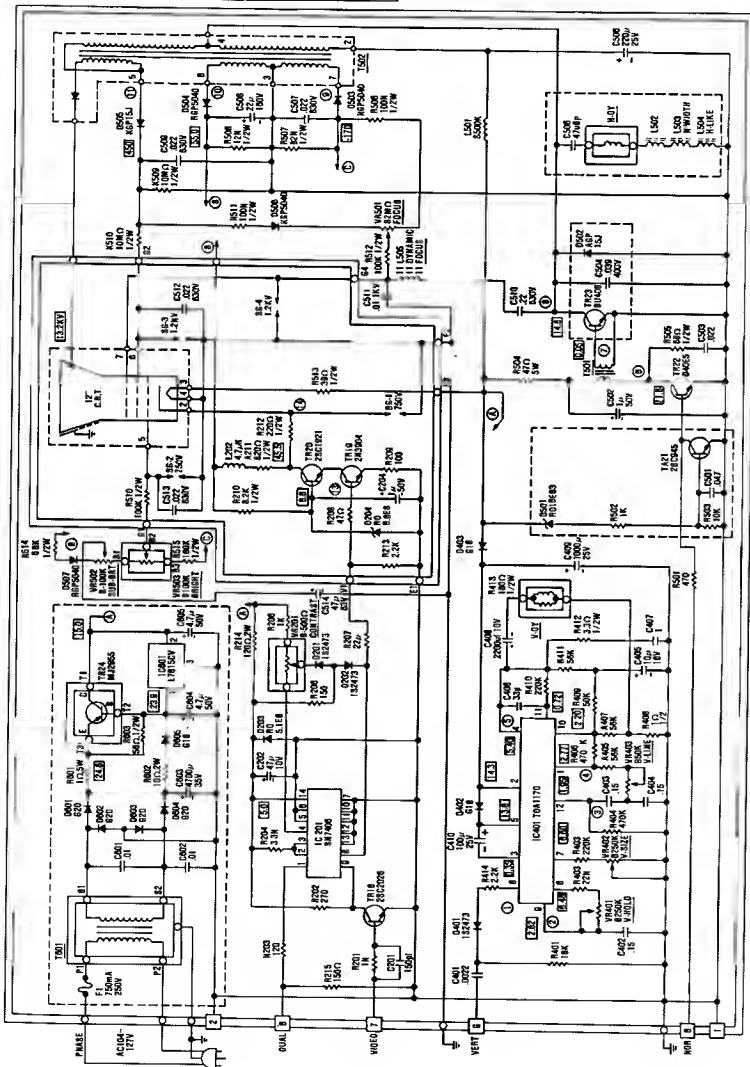
**HAZARDOUS VOLTAGES
UP TO 450 VOLTS EXIST
ON THE PRINTED
CIRCUIT BOARDS**

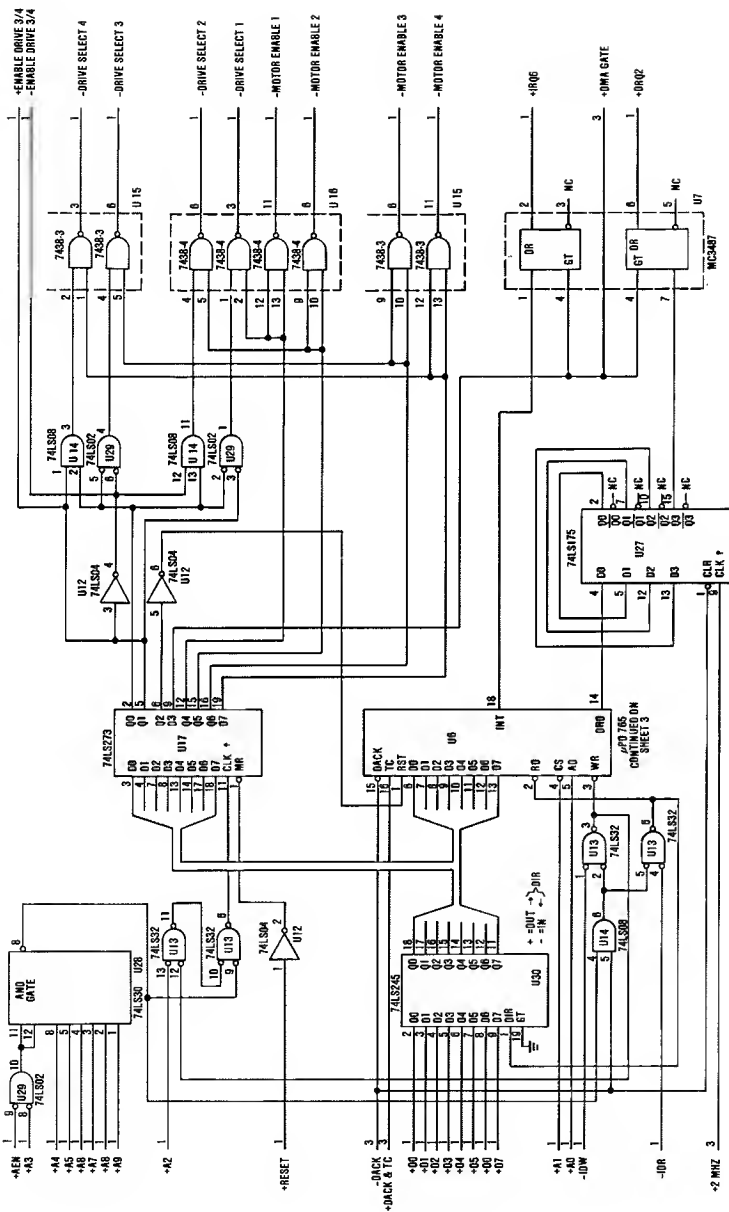
2. ALL RESISTORS ARE 1/2 WATT EXCEPT WHERE OTHERWISE INDICATED.
3. CAPACITOR VALUES ARE IN μF UNLESS OTHERWISE INDICATED P = PF.
4. ALL CAPACITORS ARE 50 VOLTS UNLESS OTHERWISE INDICATED.



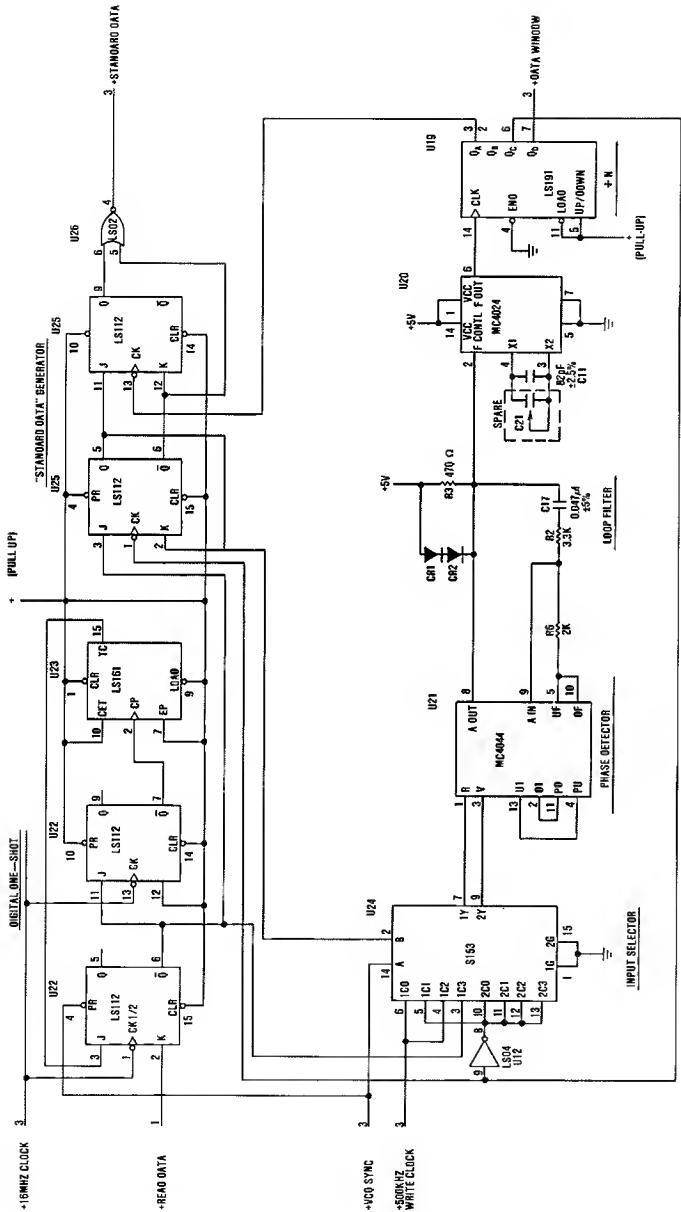
DANGER
HAZARDOUS VOLTAGES
UP TO 450 VOLTS EXIST
ON THE PRINTED
CIRCUIT BOARDS

- NOTES:**
 1 RESISTOR VALUES ARE IN OHMS (Ω), 1000Ω = 1K, 10000Ω = 10K, 100000Ω = 100K.
 2 ALL RESISTORS ARE 1/4W EXCEPT WHERE OTHERWISE INDICATED.
 3 ALL CAPACITORS ARE 50V EXCEPT WHERE OTHERWISE INDICATED.
 4 ALL CAPACITORS ARE 100V EXCEPT WHERE OTHERWISE INDICATED.
 5 AC WIRING INFORMATION:
 PHASE - BLACK/BROWN WIRE
 NEUTRAL - WHITE WIRE
 GROUND - GREEN AND YELLOW WIRE
 IMPORTANT: THE PHASE WIRE MUST GO TO THE FUSED END OF TRANSFORMER

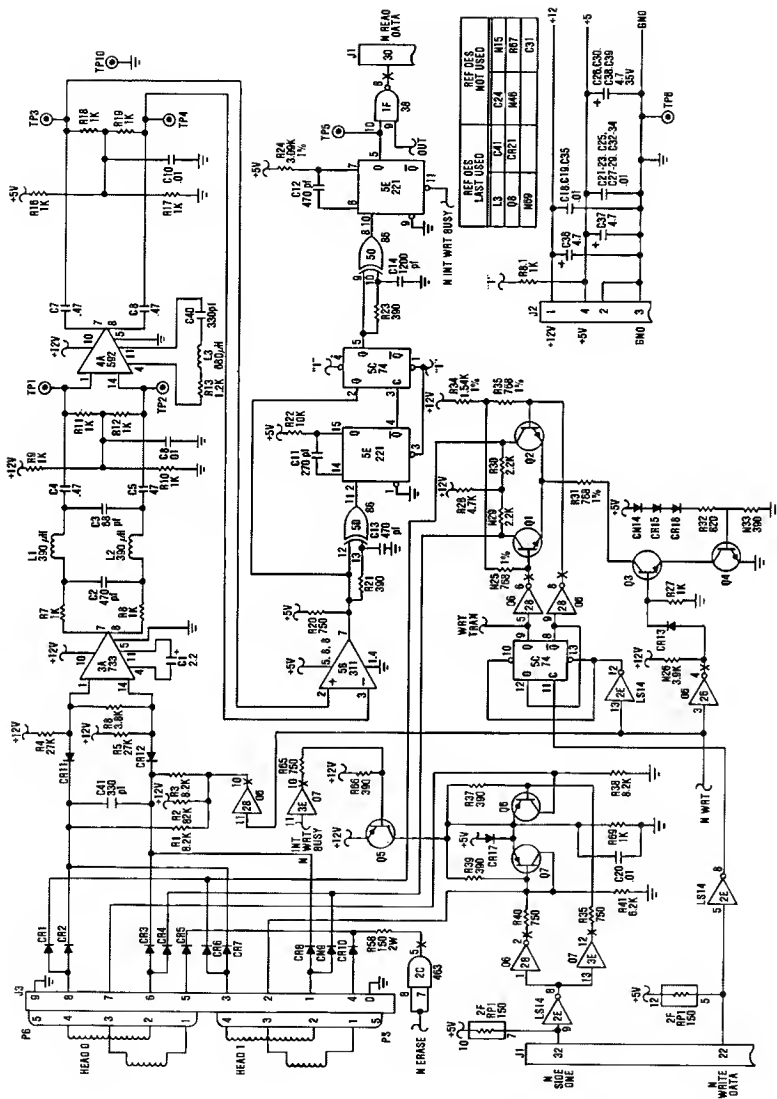




5-1/4 Inch Diskette Drive Adapter (Sheet 2 of 4)



5-1/4 Inch Diskette Drive Adapter (Sheet 4 of 4)

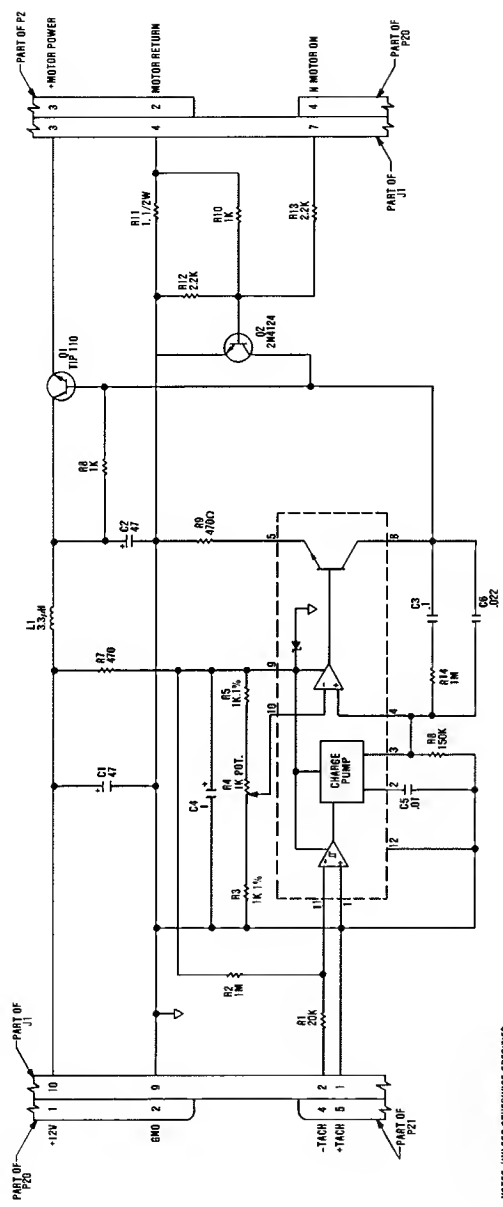


5-1/4 Inch Diskette Drive Type 1 (Sheet 1 of 3)

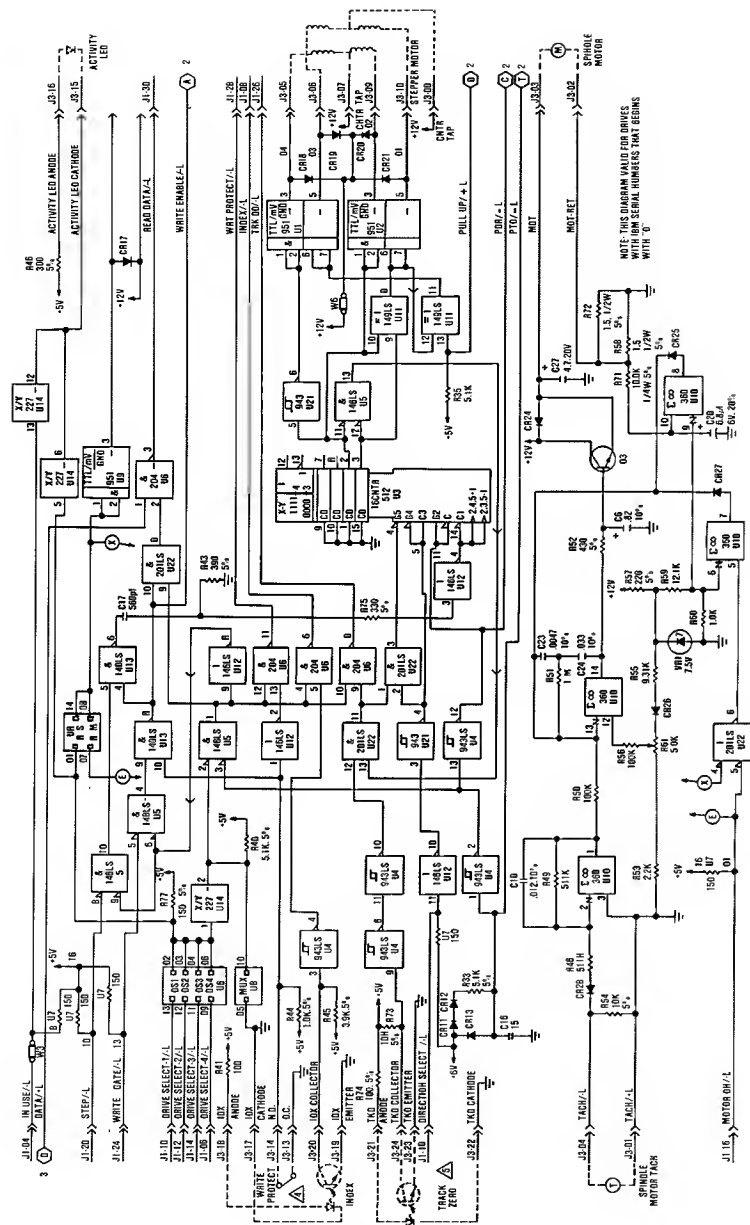


5-1/4 Inch Diskette Drive Type 1 (Sheet 2 of 3)

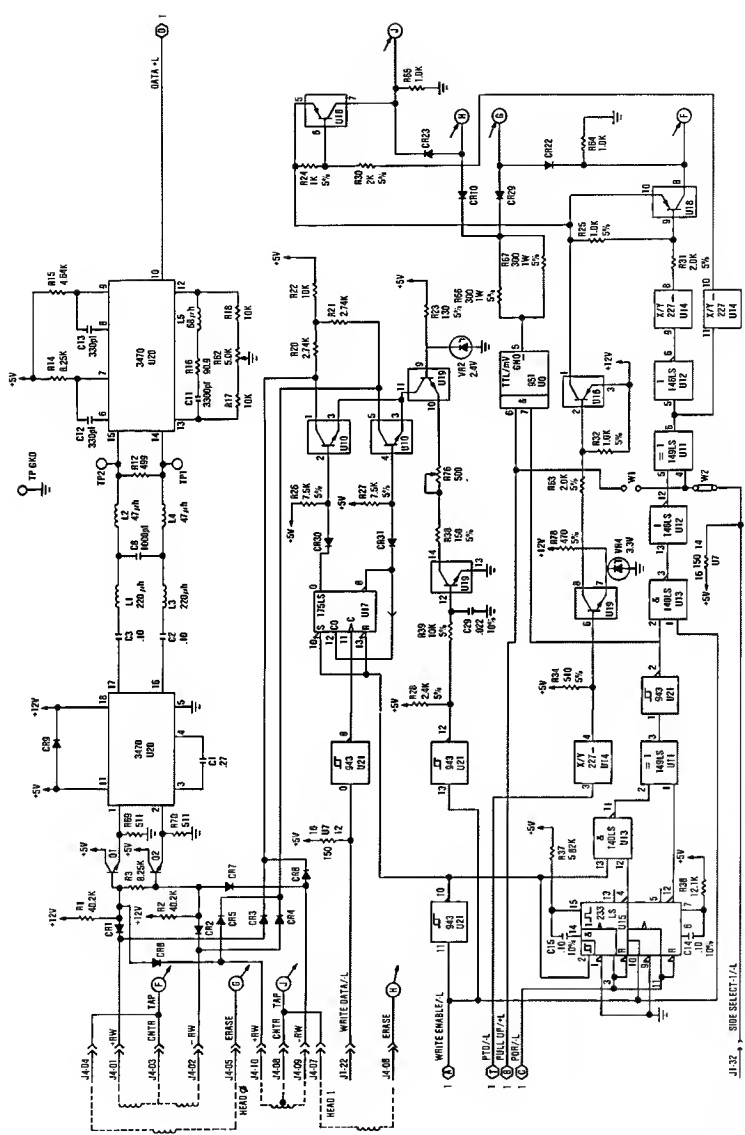
5-1/4 Inch Diskette Drive Type 1 (Sheet 3 of 3)



NOTES: UNLESS OTHERWISE SPECIFIED
 1. RESISTORS ARE IN OHMS. -5% 1/4W.
 2. 1% RESISTORS ARE 1/8W.
 3. CAPACITORS ARE IN μ F. -20% 35V.

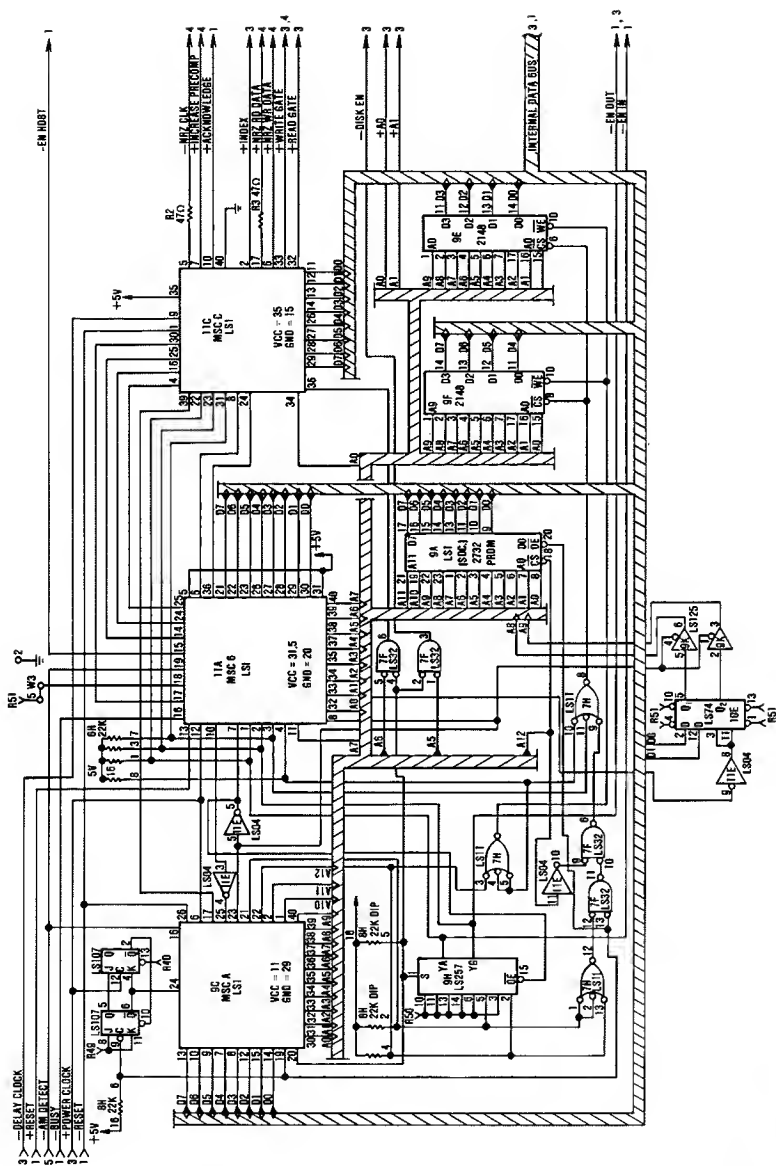


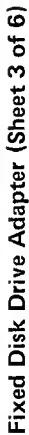
5-1/4 Inch Diskette Drive Type 2 (Sheet 1 of 2)

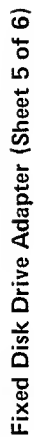


5-1/4 Inch Diskette Drive Type 2 (Sheet 2 of 2)

Fixed Disk Drive Adapter (Sheet 2 of 6)

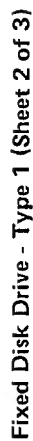


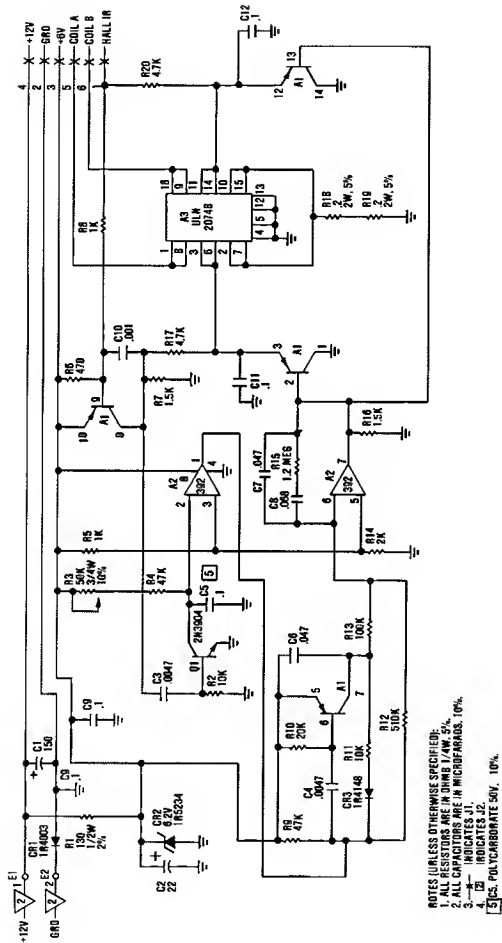




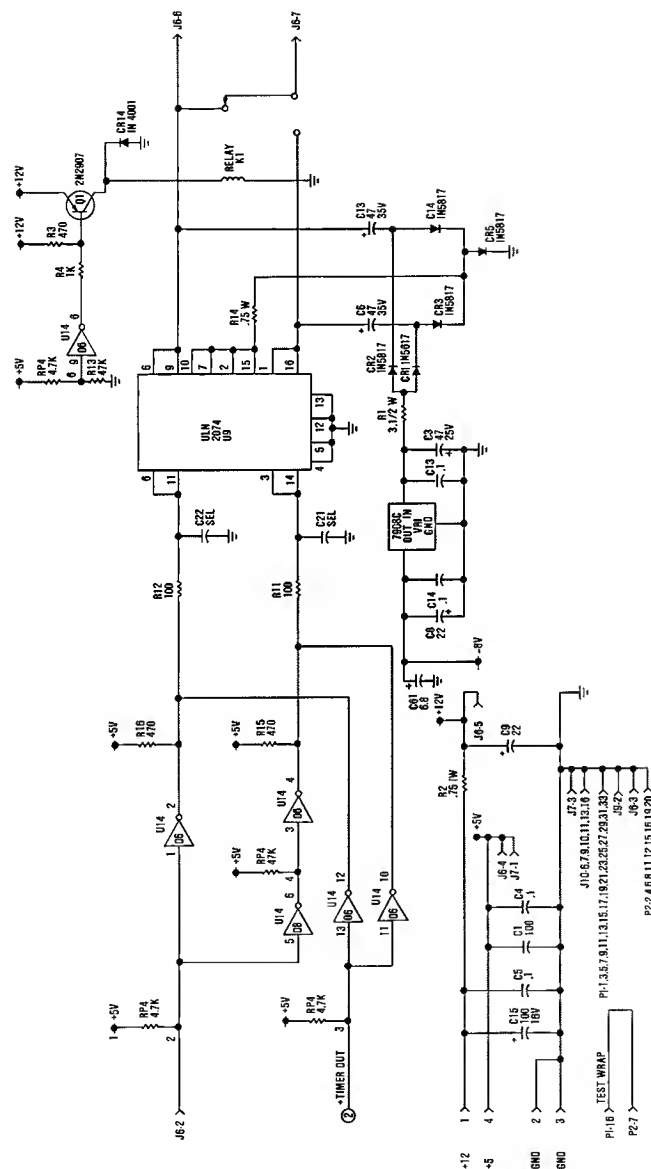


Fixed Disk Drive Adapter (Sheet 6 of 6)



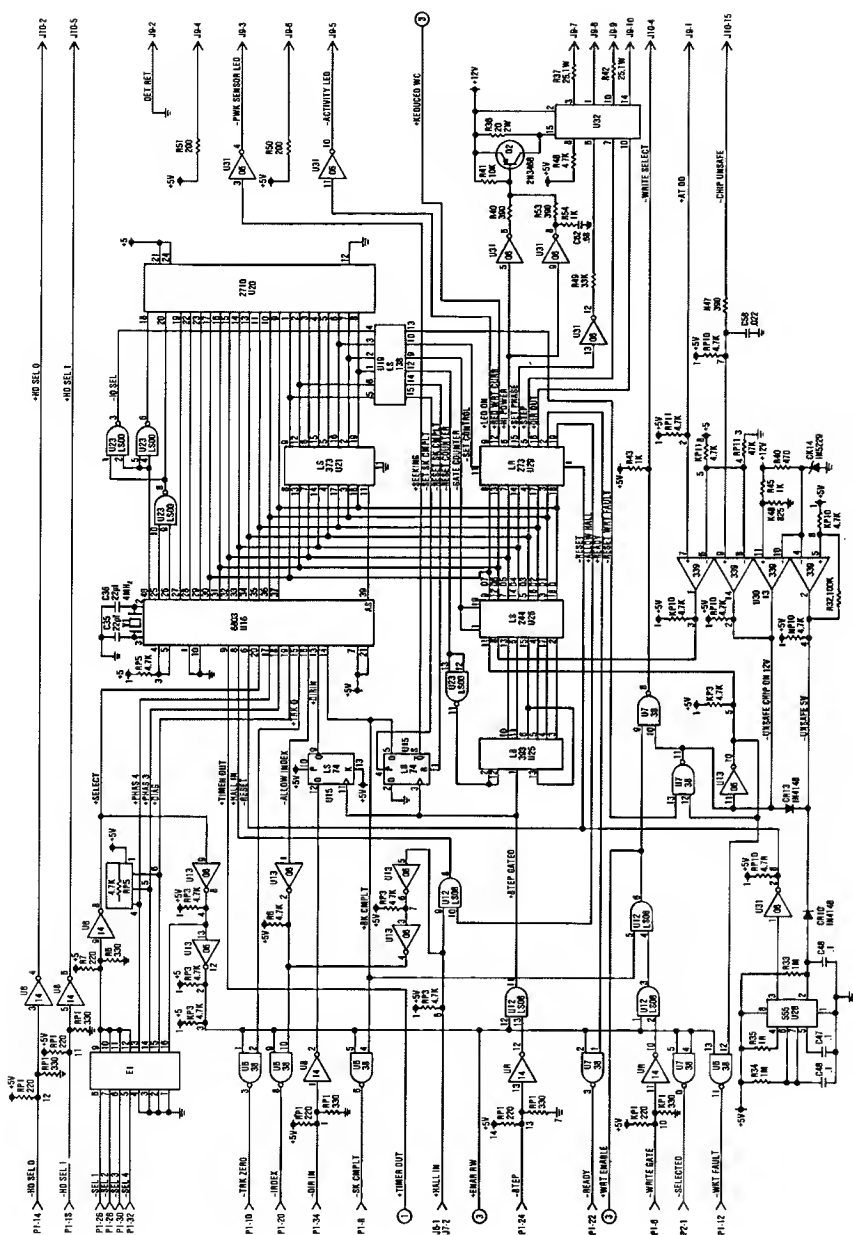


Fixed Disk Drive - Type 1 (Sheet 3 of 3)



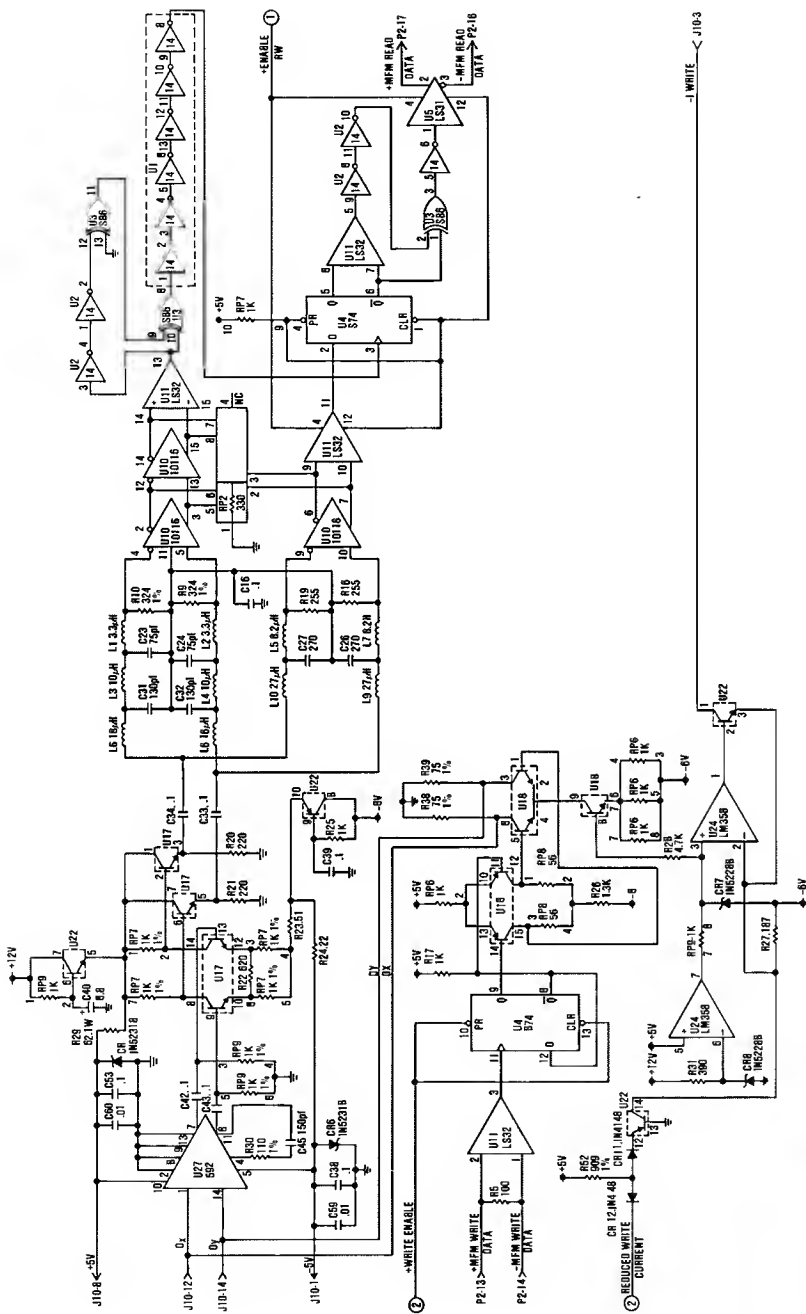
- NOTES:
1. SHEET TO SHEET CONNECTION IS AS FOLLOWS:
 2. UNLESS OTHERWISE SPECIFIED ALL RESISTORS ARE 1/4W 5% VALUE IN OHMS
 3. C1 IS A PROGRAMMABLE JUMPER SOCKET

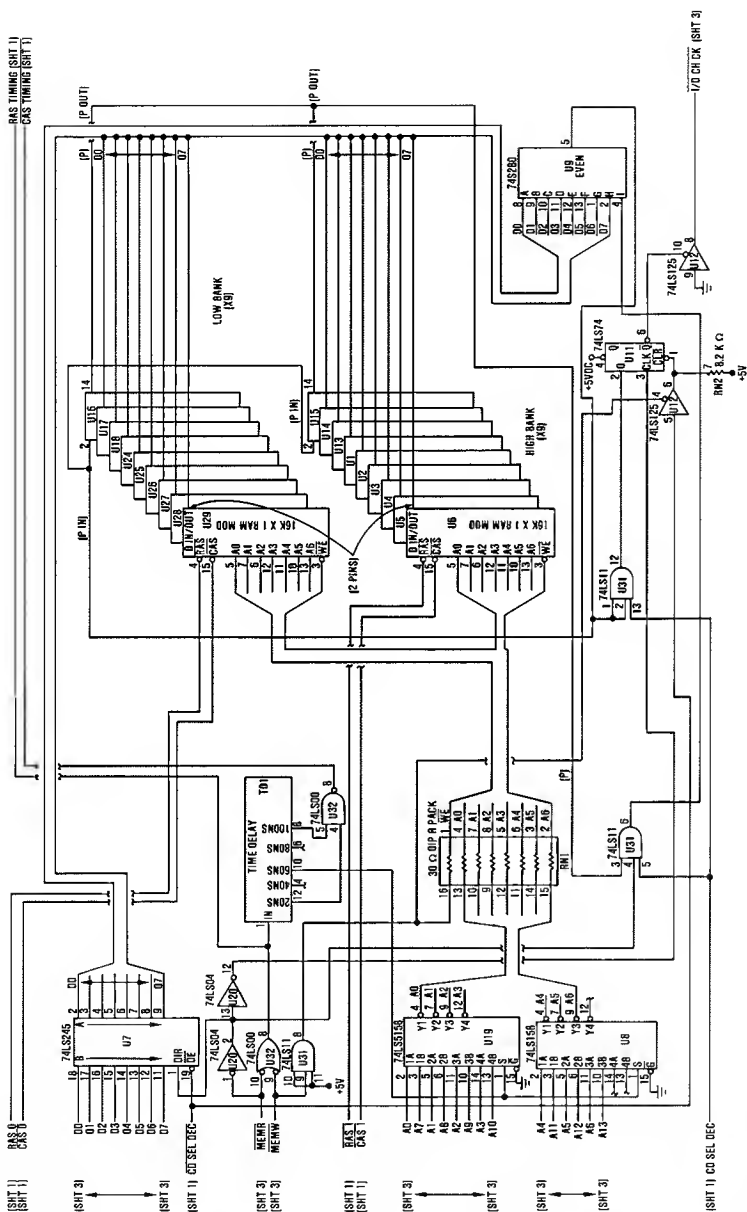
Fixed Disk Drive - Type 2 (Sheet 1 of 3)

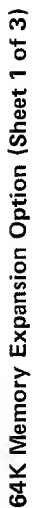


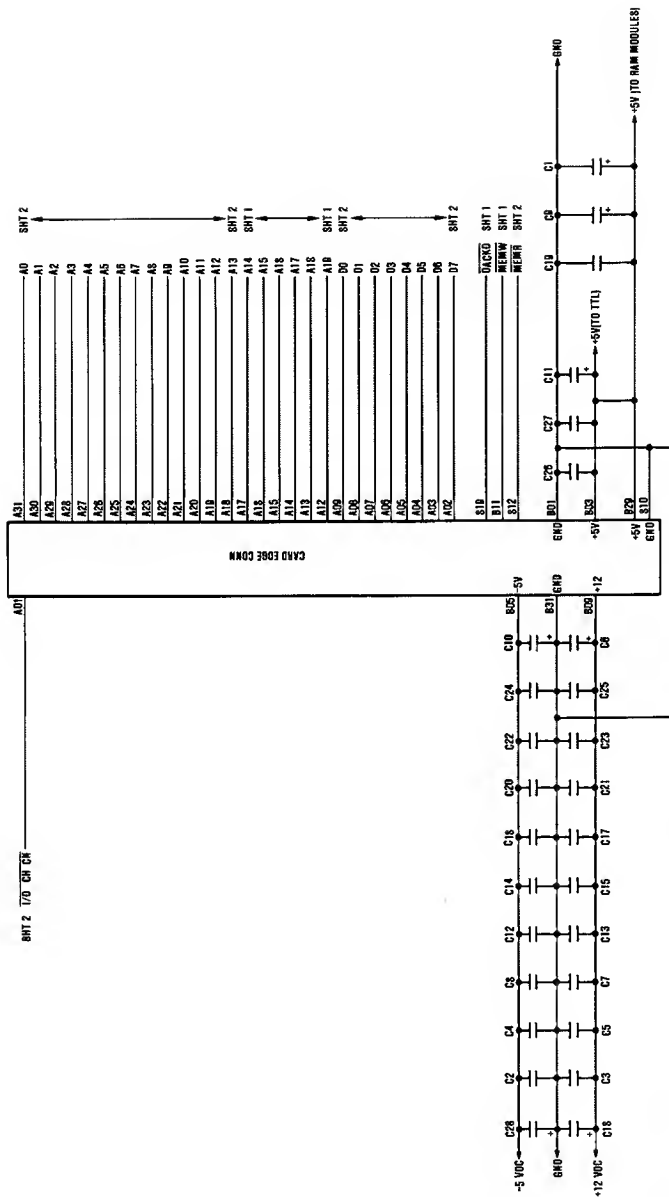
Fixed Disk Drive - Type 2 (Sheet 2 of 3)

Fixed Disk Drive - Type 2 (Sheet 3 of 3)

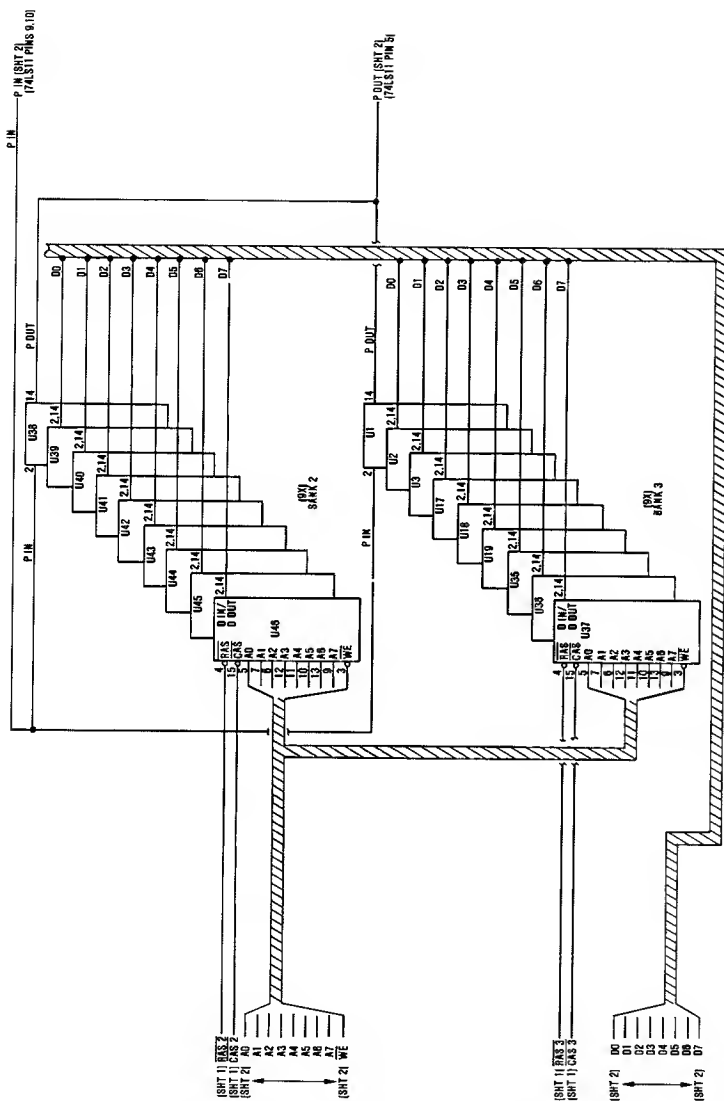




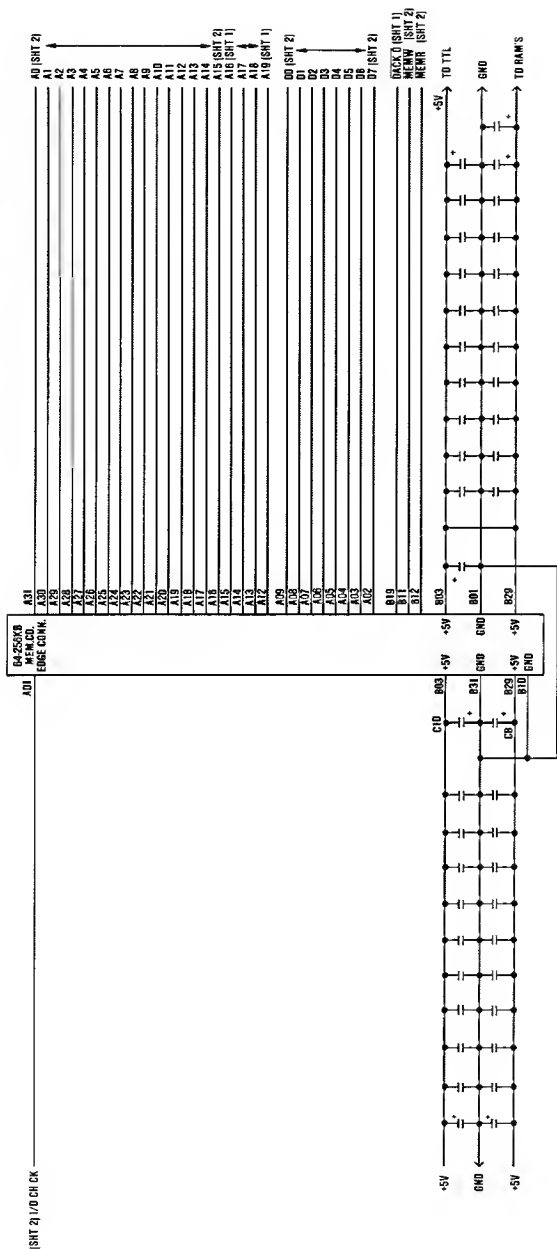


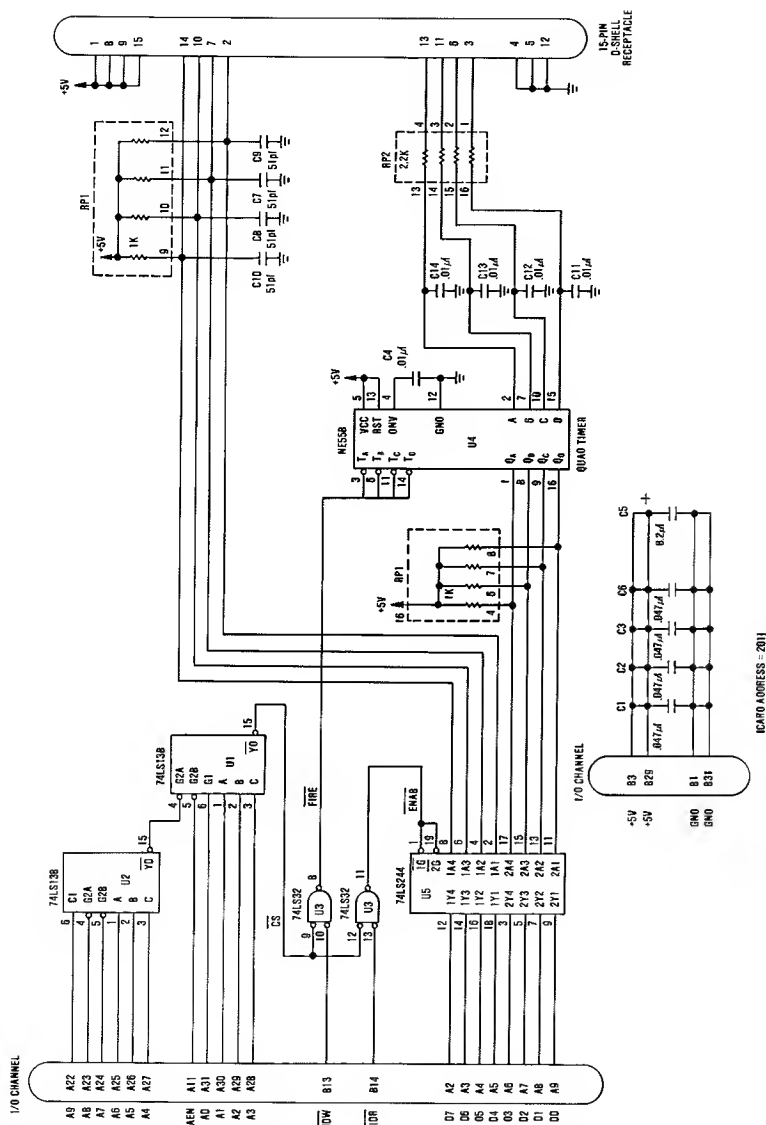


64K Memory Expansion Option (Sheet 3 of 3)

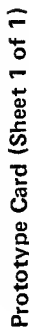


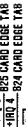
64/256K Memory Expansion Option (Sheet 3 of 4)





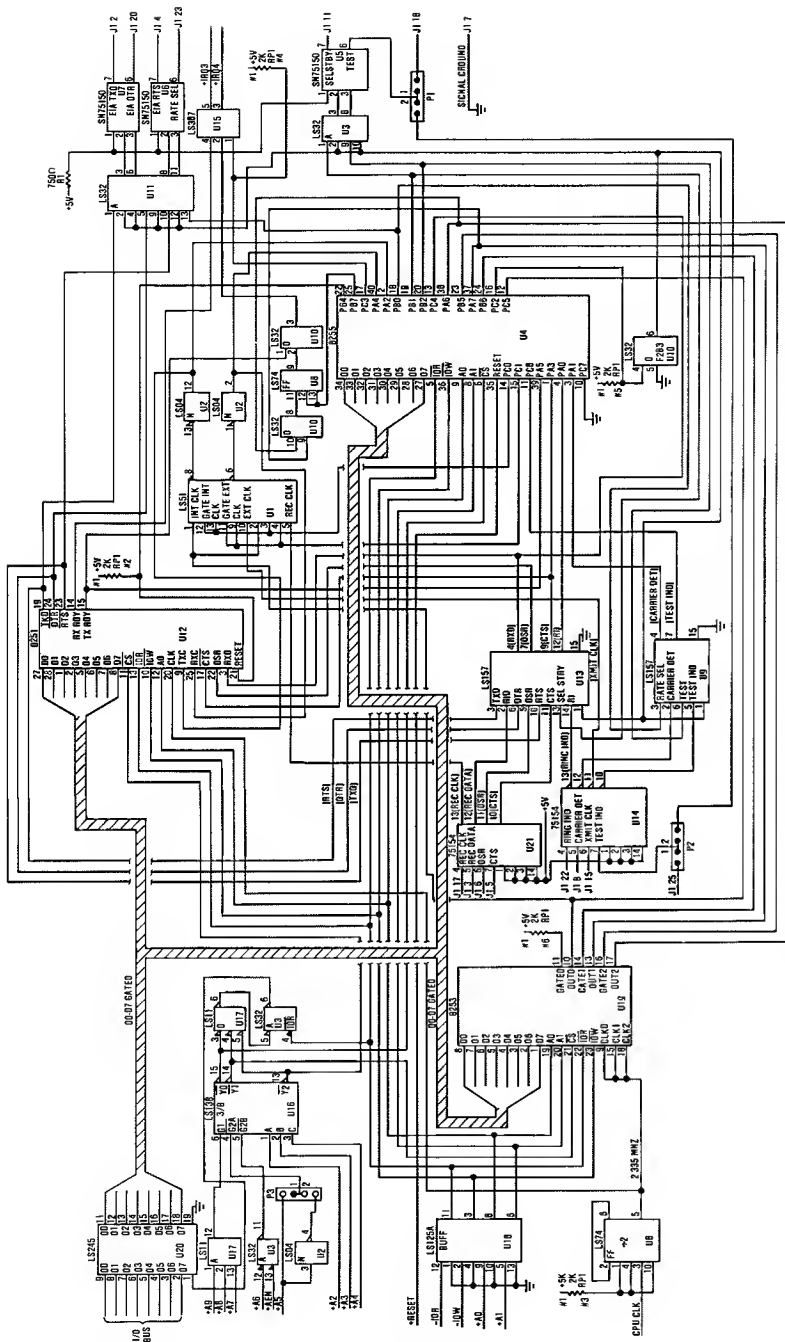
Game Control Adapter (Sheet 1 of 1)

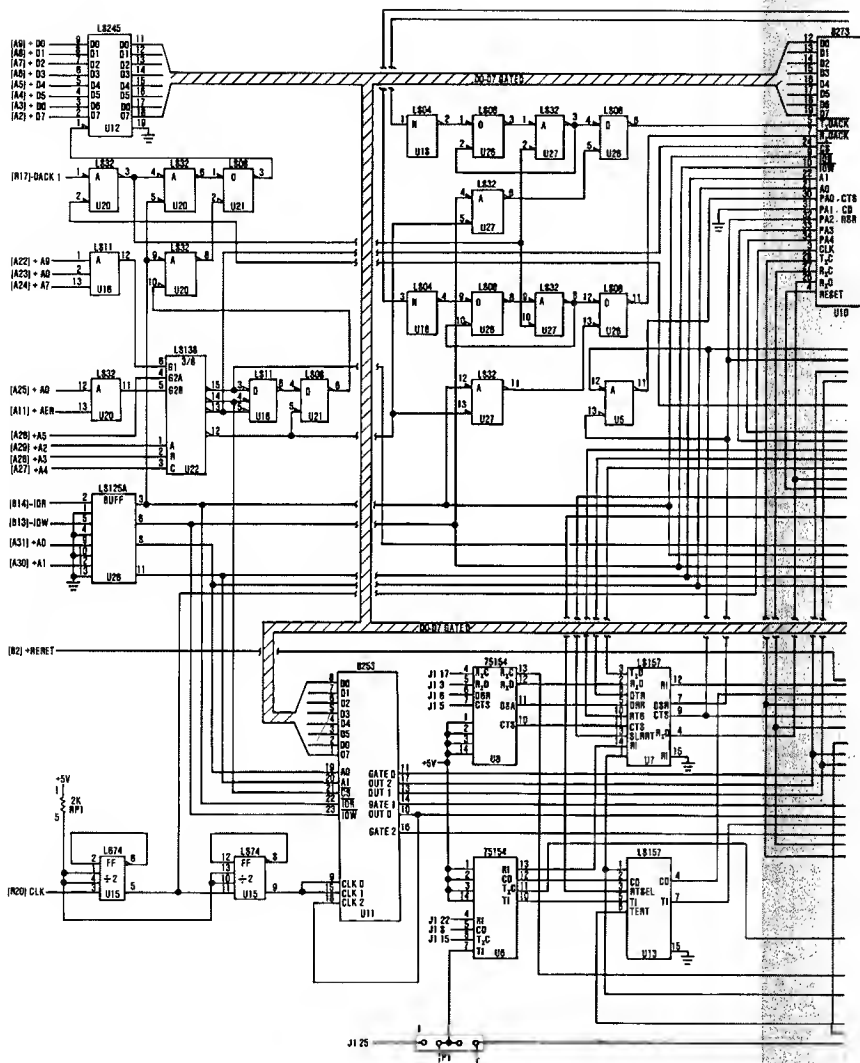




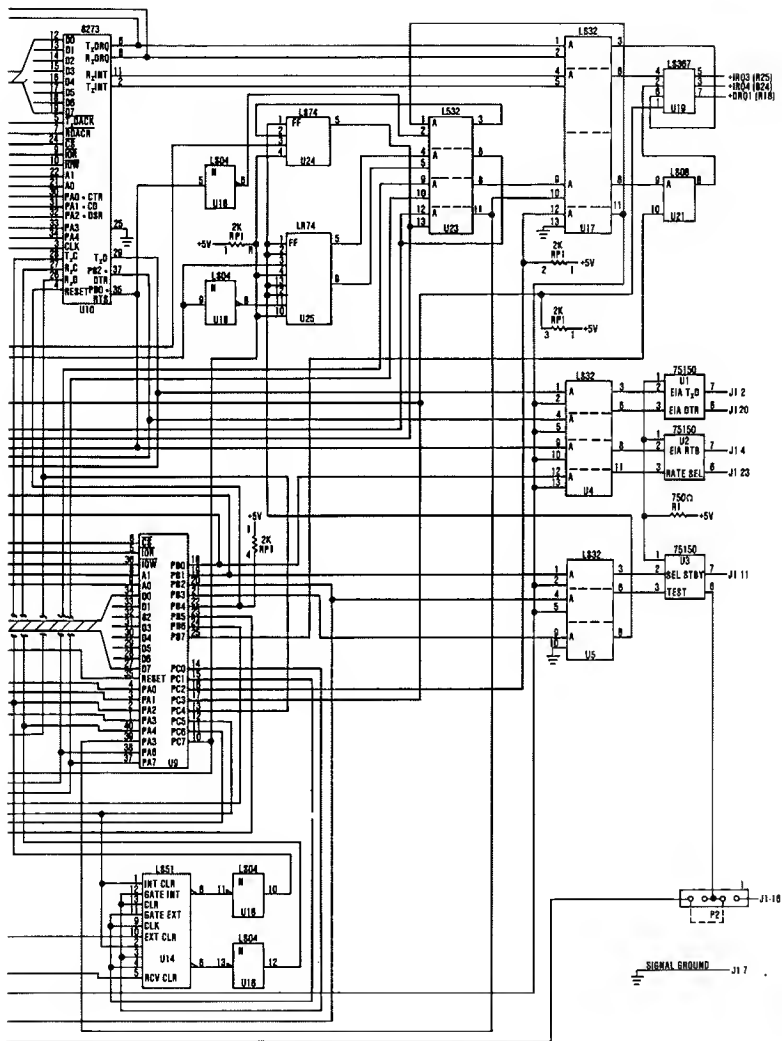
Asynchronous Communications Adapter (Sheet 1 of 1)

[illegible]





SDLC Communications Adapter (Sheet 1 of 2)



SDLC Communications Adapter (Sheet 2 of 2)

Notes:

APPENDIX E: SPECIFICATIONS

System Unit

Size:

Length--19.6 in (500 mm)

Depth--16.1 in (410 mm)

Height--5.5 in (142 mm)

Weight:

20.9 lb (9.5 kg) Without a diskette drive unit

25.0 lb (11.4 kg) With one diskette drive unit

Power Cable:

Length--6 ft (1.83 m)

Size--18 AWG

Environment:

Air Temperature

System ON, 60° to 90° F (15.6° to 32.2° C)

System OFF, 50° to 110° F (10° to 43° C)

Humidity

System ON, 8% to 80%

System OFF, 20% to 80%

Heat Output:

1083 BTU/hr

Noise Level:

56 dB Without printer

66 dB With printer

Electrical:

Nominal--120 Vac

Minimum--104 Vac

Maximum--127 Vac

kVA--0.3175 (maximum)

Keyboard

Size:

Length--19.6 in (500 mm)

Depth--7.87 in (200 mm)

Height--2.2 in (57 mm)

Weight:

6.5 lb (2.9 kg)

Color Display

Size:

Length--15.4 in (392 mm)

Depth--15.6 in (407 mm)

Height--11.7 in (297 mm)

Weight:

26 lb (11.8 kg)

Heat Output:

240 BTU/hr

Power Cable:

Length--6 ft (1.83 m)

Size--18 AWG

Signal Cable:

Length--5 ft (1.5 m)

Size--22 AWG

Expansion Unit

Size:

Length--19.6 in (500 mm)

Depth--16.1 in (410 mm)

Height--5.5 in (142 mm)

Weight:

33 lb (14.9 kg)

Power Cable:

Length--6 ft (1.83 m)

Size--18 AWG

Signal Cable:

Length--3.28 ft (1 m)

Size--22 AWG

Environment:

Air Temperature

System ON, 60° to 90° F (15.6° to 32.2° C)

System OFF, 50° to 110° F (10° to 43° C)

Humidity

System ON, 8% to 80%

System OFF, 20% to 80%

Heat Output:

717 BTU/hr

Electrical:

Nominal--120 Vac

Minimum--104 Vac

Maximum--127 Vac

Monochrome Display

Size:

Length--14.9 in (380 mm)

Depth--13.7 in (350 mm)

Height--11 in (280 mm)

Weight:

17.3 lb (7.9 kg)

Heat Output:

325 BTU/hr

Power Cable:

Length--3 ft (0.914 m)

Size--18 AWG

Signal Cable:

Length--4 ft (1.22 m)

Size--22 AWG

80 CPS Printers

Size:

Length--15.7 in (400 mm)

Depth--14.5 in (370 mm)

Height--4.3 in (110 mm)

Weight:

12.9 lb (5.9 kg)

Power Cable:

Length--6 ft (1.83 mm)

Size--22 AWG

Heat Output:

341 BTU/hr (maximum)

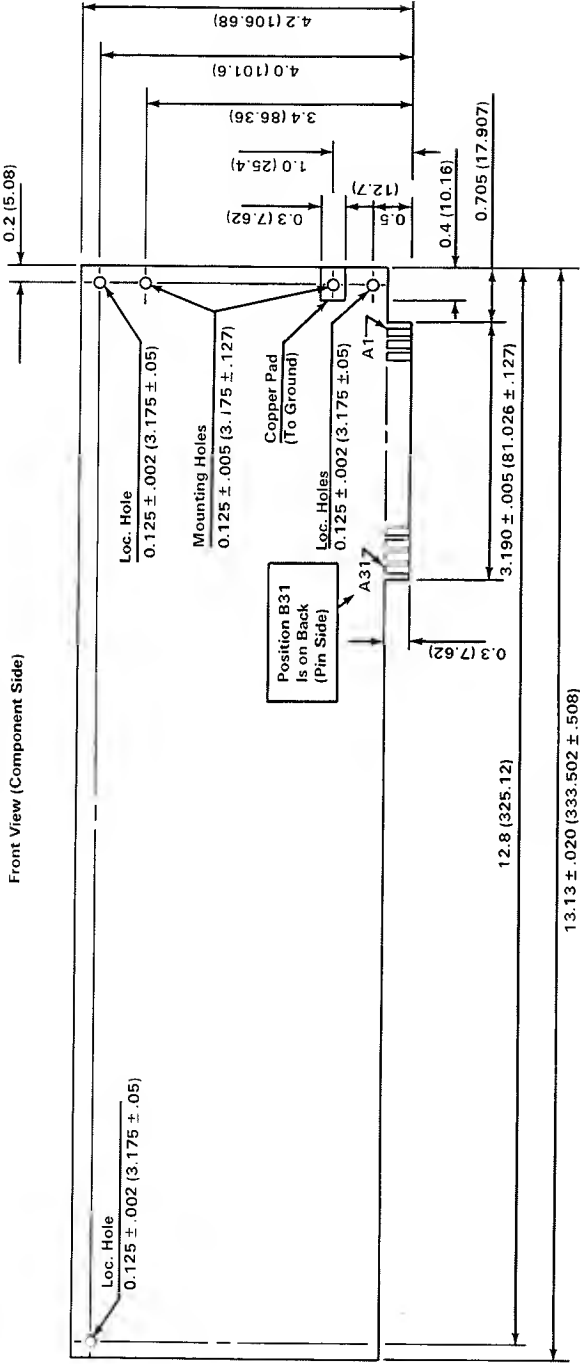
Electrical:

Nominal--120 Vac

Minimum--104 Vac

Maximum--127 Vac

Card Specifications

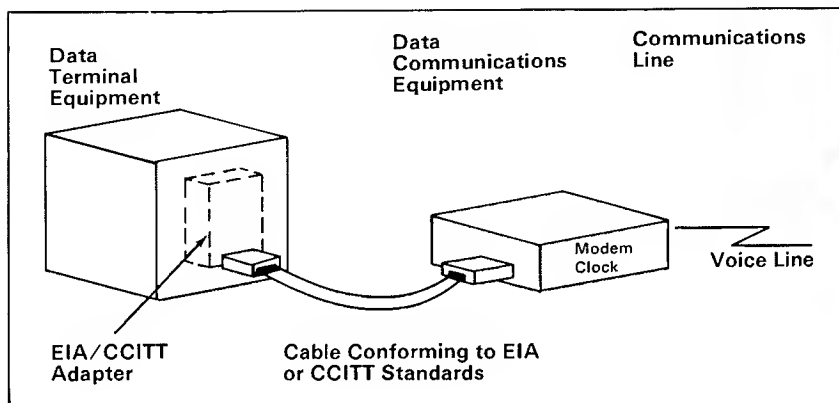


- Notes:
1. All Card Dimensions are ± .010 (.254) Tolerance (With Exceptions Indicated on Drawing or in Notes).
 2. Max. Card Length is 13.15 (334.01) Smaller Length is Permissible.
 3. Loc. and Mounting Holes are Non-Plated Thru. (Loc. 3X, Mtg. 2X).
 4. 31 Gold Tabs Each Side, 0.100 ± .0005 (2.54 ± .0127) Center to Center, 0.06 ± .0005 (1.524 ± .0127) Width.
 5. Numbers in Parentheses are in Millimeters, All Others are in Inches.

APPENDIX F: COMMUNICATIONS

Information processing equipment used for communications is called data terminal equipment (DTE). Equipment used to connect the DTE to the communications line is called data communications equipment (DCE).

An adapter is used to connect the data terminal equipment to the data communications line as shown in the following illustration:



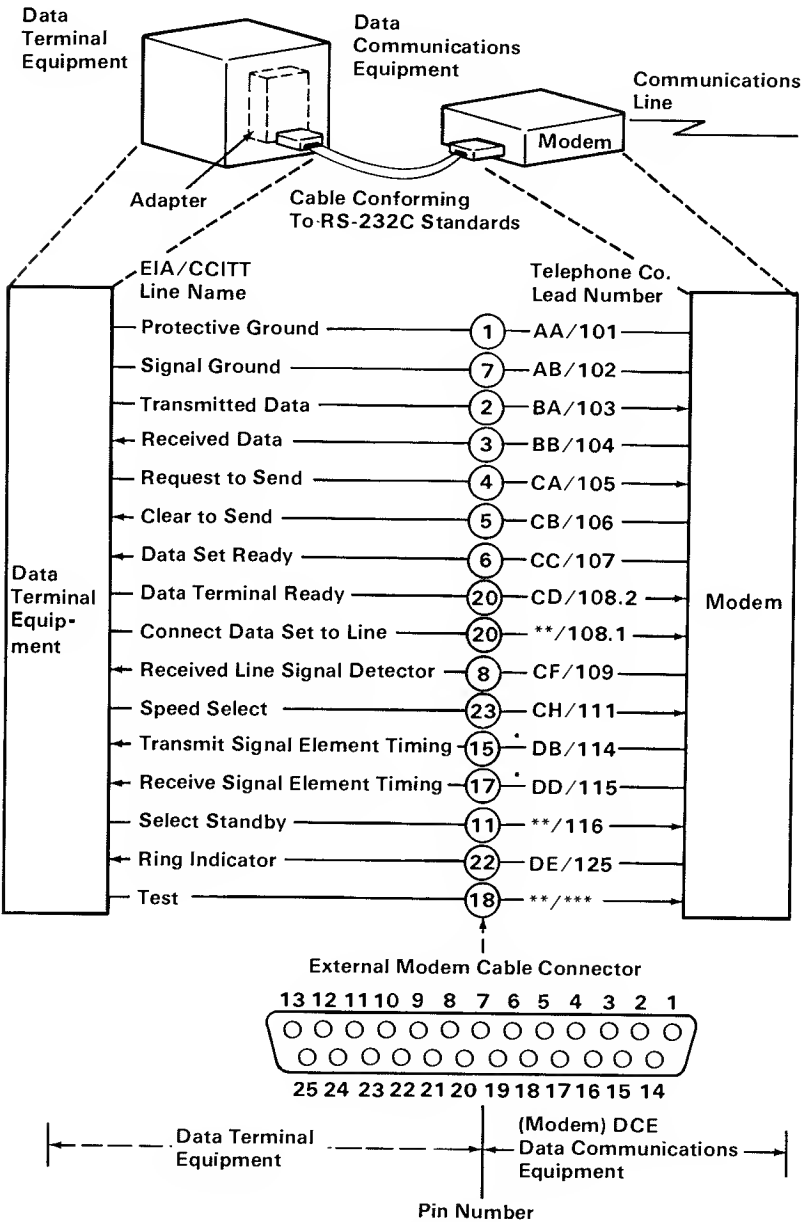
The EIA/CCITT adapter allows data terminal equipment to be connected to data communications equipment using EIA or CCITT standardized connections. An external modem is shown in this example; however, other types of data communications equipment can also be connected to data terminal equipment using EIA or CCITT standardized connections.

EIA standards are labeled RS-x (Recommended Standards-x) and CCITT standards are labeled V.x or X.x, where x is the number of the standard.

The EIA RS-232 interface standard defines the connector type, pin numbers, line names, and signal levels used to connect data terminal equipment to data communications equipment for the purpose of transmitting and receiving data. Since the RS-232 standard was developed, it has been revised three times. The three revised standards are the RS-232A, the RS-232B, and the presently used RS-232C.

The CCITT V.24 interface standard is equivalent to the RS-232C standard; therefore, the descriptions of the EIA standards also apply to the CCITT standards.

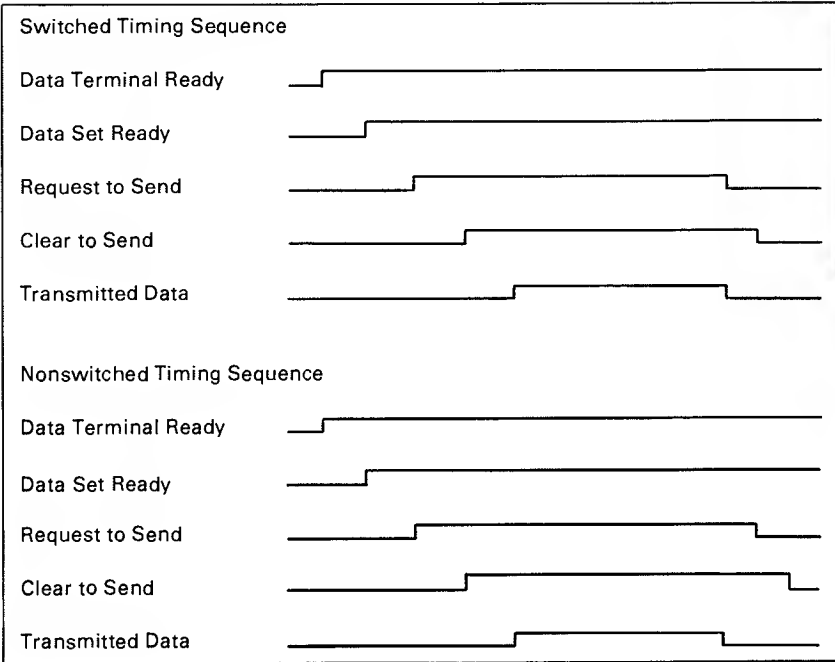
The following is an illustration of data terminal equipment connected to an external modem using connections defined by the RS-232C interface standard:



*Not used when business machine clocking is used.
**Not standardized by EIA (Electronics Industry Association).
***Not standardized by CCITT

Establishing a Communications Link

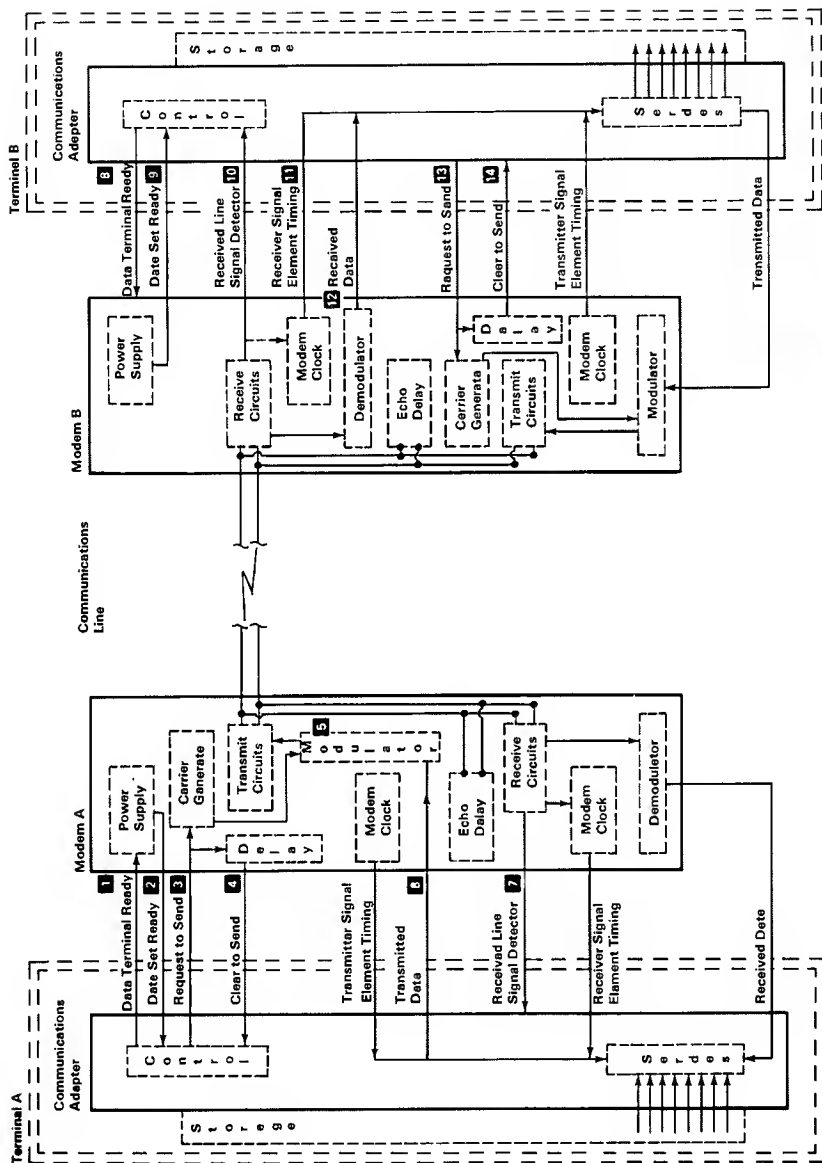
The following bar graphs represent normal timing sequences of operation during the establishment of communications for both switched (dial-up) and nonswitched (direct line) networks.



The following examples show how a link is established on a nonswitched point-to-point line, a nonswitched multipoint line, and a switched point-to-point line.

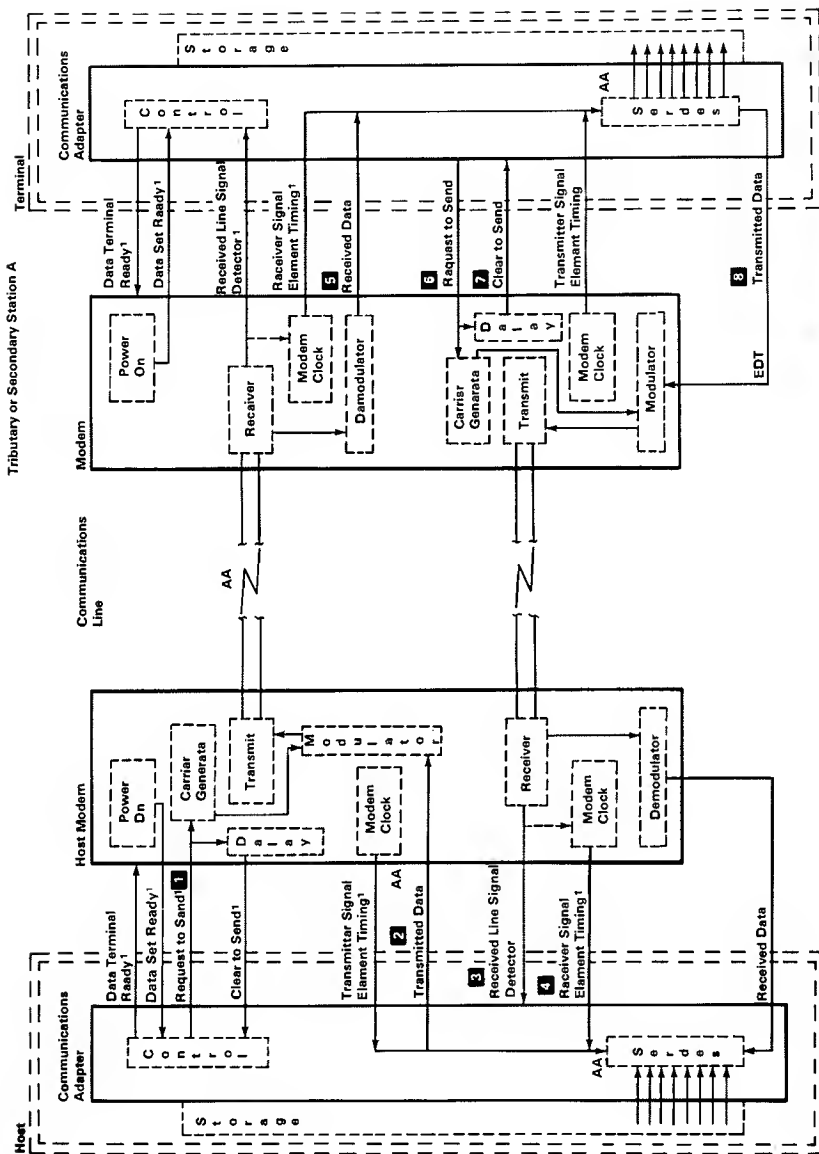
Establishing a Link on a Nonswitched Point-to-Point Line

1. The terminals at both locations activate the 'data terminal ready' lines **1** and **9**.
2. Normally the 'data set ready' lines **2** and **9** from the modems are active whenever the modems are powered on.
3. Terminal A activates the 'request to send' line **3**, which causes the modem at terminal A to generate a carrier signal.
4. Modem B detects the carrier, and activates the 'received line signal detector' line (sometimes called data carrier detect) **10**. Modem B also activates the 'receiver signal element timing' line (sometimes called receive clock) **11** to send receive clock signals to the terminal. Some modems activate the clock signals whenever the modem is powered on.
5. After a specified delay, modem A activates the 'clear to send' line **4**, which indicates to terminal A that the modem is ready to transmit data.
6. Terminal A serializes the data to be transmitted (through the serdes) and transmits the data one bit at a time (synchronized by the transmit clock) onto the 'transmitted data' line **6** to the modem.
7. The modem modulates the carrier signal with the data and transmits it to the modem B **5**.
8. Modem B demodulates the data from the carrier signal and sends it to terminal B on the 'received data' line **12**.
9. Terminal B deserializes the data (through the serdes) using the receive clock signals (on the 'receiver signal element timing' line) **11** from the modem.
10. After terminal A completes its transmission, it deactivates the 'request to send' line **3**, which causes the modem to turn off the carrier and deactivate the 'clear to send' line **4**.
11. Terminal A and modem A now become receivers and wait for a response from terminal B, indicating that all data has reached terminal B. Modem A begins an echo delay (50 to 150 milliseconds) to ensure that all echoes on the line have diminished before it begins receiving. An echo is a reflection of the transmitted signal. If the transmitting modem changed to receive too soon, it could receive a reflection (echo) of the signal it just transmitted.
12. Modem B deactivates the 'received line signal detector' line **10** and, if necessary, deactivates the receive clock signals on the 'receiver signal element timing, line **11**.
13. Terminal B now becomes the transmitter to respond to the request from terminal A. To transmit data, terminal B activates the 'request to send' line **13**, which causes modem B to transmit a carrier to modem A.
14. Modem B begins a delay that is longer than the echo delay at modem A before turning on the 'clear to send' line. The longer delay (called request-to-send to clear-to-send delay) ensures that modem A is ready to receive when terminal B begins transmitting data. After the delay, modem B activates the 'clear to send' line **14** to indicate that terminal B can begin transmitting its response.
15. After the echo delay at modem A, modem A senses the carrier from modem B (the carrier was activated in step 13 when terminal B activated the 'request to send' line) and activates the 'received line signal detector' line **7** to terminal A.
16. Modem A and terminal A are now ready to receive the response from terminal B. Remember, the response was not transmitted until after the request-to-send to clear-to-send delay at modem B (step 14).



Establishing a Link on a Nonswitched Multipoint Line

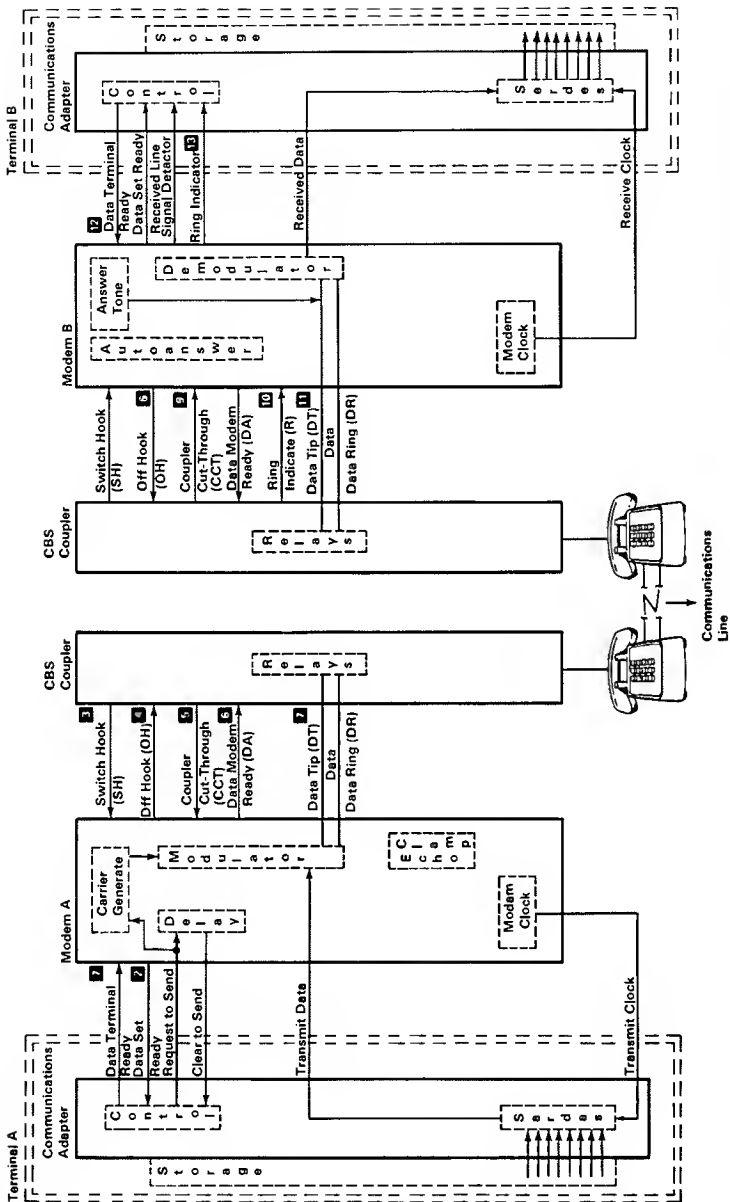
1. The control station serializes the address for the tributary or secondary station (AA) and sends its address to the modem on the 'transmitted data' line **2**.
2. Since the 'request to send' line and, therefore, the modem carrier, is active continuously **1**, the modem immediately modulates the carrier with the address, and, thus, the address is transmitted to all modems on the line.
3. All tributary modems, including the modem for station A, demodulate the address and send it to their terminals on the 'received data' line **5**.
4. Only station A responds to the address; the other stations ignore the address and continue monitoring their 'received data' line. To respond to the poll, station A activates its 'request to send' line **6**, which causes the modem to begin transmitting a carrier signal.
5. The control station's modem receives the carrier and activates the 'received line signal detector, line **3** and the 'receiver signal element timing' line **4** (to send clock signals to the control station). Some modems activate the clock signals as soon as they are powered on.
6. After a short delay to allow the control station modem to receive the carrier, the tributary modem activates the 'clear to send' line **7**.
7. When station A detects the active 'clear to send' line, it transmits its response. (For this example, assume that station A has no data to send; therefore, it transmits an EOT **8**.)
8. After transmitting the EOT, station A deactivates the 'request to send' line **6**. This causes the modem to deactivate the carrier and the 'clear to send' line **7**.
9. When the modem at the control station (host) detects the absence of the carrier, it deactivates the 'received line signal detector' line **3**.
10. Tributary station A is now in receive mode waiting for the next poll or select transmission from the control station.



*These lines are active continuously.

Establishing a Link on a Switched Point-To-Point Line

1. Terminal A is in communications mode; therefore, the 'data terminal ready' line **1** is active. Terminal B is in communication mode waiting for a call from terminal A.
 2. When the terminal A operator lifts the telephone handset, the 'switch hook' line from the coupler is activated **3**.
 3. Modem A detects the 'switch hook' line and activates the 'off hook' line **4**, which causes the coupler to connect the telephone set to the line and activate the 'coupler cut-through' line **5** to the modem.
 4. Modem A activates the 'data modem ready' line **6** to the coupler (the 'data modem ready' line is on continuously in some modems).
 5. The terminal A operator sets the exclusion key or talk/data switch to the talk position to connect the handset to the communications line. The operator then dials the terminal B number.
 6. When the telephone at terminal B rings, the coupler activates the 'ring indicate' line to modem B **10**. Modem B indicates that the 'ring indicate' line was activated by activating the 'ring indicator' line **13** to terminal B.
 7. Terminal B activates the 'data terminal ready' line to modem B **12**, which activates the autoanswer circuits in modem B. (The 'data terminal ready' line might already be active in some terminals.)
 8. The autoanswer circuits in modem B activate the 'off hook' line to the coupler **8**.
 9. The coupler connects modem B to the communications line through the 'data tip' and 'data ring' lines **11** and activates the 'coupler cut-through' line **9** to the modem. Modem B then transmits an answer tone to terminal A.
 10. The terminal A operator hears the tone and sets the exclusion key or talk/data switch to the data position (or performs an equivalent operation) to connect modem A to the communications line through the 'data tip' and 'data ring' lines **7**.
 11. The coupler at terminal A deactivates the 'switch hook' line **3**. This causes modem A to activate the 'data set ready' line **2** indicating to terminal A that the modem is connected to the communications line.
- The sequence of the remaining steps to establish the data link is the same as the sequence required on a nonswitched point-to-point line. When the terminals have completed their transmission, they both deactivate the 'data terminal ready' line to disconnect the modems from the line.



Notes:

APPENDIX G: SWITCH SETTINGS

The following switch settings are divided between two groups. The first group contains the switch settings for the 16/64K system board. The second group contains the 64/256K system board switch settings.

Determine the system board type and refer to the appropriate group of switch settings for all applications.

Switch Settings (16KB-64KB CPU)	G-3
Switch Settings (64KB-256KB CPU)	G-29

Notes:

Switch Settings (16KB-64KB CPU)

System Board Switch Settings	G-5
System Board Switch Settings	G-5
5-1/4" Diskette Drives Switch Settings	G-6
Display Type Switch Settings	G-6
Math Coprocessor Switch Settings	G-7
Memory Option Switch Settings	G-8
16K Total Memory	G-8
32K Total Memory	G-8
48K Total Memory	G-8
64K Total Memory	G-8
96K Total Memory	G-9
128K Total Memory	G-10
160K Total Memory	G-11
192K Total Memory	G-12
224K Total Memory	G-13
256K Total Memory	G-14
288K Total Memory	G-15
320K Total Memory	G-16
352K Total Memory	G-17
384K Total Memory	G-18
416K Total Memory	G-19
448K Total Memory	G-20
480K Total Memory	G-21
512K Total Memory	G-22
544K Total Memory	G-23
576K Total Memory	G-24
608K Total Memory	G-25
640K Total Memory	G-26
Extender Card Switch Settings	G-27

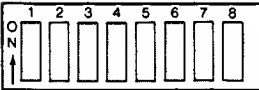
Notes:

Switch Setting Charts

System Board Switches

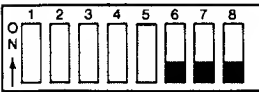
WARNING: Before you change any switch settings, make a note of how the switches are presently set.

Switch Block 1



Switch	Function
1,7,8	Number of 5-1/4 inch diskette drives installed
2	Math Coprocessor
3,4	System board memory switches
5,6	Type(s) of display(s) connected

Switch Block 2

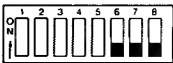
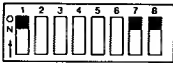


Switch	Function
1,2,3,4,5	Amount of memory options installed
6,7,8	Always in the Off position

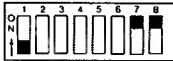
Number of 5-1/4 Inch Diskette Drives Installed

Switch Block 1 Switch Block 2

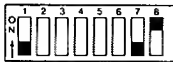
0 – Drives



1 – Drive



2 – Drives



Type(s) of display(s) connected

WARNING:

If an IBM Monochrome Display is connected to your system. Switch Block 1, switches 5 and 6, must always be Off. Damage to your display can result with any other switch settings.

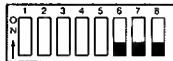
Switch Block 1 Switch Block 2

IBM Monochrome Display (or IBM Monochrome Display plus another display)

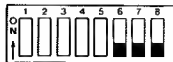


Switch Block 1 Switch Block 2

Color Display (Do not use if an IBM Monochrome Display is connected)



40x25
Mode



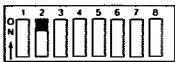
80x25
Mode

Note: The 40x25 mode means there will be 40 characters across the screen and 25 lines down the screen. The 80x25 mode means there will be 80 characters across the screen and 25 lines down the screen. The 80x25 mode, when used with home televisions and various displays, can cause loss of character quality.

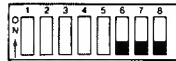
Math Coprocessor

Switch Block 1 Switch Block 2

With Math Coprocessor

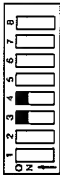
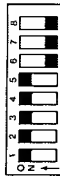


Without Math Coprocessor

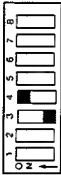
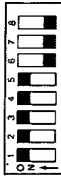


Memory Switch Settings (16KB-64KB CPU) System Board

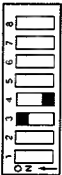

16K Total Memory

System Board Switches	<p>Switch Block 1</p> 	<p>Switch Block 2</p> 
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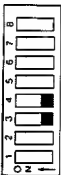

32K Total Memory

System Board Switches	<p>Switch Block 1</p> 	<p>Switch Block 2</p> 
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48K Total Memory

System Board Switches	<p>Switch Block 1</p> 	<p>Switch Block 2</p> 
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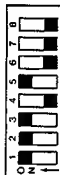

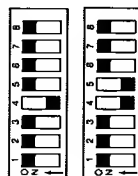
64K Total Memory

System Board Switches	<p>Switch Block 1</p> 	<p>Switch Block 2</p> 
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96K Total Memory
32K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 32K option	64/256K Option Card Switches	64K Option Card Switches
		

128K Total Memory
64K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2	
			
	64/256K Option Card Switches	64K Option Card Switches	32K Option Card Switches
1 - 64/256K option with 64K installed			
1 - 64K option			
2 - 32K options			




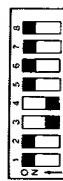
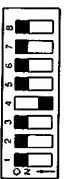




160K Total Memory
96K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 64K installed 1 - 32K option		64K Option Card Switches
1 - 64K option 1 - 32K option		
3 - 32K options		  

**192K Total Memory
128K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 64K option installed 1 - 64K option		64K Option Card Switches
2 - 64K options		
1 - 64/256K option with 64K installed 2 - 32K options		32K Option Card Switches
1 - 64K option 2 - 32K options		
1 - 64/256K option with 128K installed		

224K Total Memory
160K + (64K on System Board)

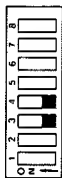
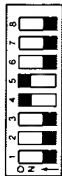





System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 64K installed 1 - 64K option 1 - 32K option	64/256K Option Card Switches 	32K Option Card Switches 
2 - 64K options 1 - 32K option	 	
1 - 64/256K option with 128K installed 1 - 32K option		

Appendix G


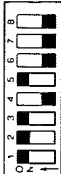

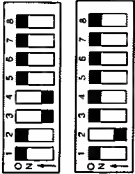



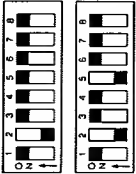

**256K Total Memory
192K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed		64K Option Card Switches
1 - 64/256K option with 128K installed 1 - 64K option		
1 - 64/256K option with 64K installed 2 - 64K options		
3 - 64K options		
1 - 64/256K option with 128K installed 2 - 32K options		

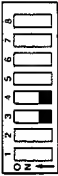





288K Total Memory
224K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed 1 - 32K option		
1 - 64/256K option with 128K installed 1 - 64K option 1 - 32K option		
	64/256K Option Card Switches	64K Option Card Switches
		
		



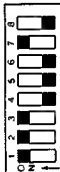
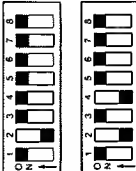
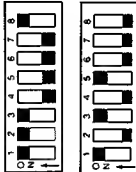


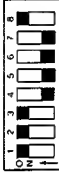
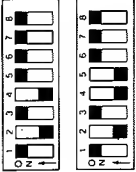
**320K Total Memory
256K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 128K installed 2 - 64K options	64/256K Option Card Switches 	64K Option Card Switches 
1 - 64/256K option with 192K installed 1 - 64K option		
1 - 64/256K option with 192K installed 2 - 32K options		
1 - 64/256K option with 256K installed		



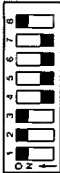



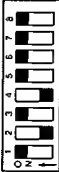
352K Total Memory
288K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed 1 - 64K option 1 - 32K option		
	64/256K Option Card Switches	64K Option Card Switches
		
		
1 - 64/256K option with 256K installed 1 - 32K option		32K Option Card Switches

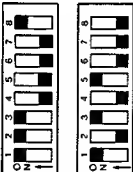

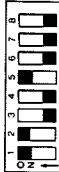
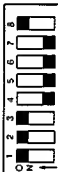
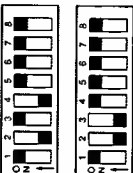
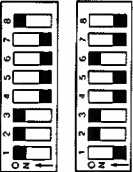
**384K Total Memory
320K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2	
			
	64/256K Option Card Switches	64K Option Card Switches	32K Option Card Switches
1 - 64/256K option with 192K installed 2 - 64K options			
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed			
1 - 64/256K option with 256K installed 1 - 64K option			
1 - 64/256K option with 256K installed 2 - 32K options			

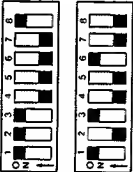

**416K Total Memory
352K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed 1 - 32K option	 	
1 - 64/256K option with 256K installed 1 - 64K option 1 - 32K option		

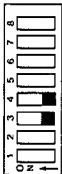





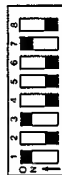
448K Total Memory
384K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2	
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed 1 - 64K option			
1 - 64/256K option with 256K installed 2 - 64K options			
1 - 64/256K option with 256K installed 1 - 64/256K option with 128K installed			

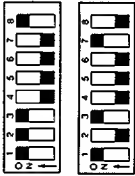
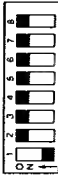
**480K Total Memory
416K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 256K installed 1 - 64/256K option with 128K installed 1 - 32K option	64/256K Option Card Switches 	32K Option Card Switches 

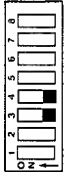

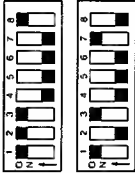

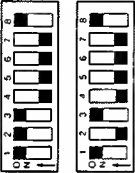
**512K Total Memory
448K + (64K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 256K installed 1 - 64/256K option with 128K installed 1 - 64K option	<div>64/256K Option Card Switches</div> <div> </div>	<div>64K Option Card Switches</div> <div></div>
1 - 64/256K option with 256K installed 1 - 64/256K option with 192K installed	<div>64/256K Option Card Switches</div> <div> </div>	

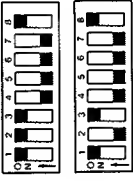

544K Total Memory
480K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 256K installed 1 - 64/256K option with 192K installed 1 - 32K option		

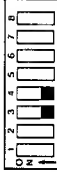
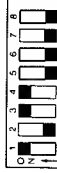
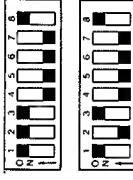
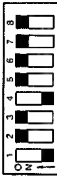
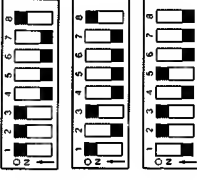
576K Total Memory
512K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 256K installed 1 - 64/256K option with 192K installed 1 - 64K option	64/256K Option Card Switches 	64K Option Card Switches 
2 - 64/256K option with 256K installed		











608K Total Memory
544K + (64K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
2 - 64/256K option with 256K installed 1 - 32K option		
	64/256K Option Card Switches	32K Option Card Switches

640K Total Memory
576K + (64K on System Board)

System Board Switches	Switch Block 1 	Switch Block 2 
2 - 64/256K option with 256K installed 1 - 64K option	64/256K Option Card Switches 	64K Option Card Switches 
2 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed	64/256K Option Card Switches 	

Extender Card Switch Settings

System Memory	Extender Card Switch Block	Memory Segment
16K to 64K		1
96K to 128K		2
160K to 192K		3
224K to 256K		4
288K to 320K		5
352K to 384K		6
416K to 448K		7
480K to 512K		8
544K to 576K		9
608K to 640K		A

Notes:

Switch Settings (64KB-256KB CPU)

System Board Switch Settings	G-31
System Board Switch Settings	G-31
5-1/4" Diskette Drives Switch Settings	G-32
Display Type Switch Settings	G-32
Math Coprocessor Switch Settings	G-32
Memory Option Switch Settings	G-34
64K Total Memory	G-34
128K Total Memory	G-34
192K Total Memory	G-34
256K Total Memory	G-34
288K Total Memory	G-35
320K Total Memory	G-36
352K Total Memory	G-37
384K Total Memory	G-38
416K Total Memory	G-39
448K Total Memory	G-40
480K Total Memory	G-41
512K Total Memory	G-42
544K Total Memory	G-43
576K Total Memory	G-44
608K Total Memory	G-45
640K Total Memory	G-46
Extender Card Switch Settings	G-47

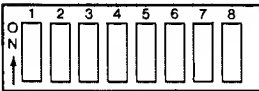
Notes:

Switch Setting Charts

System Board Switches

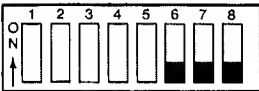
WARNING: Before you change any switch settings, make a note of how the switches are presently set.

Switch Block 1



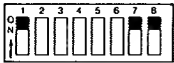

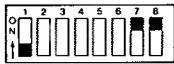
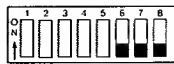
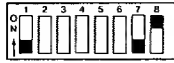

Switch	Function
1,7,8	Number of 5-1/4 inch diskette drives installed
2	Math Coprocessor
3,4	System board memory switches
5,6	Type(s) of display(s) connected

Switch Block 2




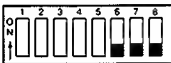
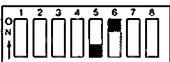
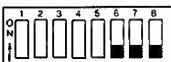
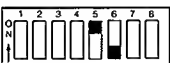
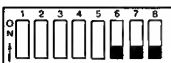
Switch	Function
1,2,3,4,5	Amount of memory options installed
6,7,8	Always in the Off position

Number of 5-1/4 Inch Diskette Drives Installed

	Switch Block 1	Switch Block 2
0 – Drives		
1 – Drive		
2 – Drives		

Type(s) of display(s) connected

WARNING: If an IBM Monochrome Display is connected to your system. Switch Block 1, switches 5 and 6, must always be Off. Damage to your display can result with any other switch settings.

	Switch Block 1	Switch Block 2	
IBM Monochrome Display (or IBM Monochrome Display plus another display)			
Color Display (Do not use if an IBM Monochrome Display is connected)			40x25 Mode
			80x25 Mode

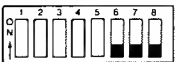
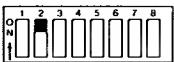
Note: The 40x25 mode means there will be 40 characters across the screen and 25 lines down the screen. The 80x25 mode means there will be 80 characters across the screen and 25 lines down the screen. The 80x25 mode, when used with home televisions and various displays, can cause loss of character quality.

Math Coprocessor

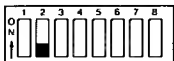
Switch Block 1

Switch Block 2

With Math Coprocessor



Without Math Coprocessor

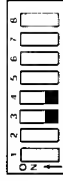


Memory Switch Settings

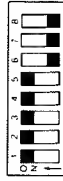
(64KB-256KB CPU) System Board

64K Total Memory

System Board Switches	Switch Block 1	Switch Block 2
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Switch Block 1



128K Total Memory

System Board Switches	Switch Block 1	Switch Block 2
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Switch Block 1

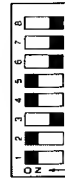


192K Total Memory

System Board Switches	Switch Block 1	Switch Block 2
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Switch Block 1

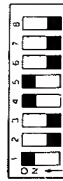


256K Total Memory

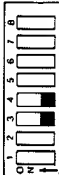


System Board Switches	Switch Block 1	Switch Block 2
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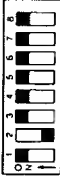
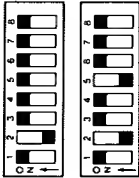
Switch Block 1









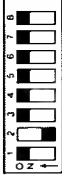


**288K Total Memory
32K + (256K on System Board)**

System Board Switches		Switch Block 2 
1 - 32K option	64/256K Option Card Switches	64K Option Card Switches
		32K Option Card Switches 


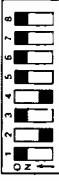



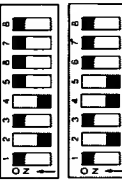
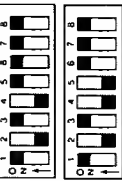

320K Total Memory
64K + (256K on System Board)

System Board Switches		Switch Block 1	Switch Block 2
			
1 - 64/256K option with 64K installed	64/256K Option Card Switches		64K Option Card Switches
1 - 64K option			
2 - 32K options			



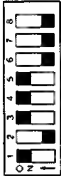


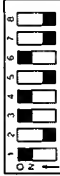

352K Total Memory
96K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 64K installed 1 - 32K option		32K Option Card Switches 
1 - 64K option 1 - 32K option		
3 - 32K options		  

**384K Total Memory
128K + (256K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 64K option installed 1 - 64K option		
2 - 64K options		
1 - 64/256K option with 64K installed 2 - 32K options		
1 - 64K option 2 - 32K options		
1 - 64/256K option with 128K installed		





416K Total Memory
160K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 64K installed 1 - 64K option 1 - 32K option		
2 - 64K options 1 - 32K option		
1 - 64/256K option with 128K installed 1 - 32K option		


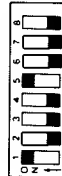

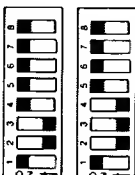



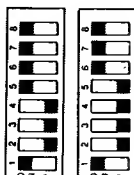

**448K Total Memory
192K + (256K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed		64K Option Card Switches
1 - 64/256K option with 128K installed 1 - 64K option		
1 - 64/256K option with 64K installed 2 - 64K options		
3 - 64K options		
1 - 64/256K option with 128 installed 2 - 32K options		







480K Total Memory
224K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed 1 - 32K option		
1 - 64/256K option with 128K installed 1 - 64K option 1 - 32K option		




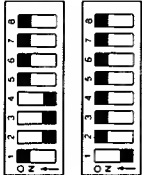
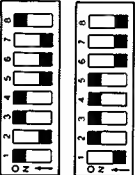



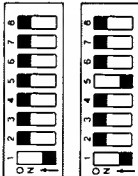
512K Total Memory
256K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
	64/256K Option Card Switches	64K Option Card Switches
1 - 64/256K option with 128K installed 2 - 64K options		
1 - 64/256K option with 192K installed 1 - 64K option		
1 - 64/256K option with 192K installed 2 - 32K options		
1 - 64/256K option with 256K installed		



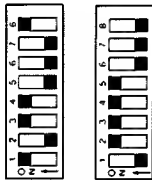

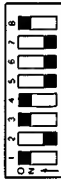

544K Total Memory
288K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
1 - 64/256K option with 192K installed 1 - 64K option 1 - 32K option		
	64/256K Option Card Switches	64K Option Card Switches
		
		
1 - 64/256K option with 256K installed 1 - 32K option		


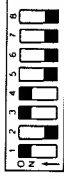
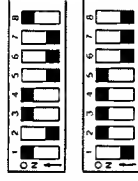


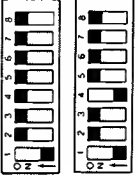
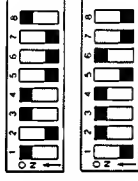
576K Total Memory
320K + (256K on System Board)

System Board Switches	Switch Block 1	Switch Block 2
		
	64/256K Option Card Switches	64K Option Card Switches
1 - 64/256K option with 192K installed 2 - 64K options		
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed		
1 - 64/256K option with 256K installed 1 - 64K option		
1 - 64/256K option with 256K installed 2 - 32K options		

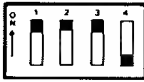
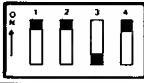








**608K Total Memory
352K + (256K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2
		
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed 1 - 32K option	64/256K Option Card Switches 	32K Option Card Switches 
1 - 64/256K option with 256K installed 1 - 64K option 1 - 32K option	64/256K Option Card Switches 	64K Option Card Switches 

**640K Total Memory
384K + (256K on System Board)**

System Board Switches	Switch Block 1	Switch Block 2	32K Option Card Switches
1 - 64/256K option with 256K installed 1 - 64/256K option with 64K installed 1 - 64K option			
	64/256K Option Card Switches	64K Option Card Switches	
			
1 - 64/256K option with 256K installed 2 - 64K options			
1 - 64/256K option with 256K installed 1 - 64/256K option with 128K installed			

Extender Card Switch Settings

System Memory	Extender Card Switch Block	Memory Segment
16K to 64K		1
96K to 128K		2
160K to 192K		3
224K to 256K		4
288K to 320K		5
352K to 384K		6
416K to 448K		7
480K to 512K		8
544K to 576K		9
608K to 640K		A

Notes:

GLOSSARY

μs: Microsecond.

adapter: An auxiliary system or unit used to extend the operation of another system.

address bus: One or more conductors used to carry the binary-coded address from the microprocessor throughout the rest of the system.

all points addressable (APA): A mode in which all points on a displayable image can be controlled by the user.

alphanumeric (A/N): Pertaining to a character set that contains letters, digits, and usually other characters, such as punctuation marks. Synonymous with alphanumeric.

American Standard Code for Information Interchange (ASCII): The standard code, using a coded character set consisting of 7-bit coded characters (8 bits including parity check), used for information interchange among data processing systems, data communication systems and associated equipment. The ASCII set consists of control characters and graphic characters.

A/N: Alphanumeric.

analog: (1) pertaining to data in the form of continuously variable physical quantities. (2) Contrast with digital.

AND: A logic operator having the property that if P is a statement, Q is a statement, R is a statement,...,then the AND of P, Q, R,...is true if all statements are true, false if any statement is false.

APA: All points addressable.

ASCII: American Standard Code for Information Interchange.

assembler: A computer program used to assemble. Synonymous with assembly program.

asynchronous communications: A communication mode in which each single byte of data is synchronized, usually by the addition of start/stop bits.

BASIC: Beginner's all-purpose symbolic instruction code.

basic input/output system (BIOS): Provides the device level control of the major I/O devices in a computer system, which provides an operational interface to the system and relieves the programmer from concern over hardware device characteristics.

baud: (1) A unit of signaling speed equal to the number of discrete conditions or signal events per second. For example, one baud equals one-half dot cycle per second in Morse code, one bit per second in a train of binary signals, and one 3-bit value per second in a train of signals each of which can assume one of eight different states. (2) In asynchronous transmission, the unit of modulation rate corresponding to one unit of interval per second; that is, if the duration of the unit interval is 20 milliseconds, the modulation rate is 50 baud.

BCC: Block-check character.

beginner's all-purpose symbolic instruction code (BASIC): A programming language with a small repertoire of commands and a simple syntax, primarily designed for numerical application.

binary: (1) Pertaining to a selection, choice, or condition that has two possible values or states. (2) Pertaining to a fixed radix numeration system having a radix of two.

binary digit: (1) In binary notation, either of the characters 0 or 1. (2) Synonymous with bit.

binary notation: Any notation that uses two different characters, usually the binary digits 0 and 1.

binary synchronous communications (BSC): A standardized procedure, using a set of control characters and control character sequences for synchronous transmission of binary-coded data between stations.

BIOS: Basic input/output system.

bit: In binary notation, either of the characters 0 or 1.

bits per second (bps): A unit of measurement representing the number of discrete binary digits which can be transmitted by a device in one second.

block-check character (BCC): In cyclic redundancy checking, a character that is transmitted by the sender after each message block and is compared with a block-check character computed by the receiver to determine if the transmission was successful.

boolean operation: (1) Any operation in which each of the operands and the result take one of two values. (2) An operation that follows the rules of boolean algebra.

bootstrap: A technique or device designed to bring itself into a desired state by means of its own action; that is, a machine routine whose first few instructions are sufficient to bring the rest of itself into the computer from an input device.

bps: Bits per second.

BSC: Binary synchronous communications.

buffer: (1) An area of storage that is temporarily reserved for use in performing an input/output operation, into which data is read or from which data is written. Synonymous with I/O area. (2) A portion of storage for temporarily holding input or output data.

bus: One or more conductors used for transmitting signals or power.

byte: (1) A binary character operated upon as a unit and usually shorter than a computer word. (2) The representation of a character.

CAS: Column address strobe.

cathode ray tube (CRT): A vacuum tube display in which a beam of electrons can be controlled to form alphanumeric characters or symbols on a luminescent screen, for example by use of a dot matrix.

cathode ray tube display (CRT display): (1) A device that presents data in visual form by means of controlled electron beams. (2) The data display produced by the device as in (1).

CCITT: Comite Consultatif International Telegrafique et Telephonique.

central processing unit (CPU): A functional unit that consists of one or more processors and all or part of internal storage.

channel: A path along which signals can be sent; for example, data channel or I/O channel.

characters per second (cps): A standard unit of measurement for printer output.

code: (1) A set of unambiguous rules specifying the manner in which data may be represented in a discrete form. Synonymous with coding scheme. (2) A set of items, such as abbreviations, representing the members of another set. (3) Loosely, one or more computer programs, or part of a computer program. (4) To represent data or a computer program in a symbolic form that can be accepted by a data processor.

column address strobe (CAS): A signal that latches the column addresses in a memory chip.

Comite Consultatif International Telegrafique et Telephonique (CCITT): Consultative Committee on International Telegraphy and Telephony.

computer: A functional unit that can perform substantial computation, including numerous arithmetic operations, or logic operations, without intervention by a human operator during the run.

configuration: (1) The arrangement of a computer system or network as defined by the nature, number, and the chief characteristics of its functional units. More specifically, the term configuration may refer to a hardware configuration or a software configuration. (2) The devices and programs that make up a system, subsystem, or network.

conjunction: (1) The boolean operation whose result has the boolean value 1 if, and only if, each operand has the boolean value 1. (2) Synonymous with AND operation.

contiguous: (1) Touching or joining at the edge or boundary. (2) Adjacent.

CPS: Characters per second.

CPU: Central processing unit.

CRC: Cyclic redundancy check.

CRT: Cathode ray tube.

CRT display: Cathode ray tube display.

CTS: Clear to send. Associated with modem control.

cyclic redundancy check (CRC): (1) A redundancy check in which the check key is generated by a cyclic algorithm. (2) A system of error checking performed at both the sending and receiving station after a block-check character has been accumulated.

cylinder: (1) The set of all tracks with the same nominal distance from the axis about which the disk rotates. (2) The tracks of a disk storage device that can be accessed without repositioning the access mechanism.

daisy-chained cable: A type of cable that has two or more connectors attached in series.

data: (1) A representation of facts, concepts, or instructions in a formalized manner suitable for communication, interpretation, or processing by humans or automatic means. (2) Any representations, such as characters or analog quantities, to which meaning is, or might be assigned.

decoupling capacitor: A capacitor that provides a low-impedance path to ground to prevent common coupling between states of a circuit.

Deutsche Industrie Norm (DIN): (1) German Industrial Norm. (2) The committee that sets German dimension standards.

digit: (1) A graphic character that represents an integer, for example, one of the characters 0 to 9. (2) A symbol that represents one of the non-negative integers smaller than the radix. For example, in decimal notation, a digit is one of the characters from 0 to 9.

digital: (1) Pertaining to data in the form of digits. (2) Contrast with analog.

DIN: Deutsche Industrie Norm.

DIN connector: One of the connectors specified by the DIN standardization committee.

DIP: Dual in-line package.

direct memory access (DMA): A method of transferring data between main storage and I/O devices that does not require processor intervention.

disk: Loosely, a magnetic disk unit.

diskette: A thin, flexible magnetic disk and a semi-rigid protective jacket, in which the disk is permanently enclosed. Synonymous with flexible disk.

DMA: Direct memory access.

DSR: Data set ready. Associated with modem control.

DTR: Data terminal ready. Associated with modem control.

dual in-line package (DIP): A widely used container for an integrated circuit. DIPs are pins usually in two parallel rows. These pins are spaced 1/10 inch apart and come in different configurations ranging from 14-pin to 40-pin configurations.

EBCDIC: Extended binary-coded decimal interchange code.

ECC: Error checking and correction.

edge connector: A terminal block with a number of contacts attached to the edge of a printed circuit board to facilitate plugging into a foundation circuit.

EIA: Electronic Industries Association.

EIA/CCITT: Electronics Industries Association/Consultative Committee on International Telegraphy and Telephony.

end-of-text-character (ETX): A transmission control character used to terminate text.

end-of-transmission character (EOT): A transmission control character used to indicate the conclusion of a transmission, which may have included one or more texts and any associated message headings.

EOT: End-of-transmission character.

EPROM: Erasable programmable read-only memory.

erasable programmable read-only memory (EPROM): A storage device whose contents can be changed by electrical means. EPROM information is not destroyed when power is removed.

error checking and correction (ECC): The detection and correction of all single-bit, double-bit, and some multiple-bit errors.

ETX: End-of-text character.

extended binary-coded decimal interchange code (EBCDIC): A set of 256 characters, each represented by eight bits.

flexible disk: Synonym for diskette.

firmware: Memory chips with integrated programs already incorporated on the chip.

gate: (1) A device or circuit that has no output until it is triggered into operation by one or more enabling signals, or until an input signal exceeds a predetermined threshold amplitude. (2) A signal that triggers the passage of other signals through a circuit.

graphic: A symbol produced by a process such as handwriting, drawing, or printing.

hertz (Hz): A unit of frequency equal to one cycle per second.

hex: Abbreviation for hexadecimal.

hexadecimal: Pertaining to a selection, choice, or condition that has 16 possible values or states. These values or states usually contain 10 digits and 6 letters, A through F. Hexadecimal digits are equivalent to a power of 16.

high-order position: The leftmost position in a string of characters.

Hz: Hertz.

interface: A device that alters or converts actual electrical signals between distinct devices, programs, or systems.

k: An abbreviation for the prefix kilo; that is, 1,000 in decimal notation.

K: When referring to storage capacity, 2 to the tenth power; 1,024 in decimal notation.

KB: Kilobyte; 1,024 bytes.

kHz: A unit of frequency equal to 1,000 hertz.

kilo (k): One thousand.

latch: (1) A feedback loop in symmetrical digital circuits used to maintain a state. (2) A simple logic-circuit storage element comprising two gates as a unit.

LED: Light-emitting diode.

light-emitting diode (LED): A semi-conductor chip that gives off visible or infrared light when activated.

low-order position: The rightmost position in a string of characters.

m: (1) Milli; one thousand or thousandth part. (2) Meter.

M: Mega; 1,000,000 in decimal notation. When referring to storage capacity, 2 to the twentieth power; 1,048,576 in decimal notation.

mA: Milliampere.

machine language: (1) A language that is used directly by a machine. (2) Another term for computer instruction code.

main storage: A storage device in which the access time is effectively independent of the location of the data.

MB: Megabyte, 1,048,576 bytes.

mega (M): 10 to the sixth power, 1,000,000 in decimal notation. When referring to storage capacity, 2 to the twentieth power, 1,048,576 in decimal notation.

megabyte (MB): 1,048,576 bytes.

megahertz (MHz): A unit of measure of frequency. 1 megahertz equals 1,000,000 hertz.

MFM: Modified frequency modulation.

MHz: Megahertz.

microprocessor: An integrated circuit that accepts coded instructions for execution; the instructions may be entered, integrated, or stored internally.

microsecond (μ s): One-millionth of a second.

milli (m): One thousand or one thousandth.

milliampere (mA): One thousandth of an ampere.

millisecond (ms): One thousandth of a second.

mnemonic: A symbol chosen to assist the human memory; for example, an abbreviation such a “mpy” for “multiply.”

mode: (1) A method of operation; for example, the binary mode, the interpretive mode, the alphanumeric mode. (2) The most frequency value in the statistical sense.

modem: (Modulator-Demodulator) A device that converts serial (bit by bit) digital signals from a business machine (or data terminal equipment) to analog signals which are suitable for transmission in a telephone network. The inverse function is also performed by the modem on reception of analog signals.

modified frequency modulation (MFM): The process of varying the amplitude and frequency of the “write” signal. MFM pertains to the number of bytes of storage that can be stored on the recording media. The number of bytes is twice the number contained in the same unit area of recording media at single density.

modulo check: A calculation performed on values entered into a system. This calculation is designed to detect errors.

monitor: (1) A device that observes and verifies the operation of a data processing system and indicates any specific departure from the norm. (2) A television type display, such as the IBM Monochrome Display. (3) Software or hardware that observes, supervises, controls, or verifies the operations of a system.

ms: Millisecond; one thousandth of a second.

multiplexer: A device capable of interleaving the events of two or more activities, or capable of distributing the events of an interleaved sequence to the respective activities.

NAND: A logic operator having the property that if P is a statement, Q is a statement, R is a statement,...,then the NAND of P,Q,R,...is true if at least one statement is false, false if all statements are true.

nanosecond (ns): One-thousandth-millionth of a second.

nonconjunction: The dyadic boolean operation the result of which has the boolean value 0 if, and only if, each operand has the boolean value 1.

non-return-to-zero inverted (NRZI): A transmission encoding method in which the data terminal equipment changes the signal to the opposite state to send a binary 0 and leaves it in the same state to send a binary 1.

NOR: A logic operator having the property that if P is a statement, Q is a statement, R is a statement,...,then the NOR of P,Q,R,...is true if all statements are false, false if at least one statement is true.

NOT: A logical operator having the property that if P is a statement, then the NOT of P is true if P is false, false if P is true.

NRZI: Non-return-to-zero inverted.

ns: Nanosecond; one-thousandth-millionth of a second.

operating system: Software that controls the execution of programs; an operating system may provide services such as resource allocation, scheduling, input/output control, and data management.

OR: A logic operator having the property that if P is a statement, Q is a statement, R is a statement,...,then the OR of P,Q,R,...is true if at least one statement is true, false if all statements are false.

output: Pertaining to a device, process, or channel involved in an output process, or to the data or states involved in an output process.

output process: (1) The process that consists of the delivery of data from a data processing system, or from any part of it. (2) The return of information from a data processing system to an end user, including the translation of data from a machine language to a language that the end user can understand.

overcurrent: A current of higher than specified strength.

overvoltage: A voltage of higher than specified value.

parallel: (1) Pertaining to the concurrent or simultaneous operation of two or more devices, or to the concurrent performance of two or more activities. (2) Pertaining to the concurrent or simultaneous occurrence of two or more related activities in multiple devices or channels. (3) Pertaining to the simultaneity of two or more processes. (4) Pertaining to the simultaneous processing of the individual parts of a whole, such as the bits of a character and the characters of a word, using separate facilities for the various parts. (5) Contrast with serial.

PEL: Picture element.

personal computer: A small home or business computer that has a processor and keyboard that can be connected to a television or some other monitor. An optional printer is usually available.

picture element (PEL): (1) The smallest displayable unit on a display. (2) Synonymous with pixel, PEL.

pinout: A diagram of functioning pins on a pinboard.

pixel: Picture element.

polling: (1) Interrogation of devices for purposes such as to avoid contention, to determine operational status, or to determine readiness to send or receive data. (2) The process whereby stations are invited, one at a time, to transmit.

port: An access point for data entry or exit.

printed circuit board: A piece of material, usually fiberglass, that contains a layer of conductive material, usually metal. Miniature electronic components on the fiberglass transmit electronic signals through the board by way of the metal layers.

program: (1) A series of actions designed to achieve a certain result. (2) A series of instructions telling the computer how to handle a problem or task. (3) To design, write, and test computer programs.

programming language: (1) An artificial language established for expressing computer programs. (2) A set of characters and rules, with meanings assigned prior to their use, for writing computer programs.

PROM: Programmable read-only memory.

propagation delay: The time necessary for a signal to travel from one point on a circuit to another.

radix: (1) In a radix numeration system, the positive integer by which the weight of the digit place is multiplied to obtain the weight of the digit place with the next higher weight; for example, in the decimal numeration system, the radix of each digit place is 10. (2) Another term for base.

radix numeration system: A positional representation system in which the ratio of the weight of any one digit place to the weight of the digit place with the next lower weight is a positive integer. The permissible values of the character in any digit place range from zero to one less than the radix of the digit place.

RAS: Row address strobe.

RGBI: Red-green-blue-intensity.

read-only memory (ROM): A storage device whose contents cannot be modified, except by a particular user, or when operating under particular conditions; for example, a storage device in which writing is prevented by a lockout.

read/write memory: A storage device whose contents can be modified.

red-green-blue-intensity (RGBI): The description of a direct-drive color monitor which accepts red, green, blue, and intensity signal inputs.

register: (1) A storage device, having a specified storage capacity such as a bit, a byte, or a computer word, and usually intended for a special purpose. (2) On a calculator, a storage device in which specific data is stored.

RF modulator: The device used to convert the composite video signal to the antenna level input of a home TV.

ROM: Read-only memory.

ROM/BIOS: The ROM resident basic input/output system, which provides the device level control of the major I/O devices in the computer system.

row address strobe (RAS): A signal that latches the row addresses in a memory chip.

RS-232C: The standard set by the EIA for communications between computers and external equipment.

RTS: Request to send. Associated with modem control.

run: A single continuous performance of a computer program or routine.

scan line: The use of a cathode beam to test the cathode ray tube of a display used with a personal computer.

schematic: The description, usually in diagram form, of the logical and physical structure of an entire data base according to a conceptual model.

SDLC: Synchronous Data Link Control.

sector: That part of a track or band on a magnetic drum, a magnetic disk, or a disk pack that can be accessed by the magnetic heads in the course of a predetermined rotational displacement of the particular device.

serdes: Serializer/deserializer.

serial: (1) Pertaining to the sequential performance of two or more activities in a single device. In English, the modifiers serial and parallel usually refer to devices, as opposed to sequential and consecutive, which refer to processes. (2) Pertaining to the sequential or consecutive occurrence of two or more related activities in a single device or channel. (3) Pertaining to the sequential processing of the individual parts of a whole, such as the bits of a character or the characters of a word, using the same facilities for successive parts. (4) Contrast with parallel.

sink: A device or circuit into which current drains.

software: (1) Computer programs, procedures, rules, and possibly associated documentation concerned with the operation of a data processing system. (2) Contrast with hardware.

source: The origin of a signal or electrical energy.

source circuit: (1) Generator circuit. (2) Control with sink.

SS: Start-stop transmission.

start bit: Synonym for start signal.

start-of-text character (STX): A transmission control character that precedes a text and may be used to terminate the message heading.

start signal: (1) A signal to a receiving mechanism to get ready to receive data or perform a function. (2) In a start-stop system, a signal preceding a character or block that prepares the receiving device for the reception of the code elements. Synonymous with start bit.

start-stop (SS) transmission: Asynchronous transmission such that a group of signals representing a character is preceded by a start signal and followed by a stop signal. (2) Asynchronous transmission in which a group of bits is preceded by a start bit that prepares the receiving mechanism for the reception and registration of a character and is followed by at least one stop bit that enables the receiving mechanism to come to an idle condition pending the reception of the next character.

stop bit: Synonym for stop signal.

stop signal: (1) A signal to a receiving mechanism to wait for the next signal. (2) In a start-stop system, a signal following a character or block that prepares the receiving device for the reception of a subsequent character or block. Synonymous with stop bit.

strobe: (1) An instrument used to determine the exact speed of circular or cyclic movement. (2) A flashing signal displaying an exact event.

STX: Start-of-text character.

Synchronous Data Link Control (SLDC): A protocol for the management of data transfer over a data communications link.

synchronous transmission: Data transmission in which the sending and receiving devices are operating continuously at the same frequency and are maintained, by means of correction, in a desired phase relationship.

text: In ASCII and data communication, a sequence of characters treated as an entity if preceded and terminated by one STX and one ETX transmission control, respectively.

track: (1) The path or one of the set of paths, parallel to the reference edge on a data medium, associated with a single reading or writing component as the data medium moves past the component. (2) The portion of a moving data medium such as a drum, tape, or disk, that is accessible to a given reading head position.

transistor-transistor logic (TTL): A circuit in which the multiple-diode cluster of the diode-transistor logic circuit has been replaced by a multiple-emitter transistor.

TTL: Transistor-transistor logic.

TX Data: Transmit data. Associated with modem control. External connections of the RS-232C asynchronous communications adapter interface.

video: Computer data or graphics displayed on a cathode ray tube, monitor or display.

write precompensation: The varying of the timing of the head current from the outer tracks to the inner tracks of the diskette to keep a constant write signal.

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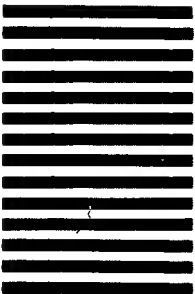
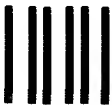
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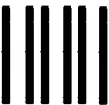
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